

Core Overview

The parallel input/output (PIO) core with Avalon® interface provides a memory-mapped interface between an Avalon® Memory-Mapped (Avalon-MM) slave port and general-purpose I/O ports. The I/O ports connect either to on-chip user logic, or to I/O pins that connect to devices external to the FPGA.

The PIO core provides easy I/O access to user logic or external devices in situations where a “bit banging” approach is sufficient. Some example uses are:

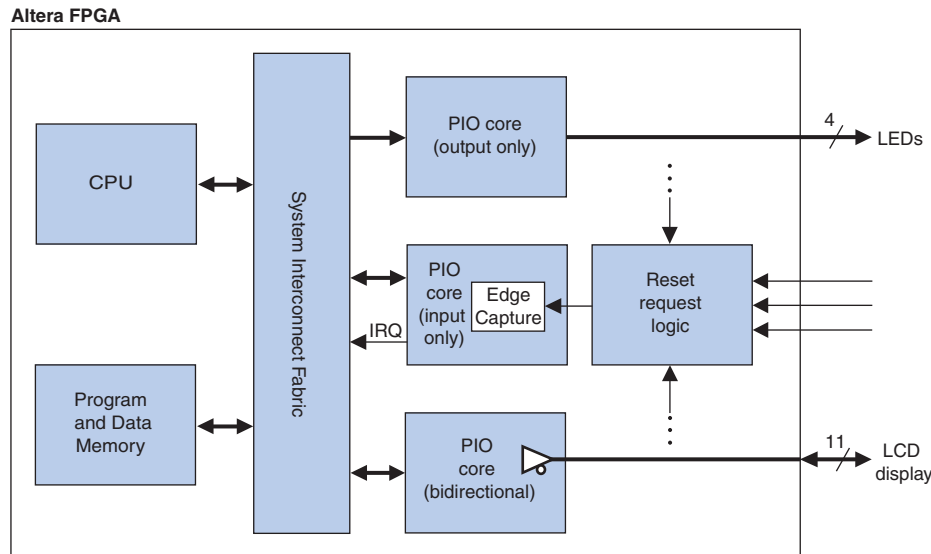
- Controlling LEDs
- Acquiring data from switches
- Controlling display devices
- Configuring and communicating with off-chip devices, such as application-specific standard products (ASSP)

The PIO core interrupt request (IRQ) output can assert an interrupt based on input signals. The PIO core is SOPC Builder ready and integrates easily into any SOPC Builder-generated system. This chapter contains the following sections:

- “Functional Description”
- “Example Configurations” on page 9–3
- “Instantiating the PIO Core in SOPC Builder” on page 9–4
- “Device Support” on page 9–5
- “Software Programming Model” on page 9–5

Functional Description

Each PIO core can provide up to 32 I/O ports. An intelligent host such as a microprocessor controls the PIO ports by reading and writing the register-mapped Avalon-MM interface. Under control of the host, the PIO core captures data on its inputs and drives data to its outputs. When the PIO ports are connected directly to I/O pins, the host can tristate the pins by writing control registers in the PIO core. [Figure 9–1](#) shows an example of a processor-based system that uses multiple PIO cores to drive LEDs, capture edges from on-chip reset-request control logic, and control an off-chip LCD display.

Figure 9-1. An Example System Using Multiple PIO Cores

When integrated into an SOPC Builder-generated system, the PIO core has two user-visible features:

- A memory-mapped register space with four registers: data, direction, interruptmask, and edgecapture
- 1 to 32 I/O ports

The I/O ports can be connected to logic inside the FPGA, or to device pins that connect to off-chip devices. The registers provide an interface to the I/O ports via the Avalon-MM interface. See [Table 9-2 on page 9-6](#) for a description of the registers.

Data Input and Output

The PIO core I/O ports can connect to either on-chip or off-chip logic. The core can be configured with inputs only, outputs only, or both inputs and outputs. If the core is used to control bidirectional I/O pins on the device, the core provides a bidirectional mode with tristate control.

The hardware logic is separate for reading and writing the data register. Reading the data register returns the value present on the input ports (if present). Writing data affects the value driven to the output ports (if present). These ports are independent; reading the data register does not return previously-written data.

Edge Capture

The PIO core can be configured to capture edges on its input ports. It can capture low-to-high transitions, high-to-low transitions, or both. Whenever an input detects an edge, the condition is indicated in the edgecapture register. The types of edges detected is specified at system generation time, and cannot be changed via the registers.

IRQ Generation

The PIO core can be configured to generate an IRQ on certain input conditions. The IRQ conditions can be either:

- *Level-sensitive*—The PIO core hardware can detect a high level. A NOT gate can be inserted external to the core to provide negative sensitivity.
- *Edge-sensitive*—The core's edge capture configuration determines which type of edge causes an IRQ

Interrupts are individually maskable for each input port. The interrupt mask determines which input port can generate interrupts.

Example Configurations

Figure 9-2 shows a block diagram of the PIO core configured with input and output ports, as well as support for IRQs.

Figure 9-2. PIO Core with Input Ports, Output Ports, and IRQ Support

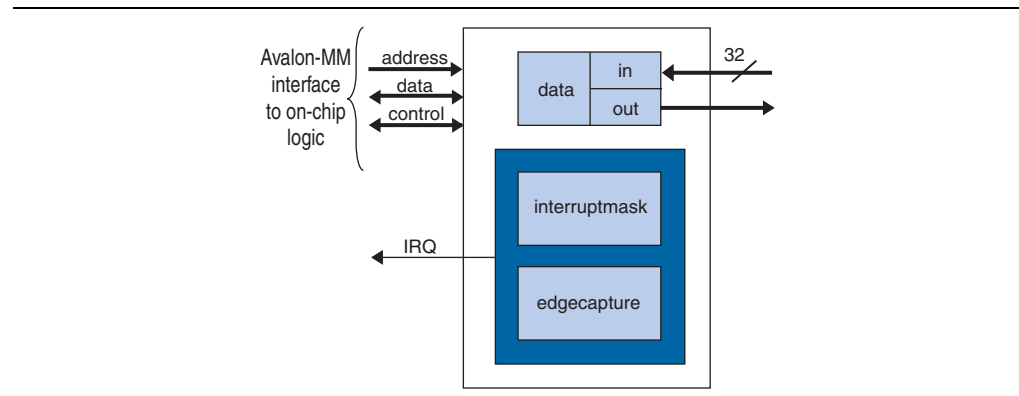
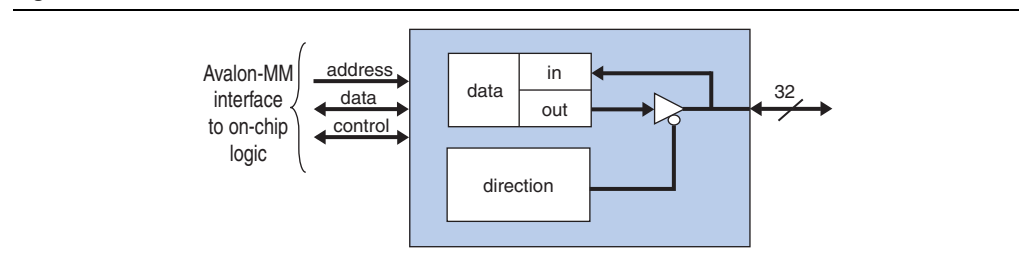


Figure 9-3 shows a block diagram of the PIO core configured in bidirectional mode, without support for IRQs.

Figure 9-3. PIO Core with Bidirectional Ports



Avalon-MM Interface

The PIO core's Avalon-MM interface consists of a single Avalon-MM slave port. The slave port is capable of fundamental Avalon-MM read and write transfers. The Avalon-MM slave port provides an IRQ output so that the core can assert interrupts.

Instantiating the PIO Core in SOPC Builder

Use the MegaWizard™ interface for the PIO core in SOPC Builder to configure the core. The following sections describe the available options.

Basic Settings

The **Basic Settings** page allows you to specify the width, direction and reset value of the I/O ports.

Width

The width of the I/O ports can be set to any integer value between 1 and 32.

Direction

You can set the port direction to one of the options shown in [Table 9-1](#).

Table 9-1. Direction Settings

Setting	Description
Bidirectional (tristate) ports	In this mode, each PIO bit shares one device pin for driving and capturing data. The direction of each pin is individually selectable. To tristate an FPGA I/O pin, set the direction to input.
Input ports only	In this mode the PIO ports can capture input only.
Output ports only	In this mode the PIO ports can drive output only.
Both input and output ports	In this mode, the input and output ports buses are separate, unidirectional buses of n bits wide.

Output Port Reset Value

You can specify the reset value of the output ports. The range of legal values depends on the port width.

Output Register

The option **Enable individual bit set/clear output register** allows you to set or clear individual bits of the output port. When this option is turned on, two additional registers—`outset` and `outclear`—are implemented. You can use these registers to specify the output bit to set and clear.

Input Options

The **Input Options** page allows you to specify edge-capture and IRQ generation settings. The **Input Options** page is not available when **Output ports only** is selected on the **Basic Settings** page.

Edge Capture Register

Turn on **Synchronously capture** to include the edge capture register, `edgecapture`, in the core. The edge capture register allows the core to detect and generate an optional interrupt when an edge of the specified type occurs on an input port. The user must further specify the following features:

- Select the type of edge to detect:
 - Rising Edge
 - Falling Edge
 - Either Edge
- Turn on **Enable bit-clearing for edge capture register** to clear individual bit in the edge capture register. To clear a given bit, write 1 to the bit in the edge capture register.

Interrupt

Turn on **Generate IRQ** to assert an IRQ output when a specified event occurs on input ports. The user must further specify the cause of an IRQ event:

- **Level**— The core generates an IRQ whenever a specific input is high and interrupts are enabled for that input in the `interruptmask` register.
- **Edge**— The core generates an IRQ whenever a specific bit in the edge capture register is high and interrupts are enabled for that bit in the `interruptmask` register.

When **Generate IRQ** is off, the `interruptmask` register does not exist.

Simulation

The **Simulation** page allows you to specify the value of the input ports during simulation. Turn on **Hardwire PIO inputs in test bench** to set the PIO input ports to a certain value in the testbench, and specify the value in **Drive inputs to** field.

Device Support

The PIO core supports all Altera® device families.

Software Programming Model

This section describes the software programming model for the PIO core, including the register map and software constructs used to access the hardware. For Nios® II processor users, Altera provides the HAL system library header file that defines the PIO core registers. The PIO core does not match the generic device model categories supported by the HAL, so it cannot be accessed via the HAL API or the ANSI C standard library.

The Nios II Embedded Design Suite (EDS) provides several example designs that demonstrate usage of the PIO core. In particular, the `count_binary.c` example uses the PIO core to drive LEDs, and detect button presses using PIO edge-detect interrupts.

Software Files

The PIO core is accompanied by one software file, `altera_avalon_pio_regs.h`. This file defines the core's register map, providing symbolic constants to access the low-level hardware.

Register Map

An Avalon-MM master peripheral, such as a CPU, controls and communicates with the PIO core via the four 32-bit registers, shown in Table 9-2. The table assumes that the PIO core's I/O ports are configured to a width of n bits.

Table 9-2. Register Map for the PIO Core

Offset	Register Name		R/W	(n-1)	...	2	1	0
0	data	read access	R	Data value currently on PIO inputs				
		write access	W	New value to drive on PIO outputs				
1	direction (1)		R/W	Individual direction control for each I/O port. A value of 0 sets the direction to input; 1 sets the direction to output.				
2	interruptmask (1)		R/W	IRQ enable/disable for each input port. Setting a bit to 1 enables interrupts for the corresponding port.				
3	edgecapture (1), (2)		R/W	Edge detection for each input port.				
4	outset		W	Specifies which bit of the output port to set.				
5	outclear		W	Specifies which output bit to clear.				

Notes to Table 9-2:

- (1) This register may not exist, depending on the hardware configuration. If a register is not present, reading the register returns an undefined value, and writing the register has no effect.
- (2) Writing any value to `edgecapture` clears all bits to 0.

data Register

Reading from `data` returns the value present at the input ports. If the PIO core hardware is configured in output-only mode, reading from `data` returns an undefined value.

Writing to `data` stores the value to a register that drives the output ports. If the PIO core hardware is configured in input-only mode, writing to `data` has no effect. If the PIO core hardware is in bidirectional mode, the registered value appears on an output port only when the corresponding bit in the `direction` register is set to 1 (output).

direction Register

The `direction` register controls the data direction for each PIO port, assuming the port is bidirectional. When bit n in `direction` is set to 1, port n drives out the value in the corresponding bit of the data register.

The `direction` register only exists when the PIO core hardware is configured in bidirectional mode. The mode (input, output, or bidirectional) is specified at system generation time, and cannot be changed at runtime. In input-only or output-only mode, the `direction` register does not exist. In this case, reading `direction` returns an undefined value, writing `direction` has no effect.

After reset, all bits of `direction` are 0, so that all bidirectional I/O ports are configured as inputs. If those PIO ports are connected to device pins, the pins are held in a high-impedance state. In bi-directional mode, to change the direction of the PIO port, reprogram the `direction` register.

interruptmask Register

Setting a bit in the `interruptmask` register to 1 enables interrupts for the corresponding PIO input port. Interrupt behavior depends on the hardware configuration of the PIO core. See “[Interrupt Behavior](#)” on page 9-7.

The `interruptmask` register only exists when the hardware is configured to generate IRQs. If the core cannot generate IRQs, reading `interruptmask` returns an undefined value, and writing to `interruptmask` has no effect.

After reset, all bits of `interruptmask` are zero, so that interrupts are disabled for all PIO ports.

edgecapture Register

Bit *n* in the `edgecapture` register is set to 1 whenever an edge is detected on input port *n*. An Avalon-MM master peripheral can read the `edgecapture` register to determine if an edge has occurred on any of the PIO input ports. If the option **Enable bit-clearing for edge capture register** is turned off, writing any value to the `edgecapture` register clears all bits in the register. Otherwise, writing a 1 to a particular bit in the register clears only that bit.

The type of edge(s) to detect is fixed in hardware at system generation time. The `edgecapture` register only exists when the hardware is configured to capture edges. If the core is not configured to capture edges, reading from `edgecapture` returns an undefined value, and writing to `edgecapture` has no effect.

outset and outclear Registers

You can use the `outset` and `outclear` registers to set and clear individual bits of the output port. For example, to set bit 6 of the output port, write 0x40 to the `outset` register. Writing 0x08 to the `outclear` register clears bit 3 of the output port.

These registers are only present when the option **Enable individual bit set/clear output register** is turned on.

Interrupt Behavior

The PIO core outputs a single IRQ signal that can connect to any master peripheral in the system. The master can read either the data register or the `edgecapture` register to determine which input port caused the interrupt.

When the hardware is configured for level-sensitive interrupts, the IRQ is asserted whenever corresponding bits in the data and `interruptmask` registers are 1. When the hardware is configured for edge-sensitive interrupts, the IRQ is asserted whenever corresponding bits in the `edgecapture` and `interruptmask` registers are 1. The IRQ remains asserted until explicitly acknowledged by disabling the appropriate bit(s) in `interruptmask`, or by writing to `edgecapture`.

Software Files

The PIO core is accompanied by the following software file. This file provides low-level access to the hardware. Application developers should not modify the file.

- **altera_avalon_pio_regs.h**—This file defines the core's register map, providing symbolic constants to access the low-level hardware. The symbols in this file are used by device driver functions.

Document Revision History

Table 9-3 shows the revision history for this chapter.

Table 9-3. Document Revision History

Date and Document Version	Changes Made	Summary of Changes
July 2010 v10.0.0	No change from previous release.	—
November 2009 v9.1.0	No change from previous release.	—
March 2009 v9.0.0	Added a section on new registers, <code>outset</code> and <code>outclear</code> .	—
November 2008 v8.1.0	Changed to 8-1/2 x 11 page size. Added the description for Output Port Reset Value and Simulation parameters.	—
May 2008 v8.0.0	No change from previous release.	—



For previous versions of this chapter, refer to the [Quartus II Handbook Archive](#).