

Chrysler comparison of forks

Pros	Neutral	Cons
Master(stock OpenPilot) No Panda		
Stock build	Uses Stock Cruise Control (ACC)	No steering under 9/39mph ☹
Safest to use	Uses Stock Lane Keep Assist (LKA)	Weak steering torque turns
No additional hardware		Doesn't recognize stopped cars

Pros	Neutral	Cons
JVEPilot with steering to zero Panda/harness using xps_wp_chrysler basic software		
Modified version of JVEPilot	Uses Stock Cruise Control (ACC)	Weak steering torque in turns
Works great with stock ACC	Uses Stock Lane Keep Assist (LKA)	Power steering heavy at low speeds
		If panda loses power, you lose P/S
Safer to use		
Steers to Zero MPH/KPH		

Pros	Neutral	Cons
XPS Long Panda/harness using xps_seps software		
Steers to Zero MPH/KPH	Uses vehicles park assist system	Still working out some bugs
Recognizes stopped cars		Unknown how it could handle a steering glitch (crash??)
Full control over ACC/Steering		If panda loses power, you lose P/S
Completely tuneable through code		Can be banned from Cabana
Super awesome :)		Retropilot Cabana security?

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