# YUNSHENG MA

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## EDUCATION

**Purdue University** — West Lafayette, IN
Ph.D., Research Field: Autonomous Driving, Transportation Engineering — Jan. 2023 – Present

**New York University** — New York City, NY
Master of Science, Computer Science — Sep. 2020 – May 2022

**Harbin Institute of Technology** — Weihai, China
Bachelor of Engineering, Computer Software Engineering — Sep. 2016 – May 2020

**University of California, Berkeley** — Berkeley, CA
Visiting Student, Electrical Engineering and Computer Sciences — Aug. 2018 – May 2019

## SELECTED PUBLICATIONS

### In Conference Proceedings ( *denotes co-first authors )

**Y. Ma***, C. Cui*, X. Cao*, W. Ye, P. Liu, J. Lu, A. Abdelraouf, R. Gupta, K. Han, A. Bera, J. M. Rehg, Z. Wang. "LaMPilot: An Open Benchmark Dataset for Autonomous Driving with Language Model Programs." In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition* (**CVPR**), 2024.

X. Cao*, T. Zhou*, **Y. Ma***, W. Ye, C. Cui, K. Tang, Z. Cao, K. Liang, Z. Wang, J. M. Rehg, and C. Zheng. "MAPLM: A Real-World Large-Scale Vision-Language Dataset for Map and Traffic Scene Understanding." In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition* (**CVPR**), 2024.

J. Lu*, C. Cui*, **Y. Ma**, A. Bera, and Z. Wang. "Quantifying Uncertainty in Motion Prediction with Variational Bayesian Mixture." In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition* (**CVPR**), 2024.

**Y. Ma***, J. Lu*, C. Cui, S. Zhao, X. Cao, W. Ye, Z. Wang. "MACP: Efficient Model Adaptation for Cooperative Perception." In *Proceedings of the IEEE/CVF Winter Conference on Applications of Computer Vision* (**WACV**), 2024.

C. Cui*, **Y. Ma***, X. Cao*, W. Ye*, Y. Zhou, K. Liang, J. Chen, J. Lu, Z. Yang, K. Liao, T. Gao, E. Li, K. Tang, Z. Cao, T. Zhou, A. Liu, X. Yan, S. Mei, J. Cao, Z. Wang, C. Zheng. "A Survey on Multimodal Large Language Models for Autonomous Driving." In *Proceedings of the IEEE/CVF Winter Conference on Applications of Computer Vision (WACV) Workshops*, 2024.

**Y. Ma**, W. Ye, X. Cao, A. Abdelraouf, K. Han, R. Gupta, Z. Wang. "CEMFormer: Learning to Predict Driver Intentions from In-Cabin and External Cameras via Spatial-Temporal Transformers." *IEEE International Conference on Intelligent Transportation Systems* (**ITSC**), 2023.

W. Ye, **Y. Ma**, X. Cao, K. Tang. "Mitigating Transformer Overconfidence via Lipschitz Regularization." In *Proceedings of the Conference on Uncertainty in Artificial Intelligence* (**UAI**), 2023.

S. Zhao*, **Y. Ma***, Y. Gu, J. Yang, T. Xing, P. Xu, R. Hu, H. Chai, and K. Keutzer. "An End-to-End Visual-Audio Attention Network for Emotion Recognition in User-Generated Videos." In *Proceedings of the AAAI Conference on Artificial Intelligence* (**AAAI**), 2020, **Oral Presentation**.

### Journal Articles

**Y. Ma**, R. Du, A. Abdelraouf, K. Han, R. Gupta, Z. Wang. "Driver Digital Twin for Online Recognition of Distracted Driving Behaviors." *IEEE Transactions on Intelligent Vehicles*, 2024.

C. Cui, **Y. Ma**, J. Lu, Z. Wang. "REDFormer: Radar Enlightens the Darkness of Camera Perception with Transformers." *IEEE Transactions on Intelligent Vehicles*, 2023.

## Work Experience

**Digital Twin Lab, Purdue University** — Aug. 2022 – Present
Graduate Research Assistant — Advised by Dr. Ziran Wang

**Embodied AI for Autonomous Driving [CVPR 2024]:** Proposed *LaMPilot*, a new benchmark for language-guided autonomous driving, which uses LLMs to translate natural language instructions into executable codes that act as driving policies. *LaMPilot* combines functional primitives with heuristics, enabling the LLM to interact safely with the driving environment through code generation. The benchmark was used to compare a variety of SOTA LLMs in 0-shot, 3-shot, and human-in-the-loop settings.

**BEV Perception [WACV 2024]:** Proposed the MACP framework to adapt a single-agent pre-trained model with cooperation capabilities. MACP achieved SOTA performance in both simulation and real-world cooperative perception benchmarks, with fewer tunable parameters and reduced communication cost.

**Driver Behavior [T-IV & ITSC 2023]:** Proposed multi-view spatial-temporal Transformers for driver intention prediction, driver action recognition, and temporal action localization.

**Didi Chuxing** — June 2019 – Sep. 2019
Research Intern — Advised by Dr. Pengfei Xu

**Video Emotion Recognition [AAAI 2020]:** Proposed a Visual-Audio Attention Network (VAANet) that integrates spatial, channel-wise, and temporal attentions into a 3D convolutional neural network. VAANet achieved SOTA performance on both the VideoEmotion-8 and Ekman-6 benchmarks.

## Professional Activities

### As a Workshop/Challenge Organizer

Co-Chair of *WACV Workshop on Large Language and Vision Models for Autonomous Driving* (**LLVM-AD**) 2024
Organizer of *MAPLM Challenge: A Vision-Language Benchmark for Map and Traffic Scene Understanding* 2024

### As a Reviewer/Program Committee Member

PC Member of *International Joint Conference on Artificial Intelligence* (**IJCAI**) 2024
Reviewer of *IEEE/CVF Conference on Computer Vision and Pattern Recognition* (**CVPR**) 2024
Reviewer of *IEEE International Symposium on Biomedical Imaging* (**ISBI**) 2024
Reviewer of *IEEE Intelligent Vehicles Symposium* (**IV**) 2023, 2024
Reviewer of *IEEE International Conference on Intelligent Transportation Systems* (**ITSC**) 2023
Reviewer of *ACM/IEEE International Conference on Cyber-Physical Systems* (**ICCPS**) 2023
Reviewer of *IEEE International Conference on Mobility: Operations, Services, and Technologies* (**MOST**) 2023
Reviewer of *IEEE Internet of Things Journal* (**IoT-J**)
Reviewer of *IEEE Transactions on Intelligent Vehicles* (**T-IV**)

### As a Volunteer

Volunteer of *Conference on Uncertainty in Artificial Intelligence* (**UAI**) 2023
Volunteer of *AAAI Conference on Artificial Intelligence* (**AAAI**) 2023
Assistant Moderator of *TRB Conference on Innovations in Travel Analysis and Planning* 2023
Webmaster of *IEEE Technical Committee on Internet of Things in Intelligent Transportation System* 2022 – Present

## Fellowships & Awards

Annual Conference on Next-Generation Transportation Systems, *Outstanding Speaker Award* 2023
*AAAI Student Scholarship Grant* 2023
*NeurIPS ML4AD Grant* by Waymo 2022

## Technical Skills

**Programming:** Python, C/C++

**Libraries:** PyTorch, Lightening, Hugging-Face, LangChain, CARLA, Gymnasium, Open3D, OpenCV

**Tools:** Git, LaTeX, SQL