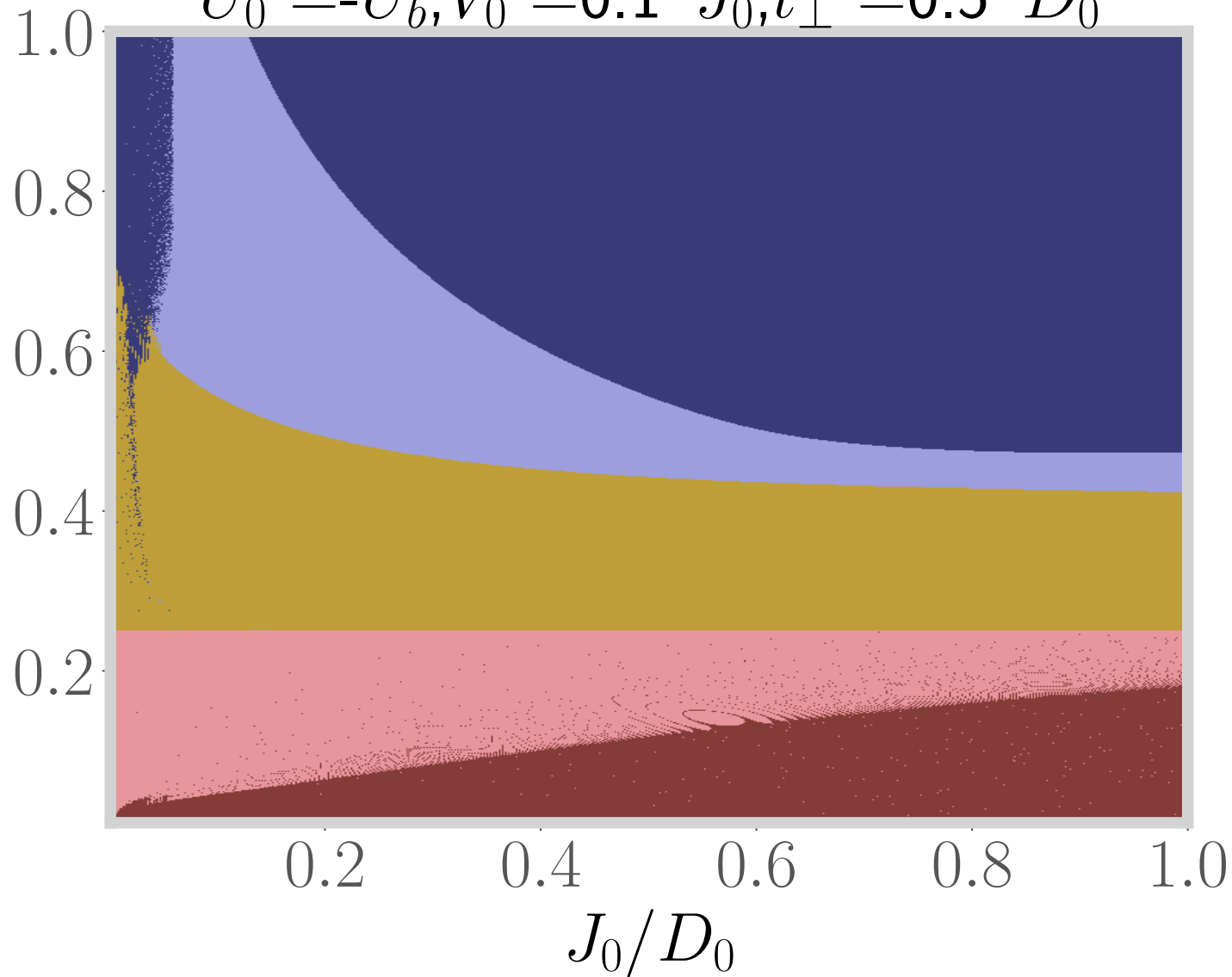


$$U_0 = -U_b, V_0 = 0.1 * J_0, t_{\perp} = 0.5 * D_0$$

 $\tau$ 


Coaxis- $J_R$

$J_R, V_{2R}$

$J_R, V_{1R}, V_{2R}$

$V_{2R}$

$V_{1R}, V_{2R}$

Dead

Ins- $U_R$