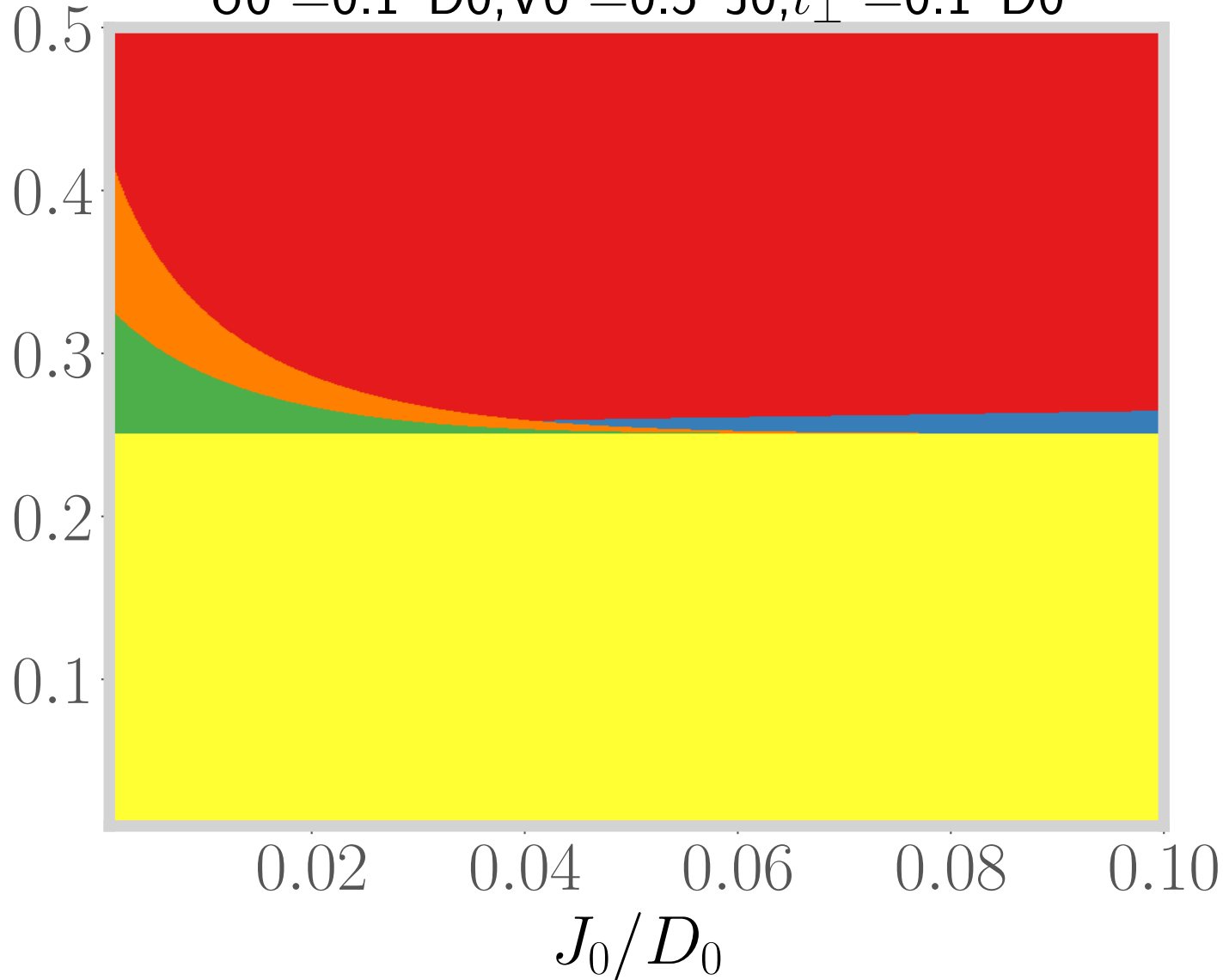


$$U_0 = 0.1 \cdot D_0, V_0 = 0.5 \cdot J_0, t_{\perp} = 0.1 \cdot D_0$$

 τ  $J_R, V2_R$

Coexis_J_R

 $J_R, V1_R, V2_R$ $V2_R$ $V1_R, V2_R$

Dead Zone

Ins_U_R