The second-order geometry of short-and-sparse blind deconvolution

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Abstract

These notes describe a set of experiments for interrogating the curvature of nonconvex objective functions for short-and-sparse blind deconvolution (SaS-BD) over the course of optimization.

1 Introduction

In SaS-BD, we observe a length-m signal

$$\mathbf{y} = \iota \mathbf{a}_0 \circledast \mathbf{x}_0 + \mathbf{w},$$

the cyclic convolution between a *short* kernel $\mathbf{a}_0 \in \mathbb{S}^{p_0-1}$, zero-padded to length m, and a *sparse* activation map $\mathbf{x}_0 \in \mathbb{R}^m$, with possible additive noise \mathbf{w} . Our goal is to recover \mathbf{a}_0 and \mathbf{x}_0 up to some scaling or cyclic shift, as

$$\iota \mathbf{a}_0 \circledast \mathbf{x}_0 \equiv \alpha s_{\ell}[\iota \mathbf{a}_0] \circledast \alpha^{-1} s_{-\ell}[\mathbf{x}_0]$$

for any $\alpha \in \{\mathbb{R} \setminus 0\}$ and $\ell \in \mathbb{Z}$. We refer to these as the scaling and shift symmetries respectively. A natural approach is to begin by formulating SaS-BD as a nonconvex optimization problem,

$$\min_{\mathbf{a} \in \mathbb{S}^{p-1}, \mathbf{x}} \left[\Psi_{\lambda}(\mathbf{a}, \mathbf{x}) \doteq \psi(\mathbf{a}, \mathbf{x}; \mathbf{y}) + \lambda \rho(\mathbf{x}) \right], \tag{1.1}$$

which minimizes a reconstruction error between y and $a \circledast x$, plus a sparse penalty ρ on x. For example, combining a squared error loss with an ℓ_1 -norm penalty yields the *bilinear-lasso* (BL) formulation

$$\Psi_{\lambda}(\mathbf{a}, \mathbf{x}) = \frac{1}{2} \|\mathbf{a} \otimes \mathbf{x} - \mathbf{y}\|_{2}^{2} + \lambda \|\mathbf{x}\|_{1}.$$
 (BL)

A simplified problem, known as the *dropped-quadratic* formulation (DQ), can be obtained when the circulant matrix of \mathbf{a} , $\mathbf{C}_{\mathbf{a}}$, satisfies $\mathbf{C}_{\mathbf{a}}^T\mathbf{C}_{\mathbf{a}}\simeq \mathbf{I}$ over the course of optimization,

$$\Psi_{\lambda}(\mathbf{a}, \mathbf{x}) = \frac{1}{2} \|\mathbf{x}\|_{2}^{2} - \langle \mathbf{a} \otimes \mathbf{x}, \mathbf{y} \rangle + \frac{1}{2} \|\mathbf{y}\|_{2}^{2} + \lambda \rho(\mathbf{x}), \tag{DQ}$$

$$\rho(\mathbf{x}) = \sum_{i} (x_i^2 + \delta^2)^{\frac{1}{2}}. \tag{1.2}$$

1.1 Regional landscape geometry

When x_0 is generic, the objective function becomes regular on a after marginalization on x,

$$(1.1) \equiv \min_{\mathbf{a} \in \mathbb{S}^{p-1}} \left[\varphi_{\lambda}(\mathbf{a}) \doteq \min_{\mathbf{x}} \Psi_{\lambda}(\mathbf{a}, \mathbf{x}) \right]. \tag{1.3}$$

This phenomenon appears to be *largely independent* of the specific formulation used for SaS-BD, but finds a relatively simple expression in the (DQ) formulation, for which it is summarized as follows [KLZW19]:

1.2 Sparsity-coherence tradeoff

2 Experimental outline

References

[KLZW19] Han-Wen Kuo, Yenson Lau, Yuqian Zhang, and John Wright. Geometry and symmetry in short-and-sparse deconvolution. arXiv preprint arXiv:1901.00256, 63(7):4497–4520, 2019.