EE-302 Control System

(Routh Table and pole location results)

Group 8: Create a GUI based system that plots the Routh table for the system shown below. Comment on the number of poles in the right-half plane, the left-half plane, and on the imaginary axis. The parameter values k0, k1, k2, k3, k4, k5, k6 will be provided from user-end.

$$U(s) \longrightarrow \frac{10}{k_6 s^6 + k_5 s^5 + k_4 s^4 + k_3 s^3 + k_2 s^2 + k_1 s + k_0} \longrightarrow Y(s)$$

Group Members:-

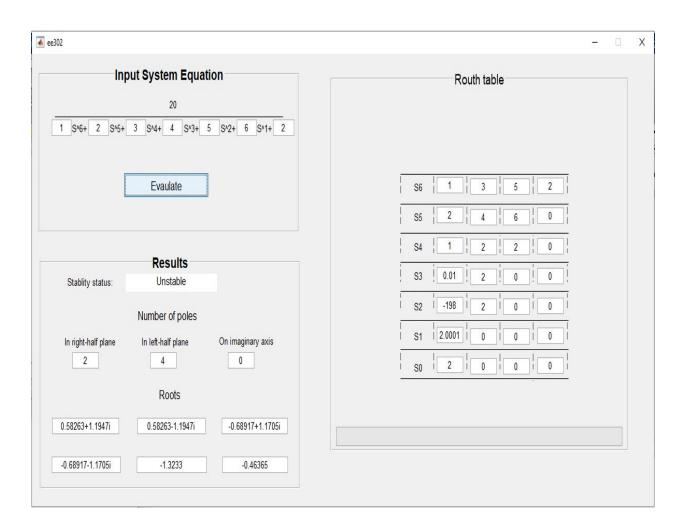
1. 170002005: Aman Gupta

2. 170002026: Deekshith Reddy Kotla

3. 170002017: Himanshu Verma

Input:- $s^6 + 2*s^5 + 3*s^4 + 4*s^3 + 5*s^2 + 6*s+2$

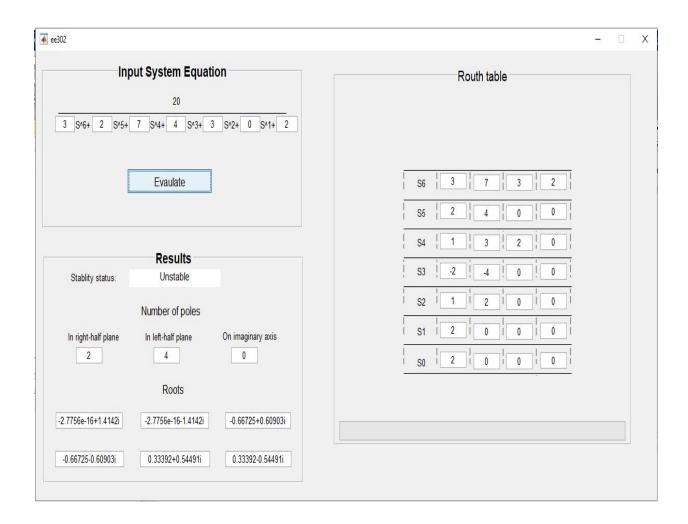
Output:-



This system is unstable.

Input:- $3*s^6 + 2*s^5 + 7*s^4 + 4*s^3 + 3*s^2 + 2$

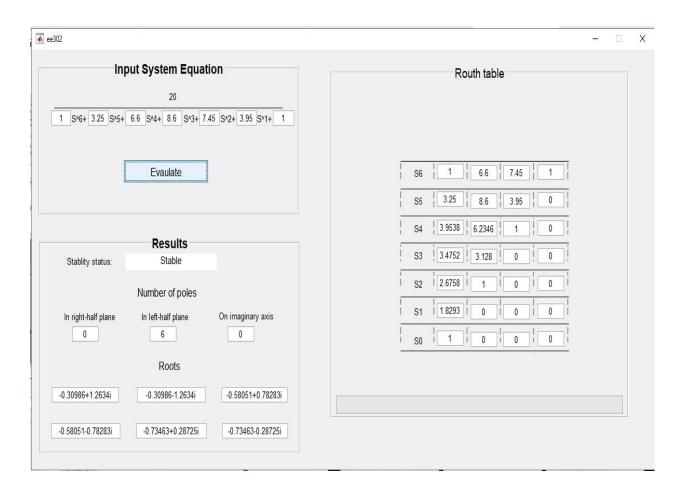
Output:-



This system is unstable.

Input:- $s^6 + (3.25)*s^5 + (6.6)*s^4 + (8.6)*s^3 + (7.45)*s^2 + (3.95)*s + 1$

Output:-



This system is stable.

Input:- s^4 + 3*s^3 + 3*s^2+ 2*s + 1

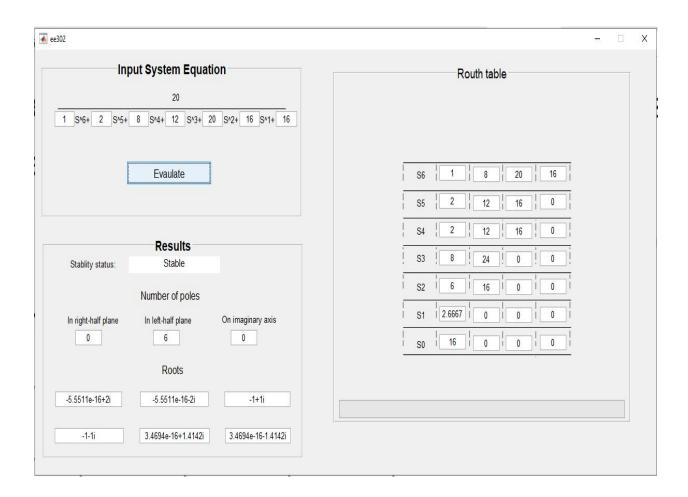
Output:-

e302		- 0
	20 1 SN4+ 3 SN3+ 3 SN2+ 2 SN1+	Routh table
0 5**0+ 0 5**5+	Evaulate	S6
	Results	S5
Stablity status:	Stable Number of poles	S2 2.3333 1 0
In right-half plane	In left-half plane On imaginary axis 4 0 Roots	S0 1 1 0 1 0 1
-1.7549	-1 -0.12256+0.74486	
-0.12256-0.74486i		

This system is stable.

Input:- $s^6 + 2*s^5 + 8*s^4 + 12*s^3 + 20*s^2 + 16*s + 16$

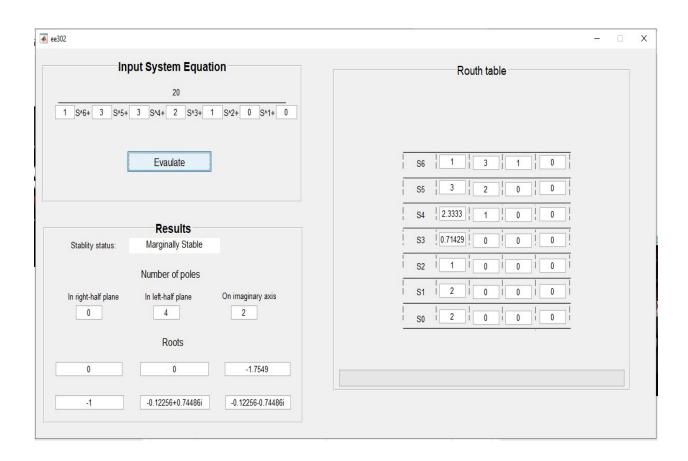
Output:-



This system is stable.

Input:- $s^6 + 3*s^5 + 3*s^4 + 2*s^3 + s^2$

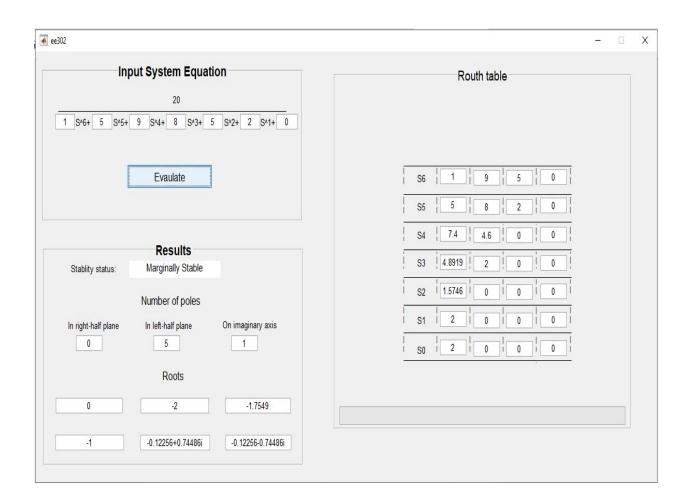
Output:-



This system is marginally stable.

Input:- $s^6 + 5*s^5 + 9*s^4 + 8*s^3 + 5*s^2 + 2*s$

Output:-



This system is marginally stable.