

3. Process Concept

[ECE30021/ITP30002] Operating Systems

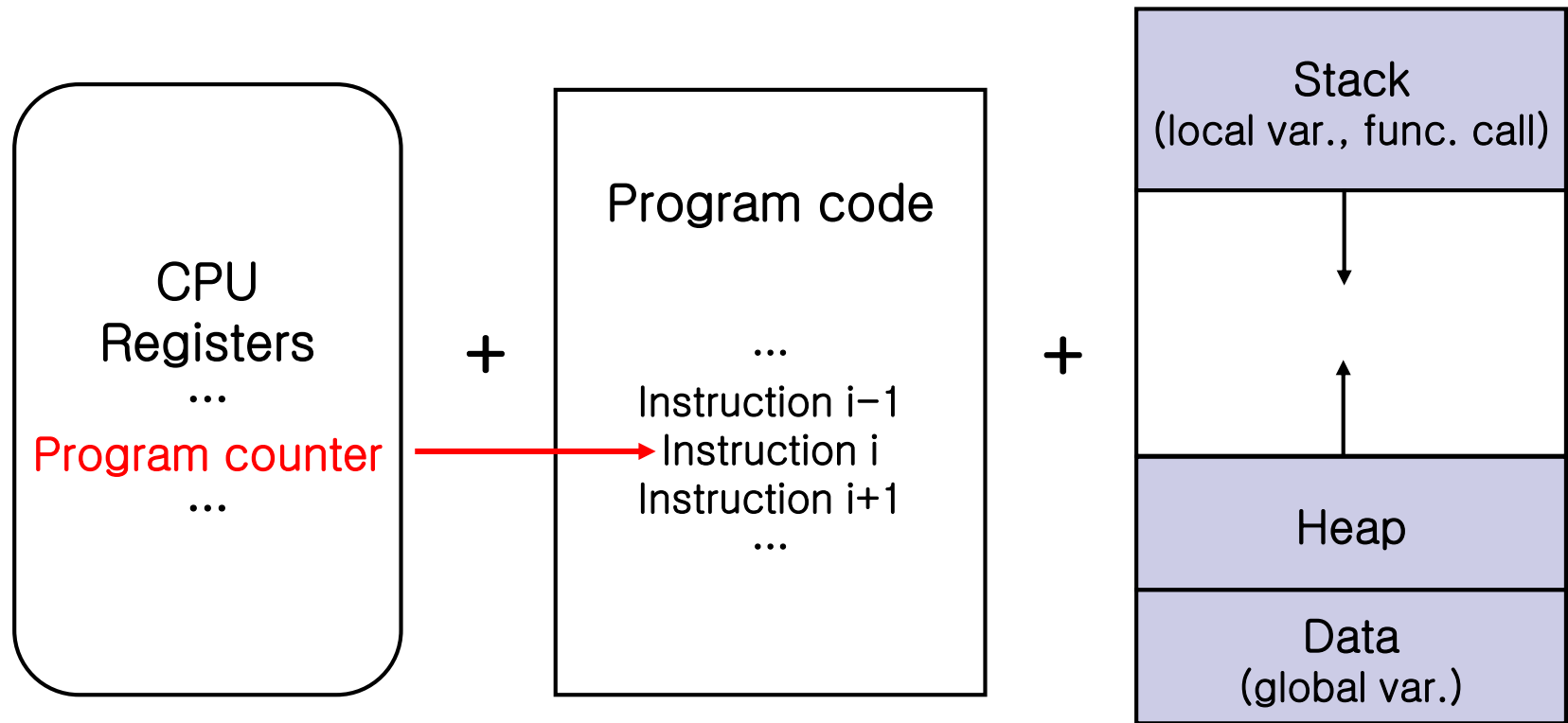
Agenda



- Overview
- Process scheduling
- Operations on processes
- Inter-process communication
- Example of IPC system
- Communication in client-server systems

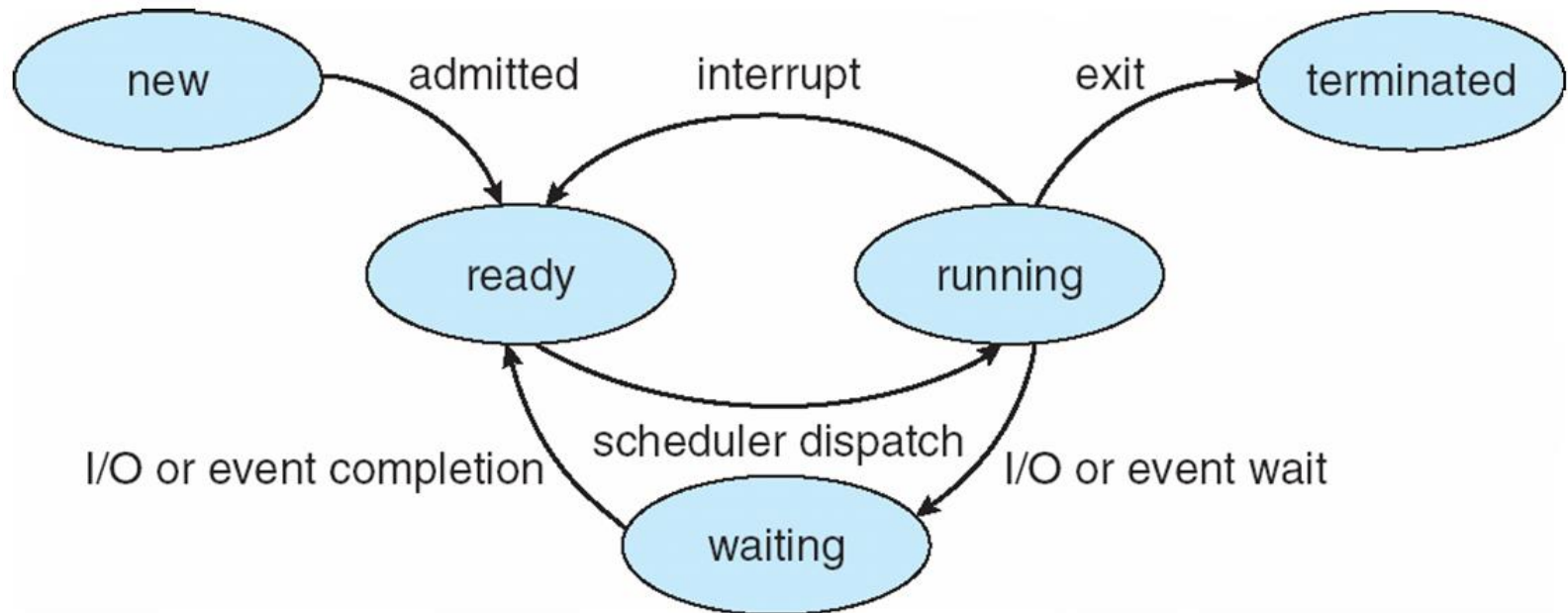
Process

- **Process** = program in execution + resource

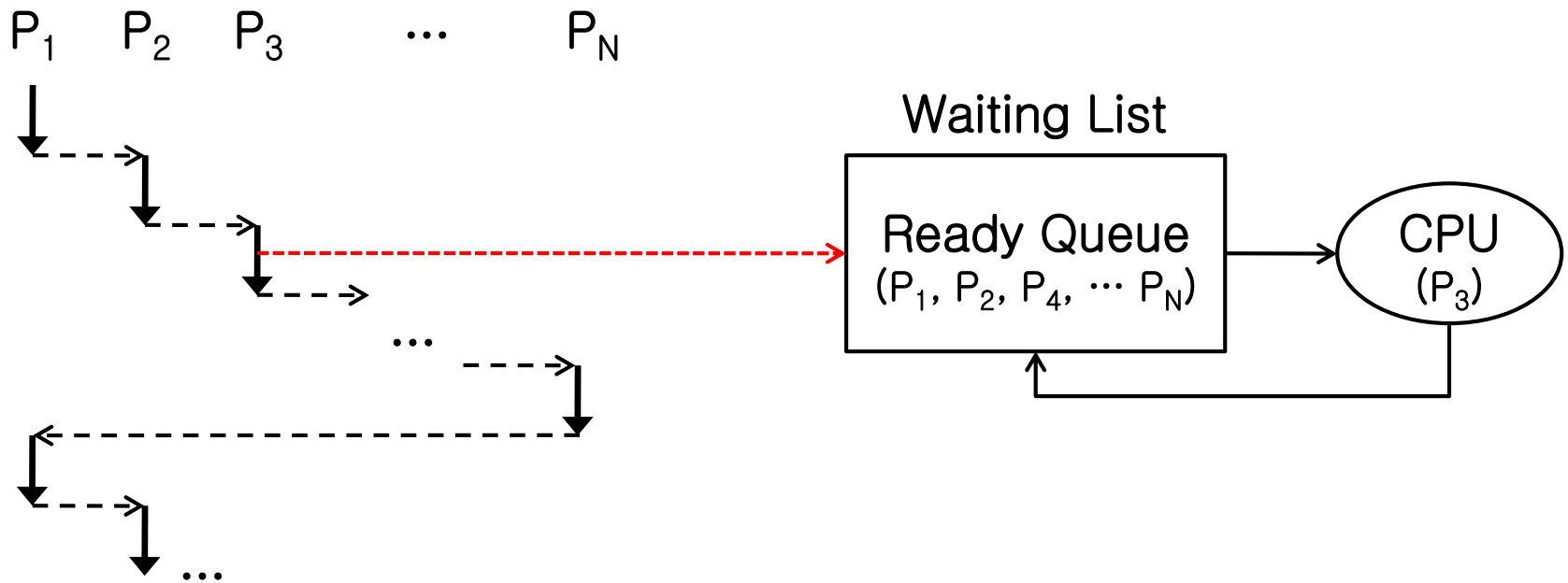


Process State

- **New:** being created
- **Running:** in execution
 - Only one process can be running on a processor at any time
- **Ready:** waiting to be assigned to a processor
- **Waiting:** waiting for some event to occur
- **Terminated**



Ready/Running State



Process Control Block (PCB)

- OS manages processes using PCB
 - **Process Control Block (PCB)**: repository for any information about process

Contents	Examples
Process state	new, ready, running, waiting, terminated, ...
Process number	pid (Process ID)
CPU Registers	<u>program counter</u> (address of next instruction to execute) accumulator, general registers, stack pointer, ...
CPU Scheduling info.	priority, pointer to queue, ...
Memory-management info.	base and limit registers, page/segment table, ...
Accounting info.	CPU-time used, time limits, account #, ...
I/O status info.	List of open files, I/O devices allocated

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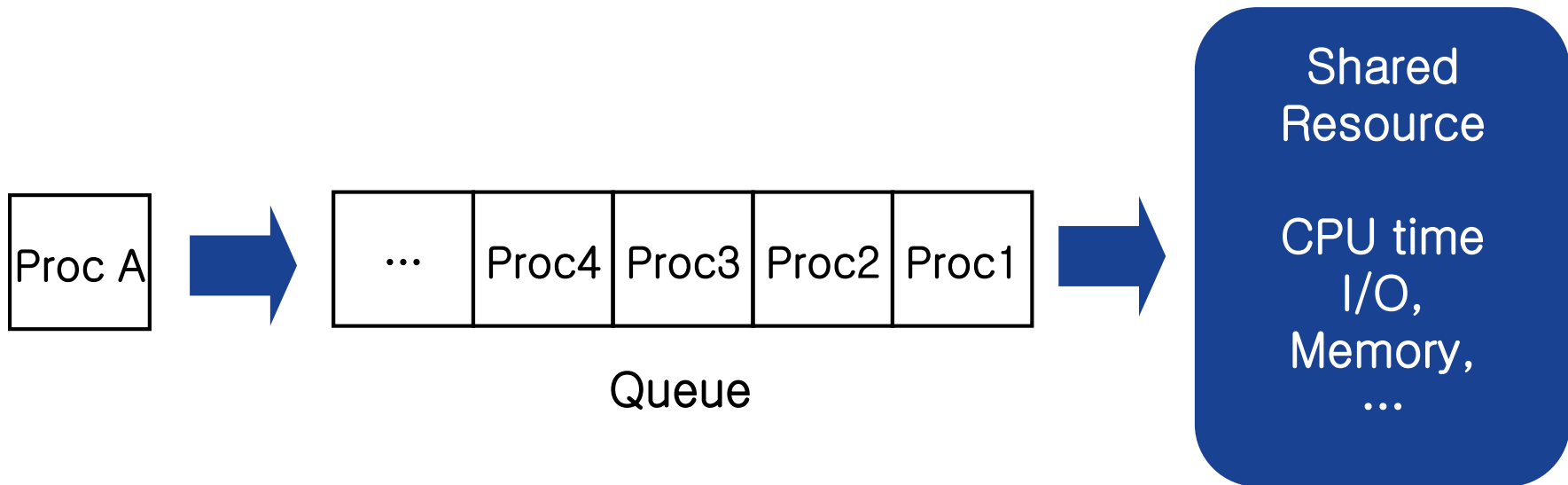
Process Scheduling



- **Scheduling**: assigning tasks to a set of resources
- **Process scheduling**: selecting a process to execute on CPU
 - Only one process can run on each processor at a time.
 - Other processes should wait
- **Objectives of scheduling**
 - Maximize CPU utilization
 - Users can interact with each program

Scheduling Queue

- **Scheduling queue**: waiting list of processes for CPU time or other resources



Types of Scheduling Queues



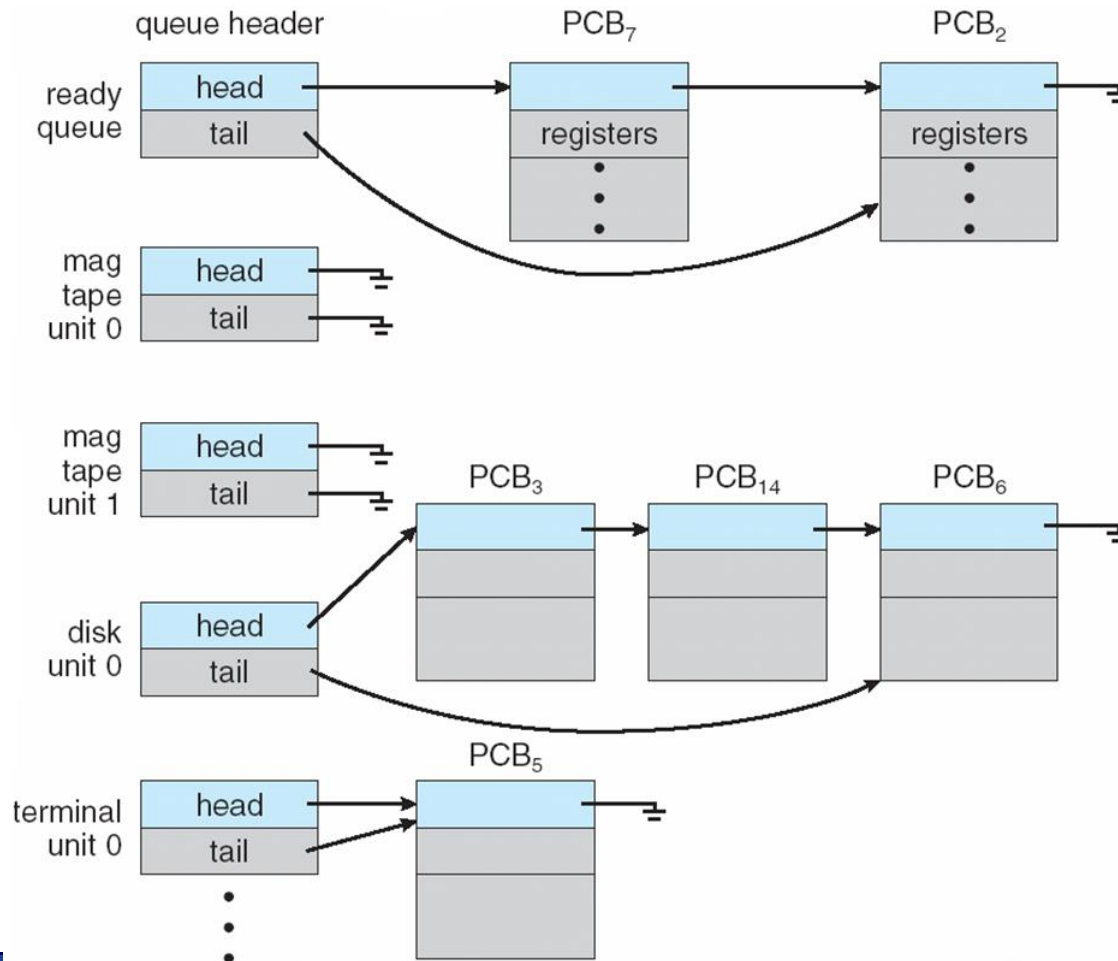
- **Job queue**
 - List of all processes in the system

- **Ready queue**
 - List of processes, residing in main memory, ready to execute

- **Device queue**
 - List of processes waiting for a particular I/O device.
 - Each device has its own device queue.

Scheduling Queue

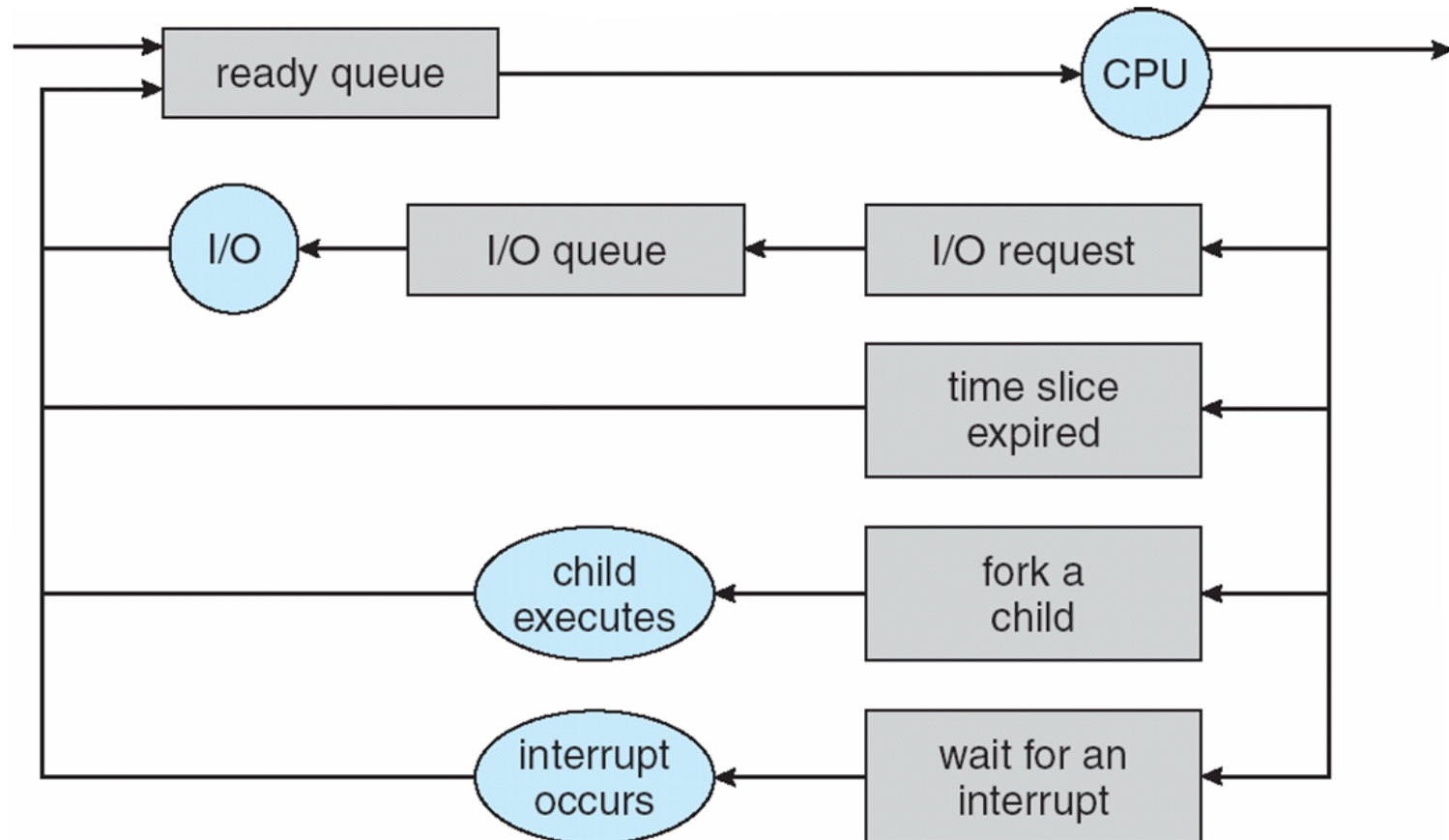
- Each queue is usually represented by linked list



Queueing Diagram

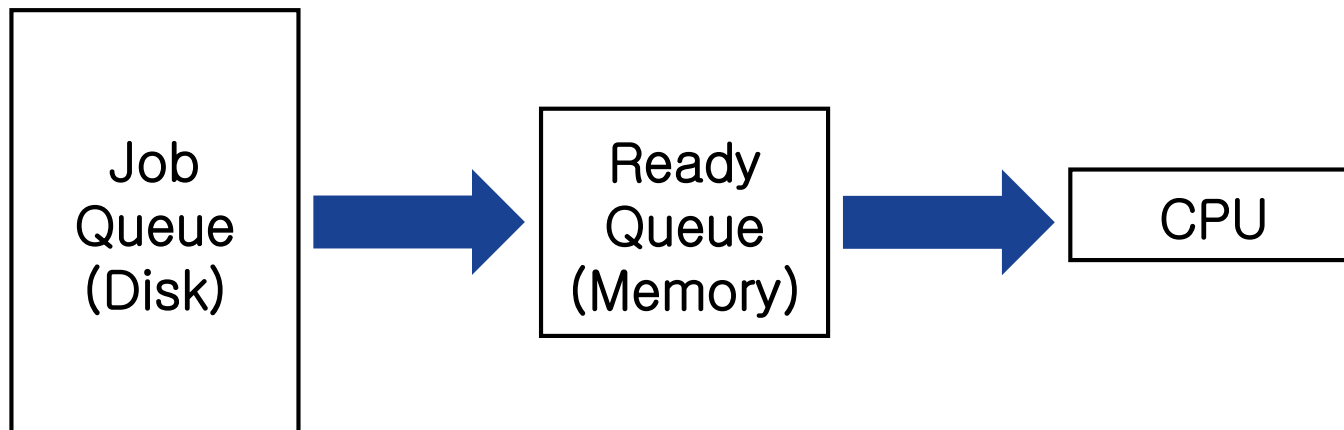
■ Representation of process scheduling

- A process migrates among various scheduling queues throughout its lifetime



Schedulers

- Scheduler selects processes from queues in some fashion.
 - Long-term scheduler (job scheduler)
 - Short-term scheduler (CPU scheduler)



Schedulers

- Short-term scheduler (CPU scheduler)



- Executed frequently (at least once every 100 msec.).
- Scheduling time should be very short.

Schedulers

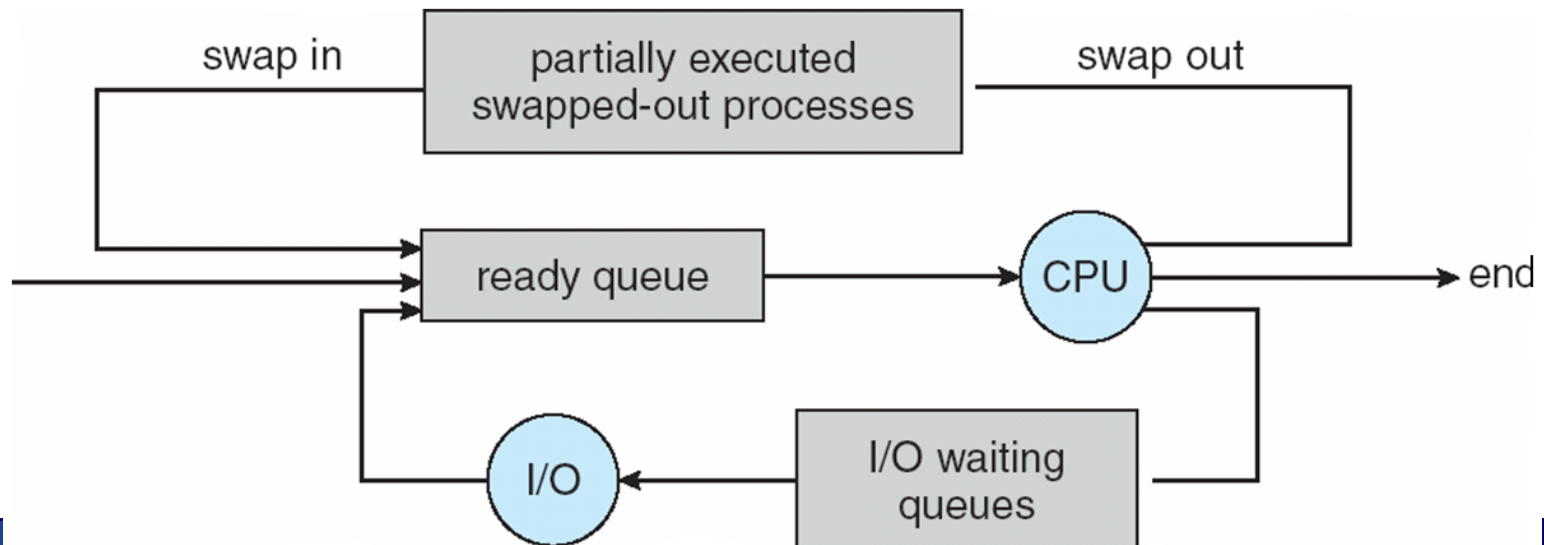
- Long-term scheduler (job scheduler)



- Controls **degree of multiprogramming**
 - ▢ In stable state, average process creation rate == average process departure rate
- Executed less frequently
 - ▢ Executed only when a process leaves the system
- Hopefully, long-term scheduler should select a good mix of **I/O-bound** and **CPU-bound** processes

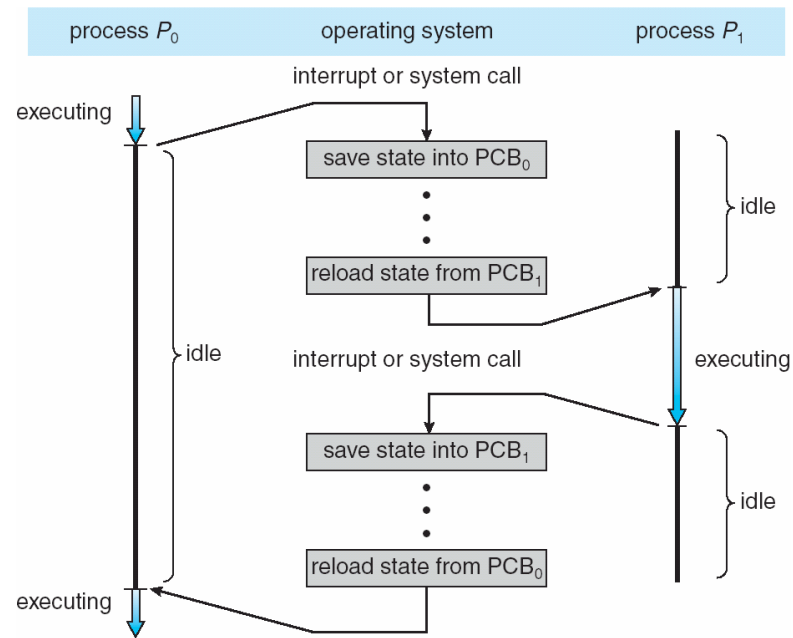
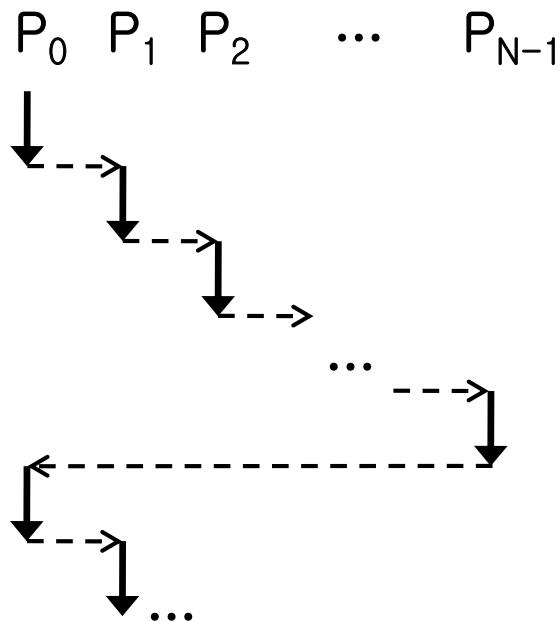
Schedulers

- In some systems, long-term scheduler may be absent or minimal
Ex) UNIX, Windows
 - System stability depends on physical limitation or self-adjusting nature of human
- Some time-sharing system has **medium-term scheduler**
 - Reduce degree of multiprogramming by removing processes from memory



Context Switch

- Switching running process requires **context switch**
 - Save state (context) of current process (PCB)
 - Restore state (context) of the next process



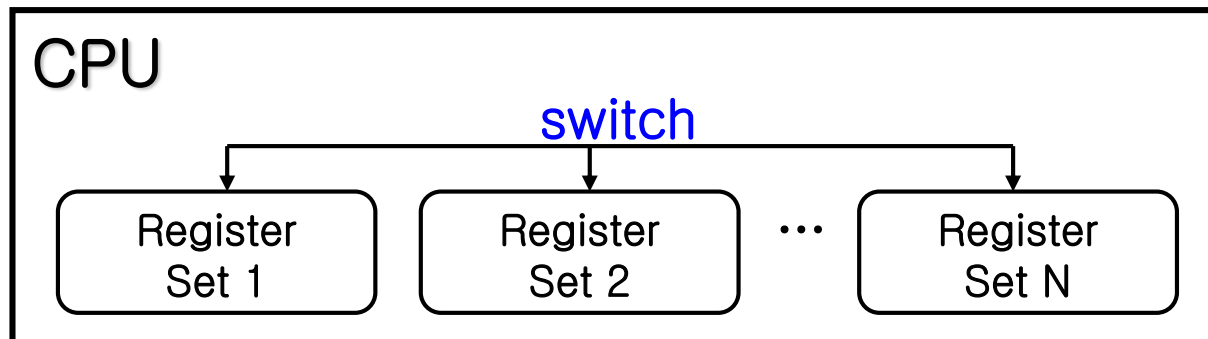
Context Switch



- **Context switch**: the computing process of storing and restoring the state (context) of a CPU such that multiple processes can share a single CPU resource.
- “Context” includes
 - Register contents
 - OS specific data
 - Extra data required by advanced memory-management technique
Ex) page table, segment table, ...
- When to switch?
 - Multitasking
 - Interrupt handling

Context Switch

- Context switching requires considerable overhead.
- H/W supports for context-switching
 - H/W switching (eg. single instruction to load/save all registers)
 - cf. However, S/W switching can be more selective and save only that portion that actually needs to be saved and reloaded.
 - Multiple set of register for fast switching
 - Ex) UltraSPARC



Operations on Processes

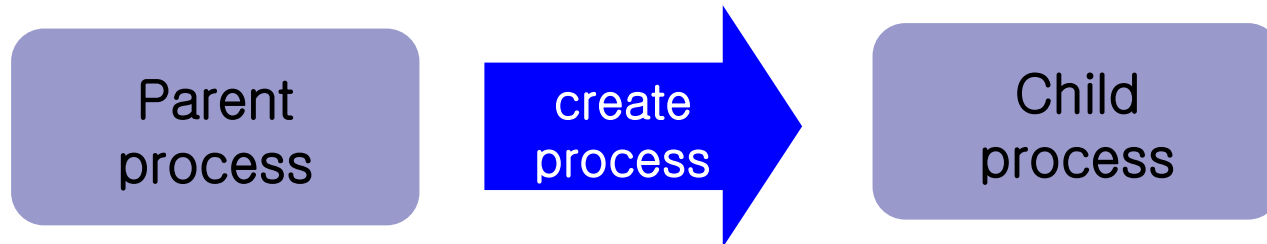


- Process create
- Process termination
- Process communication

Process Creation

- Create-process system call

- Creates a process and assigns a **pid** (process ID).

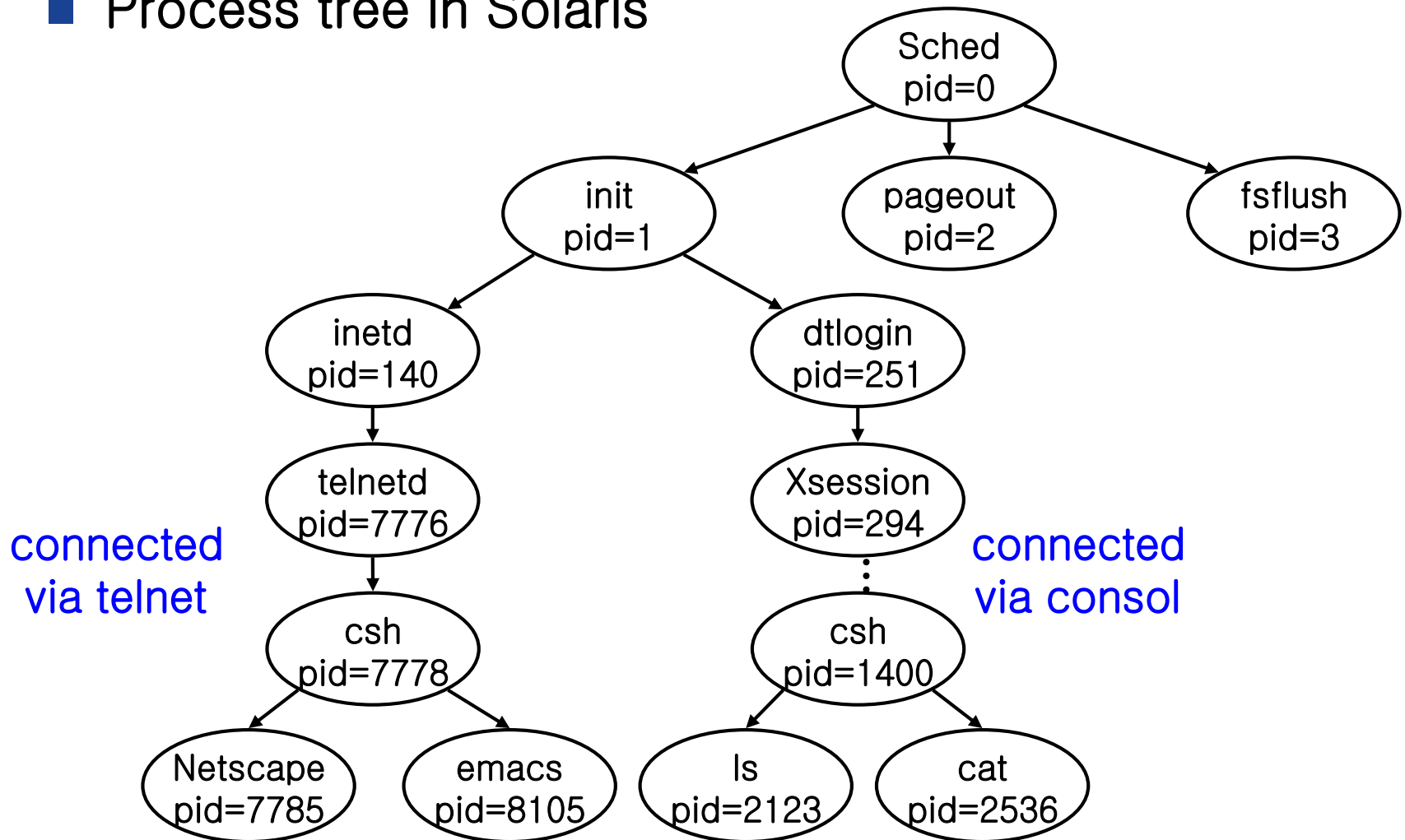


- Process tree

- Parent-child relation between processes

Example of Process Tree

■ Process tree in Solaris



Displaying Process Information



- UNIX

- `ps [-el]`

- Windows

- Task manager (windows system program)
 - [Process explorer](#) (freeware)

Process Creation

- Some options to create a process

Resource	Child requests its own resource directly from OS or A subset of parent's resource is shared
Execution	Concurrent execution or Parent waits until child is terminated
Address space	Program code and data are shared or Child process has a new program loaded into it

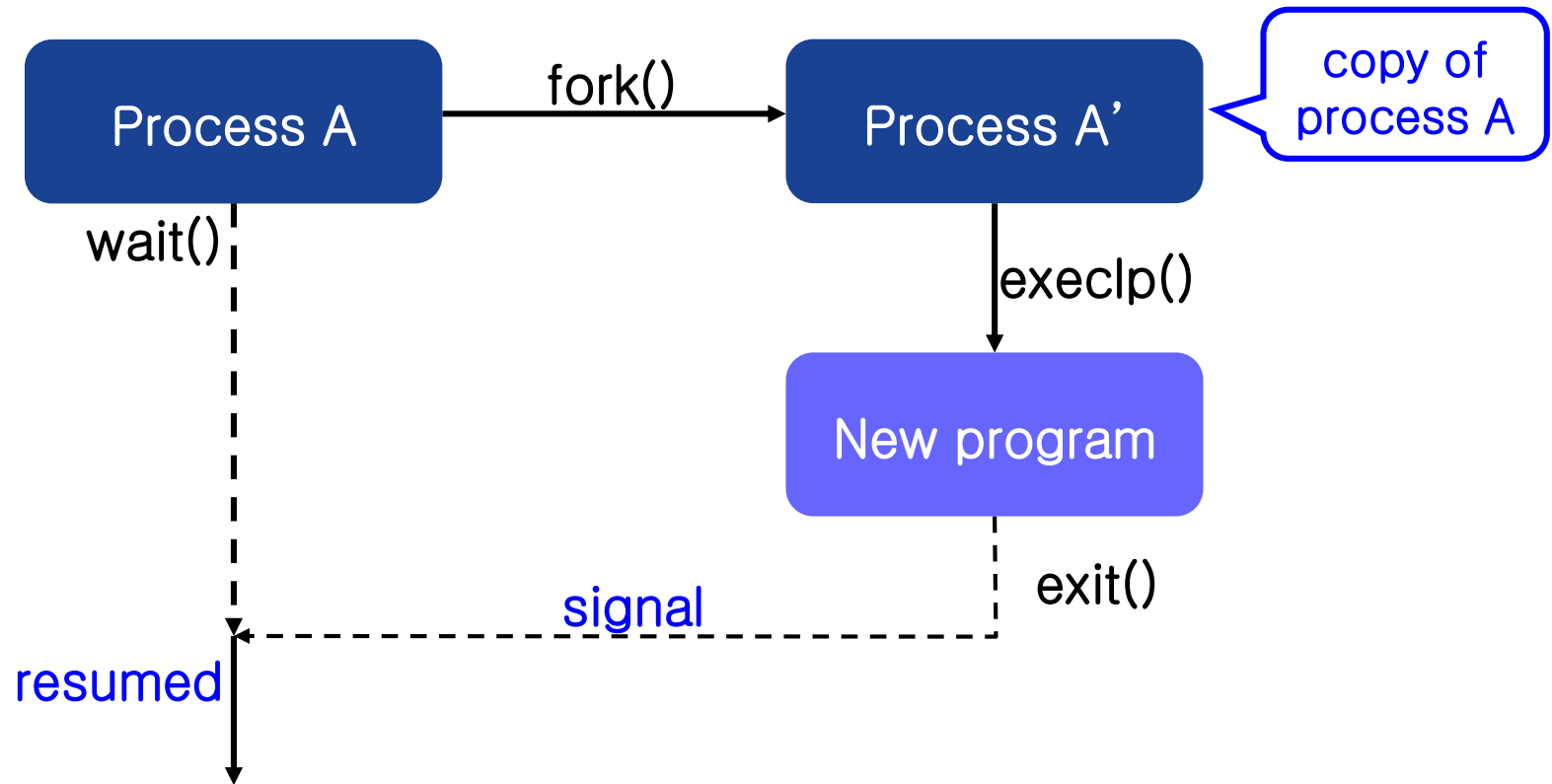
Process Creation in UNIX



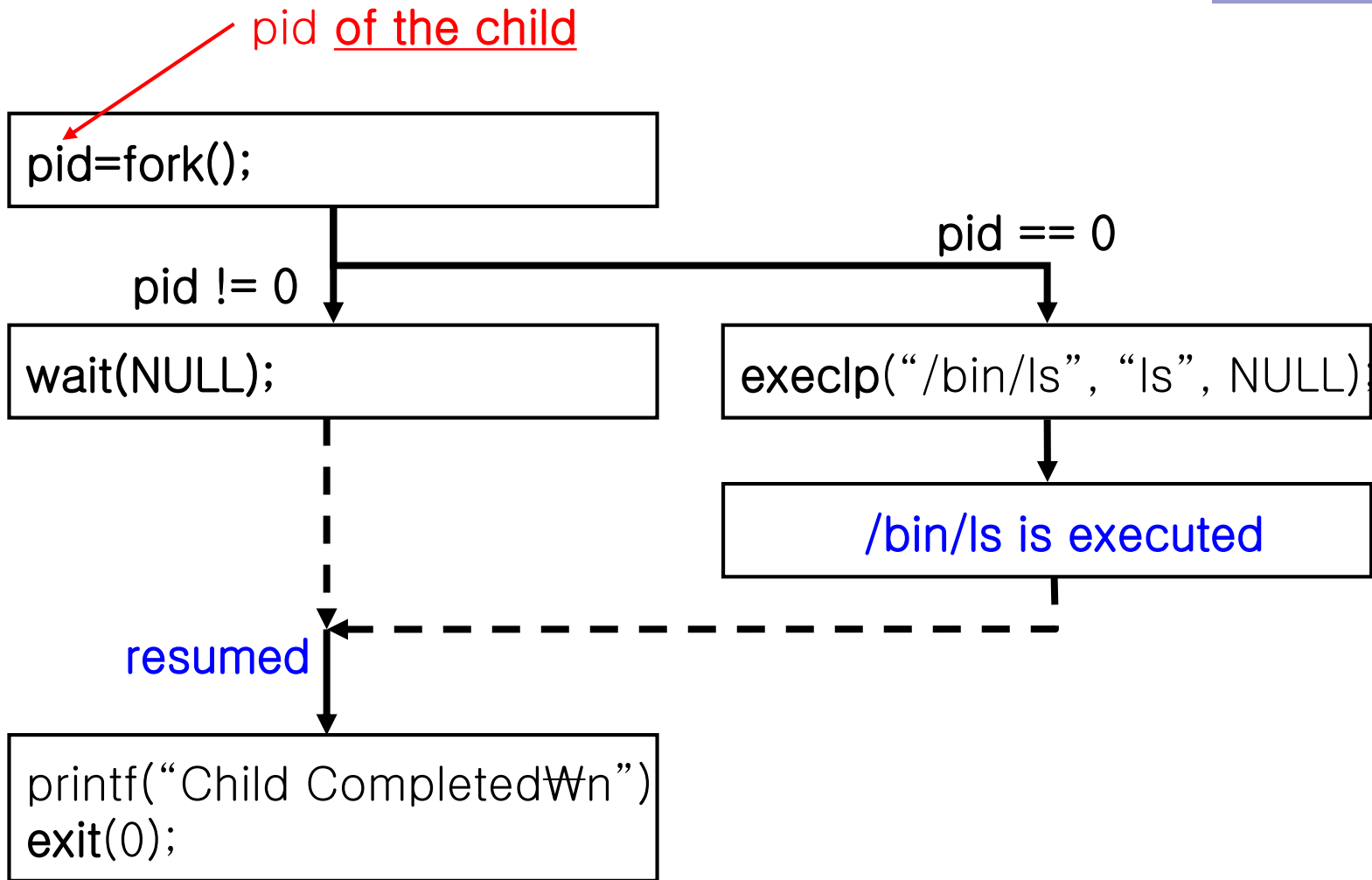
- UNIX system calls related to process creation
 - **fork()**: create process and returns its pid
 - In parent process, return value is **pid of child**
 - In child process, return value is zero
 - **exec() family**: execute a program. The new program substitutes the original one.
 - `execl()`, `execv()`, `execvp()`, `execle()`, `execve()`
 - **wait()**: waits until child process is terminated

Example of Process Creation

- Executing other program



Example of Process Creation



Example of Process Creation

```
int main()
{
    pid_t pid = fork();           // create a process
    if(pid < 0){                  // error occurred
        fprintf(stderr, "fork failed\n");
        exit(-1);
    } else if(pid == 0){         // child process
        execlp("/bin/ls", "ls", NULL);
    } else {                    // if pid != 0, parent process
        wait(NULL);             // waits for child process to complete
        printf("Child Completed\n");
        exit(0);
    }
}
```

Example of Process Creation

■ Parent process

```
int main()
{
    pid_t pid = fork();
    if(pid < 0){
        fprintf(stderr, "fork failed\n");
        exit(-1);
    } else if(pid == 0){
        execlp("/bin/ls", "ls", NULL);
    } else {
        wait(NULL);
        printf("Child Completed\n");
        exit(0);
    }
}
```

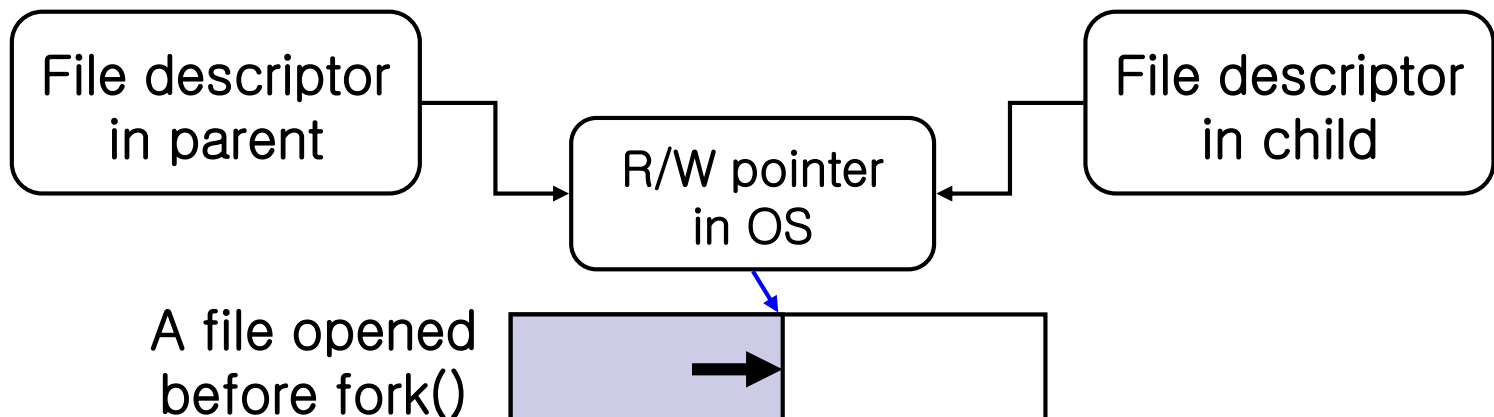
■ Child process

```
int main()
{
    pid_t pid = fork();
    if(pid < 0){
        fprintf(stderr, "fork failed\n");
        exit(-1);
    } else if(pid == 0){
        execlp("/bin/ls", "ls", NULL);
    } else {
        wait(NULL);
        printf("Child Completed\n");
        exit(0);
    }
}
```

More About fork()

■ Resource of child process

- Data (variables): copies of variables of parent process
 - Child process has its own address space
 - The only difference is **pid returned from fork()**
- Files
 - Opened before fork(): shared with parent
 - Opened after fork(): not shared



More About wait()



`pid_t wait(int *stat_loc);`

- `stat_loc` : an integer pointer
 - If `stat_loc == NULL`, it is ignored
 - Otherwise: receives status information from child process
 - `wait(&stat);` // in parent process
 - `exit(code);` // in child process
 - `code == (stat >> 8) & 0xff`
- Return value of `wait`
 - pid of child process that is alive
 - -1 means it has no child process

Process Creation in win32



- **CreateProcess()**
 - Similar to fork() of UNIX, but much more parameters to specify properties of child process
- **WaitForSingleObject()**
 - Similar to wait() of UNIX
- **void ZeroMemory(PVOID *Destination*, SIZE_T *Length*);**
 - Fills a block of memory with zeroes.

For more detail, please refer MSDN homepage
(<http://msdn.microsoft.com>)

Process Termination

■ Normal termination

- `exit(int return_code)`: invoked by child process

- Clean-up actions
 - Deallocate memory
 - Close files
 - ETC.

- `return_code` is passed to parent process

- Usually, 0 means success
- Parent can read the return code

```
int status = 0;
wait(&status);           // wait until the child is terminated.
ret = WEXITSTATUS(status); // return_code from the child
```

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Inter-process Communication (IPC)



■ Goal of IPC: cooperation

- Information sharing
 - Shared file, ...
- Computation speedup
 - Multiple CPU or I/O
- Modularity
 - Dividing system functions
- Convenience
 - Editing, printing, compiling in parallel

■ IPC Models

- Shared-memory model
- Message-passing model

Shared-Memory Systems

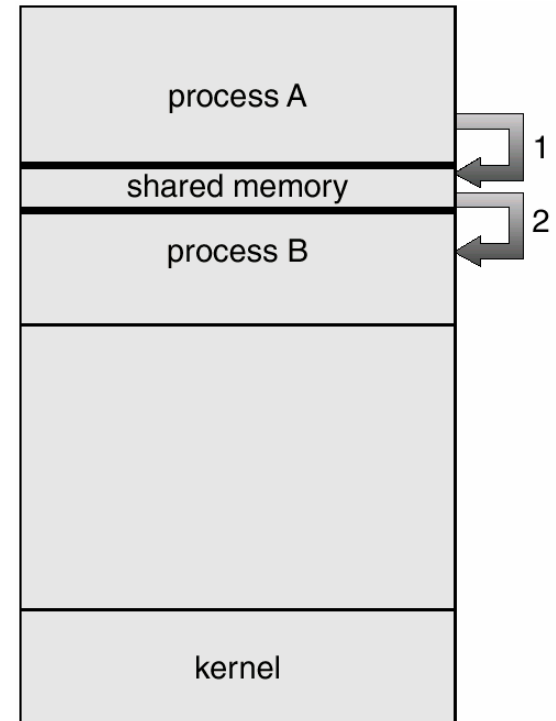
■ Shared-memory segment

- Special memory space that can be shared by two or more processes.
- Form of data and location is not determined by OS, but those processes.
 - Processes should avoid simultaneous writing by themselves

■ Advantage

- Fast
 - Suitable for large amount of data

Example) producer-consumer problem



Producer–Consumer Problem

- Producer and consumer communicate information (item) through shared memory

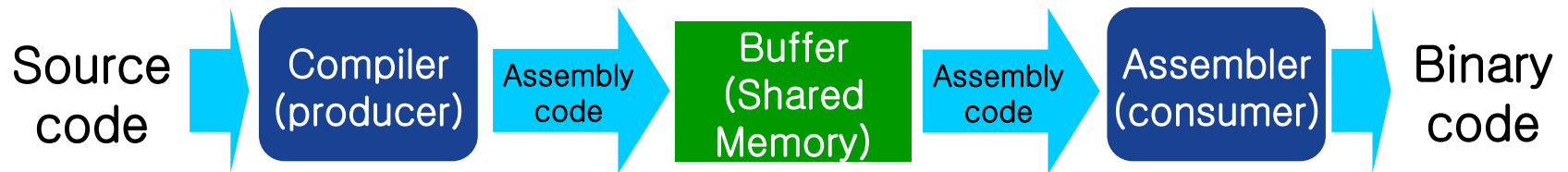
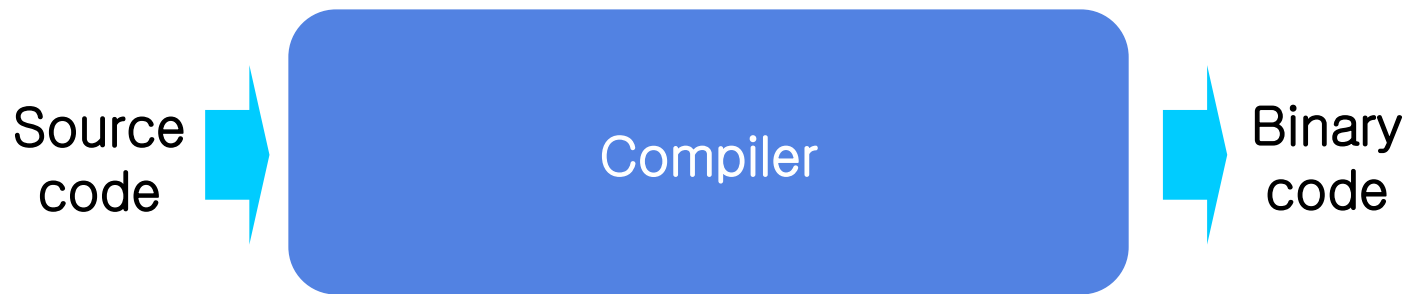


- **Producer**: produce information for consumer
 - **Consumer**: consume information written by producer
- Ex) compiler – assembler, server – client

Note! Producer and consumer should be synchronized.

→ Discussed in chapter 6

Producer-Consumer Problem



Producer–Consumer Problem

■ Two types of buffer

- Unbounded buffer
 - No practical limit on buffer size
 - Producer can always produce
- Bounded buffer
 - Producer must wait if buffer is full.

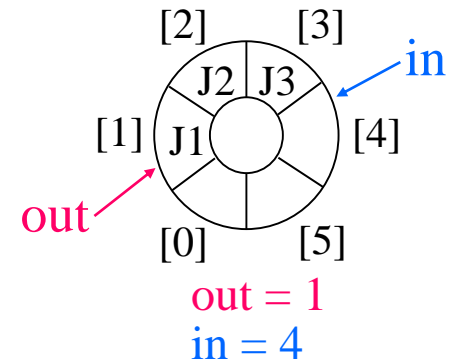


Producer–Consumer Problem using Bounded Buffer

■ Representation of buffer

- Buffer is represented by **circular queue**

```
#define BUFFER_SIZE 6
typedef struct {
    ...
} item;
item buffer[BUFFER_SIZE];
int in = 0;           // tail or rear
int out = 0;          // head or front
```



■ Empty/full condition

- $in == out$: buffer is empty
 - $(in+1) \% BUFFER_SIZE == out$: buffer is full
- Cf. Buffer can store at most $BUFFER_SIZE - 1$ items

Producer–Consumer Problem using Bounded Buffer

■ Producer

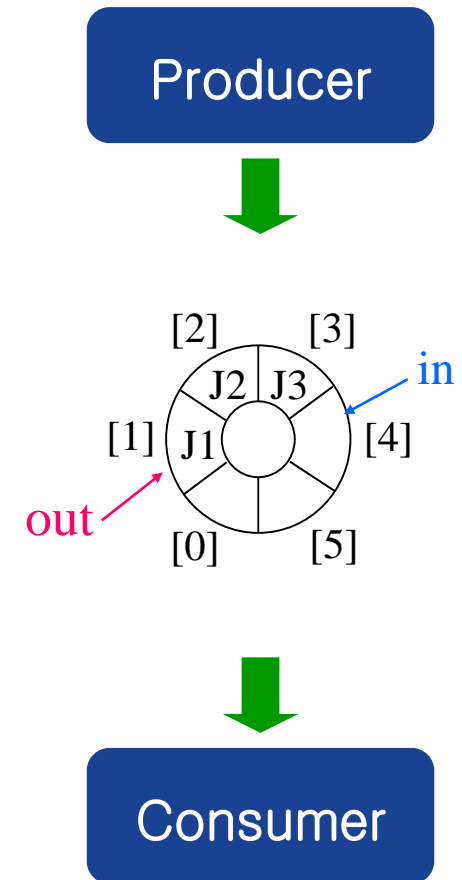
item nextProduced;

```
while (1) {  
    // produce an item in nextProduced  
    while (((in + 1) % BUFFER_SIZE) == out); // waiting  
    buffer[in] = nextProduced;  
    in = (in + 1) % BUFFER_SIZE;  
}
```

■ Consumer

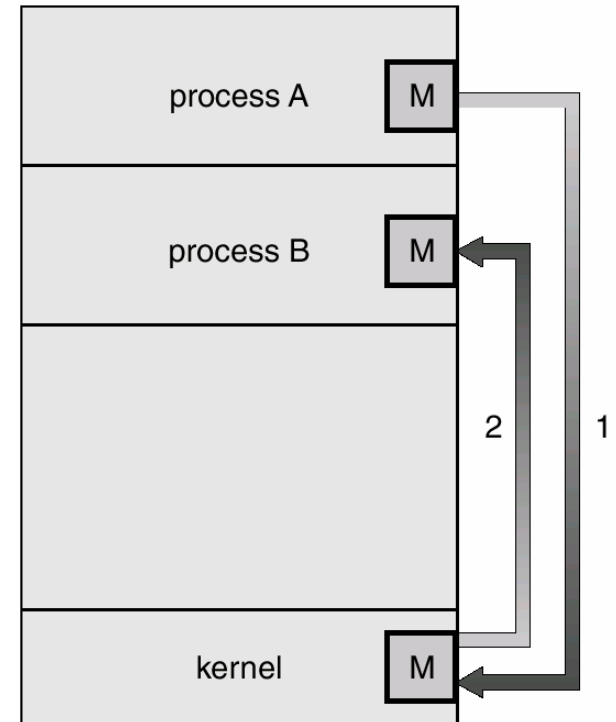
item nextConsumed;

```
while (1) {  
    while (in == out); // waiting  
    nextConsumed = buffer[out];  
    out = (out + 1) % BUFFER_SIZE;  
    // consume the item in nextConsumed  
}
```



Message-Passing Systems

- Process communication via passage-passing facility provided by OS
- Advantage
 - No conflict
 - Suitable for smaller amounts of data
 - Communication between processes on different computer



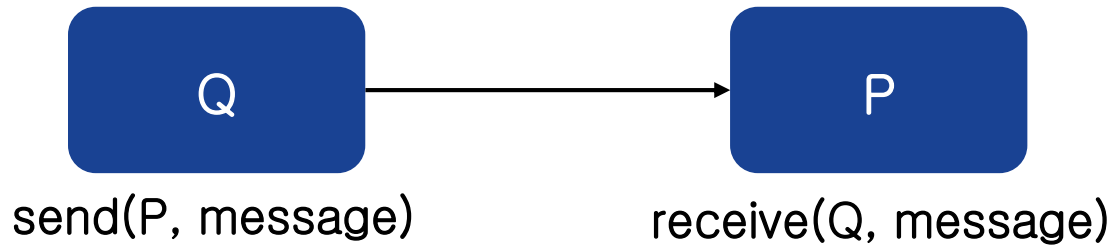
Message-Passing Systems



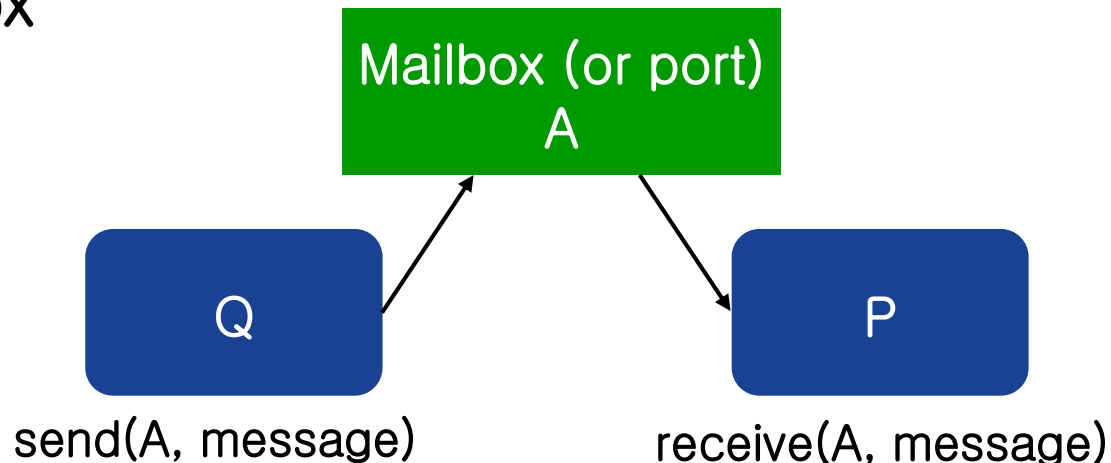
- For message passing, communication link should be exist between the processes
 - Essential operations
 - send(message)
 - receive(message)
 - (Logical) Implementation methods
 - Direct/indirect
 - Synchronous/asynchronous
 - Buffering
 - Zero/bounded/unbounded capacity
- ➔ Reading assignment: read the textbook for detail.

Direct/Indirect Communication

- **Direct communication:** connection link directly connects processes



- **Indirect communication:** processes are connected via mailbox



Buffering

- During communication, messages are stored in temporary queue (buffer)



- Three kinds of buffer capacity
 - Zero capacity: only blocking send is possible
 - Bounded capacity: buffer has finite length n
 - If buffer is full, sender must be blocked
 - Otherwise, sender can resume
 - Unbounded capacity: buffer has infinite capacity
 - Sender never blocks

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Examples of IPC Systems



- Shared-memory (POSIX)

Reading Assignment: read the following documents to understand how to allocate (shmget), attach (shmat), detach (shmdt), and deallocate (shmctl) shared memory block.

- www.xevious7.com/linux/lpg_6_4_4.html (Korean)
- www.cs.cf.ac.uk/Dave/C/node27.html (English)

- Message-passing (MACH)

- Local Procedure Call (Windows XP)

- Undocumented internal API

[POSIX] Shared-Memory

- Create shared memory

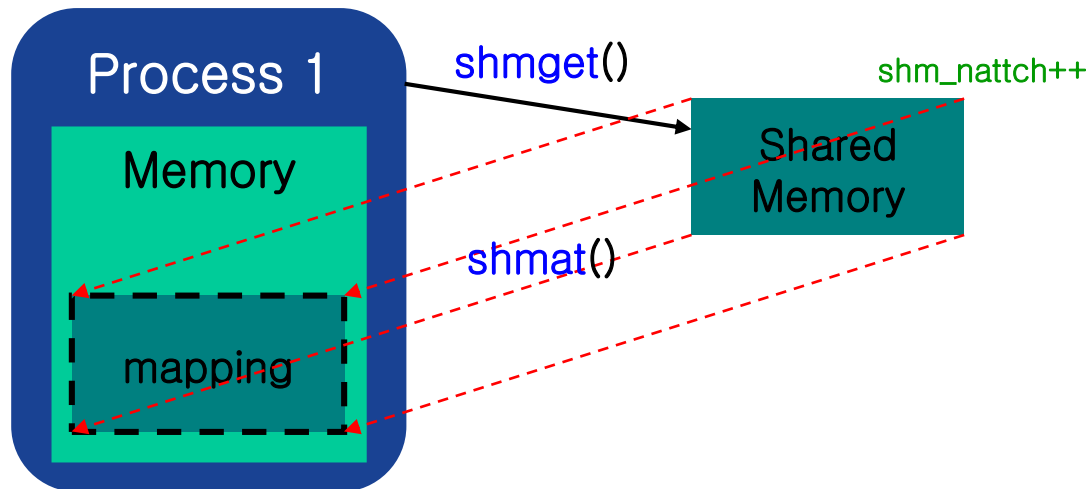
int shmget (key_t key, int size, int shmflg);

Ex) seg_id = shmget(IPC_PRIVATE, size, S_IRUSR|S_IWUSR);

- Attach shared memory to address space of a process

void shmat (int shmid, char *shmaddr, int shmflg);*

Ex) shared_mem = (char *) shmat(seg_id, NULL, 0)



[POSIX] Shared-Memory

- Use shared memory through attached address as ordinary memory

Ex) `sprintf(shared_mem, "Writing to shared memory");`

- Detach shared memory from address space of process

*`int shmdt (char *shmaddr);`*

Ex) `shmdt(shared_mem);`

- If all processes detaches the shared memory segment, OS discards it.



[POSIX] Shared-Memory



- Deallocating a shared memory block

shmctl(shmid, IPC_RMID, NULL);

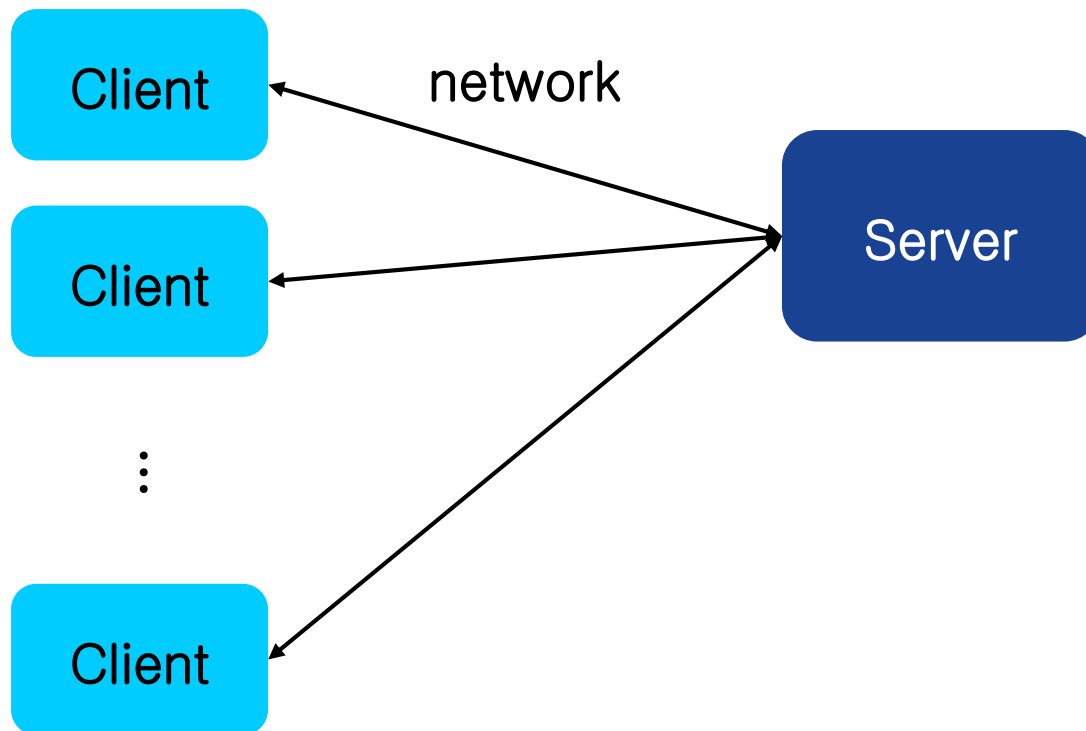
- Deallocates the shared memory block when the shm_nattach becomes zero.

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Client-Server



Communications in Client–Server Systems



- **Socket**
 - Data communication

- **RPC (Remote Procedure Call)**
 - Procedure call between systems
 - Procedural programming

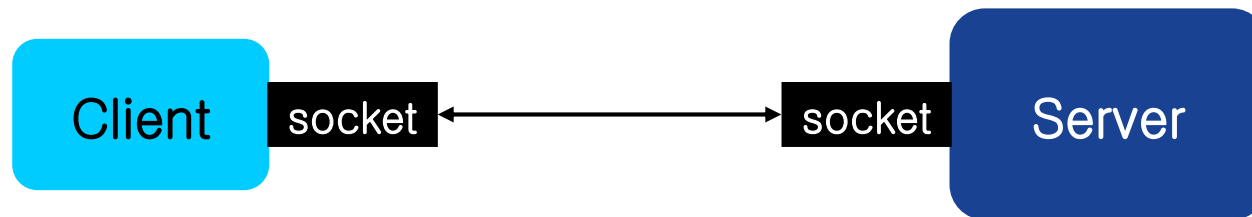
- **RMI (Remote Method Invocation) of JAVA**
 - Invoking method of object in other system
 - Object oriented programming

Socket

- **Socket**: logical endpoint for communication



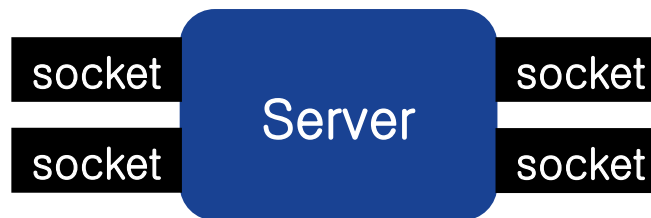
- Identified by <ip address>:<port #>



- Each connection is identified by a pair of sockets.

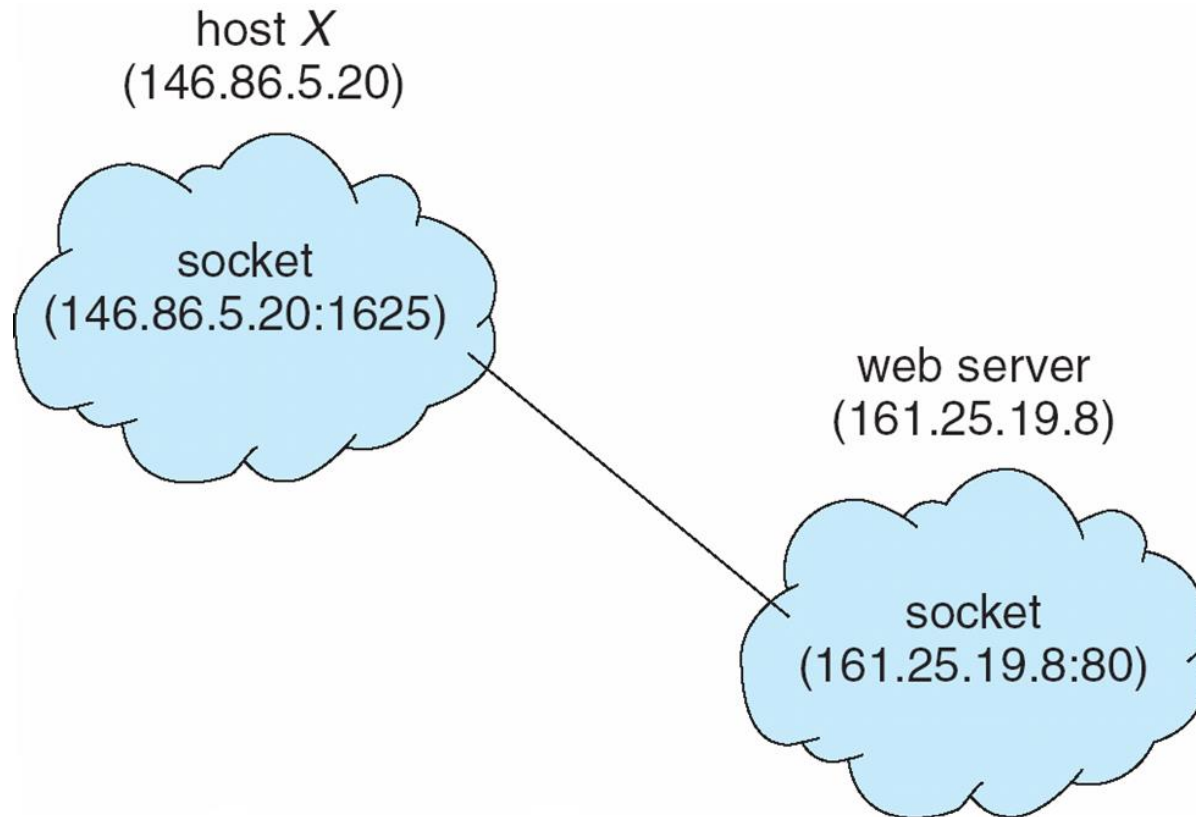
Socket

- **Port**: logical contact point to a computer recognized by TCP and UDP protocols
 - A computer may have multiple ports (0 ~ 65535)



- Well-known services have their own ports below 1024
Ex) telnet: 23, ftp: 21, http: 80
 - Server always listens corresponding port.
- Ports above 1024 can be arbitrary assigned for network communication

Socket



Socket

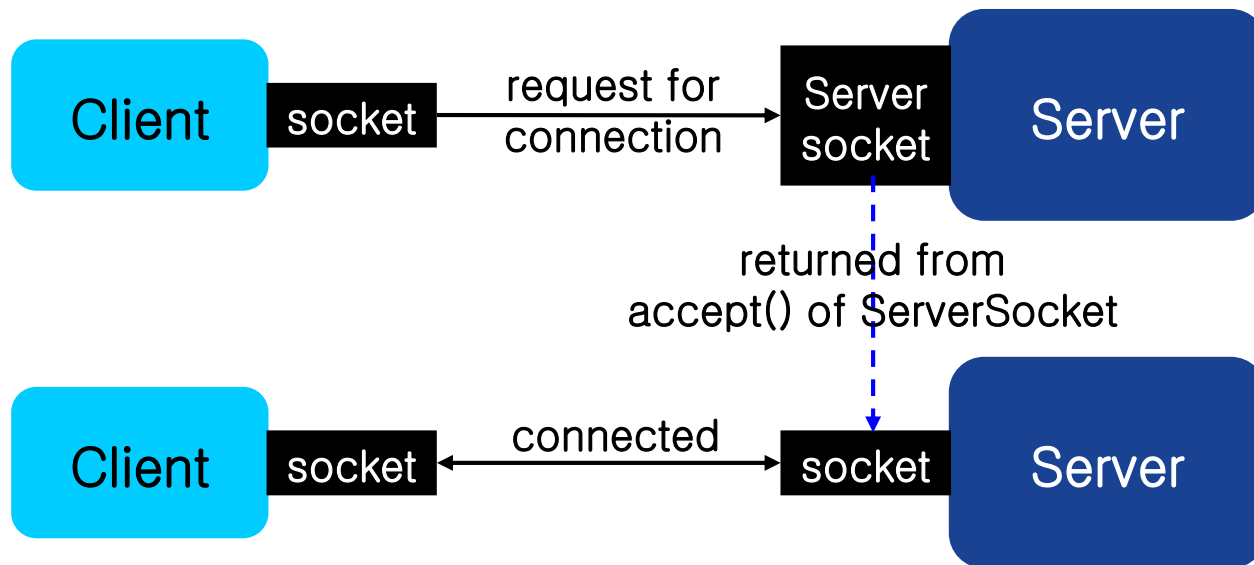


- Server opens a port to accept connection request.
- Initiating connection
 - Client arbitrary assigns a port above 1024.
Ex) a client 146.86.5.20 assigned a port 1625
 - Client request a connection to server.
Ex) a web server 161.25.19.8 (port # of web service: 80)
 - If server accepts request, connection is established.
Ex) <146.86.5.20:1625> – <161.25.19.8:80>

Java Socket

■ Socket classes

- ServerSocket: accepts request for connection
- Socket: in charge of actual communication



Java Socket



■ Server

1. Create a ServerSocket

```
ServerSocket socket = new  
    ServerSocket(6013);
```

2. Wait for a client

```
Socket client =  
    socket.accept();
```

- 4a. If a client is accepted,
 communicate with client via
 client

■ Client

3. Create a socket to server

```
Socket sock = new  
    Socket("127.0.0.1", 6013);
```

- 4b. If connection was
 established, communicate
 with server via *sock*

Java Socket

■ Server (given *client*)

```
PrintWriter pout = new  
    PrintWriter(client.getOutputS  
        tream(), true);
```

```
pout.println(new  
    java.util.Date().toString());  
  
client.close();
```

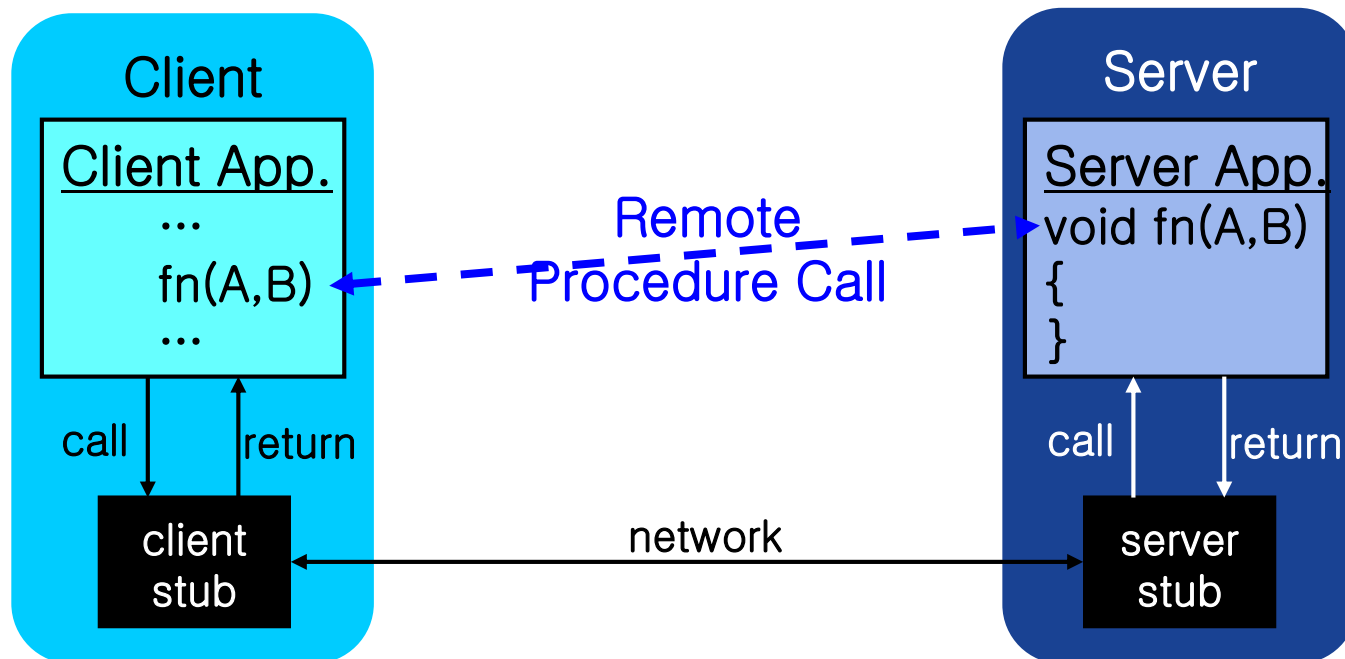
■ Client (given *sock*)

```
InputStream in =  
    sock.getInputStream();  
BufferedReader bin = new  
    BufferedReader(new  
        InputStreamReader(in))
```

```
String line;  
while((line = bin.readLine()) !=  
    null)  
    System.out.println(line);  
  
sock.close();
```

Remote Procedure Calls (RPC)

- **RPC**: procedure call mechanism between systems
- On server, **RPC daemon** listens a port
- Client sends a message containing identifier of function and parameters



Remote Procedure Calls



- RPC is served through stubs
 - Client invoke remote procedure as it would invoke a local procedure call
- **Stub**: a small program providing interface to a larger program or service on remote side
 - Client stub / server stub
 - Locate port on server
 - **Marshal** / **unmarshal** parameters

Remote Procedure Calls

■ Parameter marshaling

Motivation: each system has its own data format

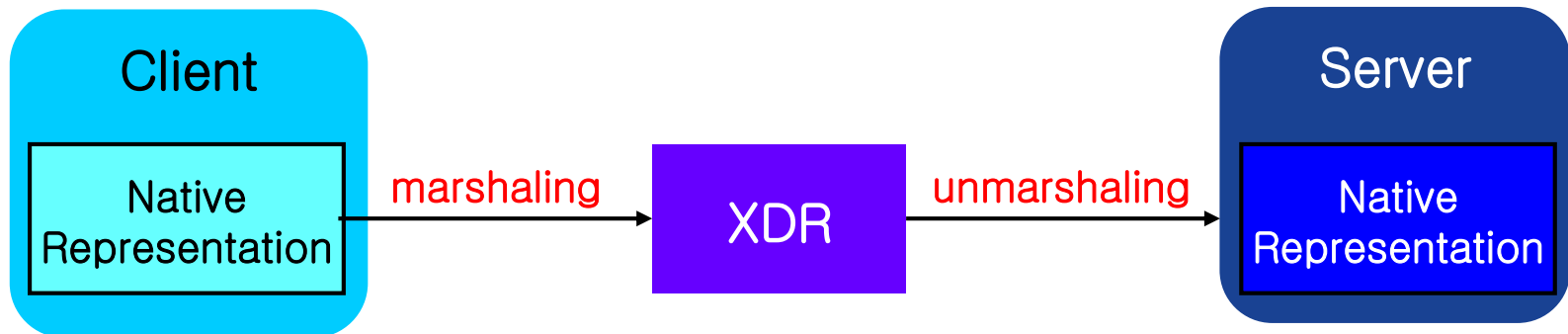
Ex) representation of integer on a system may differ from that on other system

➔ parameter should be transferred in standard format

□ XDR: eXternal Data Representation

■ **Marshalling**: native representation → XDR

■ **Unmarshalling**: XDR → native representation



RPC Reference Sites



- Windows

- MSDN RPC page:

- <http://msdn.microsoft.com/library/default.asp?url=/library/en-us/dnanchor/html/rpcank.asp>

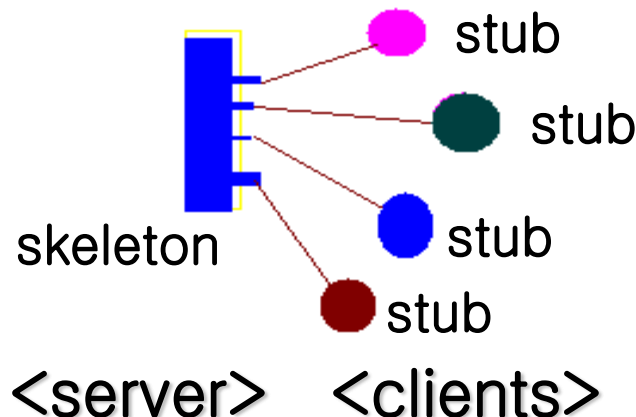
- Unix

- Document about *rpcgen*.

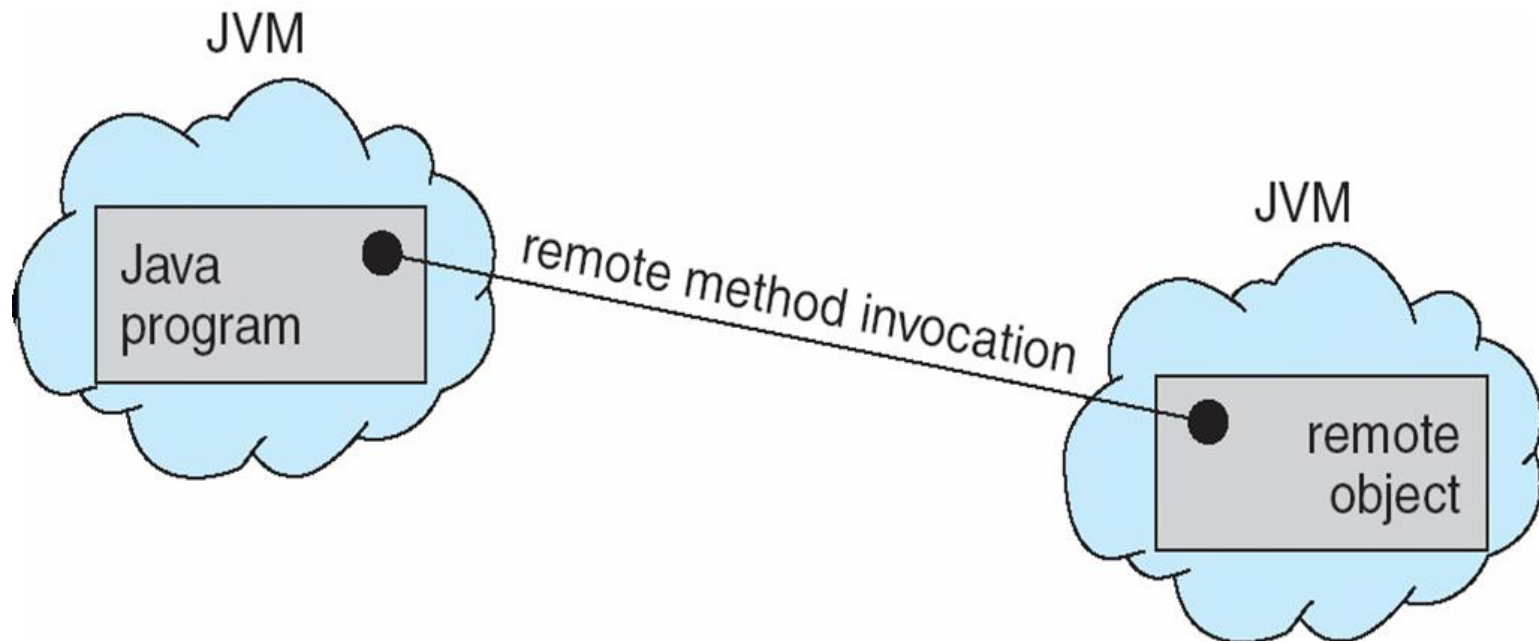
Remote Method Invocation (RMI)

- RMI: Java feature to invoke method on remote object

	RPC	RMI
Technical Background	Procedural Programming	<u>Object-oriented Programming</u>
Parameter	Ordinary data structures	Object parameter is possible
Interface	client stub / server stub	stub / skeleton



Remote Method Invocation (RMI)



Remote Method Invocation (RMI)

