

08/12/23

Date ____/____/____

Page ____

LAB-4

8 puzzle A* Approach

Class Node:

```
def (self, state, parent=None, g=0, h=0):  
    self.state = state  
    self.parent = parent  
    self.g = g  
    self.h = h
```

```
def f(self):  
    return self.g + self.h
```

```
def astar (start, goal, heuristic):  
    openset = [Node (start, None, 0, heuristic (start))]  
    visited_set = set()
```

```
    while openset:  
        current_node = heapq.heappop (openset)
```

```
        if current_node.state == goal:  
            return reconstruct_path (current_node)
```

```
        visited_set.add (current_node.state)  
        successors = expand_node (current_node)
```

```
        for successor in successors:  
            if successor.state in visited_set:  
                continue
```

```
            if successor.state not in (node.state  
                                        for node in open_set):  
                heapq.heappush (open_set, successor)
```

else:

existing_node = next(
 node for node in open_set if

node.state == successor.

if successor.g < existing_node.g:

existing_node.parent = successor.parent

existing_node.g = successor.g

return None.

def expand_node(node):

moves = [(-1, 0), (1, 0), (0, -1), (0, 1)]

for move in moves:

new_state = (node.state[0] + move[0],
 node.state[1] + move[1])

if 0 ≤ new_state[0] < len(grid) and
 0 ≤ new_state[1] < len(grid)

if grid[new_state[0]][new_state[1]]
 != "obstacle":

new_g = node.g + 1

new_h = heuristic_function(new_state)

successor = Node(new_state, node,
 new_g, new_h)

successors.append(successor)

return successor

```
def reconstruct_path(node):
```

```
    path = []
```

```
    while node:
```

```
        path.append(node.state)
```

```
        node = node.parent
```

```
    return path[::-1]
```

Pr
8/12



Harshitha R-1BM21CS075

Enter the start state matrix

1 2 3

4 5 6

_ 7 8

Enter the goal state matrix

1 2 3

4 5 6

7 8 _

|
|
|
\'/

1 2 3

4 5 6

_ 7 8

|
|
|
\'/

1 2 3

4 5 6

7 _ 8

|
|
|
\'/

1 2 3

4 5 6

7 8 _