

The Mechanical Evaluation Of Expressions

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Outline

SECD - Square Root

```
Transform(S,E,C,D) =  
  null C → [hS:S',E',C',D']  
           where S',E',C',D' = D  
  else →  
    identifier X → [location EXE:S, E, tC, D]  
    lexp X →  
      [constructclosure((E, bvX), unitlist(bodyX)):S,  
       E, tC, D]  
    X = ap → closure(hS) →  
      [( ), derive(assoc(J, 2ndS)E'),  
       C,  
       (t(tS), E, tC, D)]  
      where E',J = environmentpart(hS)  
            and C' = controlpart(hS)  
            else → [(1stS)(2nd):t(tS), E, tC, D]  
  else → [S, E, randX:(ratorX:(ap:tC)), D]  
  where X = hC
```

sqrt = \n . n * n

S = []

E = []

C = [sqrt(2)]

D = []

SECD - Square Root

```
Transform(S,E,C,D) =  
  nullC → [hS:S',E',C',D']  
           where S',E',C',D' = D  
  else →  
    identifier X → [locationEXE:S, E, tC, D]  
    lexp X →  
      [constructclosure((E, bvX),unitlist(bodyX)):S,  
       E, tC, D]  
    X = ap → closure(hS) →  
      [( ), derive(assoc(J,2ndS)E'),  
       C,  
       (t(tS), E, tC, D)]  
      where E',J = environmentpart(hS)  
            and C' = controlpart(hS)  
            else → [(1stS)(2nd):t(tS), E, tC, D]  
  else → [S, E, randX:(ratorX:(ap:tC)), D]  
  where X = hC
```

sqrt = \n . n * n

S = []

E = []

C = [\n . n * n, 2]

D = []

SECD - Square Root

```
Transform(S,E,C,D) =  
  null C → [hS:S',E',C',D']  
           where S',E',C',D' = D  
  else →  
    identifier X → [location EXE:S, E, tC, D]  
    λexp X →  
      [constructclosure((E, bvX), unitlist(bodyX)):S,  
       E, tC, D]  
    X = ap → closure(hS) →  
      [( ), derive(assoc(J, 2ndS)E'),  
       C,  
       (t(tS), E, tC, D)]  
      where E',J = environmentpart(hS)  
            and C' = controlpart(hS)  
            else → [(1stS)(2nd):t(tS), E, tC, D]  
  else → [S, E, randX:(ratorX:(ap:tC)), D]  
  where X = hC
```

```
sqrt = \n . n * n  
S = []  
E = []  
C = [2, \n . n * n, ap]  
D = []
```

SECD - Square Root

```
Transform(S,E,C,D) =  
  null C → [hS:S',E',C',D']  
           where S',E',C',D' = D  
  else →  
    identifier X → [location EXE:S, E, tC, D]  
    lexp X →  
      [construct closure((E, bv X), unit list(body X)):S,  
       E, tC, D]  
    X = ap → closure(hS) →  
      [( ), derive(assoc(J, 2nd S) E'),  
       C,  
       (t(tS), E, tC, D)]  
      where E', J = environment part(hS)  
            and C' = control part(hS)  
            else → [(1st S)(2nd):t(tS), E, tC, D]  
    else → [S, E, rand X:(rator X:(ap:tC)), D]  
    where X = hC
```

```
sqrt = \n . n * n  
S = [2]  
E = []  
C = [\n . n * n, ap]  
D = []
```

SECD - Square Root

```
Transform(S,E,C,D) =  
  null C → [hS:S',E',C',D']  
           where S',E',C',D' = D  
  else →  
    identifier X → [location EXE:S, E, tC, D]  
    λexp X →  
      [constructclosure((E, bvX), unitlist(bodyX)):S,  
       E, tC, D]  
    X = ap → closure(hS) →  
      [( ), derive(assoc(J, 2ndS)E'),  
       C,  
       (t(S), E, tC, D)]  
      where E', J = environmentpart(hS)  
            and C' = controlpart(hS)  
            else → [(1stS)(2nd):t(S), E, tC, D]  
  else → [S, E, randX:(ratorX:(ap:tC)), D]  
  where X = hC
```

```
sqrt = \n . n * n  
S = [closure [] x [x * x], 2]  
E = []  
C = [ap]  
D = []
```

SECD - Square Root

```
Transform(S,E,C,D) =  
  null C → [hS:S',E',C',D']  
           where S',E',C',D' = D  
  else →  
    identifier X → [location EXE:S, E, tC, D]  
    lexp X →  
      [construct closure((E, bv X), unit list(body X)):S,  
       E, tC, D]  
    X = ap → closure(hS) →  
      [( ), derive(assoc(J, 2nd S) E'),  
       C,  
       (t(tS), E, tC, D)]  
      where E', J = environment part(hS)  
            and C' = control part(hS)  
            else → [(1st S)(2nd):t(tS), E, tC, D]  
    else → [S, E, rand X:(rator X:(ap:tC)), D]  
    where X = hC
```

sqrt = \n . n * n

S = []

E = [[(x 2)]]

C = [x * x]

D = []

SECD - Square Root

```
Transform(S,E,C,D) =  
  null C → [hS:S',E',C',D']  
           where S',E',C',D' = D  
  else →  
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       (t(tS), E, tC, D)]  
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            and C' = controlpart(hS)  
            else → [(1stS)(2nd):t(tS), E, tC, D]  
  else → [S, E, randX:(ratorX:(ap:tC)), D]  
  where X = hC
```

sqrt = \n . n * n

S = []

E = [[(x 2)]]

C = [x x * ap]

D = []

SECD - Square Root

```
Transform(S,E,C,D) =  
  null C → [hS:S',E',C',D']  
           where S',E',C',D' = D  
  else →  
    identifier X → [location EXE:S, E, tC, D]  
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      [constructclosure((E, bvX), unitlist(bodyX)):S,  
       E, tC, D]  
    X = ap → closure(hS) →  
      [( ), derive(assoc(J, 2ndS)E'),  
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       (t(tS), E, tC, D)]  
      where E',J = environmentpart(hS)  
            and C' = controlpart(hS)  
            else → [(1stS)(2nd):t(tS), E, tC, D]  
  else → [S, E, randX:(ratorX:(ap:tC)), D]  
  where X = hC
```

```
sqrt = \n . n * n  
S = [[x x]]  
E = [[(x 2)]]  
C = [* ap]  
D = []
```

SECD - Square Root

```
Transform(S,E,C,D) =  
  null C → [hS:S',E',C',D']  
           where S',E',C',D' = D  
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    X = ap → closure(hS) →  
      [( ), derive(assoc(J, 2nd S) E'),  
       C,  
       (t(tS), E, tC, D)]  
      where E', J = environment part(hS)  
            and C' = control part(hS)  
            else → [(1st S)(2nd):t(tS), E, tC, D]  
    else → [S, E, rand X:(rator X:(ap:tC)), D]  
    where X = hC
```

```
sqrt = \n . n * n  
S = [[2 2]]  
E = [[(x 2)]]  
C = [* ap]  
D = []
```

SECD - Square Root

```
Transform(S,E,C,D) =  
  null C → [hS:S',E',C',D']  
           where S',E',C',D' = D  
  else →  
    identifier X → [location EXE:S, E, tC, D]  
    λexp X →  
      [construct closure((E, bv X), unit list(body X)):S,  
       E, tC, D]  
    X = ap → closure(hS) →  
      [( ), derive(assoc(J, 2nd S) E'),  
       C,  
       (t(tS), E, tC, D)]  
      where E', J = environment part(hS)  
            and C' = control part(hS)  
            else → [(1st S)(2nd):t(tS), E, tC, D]  
    else → [S, E, rand X:(rator X:(ap:tC)), D]  
    where X = hC
```

sqrt = \n . n * n

S = [4]

E = [[(x 2)]]

C = []

D = []