

**Start Instructions (for internal network use):**

Steps	What the step does?
1. In the “RACS Project” folder execute with double-click the “Start_Execute_Script.bat” file, which will open a window Terminal.	This will connect your computer to the glove microcontroller (raspberry Pi Zero 2W)
2. When you are connected to the glove microcontroller it will ask you to type the password (this is: 12345678)	This ensures secure connection with a single user
3. In the same Terminal window, type “python 1.py”	This will open the socket commands pipeline with the glove IMU and waits for the client computer to subscribe to the data stream of the IMU sensor.
4.	
5. On your computer, in the “RACS Project” folder, execute “Start_Robot_Control.bat” file	This will automatically run the python script “activate_glove.py”
6. Control should be operational on the glove now. Enjoy!	