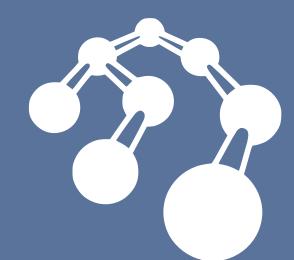
# AUTOTUNING UNDER TIGHT BUDGET CONSTRAINTS: A TRANSPARENT DESIGN OF EXPERIMENTS APPROACH



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#### Autotuning: Optimizing Program Configurations

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- How to write efficient code for each of these?
- ► We can use autotuning: the process of automatically finding a configuration of a program that optimizes an objective

### Strategies for Exploring Search Spaces

System	Domain	Approach
ATLAS	Dense Linear Algebra	Exhaustive
INSIEME Active Harmony ParamILS OPAL OpenTuner	Compiler Runtime Domain-Agnostic Domain-Agnostic Domain-Agnostic	Genetic Algorithm Nelder-Mead Stochastic Local Search Direct Search Ensemble
MILEPOST GCC Apollo	•	Machine Learning Decision Trees

Exhaustive, Meta-Heuristics, Machine Learning

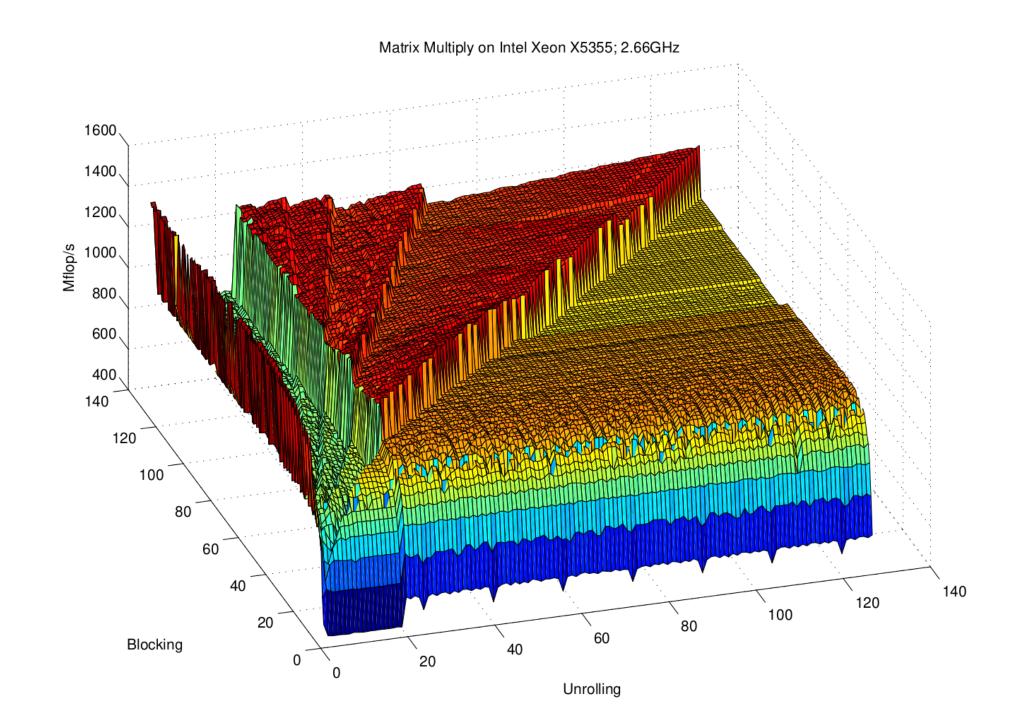
#### Assumptions:

Many measurements, "smoothness", reachable solutions

#### After optimizing:

Learn "nothing", can't explain choices

#### Autotuning: Search Spaces are Hard to Explore



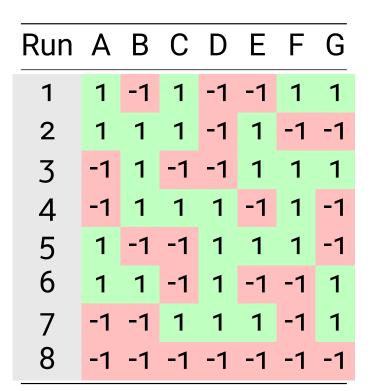
Unrolling, blocking and Mflops/s for matrix multiplication Seymour K, You H, Dongarra J. A comparison of search heuristics for empirical code optimization. InCLUSTER 2008 Oct 1 (pp. 421-429)

- Represent the effect of all possible configurations on the objectives, can be difficult to explore, with multiple local optima and undefined regions
- Main issues are exponential growth, geometry, & measurement time

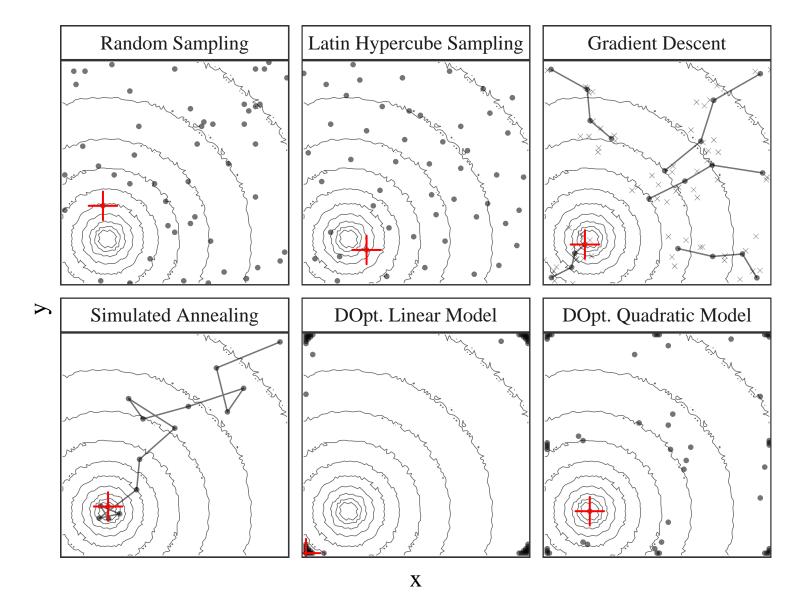
#### Design of Experiments: Exploration under a Budget

#### Design of Experiments (DoE):

- ► Factors are program parameters, and levels are possible factor values
- ► An experiment fixes levels, and a design is a selection of experiments to run
- A performance model is required to construct designs

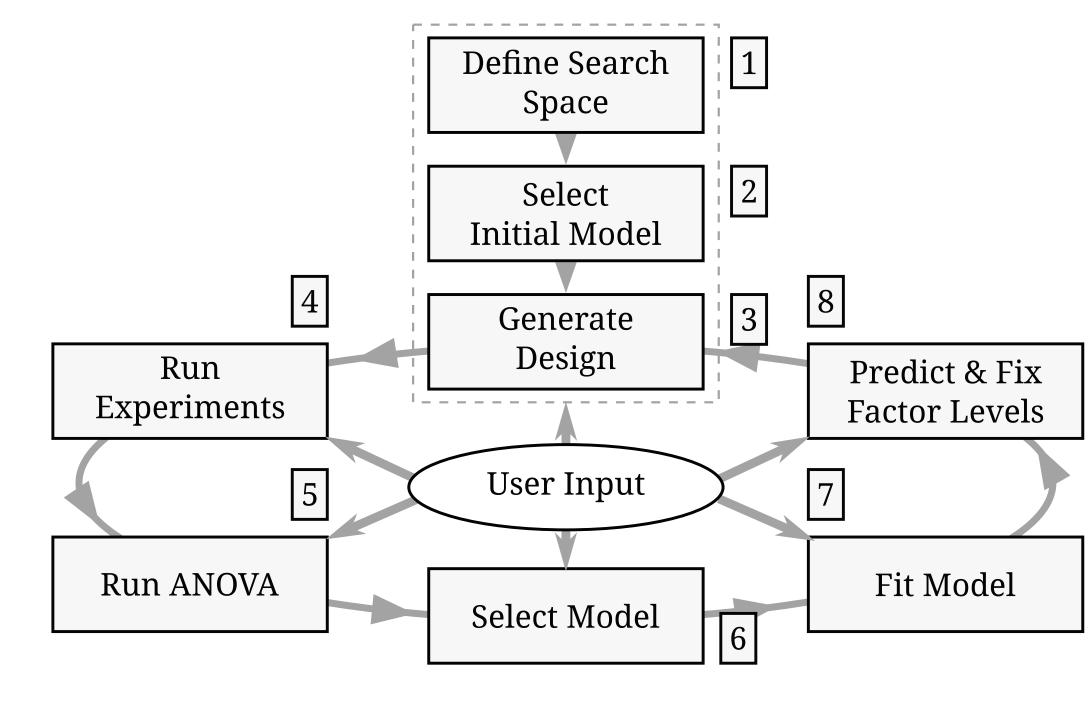


- A Plackett-Burman design for 7 2-level factors
- Results, or responses, can be used to identify relevant parameters and to fit a linear regression model



Exploration of a search space using a fixed budget of 50 points, the red "+" represents the best point found by each strategy

## A Transparent Design of Experiments Approach



- An initial model is provided by the user (steps 1 & 2)
- Design of Experiments guides exploration (steps 3 & 4)
- Significant factors are identified by Analysis of Variance (ANOVA) (steps 5 & 6)
- New fitted model predicts best value for significant factors (steps 7 & 8)

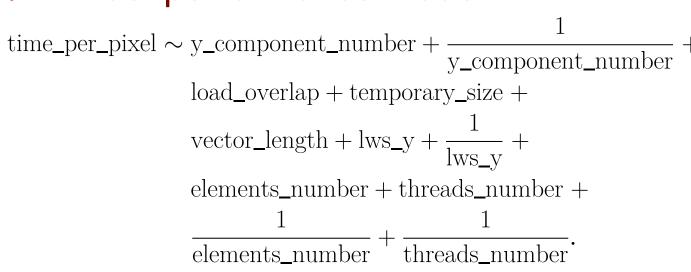
Transparent: factor and level selections based on ANOVA Parsimonious: DoE decreases measurements

# A Motivating Result on a GPU Kernel

#### Kernel factors:

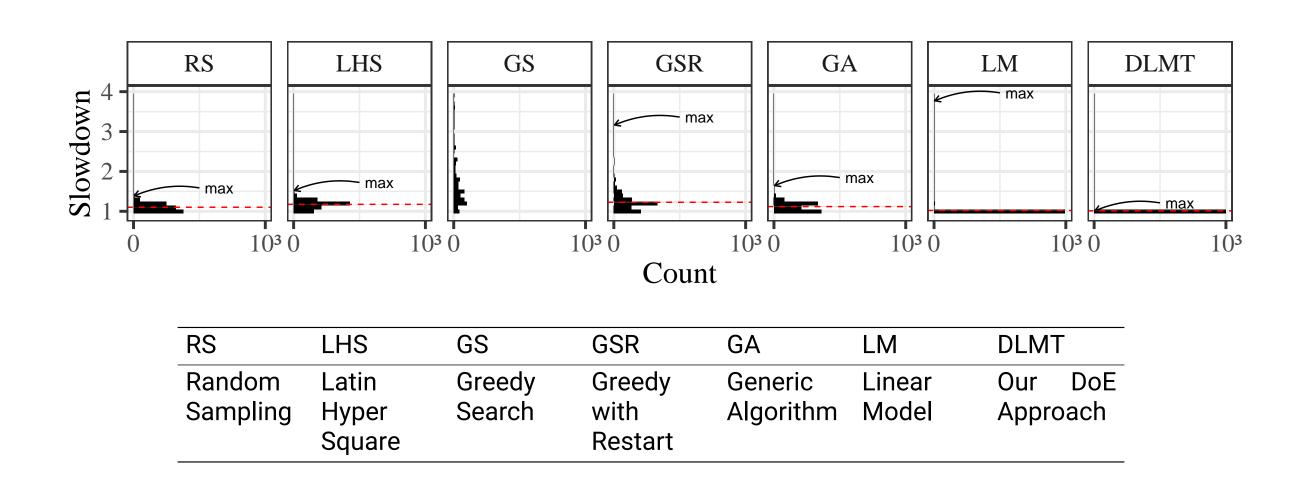
Factor	Levels	Short Description	
vector_length	$2^0, \dots, 2^4$	Size of support	
		arrays	
load_overlap	true, false	Load overlaps in	
		vectorization	
temporary_size	2, 4	Byte size of tem-	
		porary data	
elements_number	$1,\ldots,24$	Size of equal	
		data splits	
y_component_number	$1,\ldots,6$	Loop tile size	
threads_number	$2^5, \dots, 2^{10}$	Size of thread	
		groups	
lws_y	$2^0, \dots, 2^{10}$	Block size in $y$ di-	
		mension	

Initial performance model:



This simple case had known valid search space and global optimum, and fixed budget

#### Our approach (DLMT) was always within 1% of the optimum



#### Extensive Evaluation on the SPAPT Benchmark

- $\blacktriangleright$  SPAPT is an autotuning benchmark for CPU kernels, with search space sizes between  $10^7$  and  $10^{36}$
- ► We evaluated DLMT on 17 kernels (3 shown below) using the same initial performance model, and fixed budget

Our approach (DLMT) achieved good speedups using a smaller budget, while exploring better configurations

