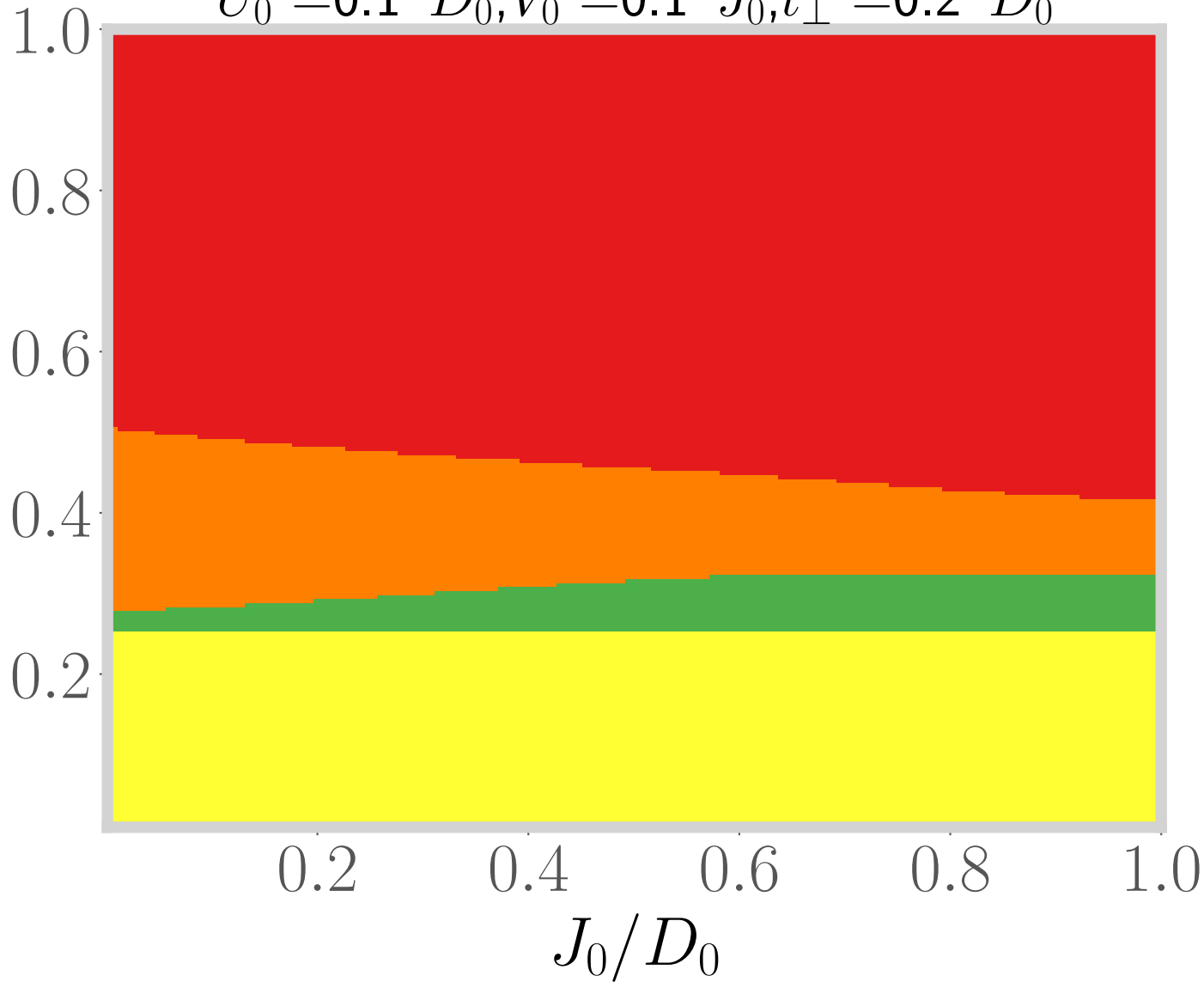


$$U_0 = 0.1 * D_0, V_0 = 0.1 * J_0, t_{\perp} = 0.2 * D_0$$

 τ 

- $J_R, V2_R$
- Coaxis_J_R
- $J_R, V1_R, V2_R$
- $V2_R$
- $V1_R, V2_R$
- Dead Zone
- Ins_U_R