

# Models for Higher Brain Function

## Exercise Sheet 5: Observer Models in Signal Detection

July 5, 2010

In signal detection theory, it is typically assumed that an observer performs a psychophysical task by monitoring an internal random variable  $X$ . The distribution of  $X$  is typically assumed to depend on the input stimulus  $S$ . In this exercise sheet, we will only consider detection experiments, in which  $S$  can only take one of two values —  $S = 1$  implies that a signal was presented,  $S = 0$  implies that no signal was presented.

In order to use signal detection theory to understand psychophysical data, it is necessary to define a rule that maps different realizations of  $X$  to different responses  $R$ .

### 1 High threshold model

Threshold models assume that the internal random variable  $X$  can only take two values —  $X = 1$ , the “detect” state, or  $X = 0$ , the “non-detect” state. The characterizing assumption of the high threshold model is that a no signal stimulus can never trigger a detect state. In contrast, a signal stimulus can trigger a detect state with a certain probability  $p$ . Based on the value of  $X$ , an observer can also “guess”. Guessing in this case means that the observer can choose to respond “yes” on some non-detect trials (being aware of the fact that  $X = 0$  doesn’t necessarily imply “no signal present”).

- Write a function that simulates a signal detection experiment for an observer that follows the assumptions of the high threshold model.
- Use this function to trace out an ROC curve for the cases that  $p = 0.3$ ,  $p = 0.5$ , and  $p = 0.8$ . Use 300 signal trials and 300 noise trials per simulated experiment and simulate 7 different experiments (i.e. guessing rates). How are these function related?

- How can you determine  $p$  from the ROC graph?

## 2 Low threshold model

The low threshold model is similar to the high threshold model: It also assumes  $X \in \{0, 1\}$  and interpolates different strategies by guessing. However, the low threshold model also allows “detect” states to be triggered by no signal trials. Thus, there are two probabilities:

1.  $p_1$  is the probability that a detect state was triggered by a signal stimulus,
2.  $p_0$  is the probability that a nondetect state was triggered by a no-signal stimulus.

In addition, we have two guessing rates now:

1.  $\gamma_1$  the probability to respond “yes” although  $X = 0$ ,
2.  $\gamma_0$  the probability to respond “no” although  $X = 1$ .

Note that any strategy in the low threshold model will have either  $\gamma_1 = 0$  or  $\gamma_0 = 0$  (Why?)!

Perform the same analysis as for the high threshold model. Instead of using  $p = 0.3$ ,  $p = 0.5$ ,  $p = 0.8$ , use  $p := (p_1, p_0)$ , with  $p = (0.5, 0.3)$ ,  $p = (0.6, 0.3)$ ,  $p = (0.5, 0.2)$ .

## 3 Equal variance gaussian model

A very prominent model assumes that  $X$  is a real random variable. Typically,  $X$  is given in terms of conditional distributions. If  $S = 0$ ,  $X \sim \mathcal{N}(0, 1)$  and if  $S = 1$ ,  $X \sim \mathcal{N}(d', 1)$ . There are two different strategies to map the values of  $X$  to responses:

1. A criterion value  $c \in \mathbb{R}$  is selected and the observer responds “yes”, whenever  $X > c$ .

2. The observer internally calculates a likelihood ratio

$$\ell = \frac{\mathbb{P}(X|S = 1)}{\mathbb{P}(X|S = 0)},$$

and responds “yes” whenever  $\ell > c$ .

Perform the same steps as for the high threshold model for both response strategies. Use  $d' = 0.5$ ,  $d' = 1$ ,  $d' = 1.5$ . What happens if you rescale the axes of the ROC graph: Use  $\Phi^{-1}(p)$  instead of  $p$ . The functions  $\Phi^{-1}$  is the “percent point function” of the Normal distribution and can be found in python as

`scipy.stats.norm.ppf`

Can you see from the simulation results, why the two strategies are equivalent?

## 4 Unequal variance gaussian model

Here, we relax the assumptions of the equal variance gaussian model. We still assume that for  $S = 0$ ,  $X \sim \mathcal{N}(0, 1)$ , but for  $S = 1$ , we assume  $X \sim \mathcal{N}(d, \sigma)$ .

Perform the same steps as in the previous exercise. In this case, the two strategies are actually different. Can you see why? For what values of  $c$  can you observe clearly different experimental results?