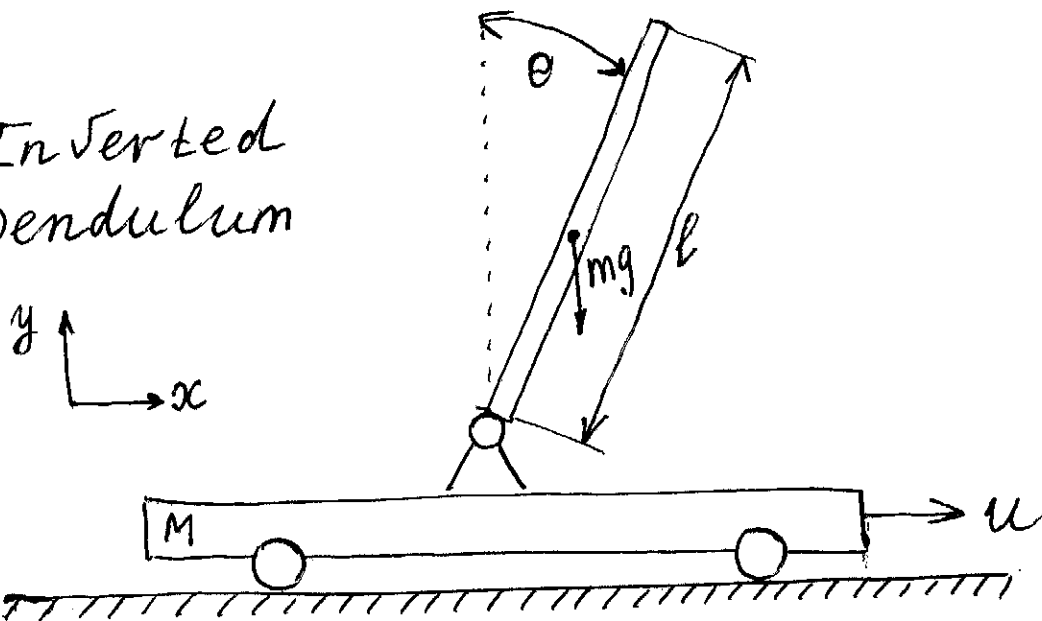


# Control Problem

Inverted  
pendulum

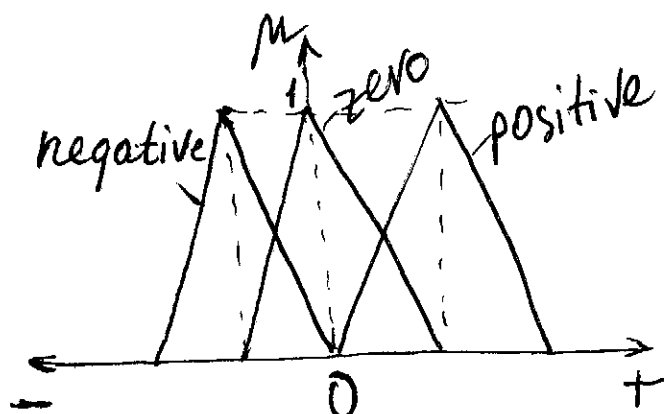


$$\ddot{\theta} = \frac{3g(M+m)}{4M+m} \theta + \frac{3u}{(4M+m)l}$$

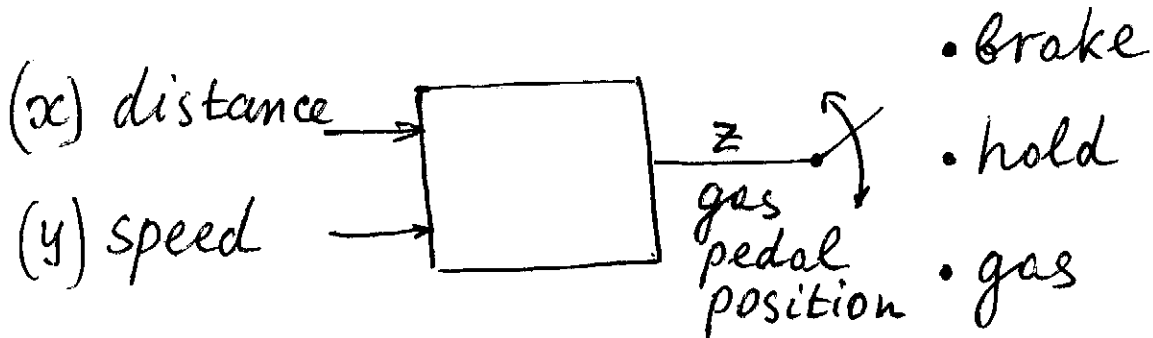
## Fuzzy IF - THEN RULES

IF  $\theta = \begin{cases} \text{negative} \\ \text{zero} \\ \text{positive} \end{cases}$  AND  $\dot{\theta} = \begin{cases} \text{negative} \\ \text{zero} \\ \text{positive} \end{cases}$  THEN  $u = \begin{cases} \text{negative} \\ \text{zero} \\ \text{positive} \end{cases}$

$\theta \backslash \dot{\theta}$	N	Z	P
N	N	N	P
Z	N	Z	P
P	Z	P	P

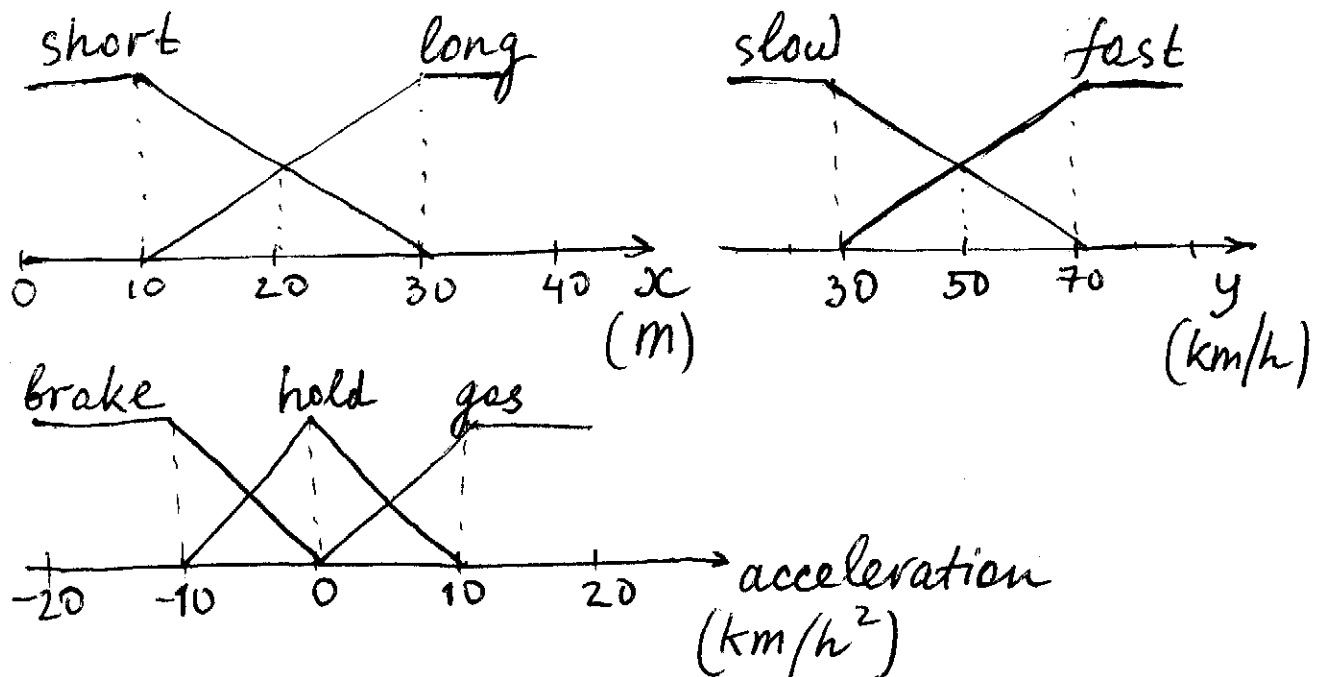


# Automobile Driving

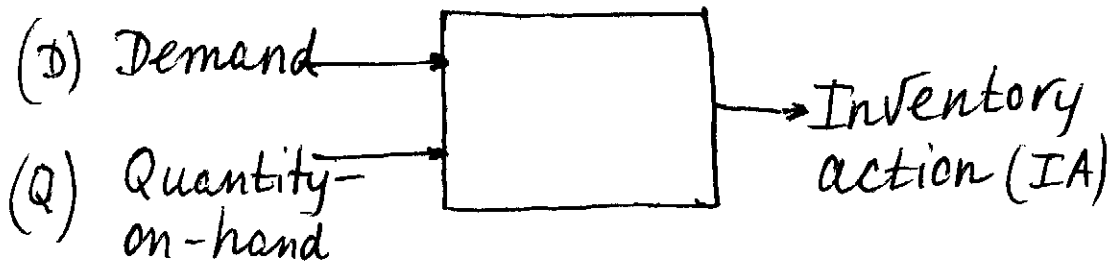


IF		THEN
distance (x)	speed (y)	pedal position (z)
short	slow	maintain speed (hold)
short	fast	reduce speed (brake)
long	slow	increase speed (gas)
long	fast	maintain speed (hold)

## MEMBERSHIP FUNCTIONS



# INVENTORY CONTROL



Demand = {
 

- F = falling
- D = decreased
- S = steady
- I = increased
- R = rising

 }
 Quantity-on-hand (Q) = {
 

- minimal (M)
- low (L)
- Adequate (A)
- high (H)
- Excessive (E)

Inventory action = {
 

- negative large (NL)
- negative moderate (NM)
- negative small (NS)
- Zero (O)
- positive small (PS)
- positive moderate (PL)
- positive large

D \ Q	M	L	A	H	E
F	O	O	NS	NM	NL
D	PS	O	NS	NM	NM
S	PM	PS	O	NS	NM
I	PM	PM	PS	O	O
R	PL	PL	PM	PS	O

# CONCLUSIONS

1. Corsons low:

"It's better to be rich and healthy than poor and sick"

2. Difference between literature and science

