# ITP20001/ECE20010 Data Structures Chapter 6

- Introduction
- Graph API
- Elementary Graph Operations
  - DFS: Depth first search
  - BFS: Breadth first search
  - CC: Connected Components

#### Major references:

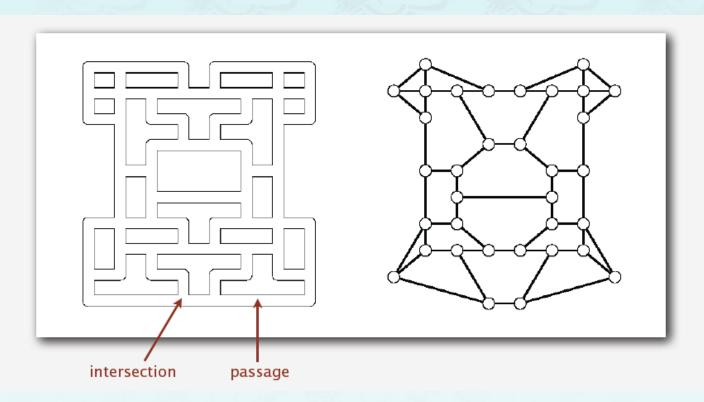
- 1. Fundamentals of Data Structures by Horowitz, Sahni, Anderson-Freed,
- 2. Algorithms 4<sup>th</sup> edition Part 1 & Part 2 by Robert Sedgewick and Kevin Wayne
- 3. Wikipedia and many resources available from internet

Prof. Youngsup Kim, idebtor@gmail.com, Data Structures, CSEE Dept., Handong Global University

# Depth first search

# Algorithm:

- Vertex = intersection
- Edge = passage



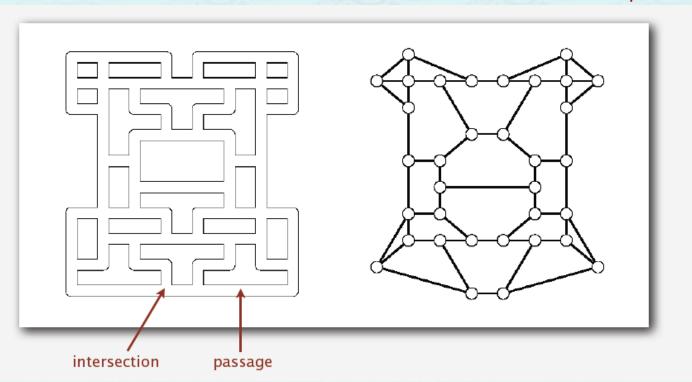
Maze Goal: Explore every intersection in the maze.

# Depth first search

# Algorithm:

- Vertex = intersection
- Edge = passage

pacman

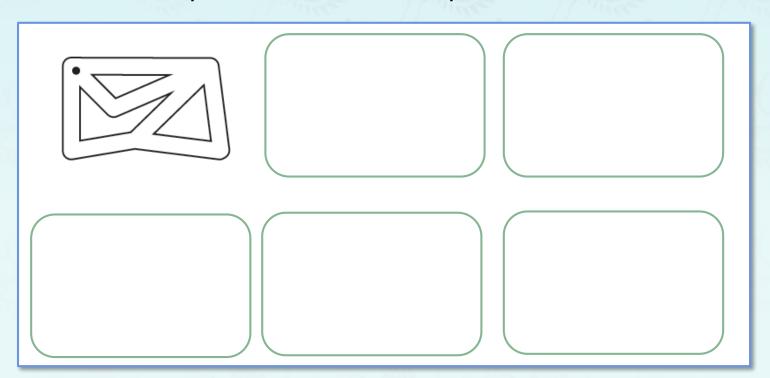


Maze Goal: Explore every intersection in the maze.

# **Depth first search**

### Maze graph:

- Unroll a ball of string behind you.
- Mark each visited intersection and each visited passage.
- Retrace steps when no unvisited options



Maze Goal: Explore every intersection in the maze.

Good Visualization: https://www.cs.usfca.edu/~galles/visualization/DFS.html



# **©**

# Depth first search

# Maze graph:

- Unroll a ball of string behind you.
- Mark each visited intersection and each visited passage.
- Retrace steps when no unvisited options



Theseus, a hero of Greek mythology, is best known for slaying a monster called the Minotaur. When Theseus entered the Labyrinth where the Minotaur lived, he took a ball of <u>yarn</u> to unwind and mark his route. Once he found the Minotaur and killed it, Theseus used the string to find his way out of the maze.

Read more:

http://www.mythencyclopedia.com/Sp-Tl/Theseus.html#ixzz3owFO3ofe

Maze Goal: Explore every intersection in the maze.



# **©**

## Depth-first search

# Maze graph:

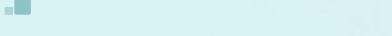
- Unroll a ball of string behind you.
- Mark each visited intersection and each visited passage.
- Retrace steps when no unvisited options



Shannon and his famous <u>electromechanical</u> mouse *Theseus* (named after <u>Theseus</u> from Greek mythology) which he tried to have solve the maze in one of the first experiments in <u>artificial intelligence</u>.

The Las Vegas connection: Shannon and his wife Betty also used to go on weekends to Las Vegas with MIT mathematician Ed Thorp, and made very successful forays in blackjack using game theory.

Maze Goal: Explore every intersection in the maze.



## Design pattern for graph processing

Design pattern: Decouple graph data type

Idea: Mimic maze exploration

# DFS (to visit a vertex v)

- Mark v as visited.
- Recursively visit all unmarked vertices w adjacent to v.

# **Typical applications:**

- Find all vertices connected to a given source vertex.
- Find a path between two vertices.

# **Challenge:**

How to implement?

# Design pattern for graph processing

Goal: Systematically search through a graph from graph processing

- Create a graph object
- Pass the graph to a graph processing routine
- Query the graph-processing routine

```
public class Paths

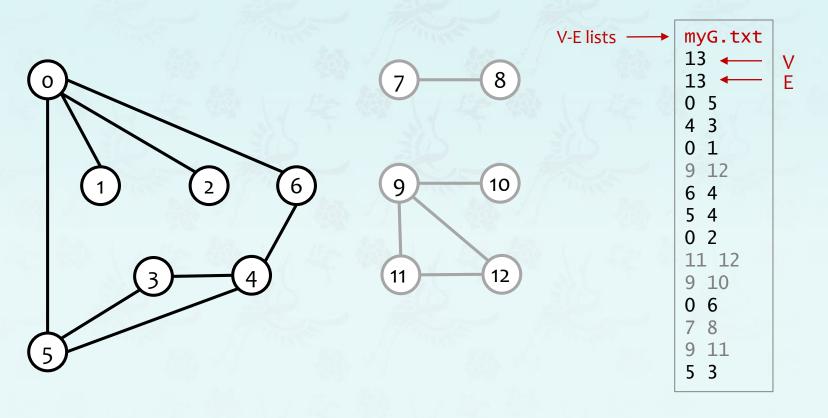
Paths(Graph G, int s) find paths in G from source s

boolean hasPathTo(int v) is there a path from s to v?

Iterable<Integer> pathTo(int v) path from s to v; null if no such path
```

For each edge(v, w) in the list

Insert front each vertex both (adj[v], w) and (adj[w], v)
 addEdgeUniDirection(g, v, w); // add an edge from v to w.



Graph g:

**Challenge:** build adjacency lists?

# Adjacency-list graph representation: C implementation

create an empty graph with V vertices

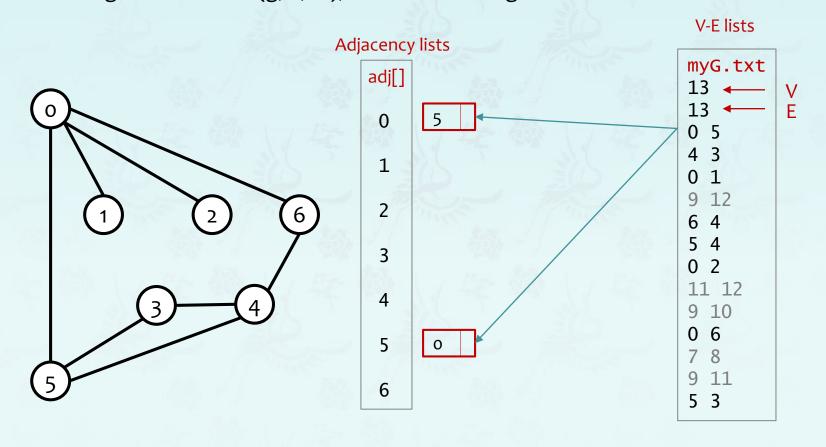
```
pGraph newGraph(int V) {
                                                         typedef struct Graph *pGraph;
  pGraph g = (pGraph) malloc(sizeof(Graph));
                                                         typedef struct Graph {
                                                                              // num of vertices in G
  assert(g != NULL);
                                                          int
                                                                   V;
                                                                             // num of edges G
                                                          int
  g \rightarrow V = V;
                                                                             // an array of adj lists
                                                          pGNode adi;
  g -> E = 0;
                                                         } Graph;
  // create an array of adjacency list. size of array will be V
                                                                         adjacency list
  g->adj = (pGNode)malloc(V * sizeof(GNode));
                                                                         (using an array)
  assert(g->adj!= NULL);
  // initialize each adjacency list as empty by making head as NULL;
  for (int i = 0; i < V; i++)
                                            adjacency list
    g->adj[i].next = NULL;
                                            set head node NULL
    g->adj[i].item = i
  return g;
                                  unused; but may store the size of degree.
```

# Adjacency-list graph representation: C implementation

```
// add an edge to an undirected graph
void addEdgeUniDirection(pGraph g, int v, int w) {
  // add an edge from v to w.
  // A new node is added to the adjacency list of v.
  // The node is added at the beginning
                                                           instantiate a node w insert it
                                                           at the front of adjacency list[v]
  pGNode node = newGNode(w);
  node->next = g->adj[v].next;
  g->adj[v].next = node;
                                                           add an edge for undirected graph
// add an edge to an undirected graph
void addEdge(pGraph g, int v, int w) {
  addEdgeUniDirection(g, v, w);
                                          // add an edge from v to w.
  addEdgeUniDirection(g, w, v);
                                          // if graph is undirected, add both
```



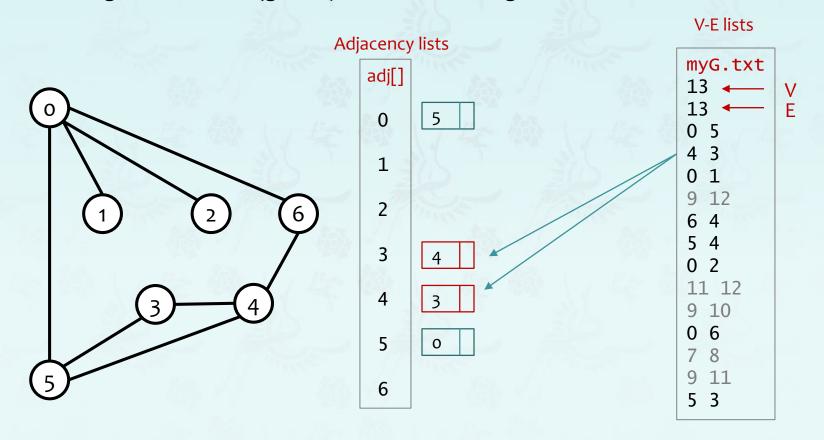
For each edge(v, w) in the list



Graph g



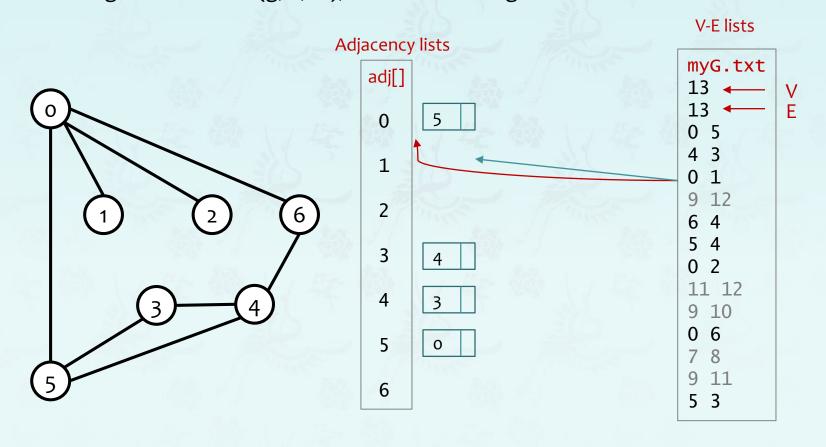
For each edge(v, w) in the list



Graph g



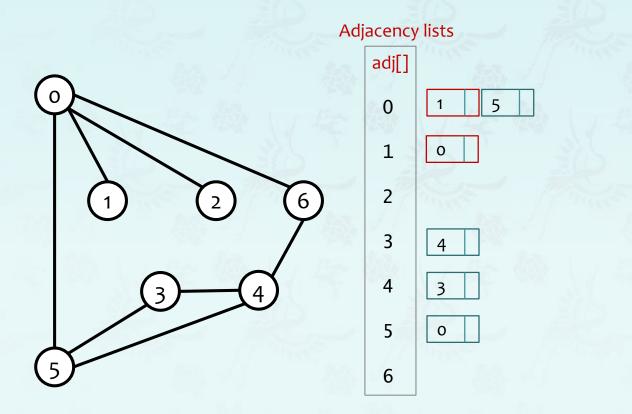
For each edge(v, w) in the list

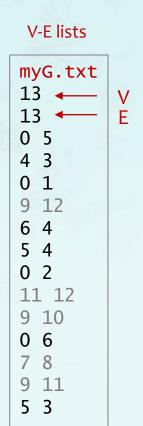


Graph g



For each edge(v, w) in the list

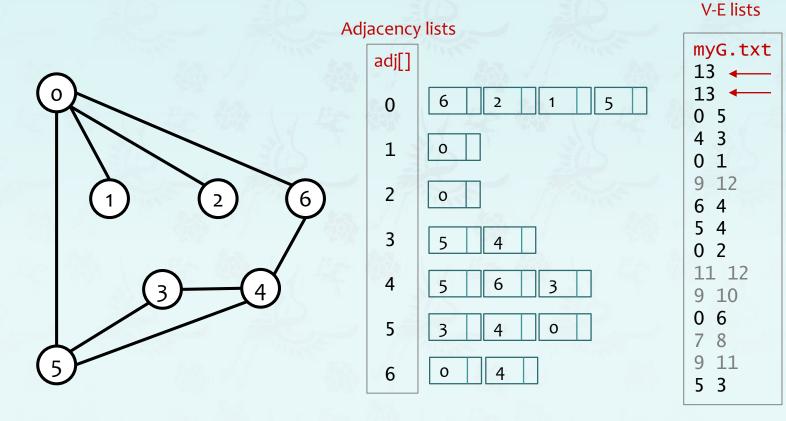






For each edge(v, w) in the list

Insert front each vertex both (adj[v], w) and (adj[w], v)
 addEdgeUniDirection(g, v, w); // add an edge from v to w.



Graph g

V E



### To visit a vertex v:

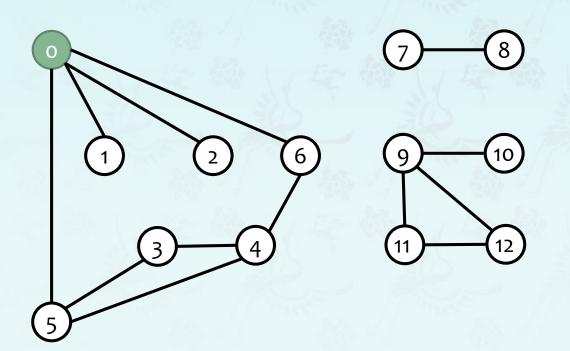
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.

# ...

# Depth-first search demo

### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.

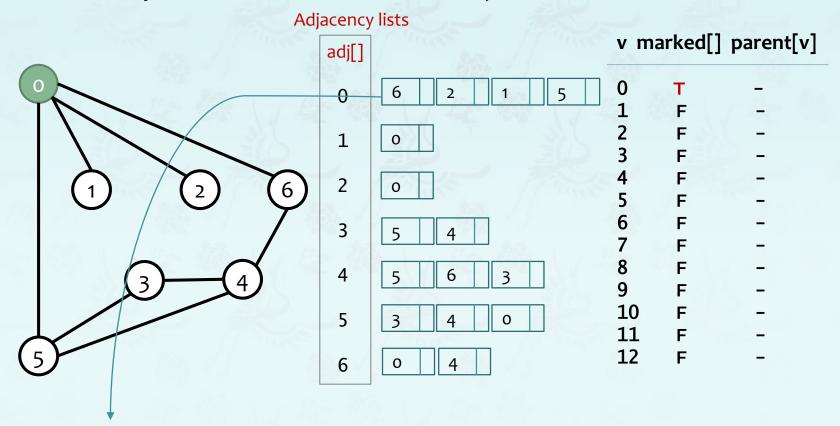


v marked[] parent[v]		
0	Т	- 98
1	F	/ <del>-</del> - ***
1 2 3 4 5	F	_
3	F	<u> </u>
4	F	<del>-</del>
	F	_
6	F	_
7	F	-
8	F	_
9	F	<u>-</u>
10	F	-
11	F	-
12	F	-

visit o: Which one first?

### To visit a vertex v:

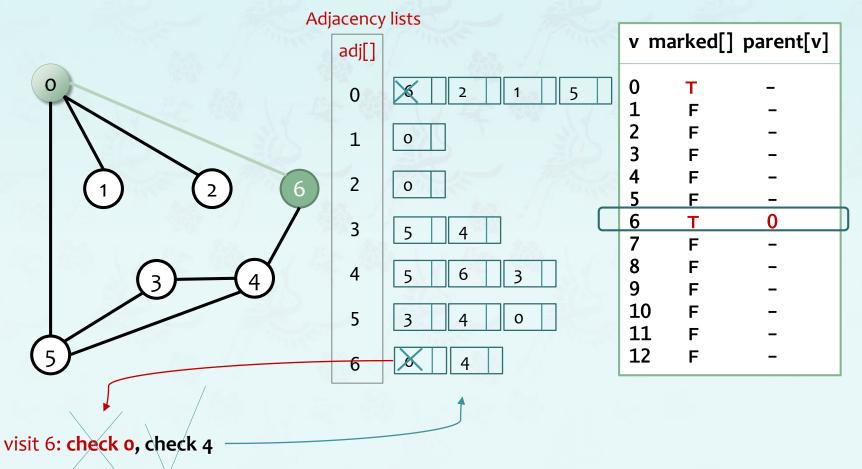
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



visit 0: check 6, check 2, check 1, and check 5

### To visit a vertex v:

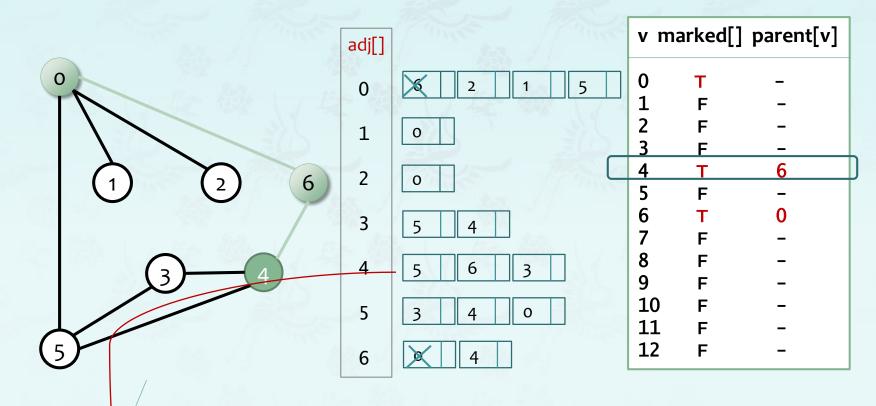
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



DFS o 6

### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.

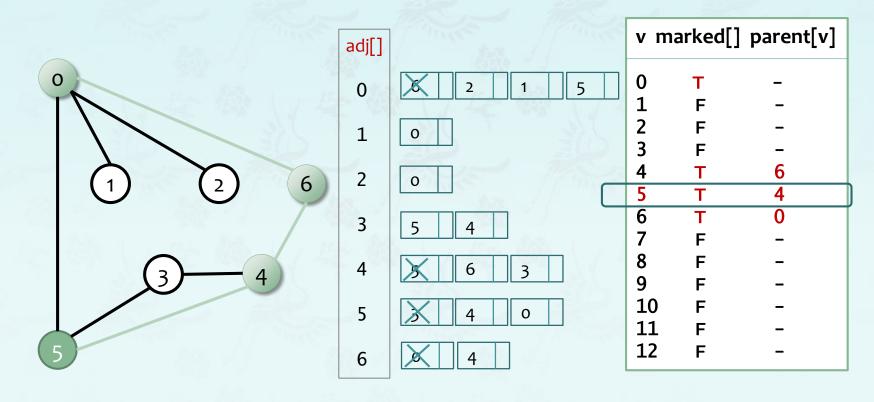


visit 4: check 5, check 6, check 3

DFS 0 6 4

### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.

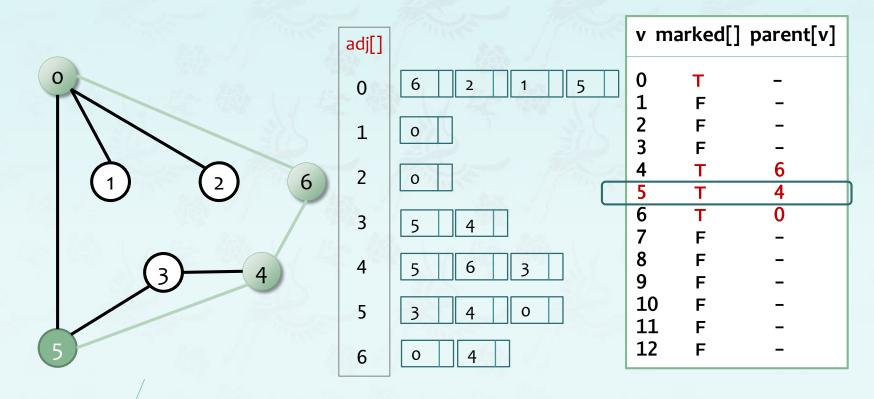


visit 5: check 3, check 4, check 0

DFS o 6 4 5

### To visit a vertex v:

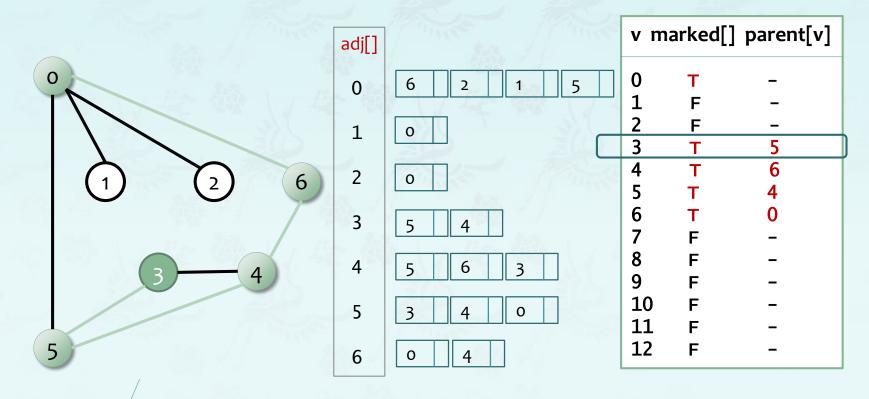
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



visit 5: check 3, check 4, check o

### To visit a vertex v:

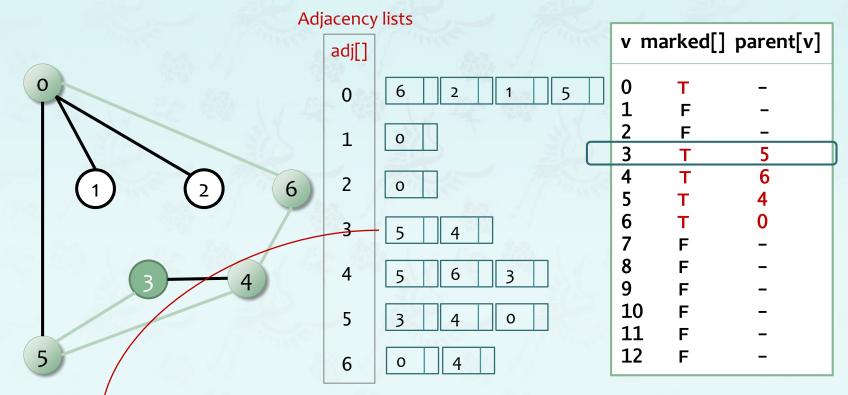
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



visit 5: check 3, check 4, check o

### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.

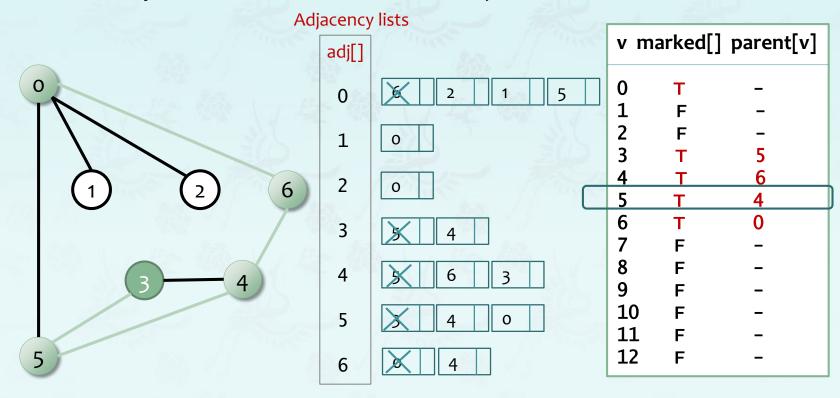


visit 3: check 5, check 4

DFS 0 6 4 5 3

### To visit a vertex v:

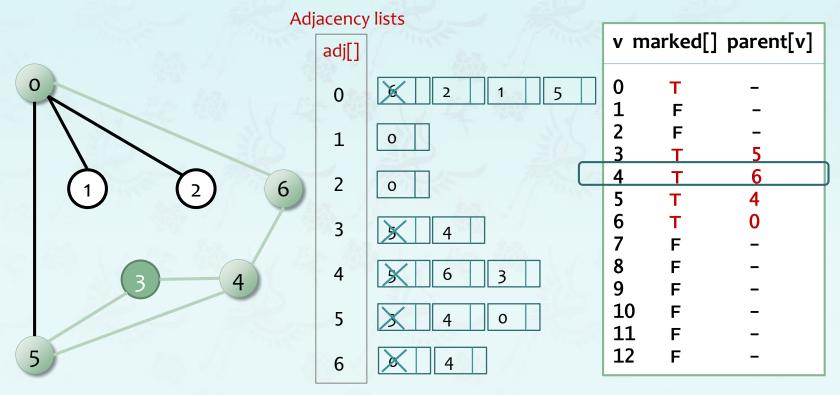
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.





### To visit a vertex v:

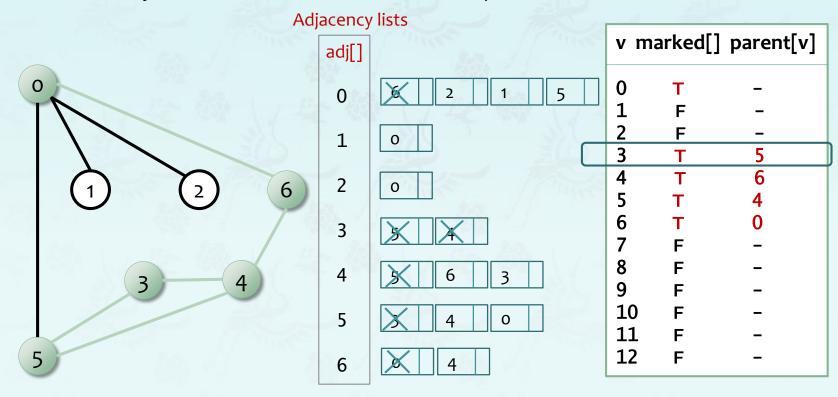
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.





### To visit a vertex v:

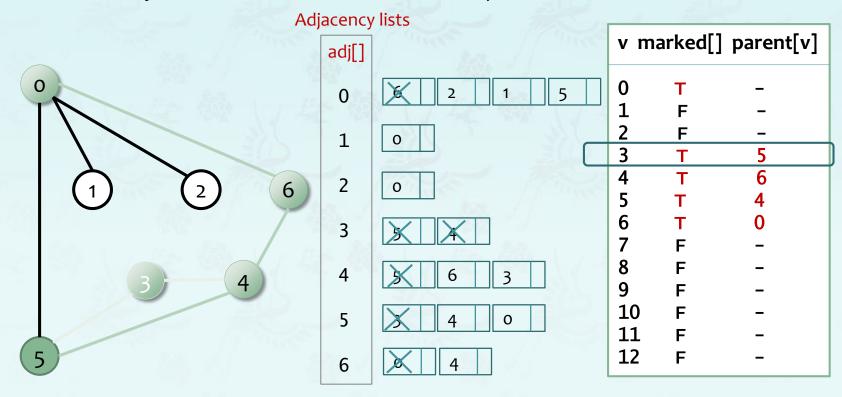
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



visit 3: check 5, check 4

### To visit a vertex v:

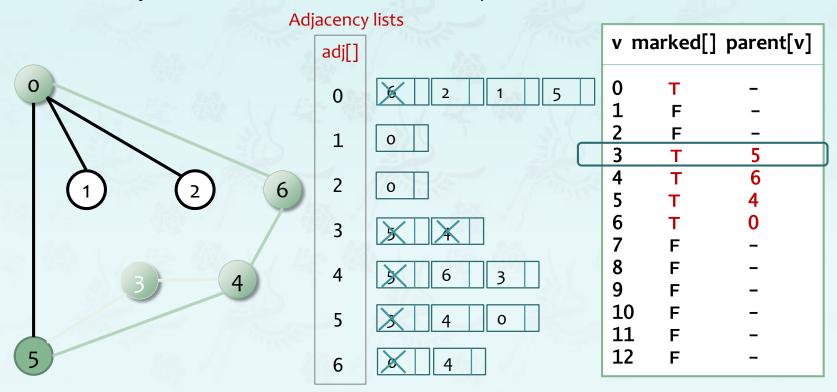
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



3 done: What's the next?

#### To visit a vertex v:

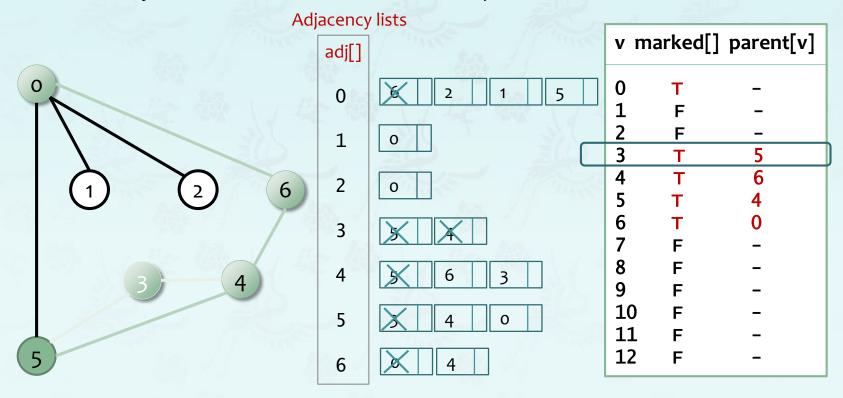
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



3 done: What's the next? Backtrack!

#### To visit a vertex v:

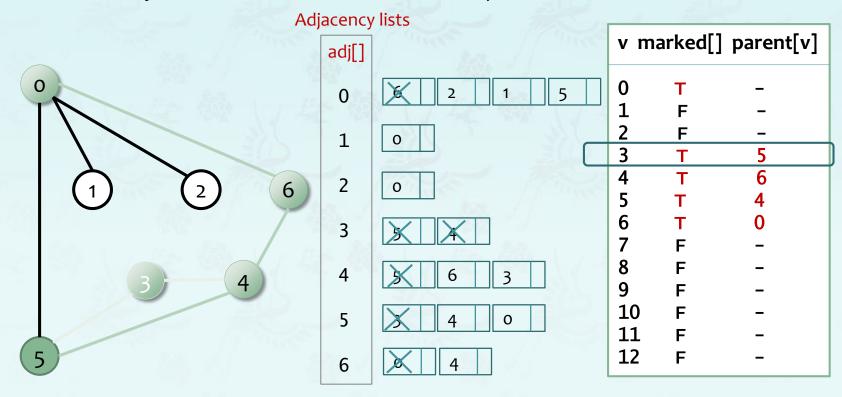
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



3 done: What's the next? **Backtrack!** How to?

#### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



3 done:

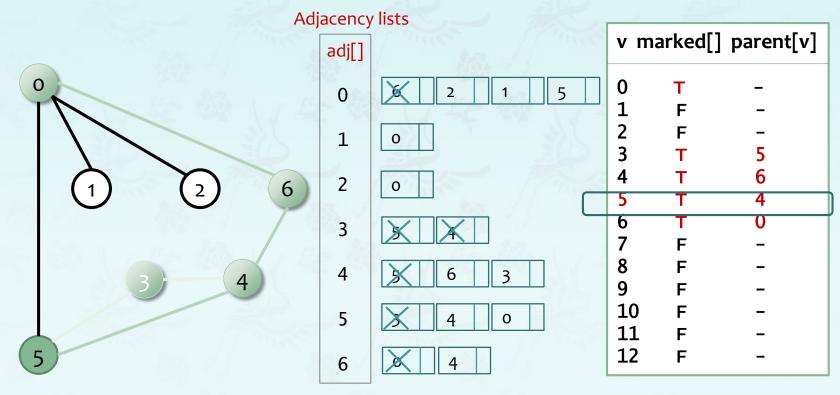
What's the next? **Backtrack!** How to?

Use parent[v]

parent[3] = 5

### To visit a vertex v:

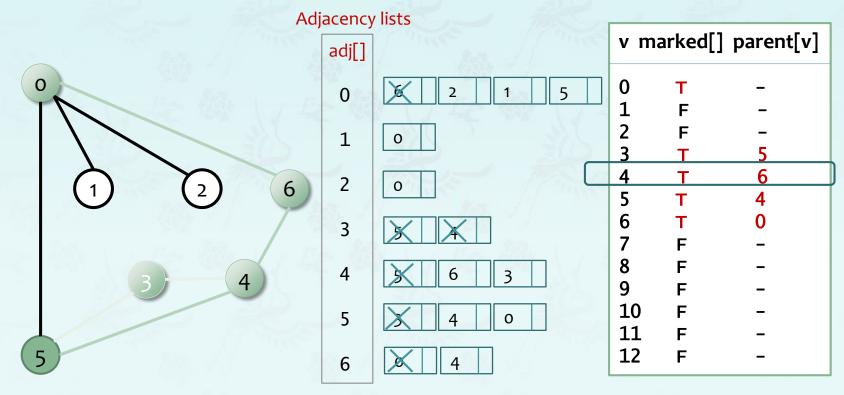
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



visit 5: check 3, check 4, check o

### To visit a vertex v:

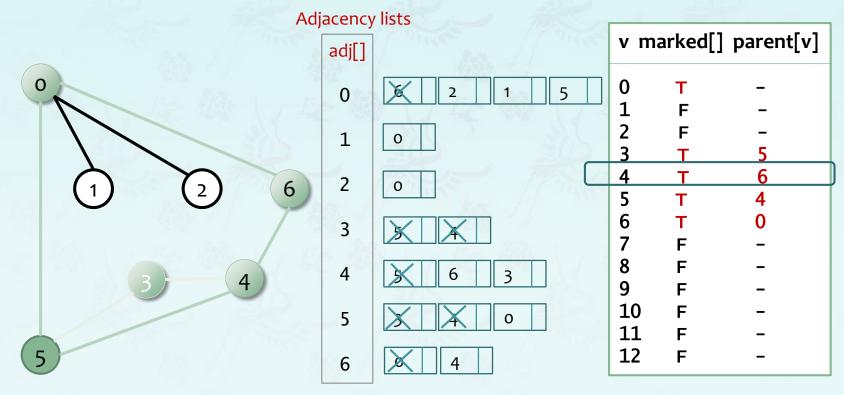
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



visit 5: check 3, check 4, check o

### To visit a vertex v:

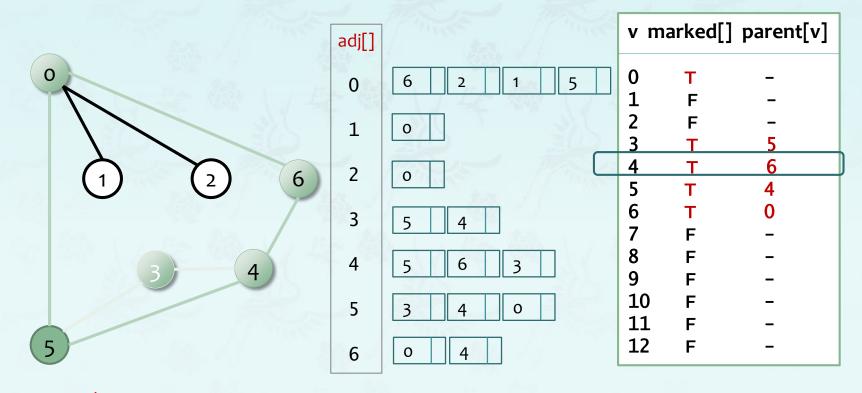
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.





### To visit a vertex v:

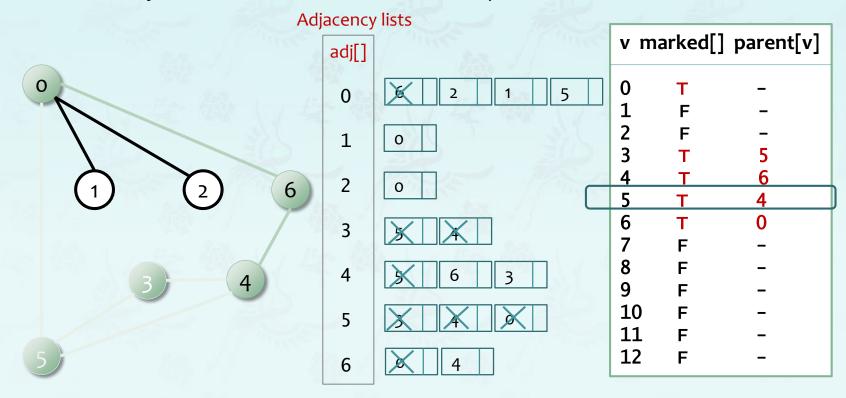
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



visit 5: check 3, check 4, check o

#### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



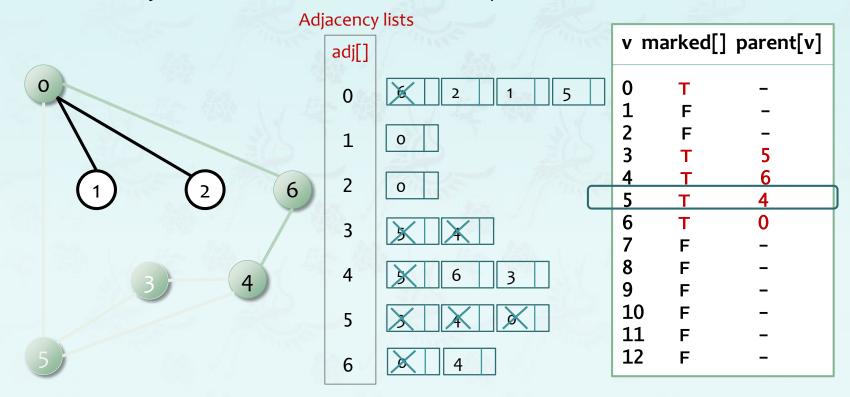
5 done

What's the next? **Backtrack!** How to?



#### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.

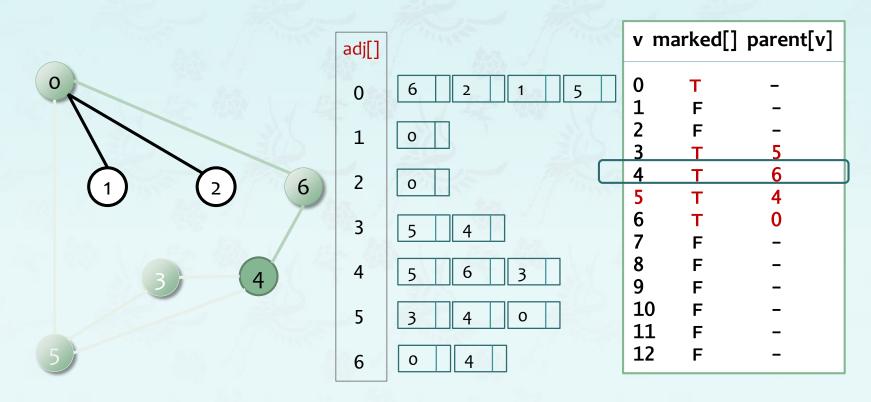


5 done

What's the next? **Backtrack!** How to?

Use parent[v]

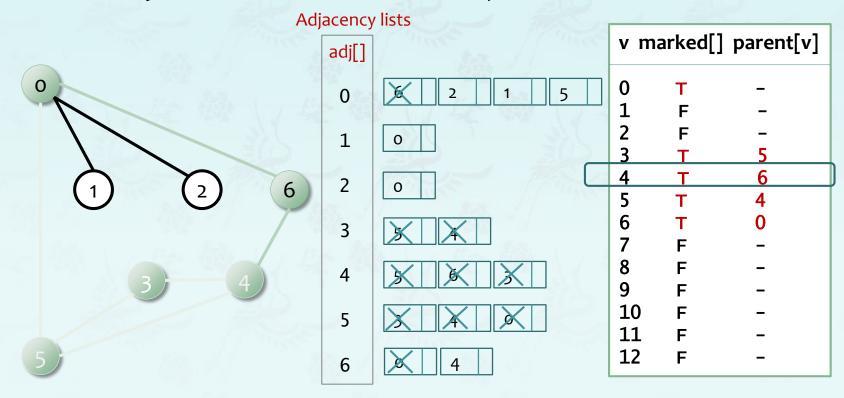
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



visit 4: check 5, check 6, check 3

### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



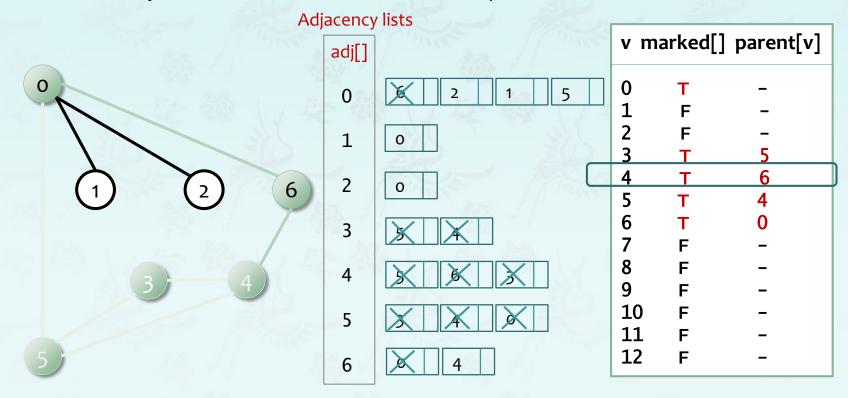
visit 4: check 5, check 6, check 3

4 done



#### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.

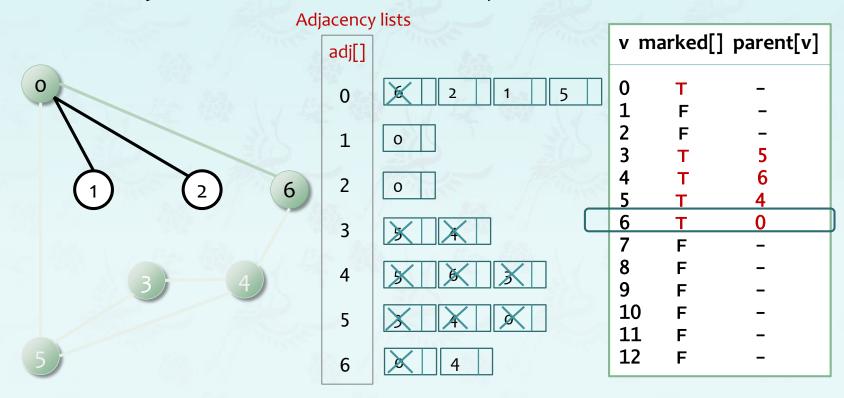


visit 4: check 5, check 6, check 3

4 done

Backtrack! parent[4] = 6

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.

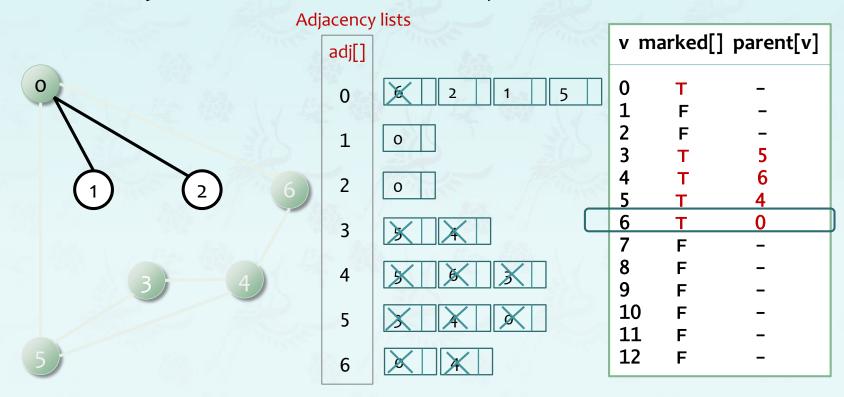


visit 6: check o, check 4



#### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.

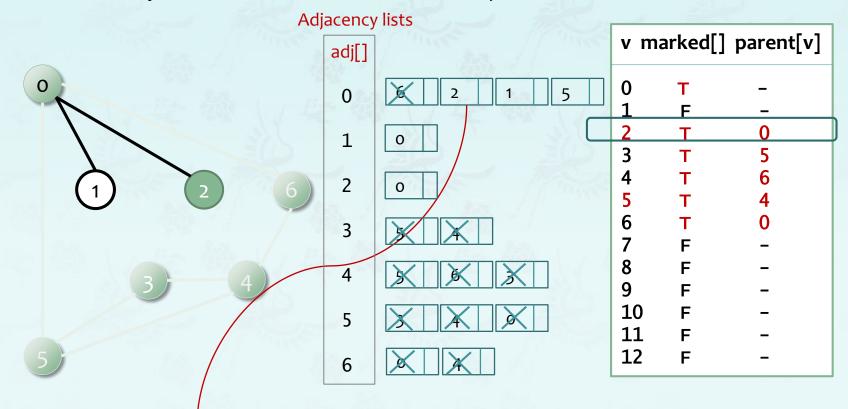


visit 6: check o, check 4

done 6

Backtrack! parent[6] = 0

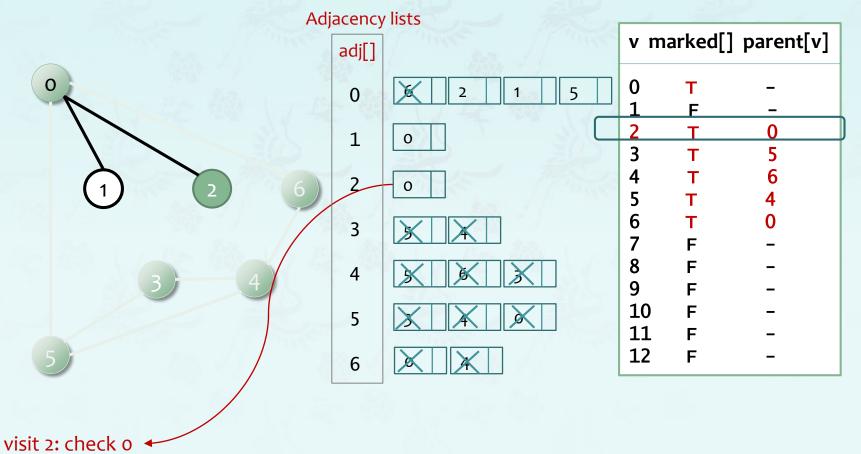
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



visit 0: check 6, check 2, check 1, and check 5

### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.

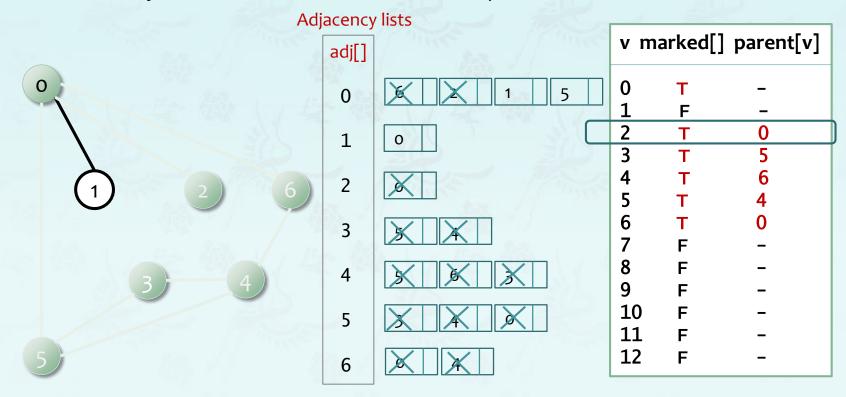


DFS: 064532



#### To visit a vertex v:

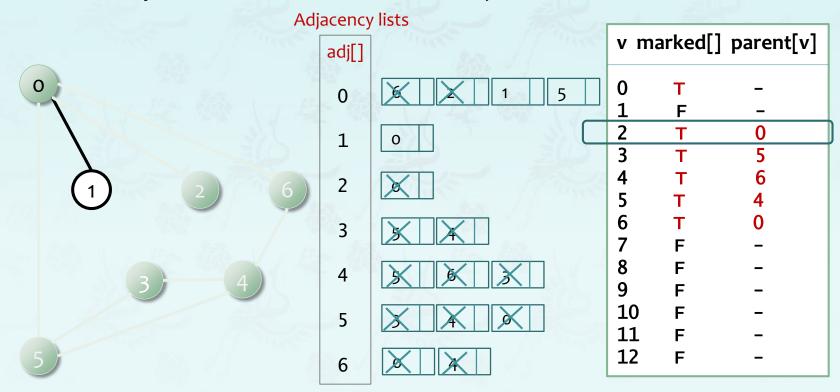
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



visit 2: check 0 2 done Backtrack! parent[2] = 0

#### To visit a vertex v:

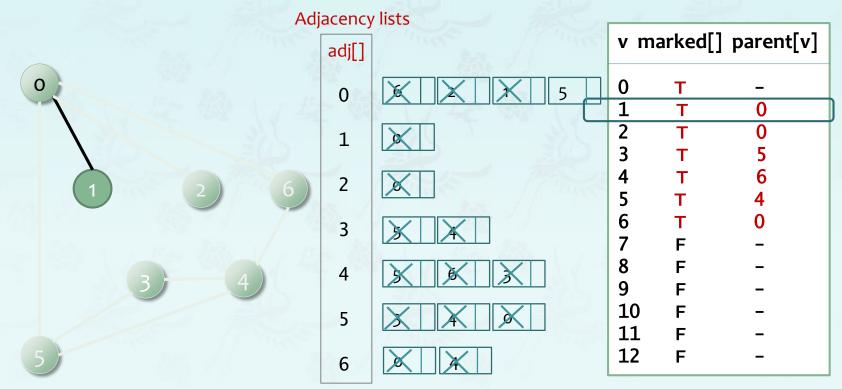
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



visit 0: check 6, check 2, check 1, and check 5

#### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.

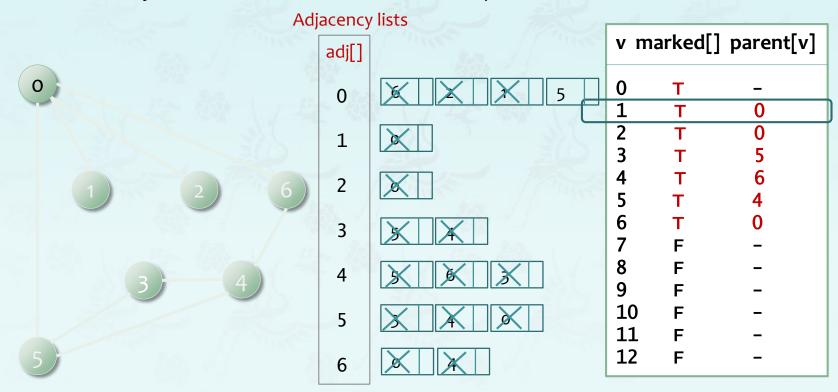


visit 1: check 0 1 done Backtrack! parent[1] = 0

DFS: 0 6 4 5 3 2 1

#### To visit a vertex v:

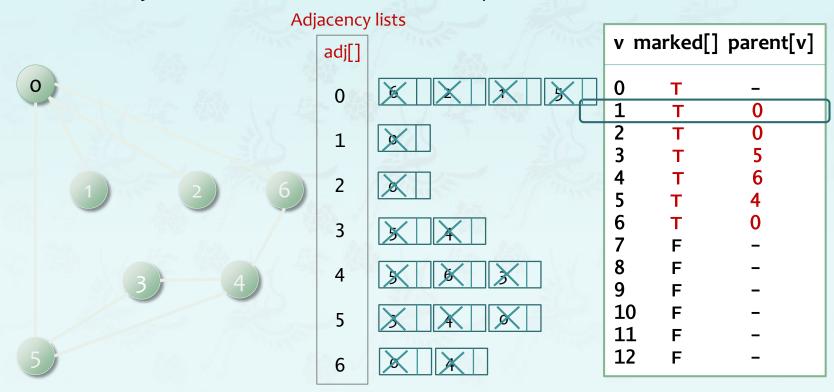
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



visit 0: check 6, check 2, check 1, and check 5

#### To visit a vertex v:

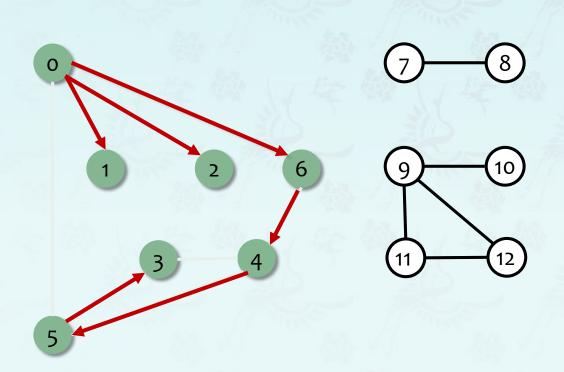
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



visit 0: check 6, check 2, check 1, and check 5 o done

### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



	V	marked[]	parent[v]			
	0	Т	-			
4	1	Т	0			
	2	Т	0			
		Т	5			
4	4 5	Т	6			
	5	Т	4			
	6	Т	0			
	7	F	-			
	8	F	-			
	9	F	-			
	10	) F	-			
	11	L F	-			
	12	2 F	-			

**DFS Output:** DFS: 0645321

- found vertices reachable from o
- build a data structure parent[v]

# **Depth-first search**

Goal: Find all vertices connected to s (and a corresponding path).

Idea: Mimic maze exploration

# Algorithm:

- Use recursion (ball of string).
- Mark each visited vertex (and keep track of edge taken to visit it).
- Return (retrace steps) when no unvisited options.

#### **Data Structures:**

- Boolean[] marked to mark visited vetices.
- int[] parent to keep tree of paths.
   (parent[w] == v) means that edge v-w taken to visit w for first time



# Depth-first search Implementation in C

```
// DFS - find vertices connected to v
void depthFirstSearch(pGraph g, int v){
  short *marked = (short *)malloc(V(g) * sizeof(short)); assert(marked!=NULL);
       *parent = (int *)malloc(V(g) * sizeof(int )); assert(marked!=NULL);
  int
  for (int i = 0; i < V(g); i++) {
        marked[i] = false;
                                          this function does the job recursively
        parent[i] = -1;
  }
  dfs(g, v, marked, parent);  // printf("Depth First Search: ");
  free(marked);
  free(parent);
                                   // we may keep this info pGraph g.
}
```



# Depth-first search Implementation in C

```
// Recursive DFS does the work
void dfs(pGraph g, int v, short *visited, int *parent) {
  visited[v] = true;
                                  visiting node currently
  printf("%d ", v);
  loop through from the current node v to the rest)
    if this node w is not visited
       dfs ( with w )
                                               where it reached from
       update parent with w & ∨ ← ← ←
}
```

# **Depth-first search properties**

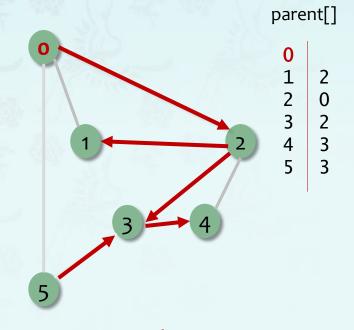
**Proposition:** After DFS, can find vertices connected to s in constant time and can find a path to s (if one exists) in time proportional to its length.

Pf: parent[] is parent-link representation of a tree rooted at s.

```
public boolean hasPathTo(int v)
{ return marked[v]; }

public Iterable<Integer> pathTo(int v){
  if (!hasPathTo(v)) return null;

  Stack<Integer> path = new Stack<Integer>();
  for (int x = v; x != s; x = parent[x])
    path.push(x);
  path.push(s);
  return path;
}
```



a wrong edge?

## **ECE20010 Data Structures**

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  - DFS: Depth first search
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#### Major references:

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- 3. Wikipedia and many resources available from internet

Prof. Youngsup Kim, idebtor@handong.edu, 2014 Data Structures, CSEE Dept., Handong Global University

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# **Connectivity queries**

**Def.:** Vertices v and w are connected if there is a path between them.

**Goal:** Preprocess graph to answer queries of the form "is v connected to w?" in constant time.

public class <mark>CC</mark>					
	CC(Graph G)	find connected components in G			
boolean	<pre>connected(int v, int w)</pre>	are v and w connected?			
int	count()	number of connected components			
int	id(int v)	component identifier for v			

**Union-Find?** Not quite. **Depth-first search?** Yes ...



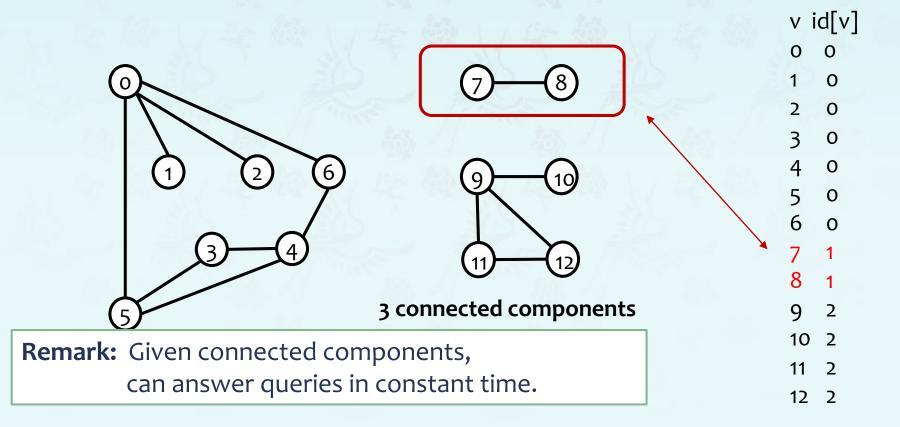
The relation "is connected to" is equivalence relation:

**Reflexive:** v is connected to v.

**Symmetric:** if v is connected to w, then w is connected v.

**Transitive**: if v connected to w and w connected to x, then v connected to x

**Def.:** A connected component is a maximal set of connected vertices.



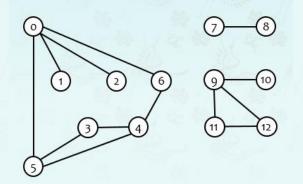


Goal: Partition vertices into connected components.

## **Connected components**

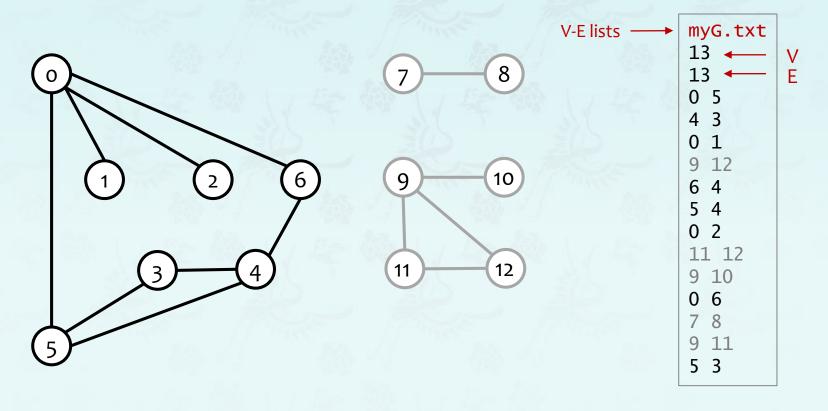
Initialize all vertices v as unmarked.

For each unmarked vertex v, run DFS to identify all vertices discovered as part of the same component.



### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.

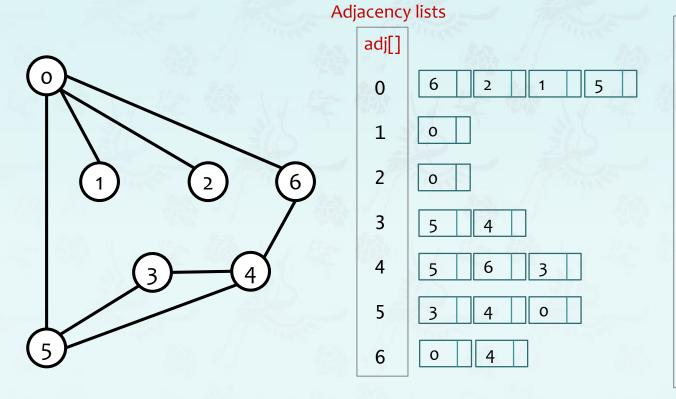


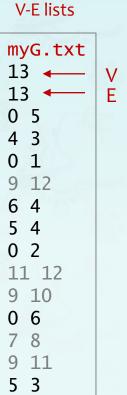
Graph g:

**Challenge:** build adjacency lists?

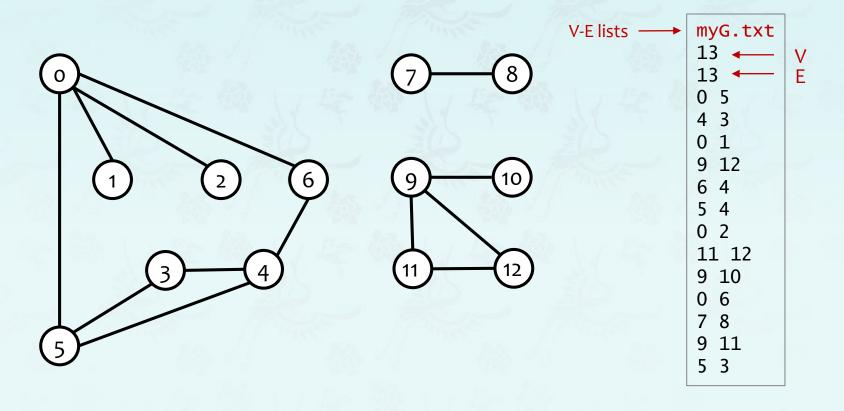


- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.





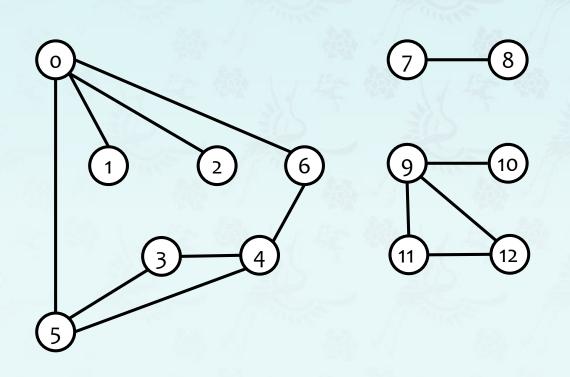
- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



Graph g:



- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.

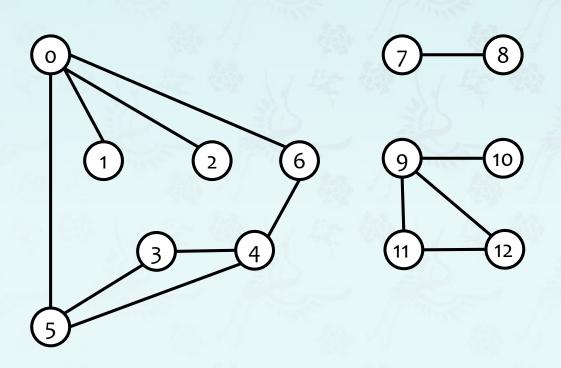


v	marked[]	id[]
0	F	_
1	F	-
2	F	-
3	F	-
4	F	-
5	F	-
6	F	-
7	F	-
8	F	-
9	F	-
10	F	-
11	F	-
12	F	-

Graph g:

### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



v	marked[]	id[]
0	Т	0
1	Т	0
2	Т	0
3	Т	0
4	Т	0
5	Т	0
6	Т	0
7	Т	1
8	Т	1
9	Т	2
10	Т	2
11	Т	2
12	Т	2

#### Done:



# Finding Connected components – implementation in Java

```
public class CC {
  private boolean[] marked;
                                             id[v]=id of component containing v
  private int[] id;
  private int count;
                                             number of components
  public CC(Graph G) {
    marked = new Boolean[G.V()];
    id = new int[G.V()];
    for (int v = 0; v < G.V(); v + +) {
      if (!marked[v]) {
                                             run DFS from one vertex in
        dfs(G, v);
                                             each component
        count++;
                                             see next slide
    public int count()
    public int id(int v)
    private void dfs(Graph G, int v)
```



# Finding Connected components – implementation in Java

```
public class count() {
                                               number of components
  return count;
}
public int id(int v) {
                                               id of component containing v
  return id[v];
}
public void dfs(Graph G, int v) {
  marked[v] = true;
                                               all vertices discovered in the
  id[v] = count;
                                               same call of dfs has the same id
  for (int w : G.adj[v]))
    if (!marked[w])
      dfs(G, w);
}
```

## **ECE20010 Data Structures**

# Chapter 6

- Introduction
- Graph API
- Elementary Graph Operations
  - DFS: Depth first search
  - BFS: Breadth first search
  - CC: Connected Components
- HSet10 graph.c
  - implement DFS, BFS, CC and others
  - submit it in dropbox

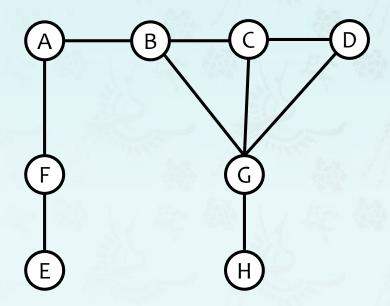
#### Major references:

- 1. Fundamentals of Data Structures by Horowitz, Sahni, Anderson-Freed,
- 2. Algorithms 4<sup>th</sup> edition Part 1 & Part 2 by Robert Sedgewick and Kevin Wayne
- 3. Wikipedia and many resources available from internet

### **DFS** Exercise

### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



## adjacent list

A: BF

B: G C A

C: DGB

D: C G

E: F

F: EA

G: HBCD

H: G

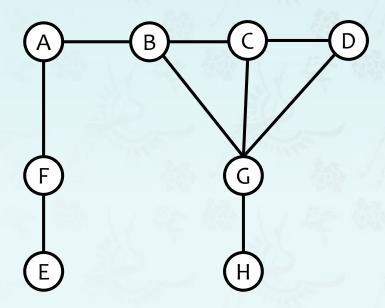
Graph g:

Hint: A B...?... F E

#### **DFS** Exercise

#### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



### adjacent list

A: B F
B: G C A
C: D G B
D: C G
E: F
F: E A
G: H B C D
H: G

check B dfs(C)dfs(D) check C check G D done check G check B C done check D G done check C check A B done dfs(F) dfs(E) check F E done check A F done A done check B check C check D check E check F check G check H

dfs(A) dfs(B)

> dfs(G) dfs(H) check G

H done

#### Graph g:

Hint: A B G H C D F E