

Analysis of Electrical Circuits and Mechanical Systems with Fractional-order Elements: A Systems Theory Approach

Dissertation-I

By

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Outline

- 1 Introduction.
- 2 What is Fractional Calculus.
- 3 Fractional Order (FO) Elements.
- 4 Circuit With FO Elements.
- 5 Fractional Order Transfer Function.
- 6 Stability Of FO System.
- 7 Problem Definition.

Introduction

- Integer Order System and its limitations.
- Fractional Order System and its approach.
- Basics of Fractional Order System.
- FO elements and its applications.
- Problem Definition.
- Conclusion.

Fractional Calculus

Real order generalization of fractional calculus

$$D^\alpha = \begin{cases} \frac{d^\alpha}{dt^\alpha} & \alpha > 0 \\ 1 & \alpha = 0 \\ \int_a^t (d\tau)^\alpha & \alpha < 0 \end{cases} \quad (1)$$

with $\alpha \in \mathcal{R}$.

Riemann-Liouville:

Integral:

$$J_c^\alpha f(t) = \frac{1}{\Gamma(\alpha)} \int \frac{f(\tau)}{(t - \tau)^{1-\alpha}} d\tau \quad (2)$$

Derivative:

$$D^\alpha f(t) = \frac{d^m}{dt^m} \left[\frac{1}{\Gamma(m - \alpha)} \int_a^t \frac{f(\tau)}{(t - \tau)^{\alpha+1-m}} d\tau \right], m \in \mathbb{Z}^+, m - 1 < \alpha \leq m. \quad (3)$$

Grunwald-Letnikov:

Integral:

$$D^{-\alpha} = \lim_{h \rightarrow 0} h^{\alpha} \sum_{m=0}^{(t-a)/h} \frac{\Gamma(\alpha + m)}{m! \Gamma(\alpha)} f(t - mh), \quad (4)$$

Derivative:

$$D^{\alpha} = \lim_{h \rightarrow 0} \frac{1}{h^{\alpha}} \sum_{m=0}^{(t-a)/h} (-1)^m \frac{\Gamma(\alpha + 1)}{m! \Gamma(\alpha - m + 1)} f(t - mh), \quad (5)$$

Caputo:

$$D^{\alpha}f(t) = \frac{1}{\Gamma(m-\alpha)} \int_0^t \frac{f^{(m)}(\tau)}{(t-\tau)^{\alpha+1-m}} d\tau, \quad (6)$$

- Inductor or lossy coil have hysteresis and eddy current losses.
- Capacitors produces dielectric losses.
- FO inductors or FO capacitors yield a more accurate description.

FO Elements

Schematic of FO Capacitor

FOmodelRpztn0fossyC.pdf

The voltage-current relationships for an FO capacitor are

$$i_c(t) = C_\alpha \frac{d^\alpha}{dt^\alpha} v_c(t), \quad (7)$$

or

$$v_c(t) = \frac{1}{C_\alpha} {}_0J_t^\alpha i_c(t), \quad (8)$$

where the constant $0 < \alpha < 1, \alpha \in \mathbf{R}$ is a measure of the losses in the capacitor.

$$j^{-\alpha} = \cos(\alpha\pi/2) - j \sin(\alpha\pi/2) = e^{-j\alpha\pi/2} \quad (9)$$

FO Elements

Phase Relationship Between V and I for FO capacitor

PhaseRelationBtwnVandIforFOC.pdf

FO Elements

Schematic of FO Inductor

F0modelofL.pdf

For an FO inductor we have,

$$V_L(t) = L_\beta \frac{d^\beta}{dt^\beta} i_L(t) \quad (10)$$

where the fractional power β is related to the phenomenon of proximity effect. In frequency domain,

$$V_L(s) = s^\beta L_\beta I_L(s) \quad (11)$$

$$j = \cos(\pi/2) + j \sin(\pi/2) = e^{j\pi/2} \quad (12)$$

$$j^\beta = \cos(\beta\pi/2) + j \sin(\beta\pi/2) = e^{j\beta\pi/2} \quad (13)$$

FO Elements

Phase Relationship Between V and I for FO inductor

PhasorDiagForFOL.pdf

Stability of FO System

- Fractional Domain
- Mapping of S-plane to F-plane.
- α increases the stable F-domain regions decreases.
- Stability decreases for $\alpha > 2$

Stability of FO

stability2.pdf

Problem Definition

R-Lckt.pdf

Transfer Function of FO

$$\frac{I(s)}{V(s)} = \frac{\frac{1}{L_\beta}}{s^\beta + \frac{R}{L_\beta}}. \quad (14)$$

Future Work

- Analysis of electrical circuits and mechanical systems with fractional-order elements.
- Development of various linear models.
- Stability analysis using Riemann sheet concept.
- Analysis of controllability, observability, reachability, and solution of the state-equation.
- Design of linear compensators and controllers.
- Development of equivalent relationship between FO electrical and mechanical systems.

Thank You...