

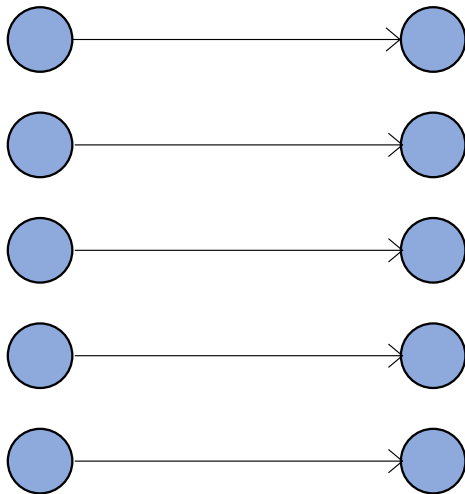
# Application of Generative Models: X Learning

Hao Dong

Peking University

# From **Data** Point of View

Data in both input  $x$  and output  $y$   
with known mappings  
(Learn the mapping  $f$ )

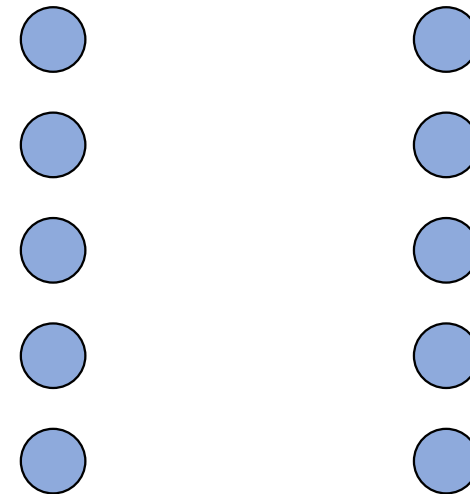


$$y = f(x)$$

**Supervised Learning**

- Image classification
- Object detection
- ...

Data in both input  $x$  and output  $y$   
**without** known mappings  
(Learn the mapping  $f$ )



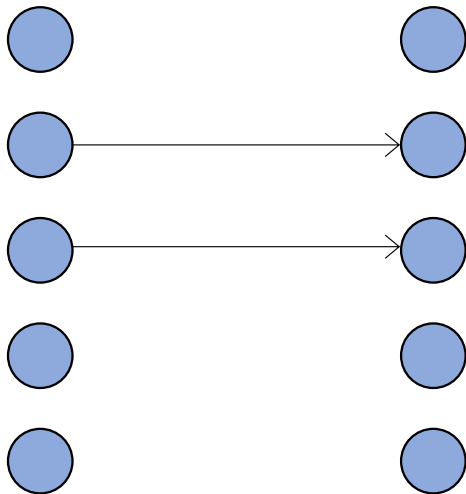
$$y = f(x)$$

**Unsupervised Learning**

- Autoencoder  
(when output is features)
- GANs
- ...

## From Data Point of View

Data in both input  $x$  and output  $y$   
with known **partial** mappings  
(Learn the mapping  $f$ )

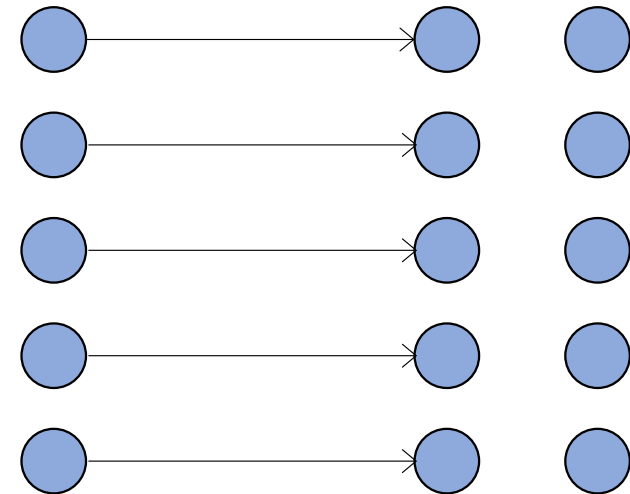


$$y = f(x)$$

**Semi-supervised Learning**

- ...

Data in both input  $x$  and output  $y$   
with known mappings for  $y$   
(Learn the mapping  $f$  for **another** output  $y'$ )



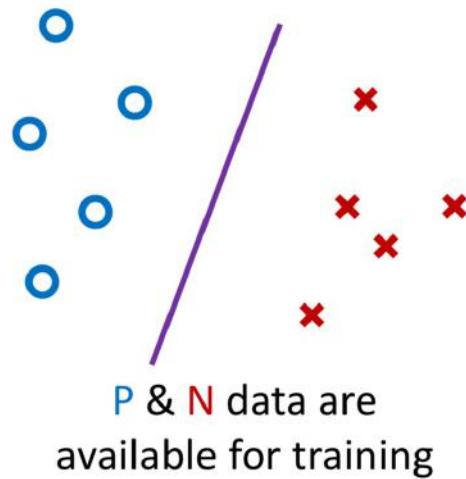
$$y' = f(x)$$

**Weakly-supervised Learning**

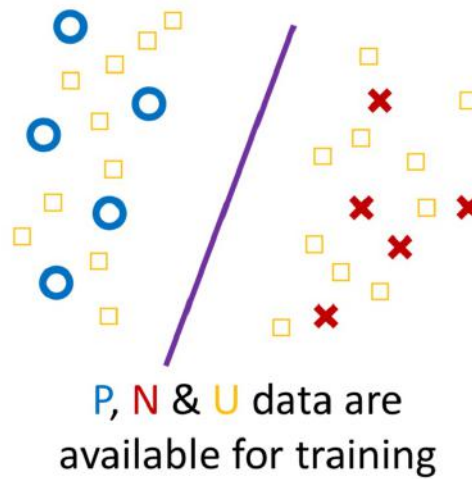
- Learn segmentation via classification
- ...

## From Data Point of View

**PN learning**  
(i.e., supervised learning)



**PNU learning**  
(i.e., semi-supervised learning)



**PU learning**  
weakly-supervised learning



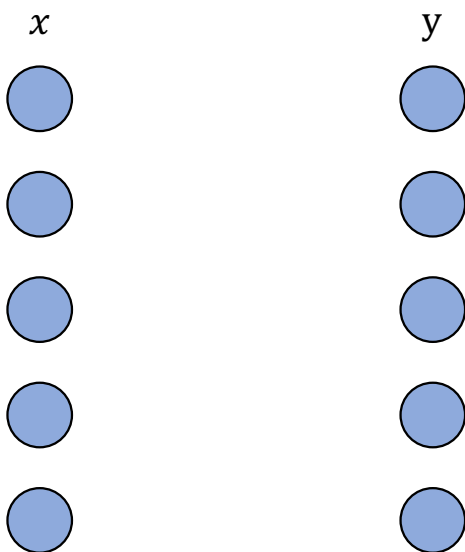
○ : positive data

✕ : negative data

□ : unlabeled data

# From Mapping Point of View

Data in both input and output  
(Learn the mapping  $f, f'$ )

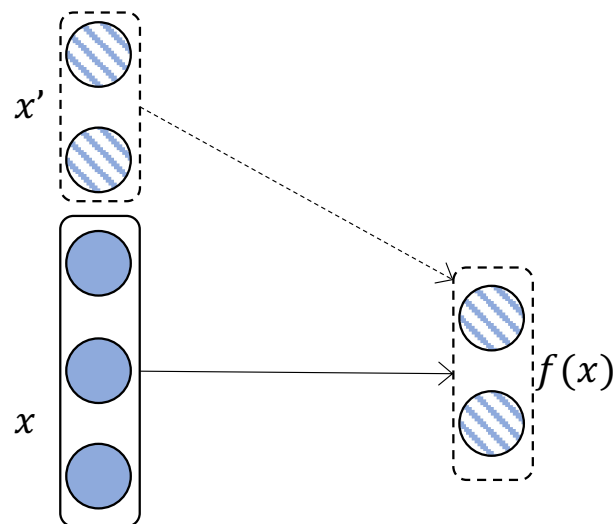


$$y = f(x), x = f'(y)$$

**(Unsupervised) Dual Learning**

- VAE
- CycleGAN
- ...

Data in input  $x, x'$  only  
with known mapping  $f'$   
(Learn the mapping  $f$ )

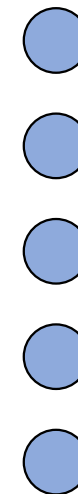


$$x' = f(x)$$

**Self-supervised Learning**

- Word2Vec
- Denoising Autoencoder
- ...

Data in input only  
with known **inverse** mapping  $f'$   
(Learn the mapping  $f$  and output  $y$ )



$$y = f(x), x = f'(y)$$

**Self-augmented Learning**

- ?

# Application of Generative Models: Learning Methods

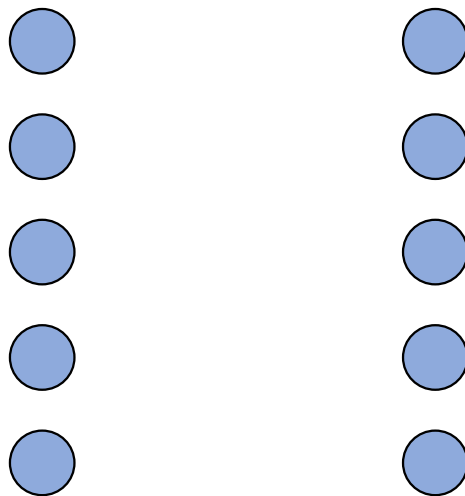


- Unsupervised Learning
- Semi-supervised Learning
- Weakly-supervised Learning
- Dual Learning
- Self-supervised Learning
- Self-augmented Learning

- Unsupervised Learning
- Semi-supervised Learning
- Weakly-supervised Learning
- Dual Learning
- Self-supervised Learning
- Self-augmented Learning

# Unsupervised Learning

Data in both input  $x$  and output  $y$   
(Learn the mapping  $f$ )



$$y = f(x)$$

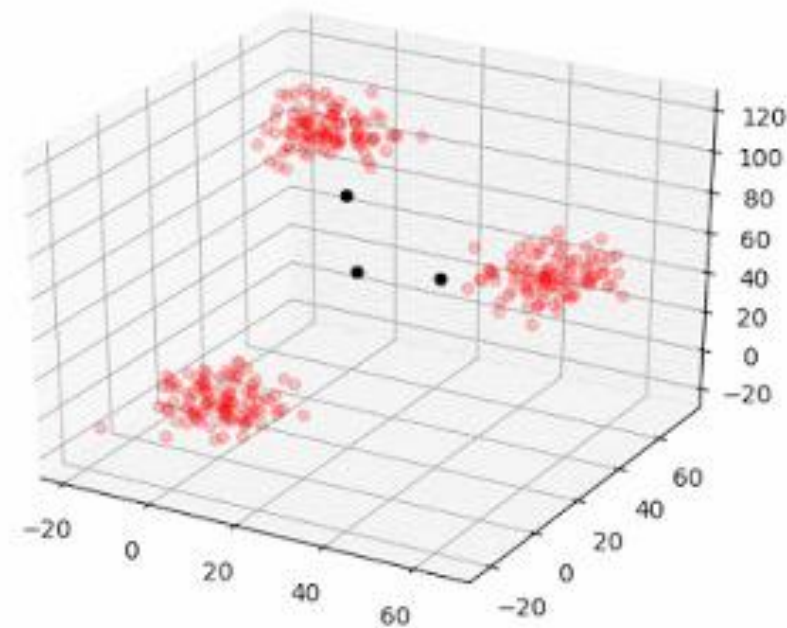
Unsupervised Learning

- In practice, it is difficult to obtain a large amount of labelled data, but it is easy to get a large amount of unlabeled data.
- Learn a good feature extractor using unlabelled data and then learn the classifier using labelled data can improve the performance.



# Unsupervised Learning

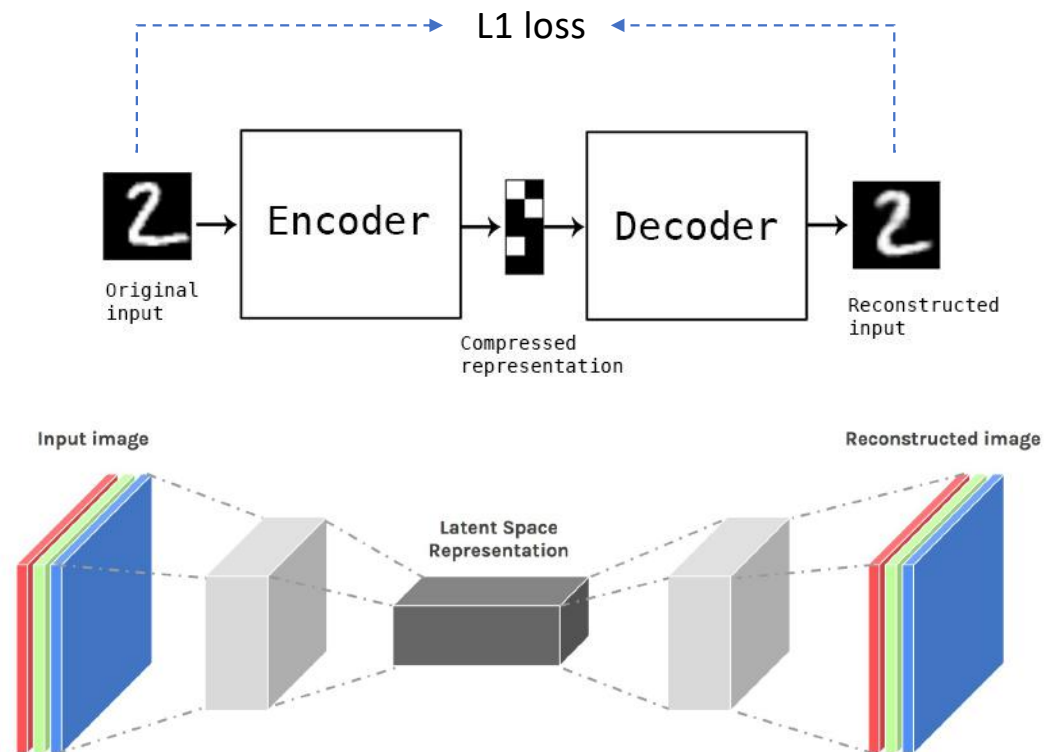
- Unsupervised learning is about problems where we don't have labelled answers, such as clustering, dimensionality reduction, and anomaly detection.
- Clustering: EM
- Dimension Reduction: PCA
- ...



# Unsupervised Learning

- **Autoencoder**

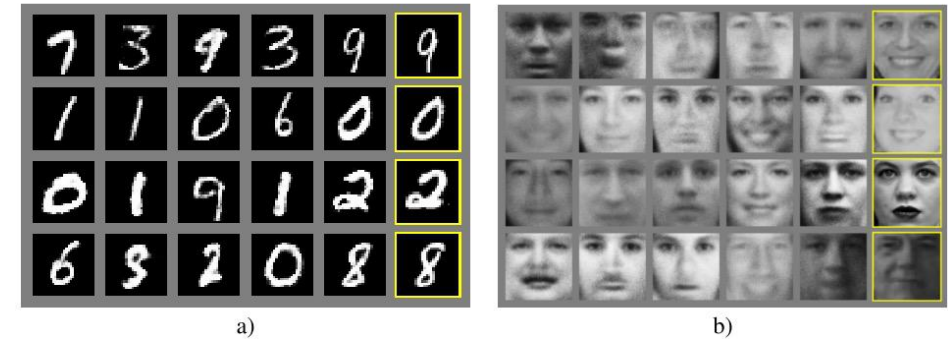
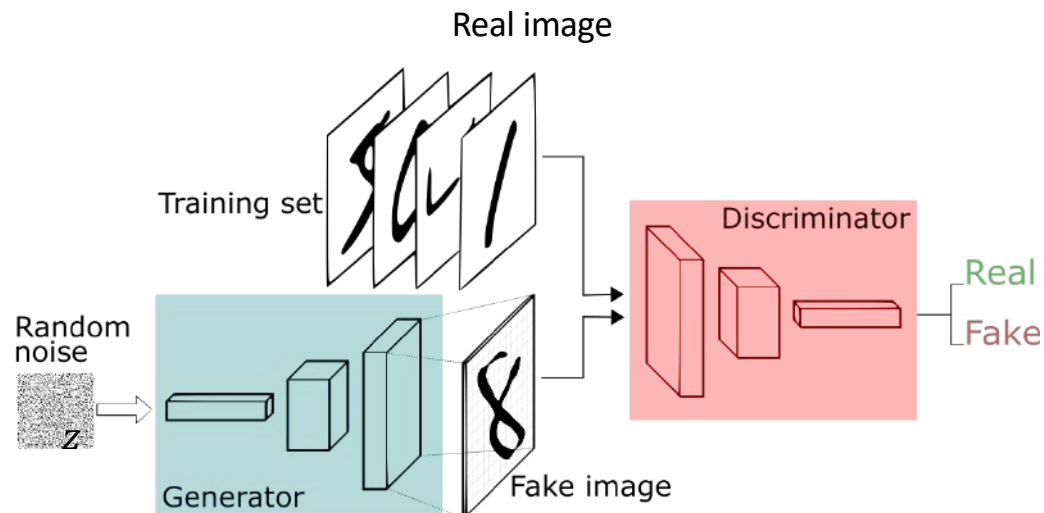
(when the output is extracted features)



Autoencoder: Encode the input image  $x$  into a hidden state, then decode the latent space representation into a image  $\bar{x}$ . Then minimize the reconstruction loss between  $x$  and  $\bar{x}$ .

# Unsupervised Learning

- GANs



Update the discriminator – ascending gradient:

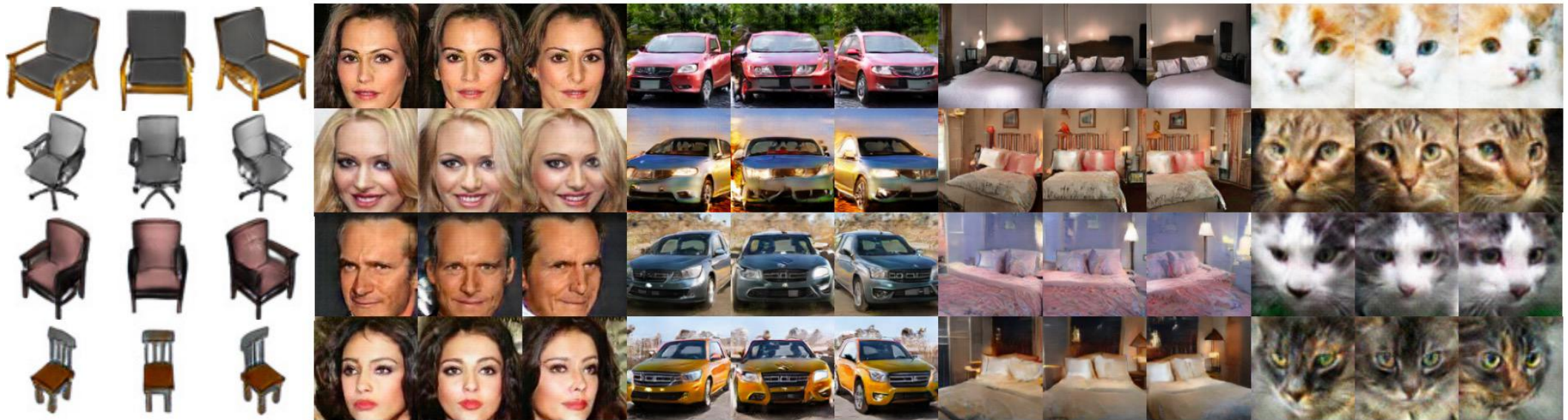
$$\nabla_{\theta_d} \frac{1}{m} \sum_{i=1}^m \left[ \log D(x^{(i)}) + \log (1 - D(G(z^{(i)}))) \right].$$

Update the generator – descending gradient:

$$\nabla_{\theta_g} \frac{1}{m} \sum_{i=1}^m \log (1 - D(G(z^{(i)}))).$$

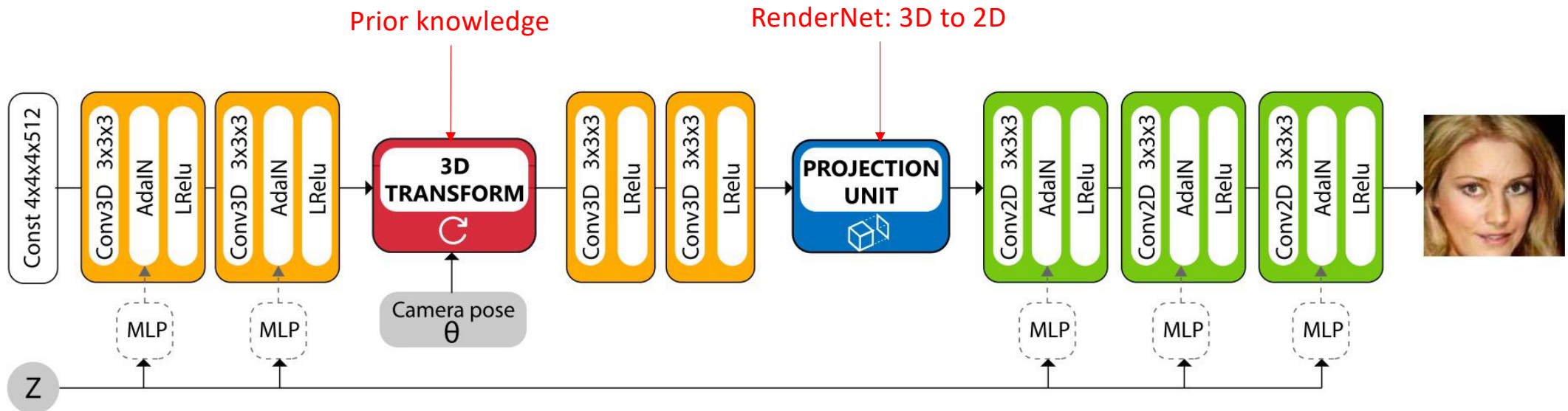
# Unsupervised Learning

- HoloGAN: learn the rotation concept



# Unsupervised Learning

- HoloGAN: How it works**

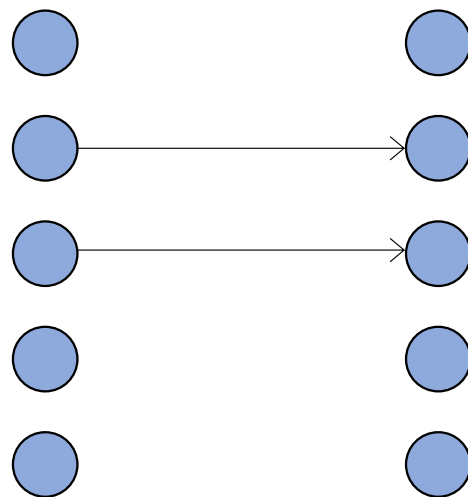




- Unsupervised Learning
- **Semi-supervised Learning**
- Weakly-supervised Learning
- Dual Learning
- Self-supervised Learning
- Self-augmented Learning

# Semi-supervised Learning

Data in both input  $x$  and output  $y$   
with known **partial** mappings  
(Learn the mapping  $f$ )



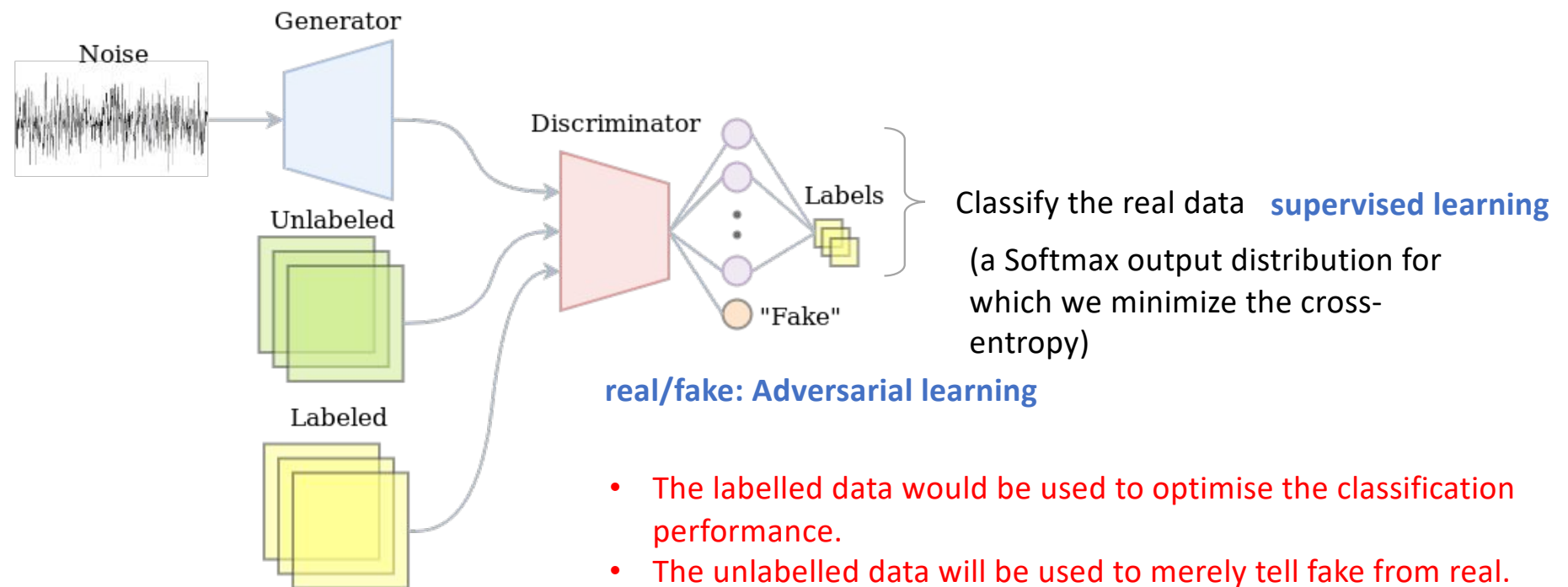
$$y = f(x)$$

Semi-supervised Learning

- **Motivation:**
  - Unlabelled data is easy to be obtained
  - Labelled data can be hard to get
- **Goal:**
  - Semi-supervised learning mixes labelled and labelled data to produce better models.
- **vs. Transductive Learning:**
  - Semi-supervised learning is eventually applied to the testing data
  - Transductive learning is only related to the unlabelled data

# Semi-supervised Learning

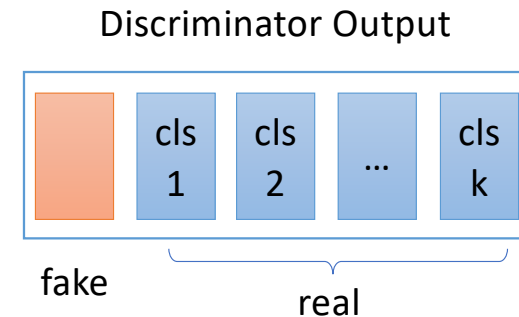
- **Semi-supervised GAN**





# Semi-supervised Learning

- **Semi-supervised GAN**
- Discriminator loss



the probability of it being real: 
$$p(x) = \frac{Z(x)}{Z(x) + \exp(l_{fake})} = \frac{Z(x)}{1 + Z(x)}$$

where  $Z(x)$  is the sum of the unnormalised probabilities in the softmax operation.  
 $\log(Z(x)) = \text{logsumexp}(l_1, \dots, l_k)$

Gradient descent:

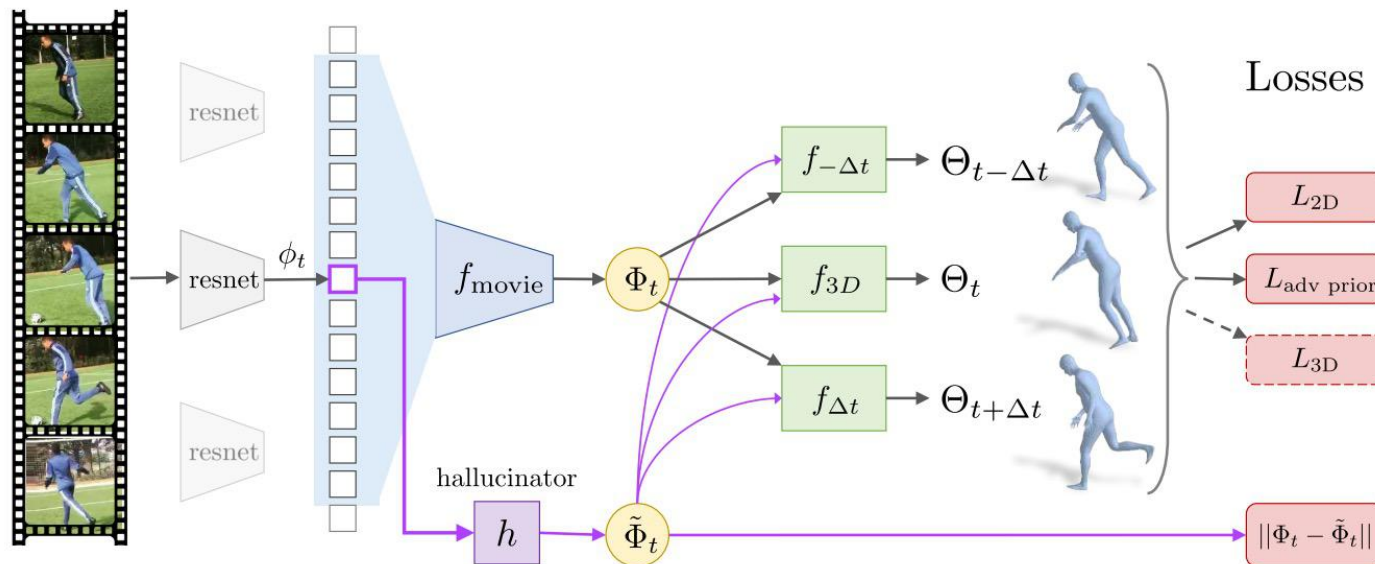
$$\begin{aligned}
 & -\log(D(x)) - \log(1 - D(G(\mathbf{z}))) \\
 & = -\log\left(\frac{Z(x)}{1 + Z(x)}\right) - \log\left(1 - \frac{Z(G(\mathbf{z}))}{1 + Z(G(\mathbf{z}))}\right)
 \end{aligned}$$

# Semi-supervised Learning

## • Example: 2D Video to 3D shape

The model can learn from videos with only 2D pose annotations in a semi-supervised manner.

$L_{2D}$ ,  $L_{3D}$  : supervision from ground-truth



train a temporal encoder  $f_{\text{movie}}$  that learns a representation of 3D human dynamics  $\Phi_t$  over the **temporal window centered at frame t**

$L_{\text{adv prior}}$ : each prior discriminator judge a corresponding joint rotation of the body model

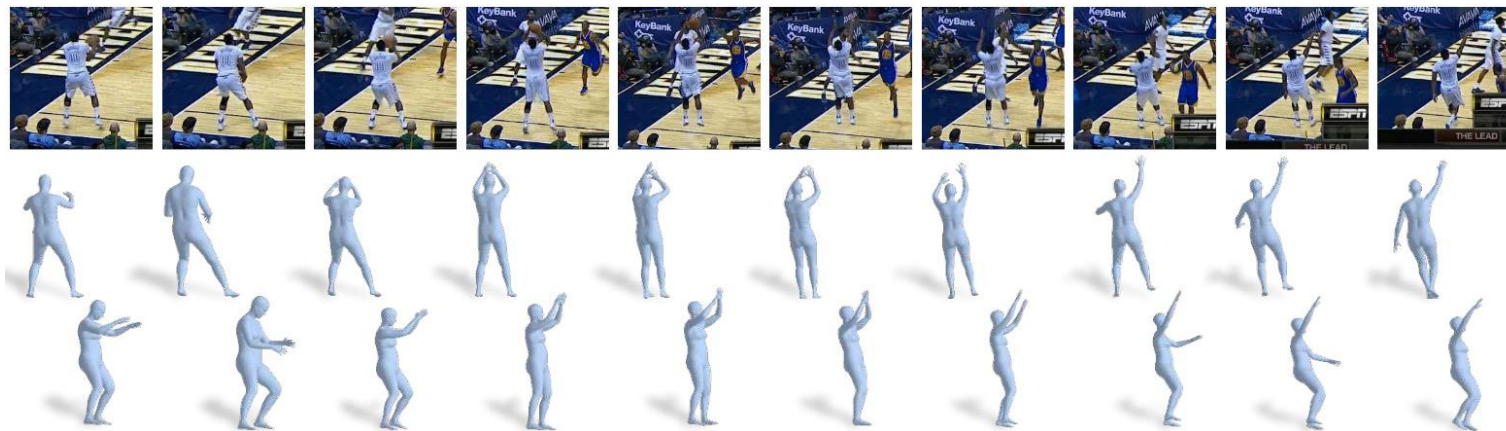
$$\sum_k (D_k(\Theta) - 1)^2$$

make sure that the **hallucinator** can recover the current 3D mesh as well as its 3D past and future motion.

# Semi-supervised Learning

- Example: 2D Video to 3D shape**

From a single image, the model can recover the current 3D mesh as well as its 3D past and future motion.



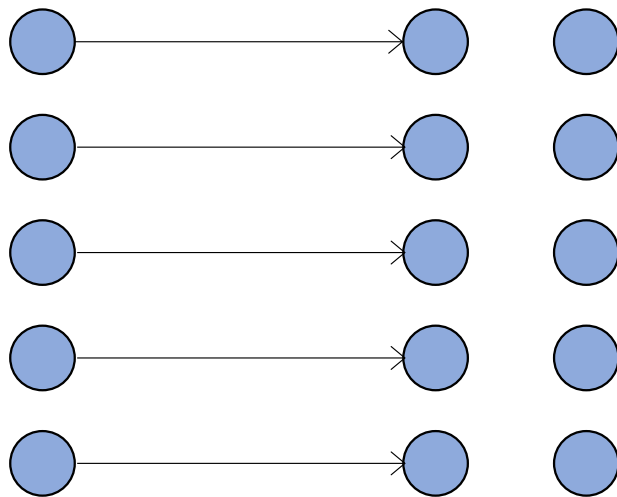
$$L_t = L_{2D} + L_{3D} + L_{\text{adv prior}} + L_{\beta \text{ prior}}$$

$$L_{\text{const shape}} = \sum_{t=1}^{T-1} \|\beta_t - \beta_{t+1}\|. \quad L_{\text{temporal}} = \sum_t L_t + \sum_{\Delta t} L_{t+\Delta t} + L_{\text{const shape}}.$$

- Unsupervised Learning
- Semi-supervised Learning
- **Weakly-supervised Learning**
- Dual Learning
- Self-supervised Learning
- Self-augmented Learning

# Weakly-supervised Learning

Data in both input  $x$  and output  $y$   
with known mapping for  $y$   
(Learn the mapping  $f$  for another output  $y'$ )



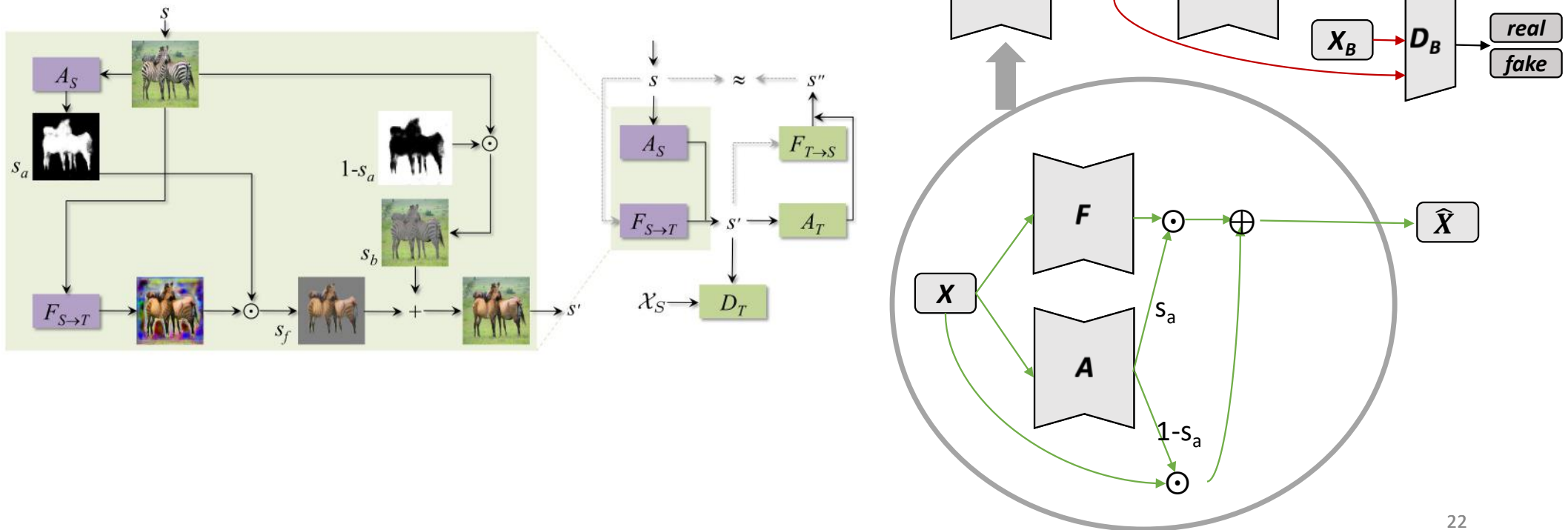
$$y' = f(x)$$

Weakly-supervised Learning

- Weakly supervised learning is a machine learning framework where the model is trained using examples that are only partially annotated or labeled.

# Weakly-supervised Learning

- **Attention CycleGAN**
- Learn the segmentation via synthesis





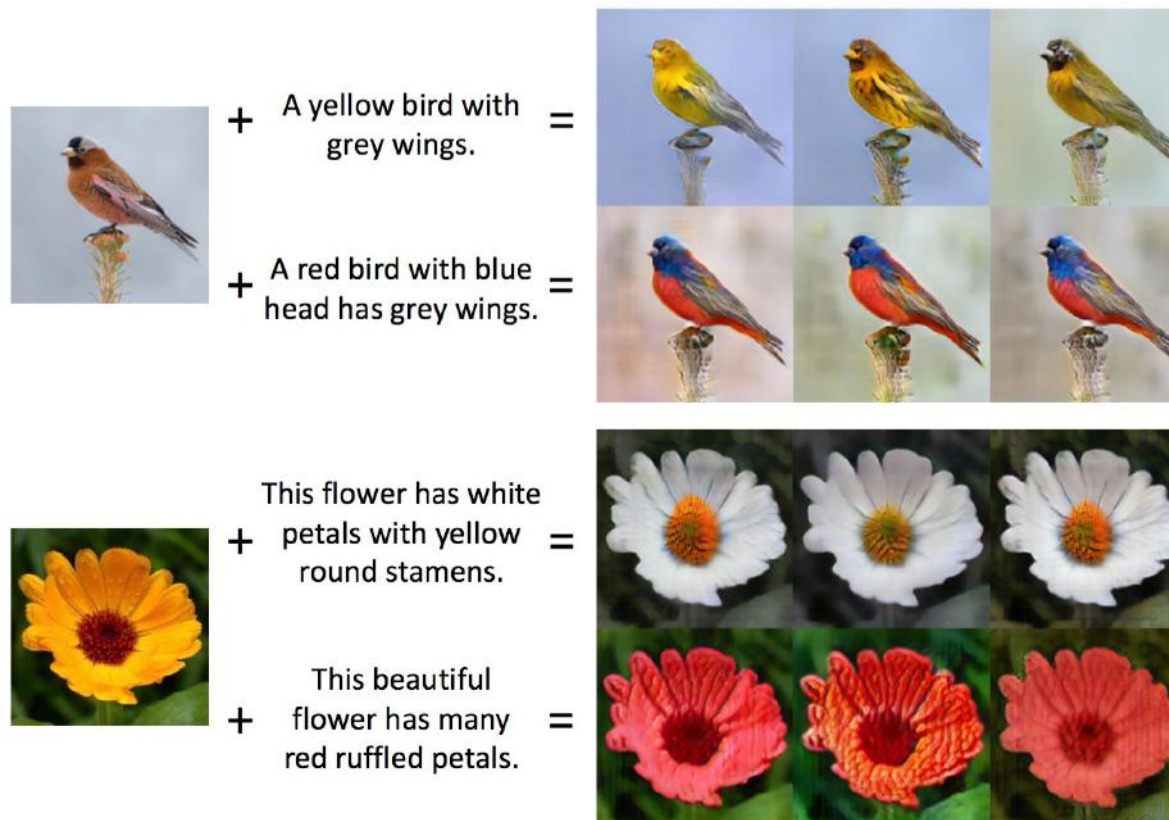
# Weakly-supervised Learning

- **Attention CycleGAN**
  - Learn the segmentation without segmentation masks



## Weakly-supervised Learning

- Semantic Image Synthesis: Language Image Manipulation**

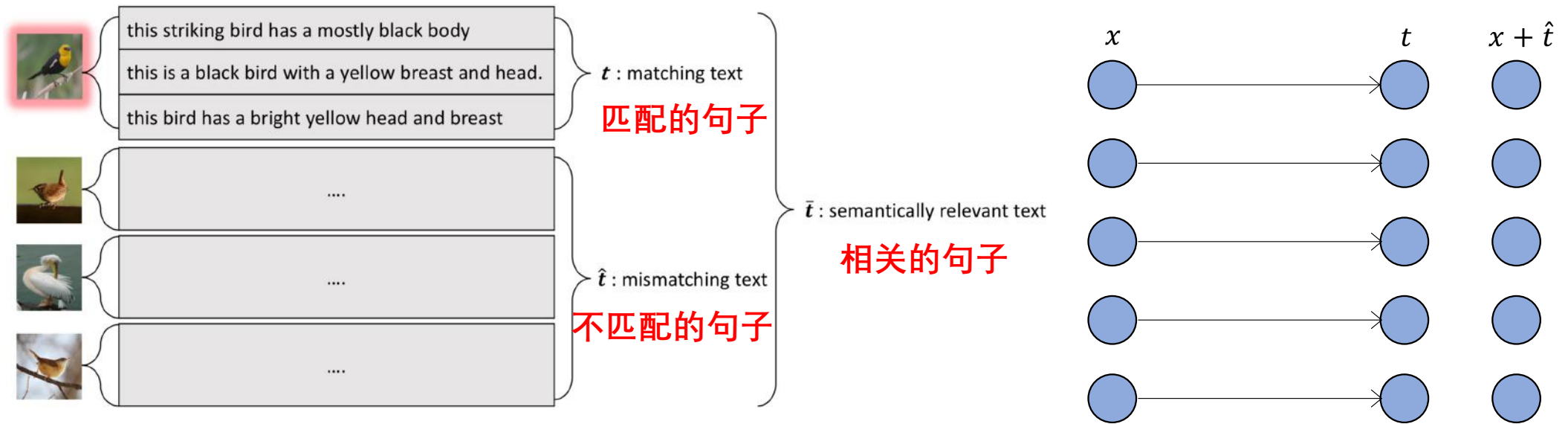


Semantic Image Synthesis via Adversarial Learning. *H. Dong, S. Yu et al. ICCV 2017.*



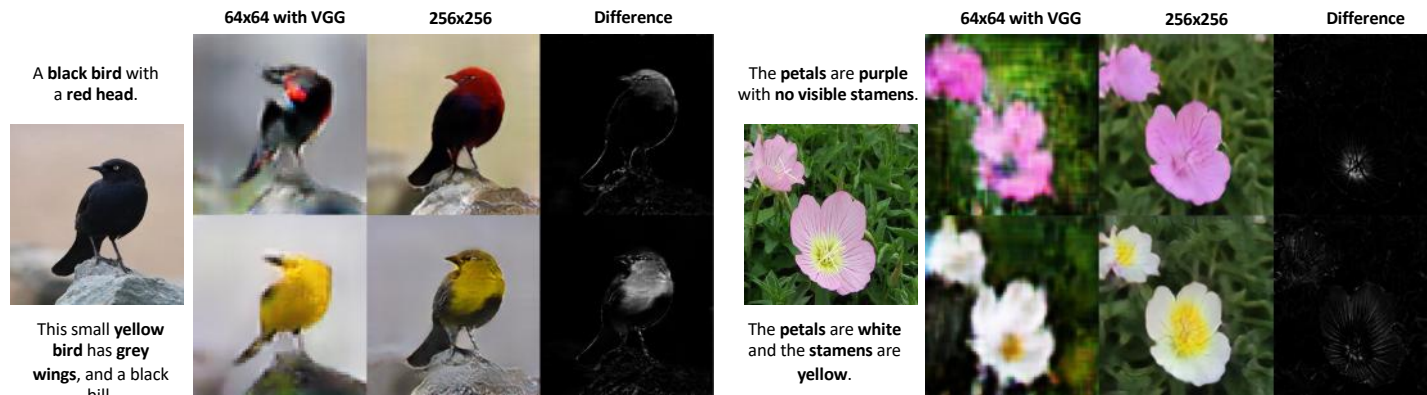
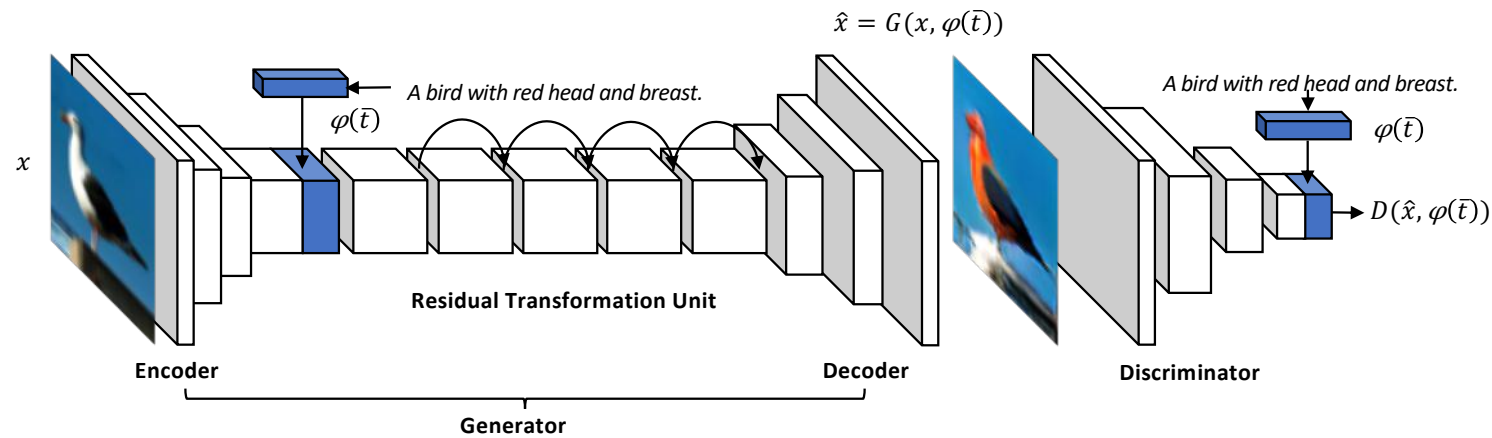
# Weakly-supervised Learning

- Semantic Image Synthesis: Language Image Manipulation**



# Weakly-supervised Learning

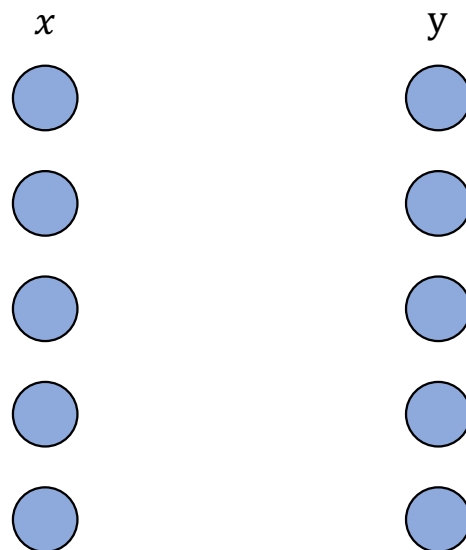
- Semantic Image Synthesis: Learn the segmentation via synthesis**



- Unsupervised Learning
- Semi-supervised Learning
- Weakly-supervised Learning
- **Dual Learning**
- Self-supervised Learning
- Self-augmented Learning

# Dual Learning

Data in both input and output  
(Learn the mapping  $f, f'$ )



$$y = f(x), x = f'(y)$$

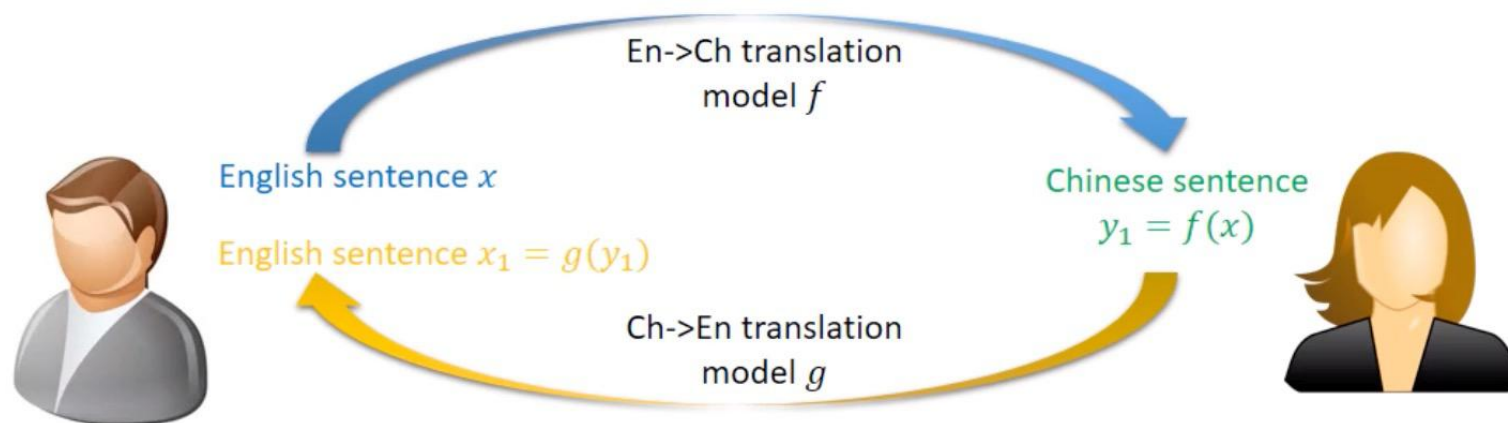
(Unsupervised) Dual Learning

- Motivation
  - Human label is expensive
  - No feedback if using unlabeled data

Application	Primal Task	Dual (Inverse) Task
Machine translation	Translate language from A to B	Translate language from B to A
Speed processing	Speech to text (STT)	Text to speech (TTS)
Image understanding	Image captioning	Image generation
Conversation engine	Question	Answer
Search engine	Search	Query

# Dual Learning

- Language Translation



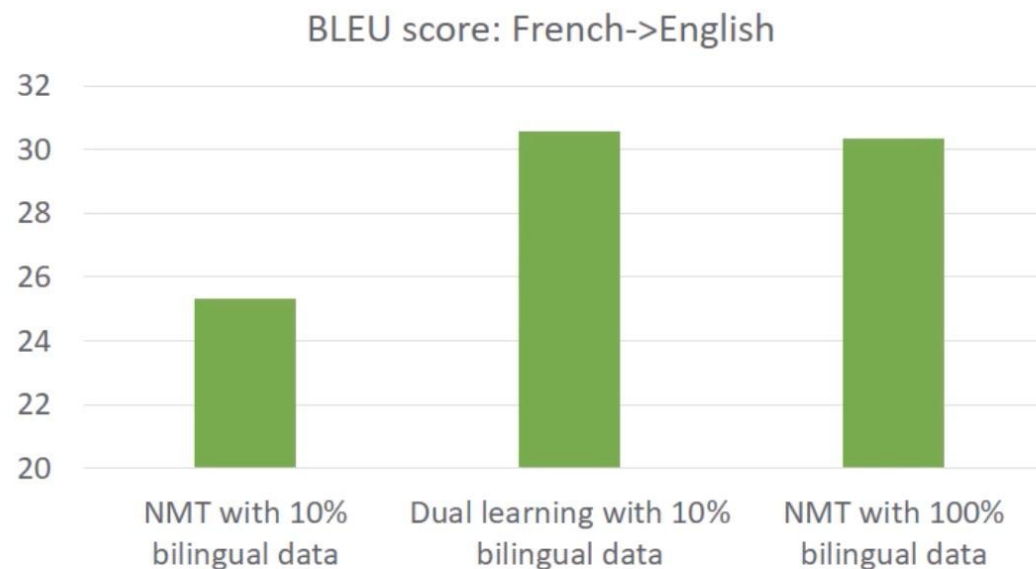
Feedback signals during the loop:

- $s(x, x_1)$ : BLEU score of  $x_1$  given  $x$
- $L(y)$  and  $L(x_1)$ : Likelihood and language model of  $y_1$  and  $x_1$

Reinforcement learning is used to improve the translation models from these feedback signals

# Dual Learning

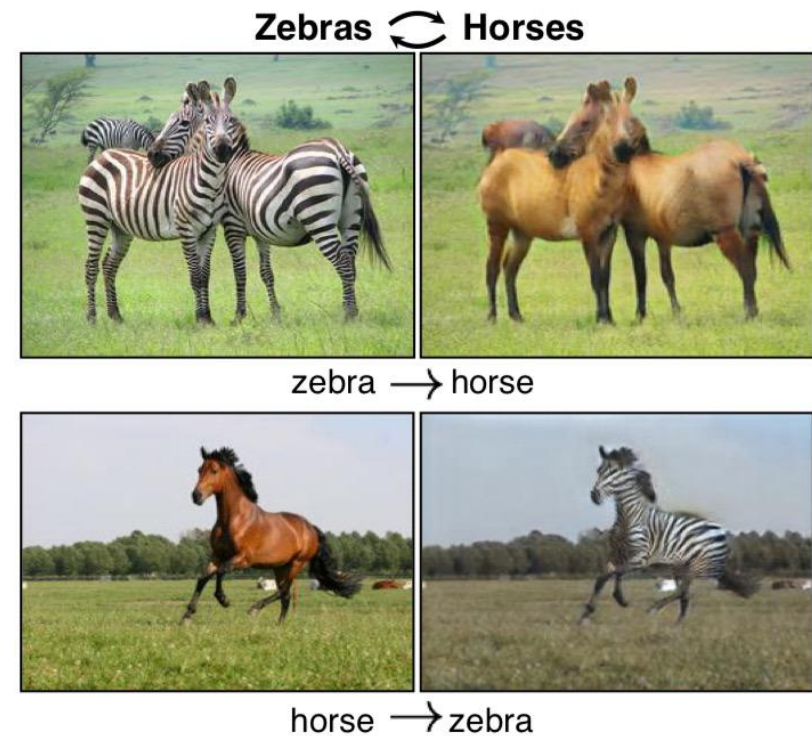
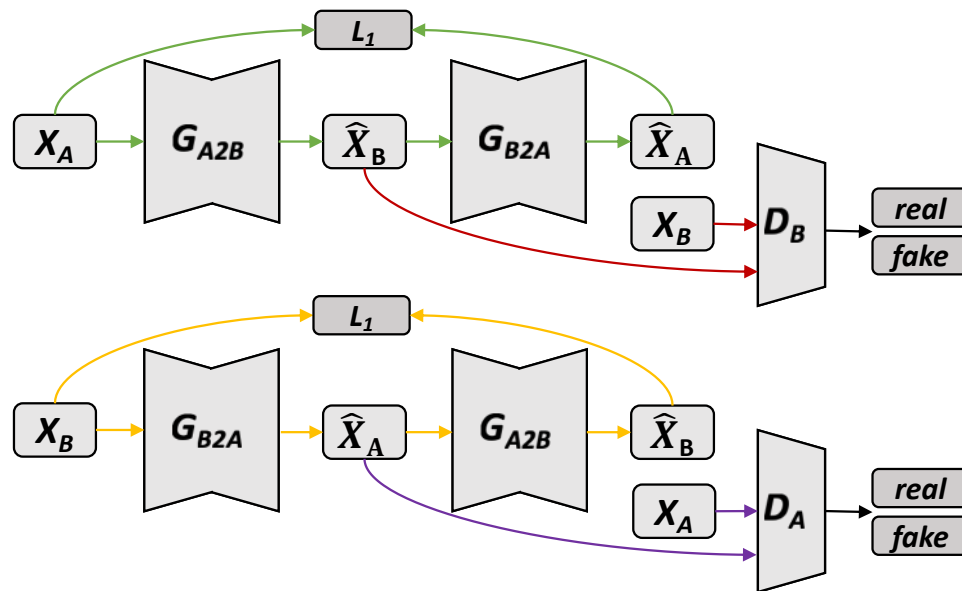
- Language Translation



Starting from initial models obtained from only 10% bilingual data, dual learning can achieve similar accuracy as the NMT model learned from 100% bilingual data!

# Dual Learning

- Unpaired Image-to-Image Translation



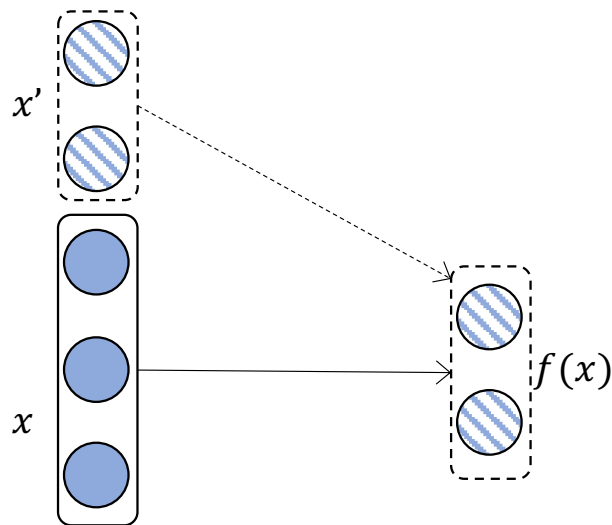


- Unsupervised Learning
- Semi-supervised Learning
- Weakly-supervised Learning
- Dual Learning
- **Self-supervised Learning**
- Self-augmented Learning



# Self-supervised Learning

Data in input  $x, x'$  only  
with known mapping  $f'$   
(Learn the mapping  $f$ )



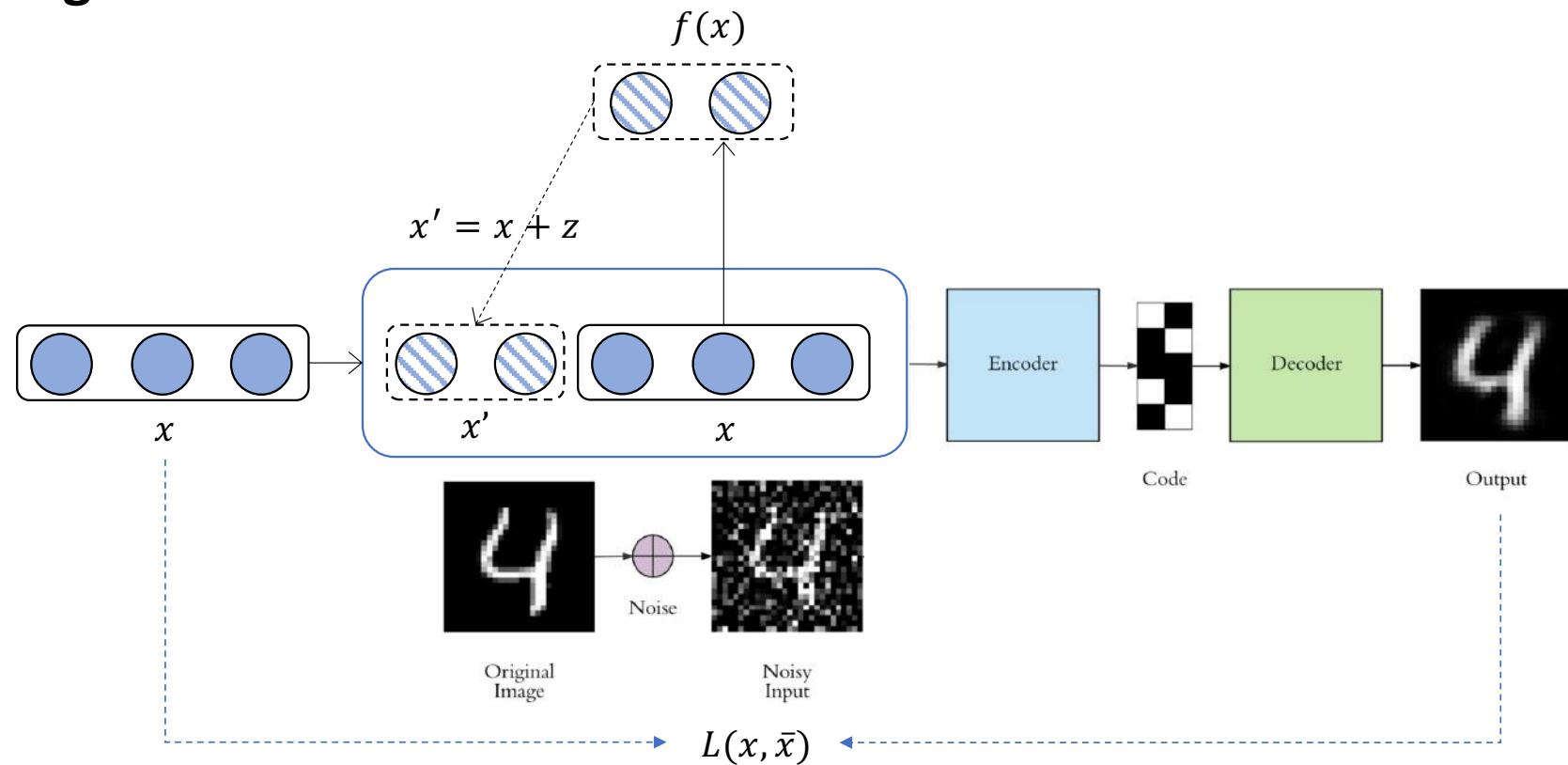
$$x' = f(x)$$

**Self-supervised Learning**

- Self-supervised learning is autonomous supervised learning, it learns to predict part of its input from other parts of its input.
- Examples: Word2Vec, Denoising Autoencoder
- Self-supervised vs. unsupervised learning: Self-supervised learning is like unsupervised Learning because the system learns without using explicitly-provided labels. It is different from unsupervised learning because we are not learning the inherent structure of data. Self-supervised learning, unlike unsupervised learning, is not centered around clustering and grouping, dimensionality reduction, recommendation engines, density estimation, or anomaly detection.

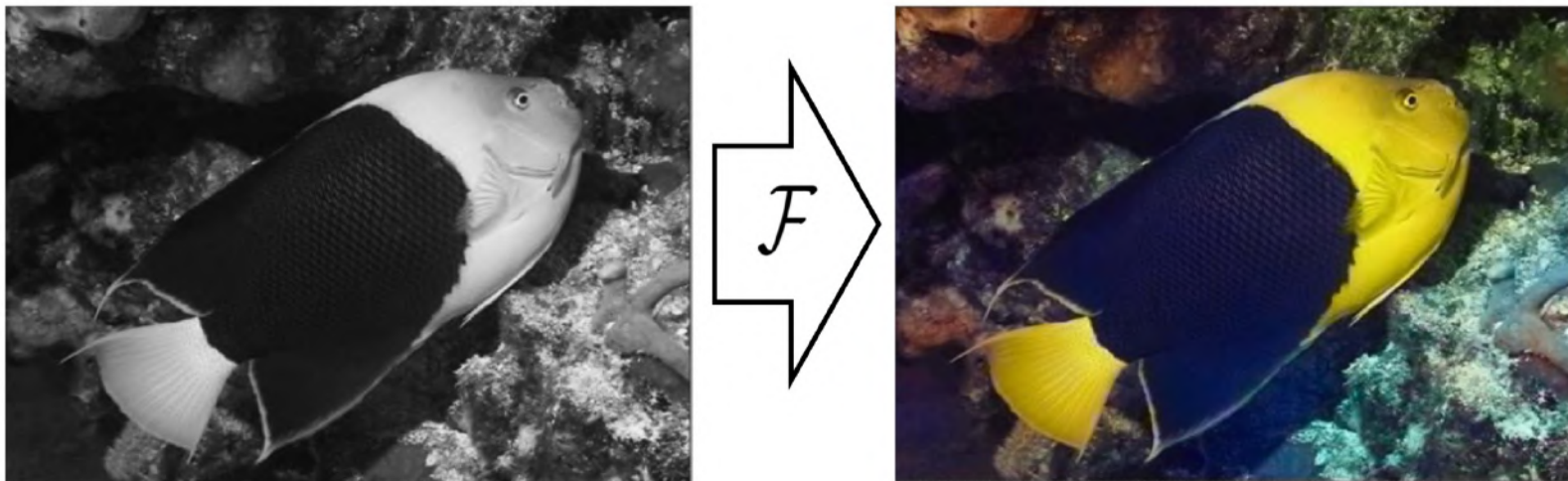
# Self-supervised Learning

- Denoising Autoencoder



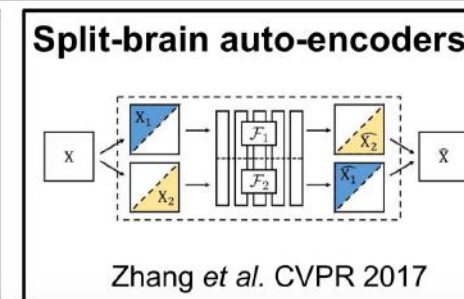
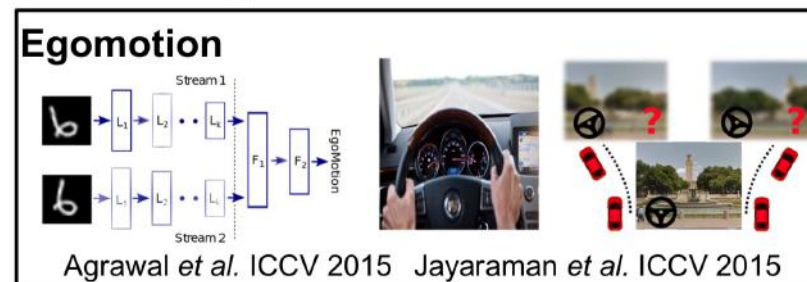
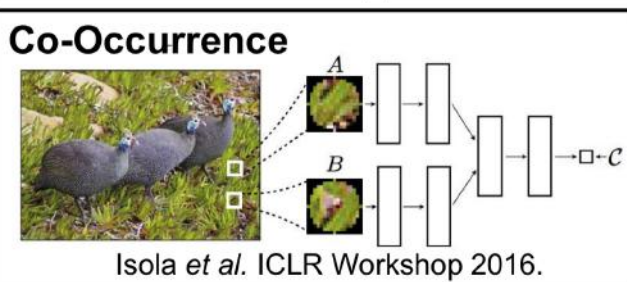
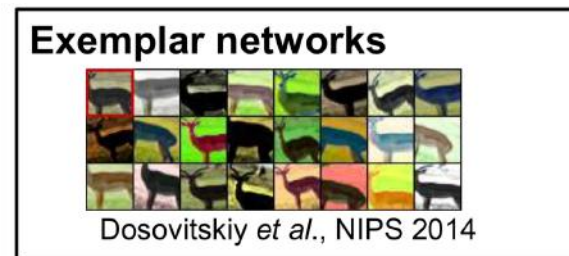
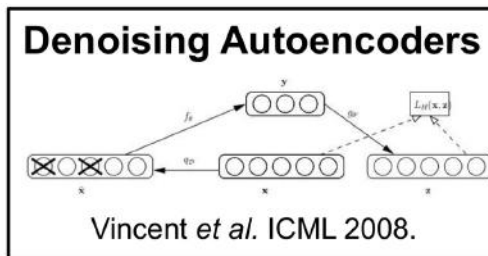
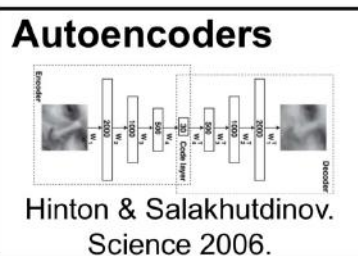
## Self-supervised Learning

- Image Example: Colorisation



# Self-supervised Learning

- Image Examples



# Self-supervised Learning

- **Video Example**



- Videos contain
  - Colour, Temporal info
- Possible proxy tasks
  - Temporal order of the frames
  - Optical flow: Motion of objects
  - ...



## Self-supervised Learning

- Video Example: Shuffle and Learn

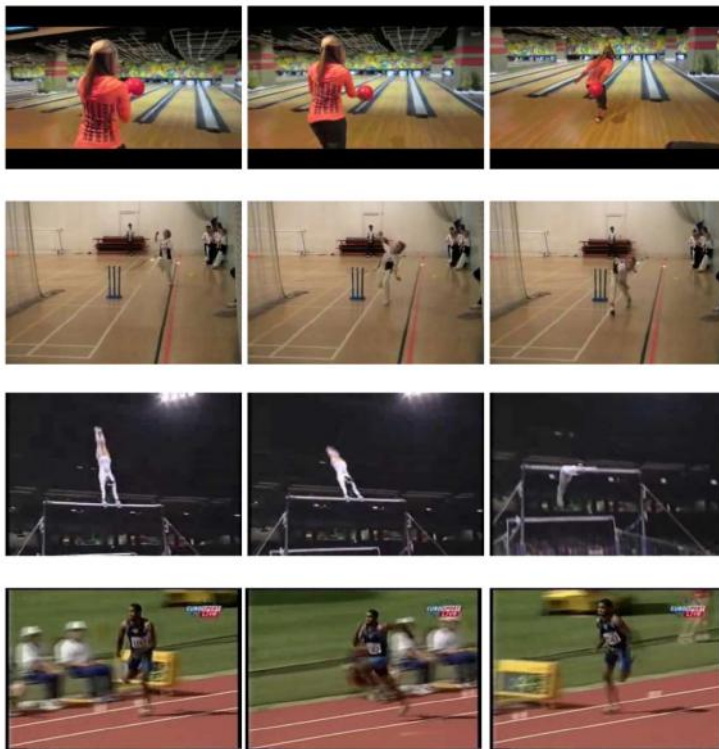
Given a start and an end, can this point lie in between?



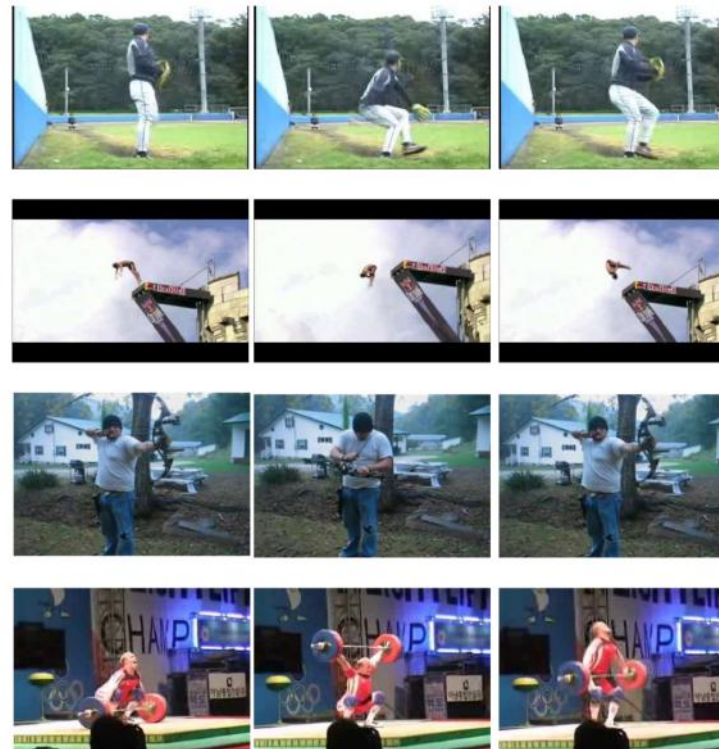
# Self-supervised Learning

- Video Example: Shuffle and Learn

True

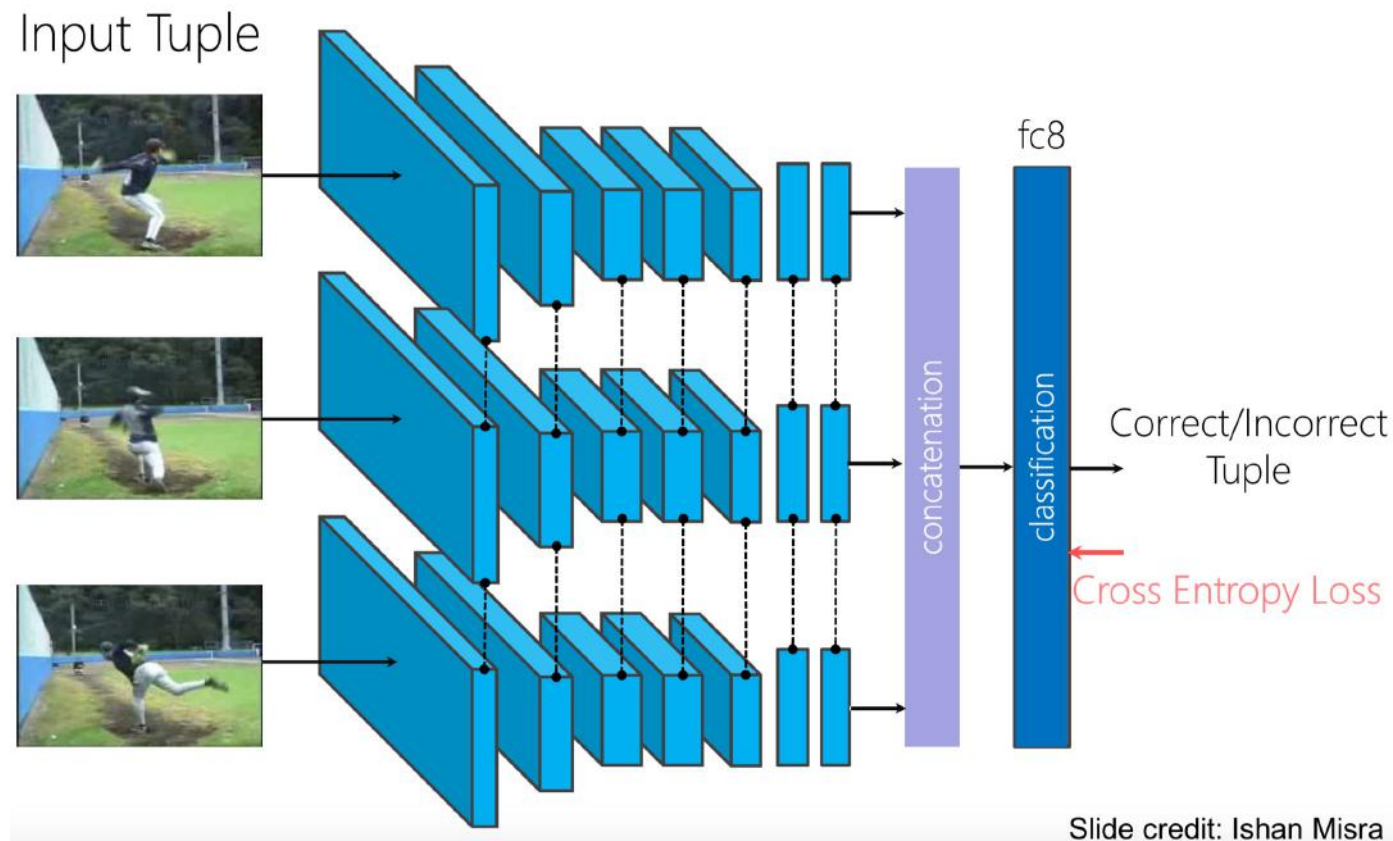


False



# Self-supervised Learning

- Video Example: Shuffle and Learn





# Self-supervised Learning

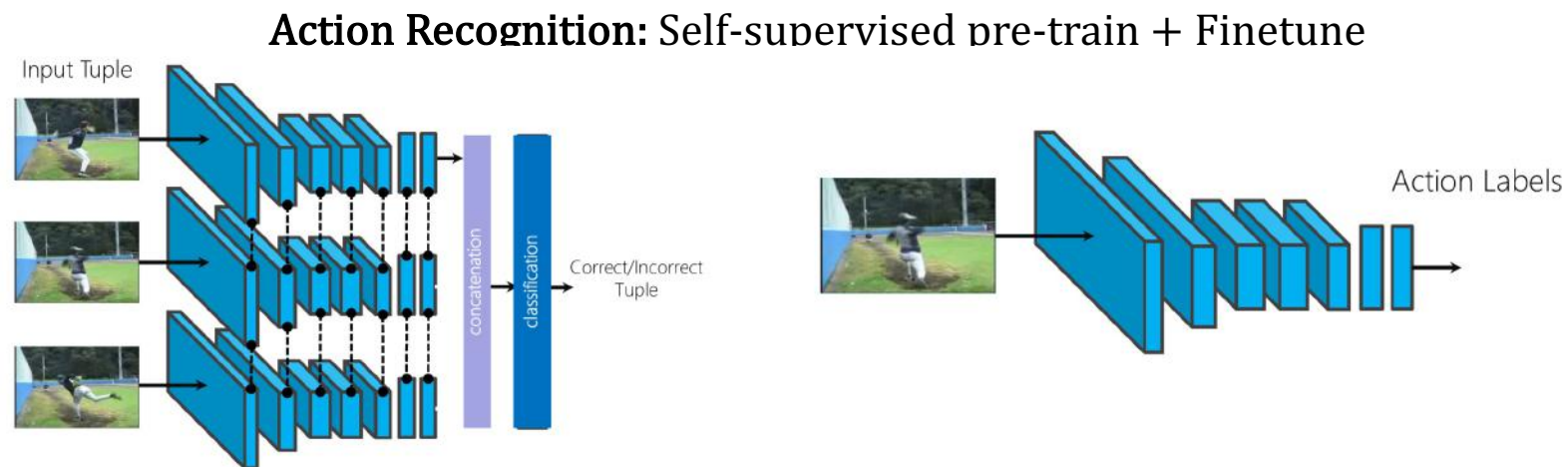
- Video Example: Shuffle and Learn

**Image Retrieval:** Nearest Neighbors of Query Frame (FC5 outputs)



# Self-supervised Learning

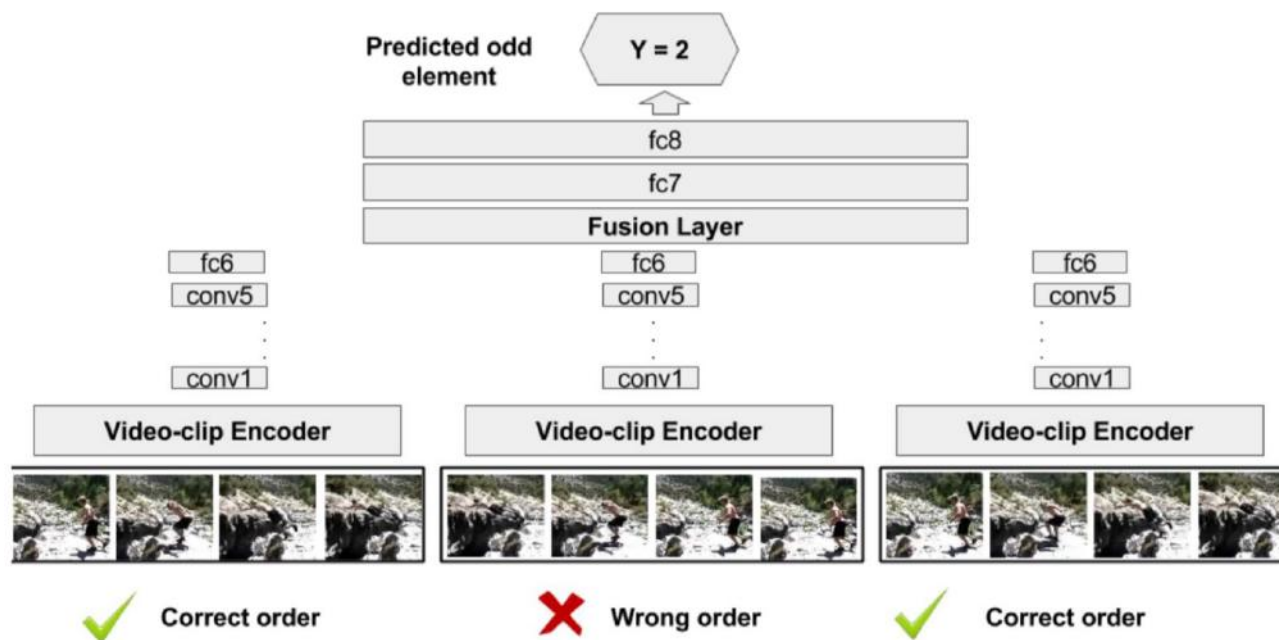
- Video Example: Shuffle and Learn



Dataset	Initialization	Mean Classification Accuracy
UCF101	Random	38.6
	Shuffle & Learn	50.2
	ImageNet pre-trained	<b>67.1</b>

# Self-supervised Learning

- Video Example: Odd-One-Out



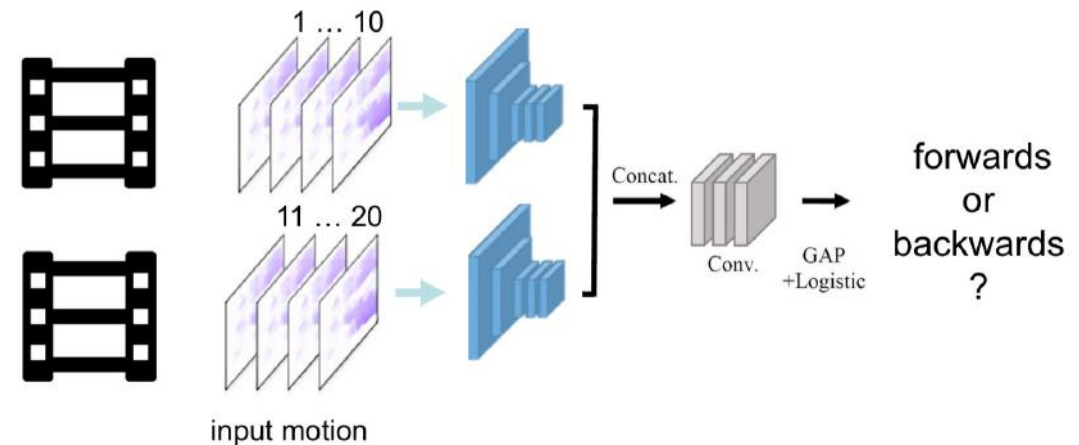
Initialization	Mean Classification Accuracy
Random	38.6
Shuffle and Learn	50.2
Odd-One-Out	60.3
ImageNet pre-trained	<b><u>67.1</u></b>

Self-Supervised Video Representation Learning With Odd-One-Out Networks. *Basura Fernando, Hakan Bilen, Efstratios Gavves, and Stephen Gould*, ICCV 2017

# Self-supervised Learning

- Video Example: Learning the Arrow of Time

Forward or backward plays?



- Depending on the video, solving the task may require
  - (a) low-level understanding (e.g. physics)
  - (b) high-level reasoning (e.g. semantics)
  - (c) familiarity with very subtle effects
  - (d) camera conventions

- Input: optical flow in two chunks
- Final layer: global average pooling to allow class activation map (CAM)

## Self-supervised Learning

- Video Example: Temporal Coherence of Color

Colorize all frames of a grey scale version using a reference frame



Reference Frame

What color is that?



Tracking Emerges by Colorizing Videos

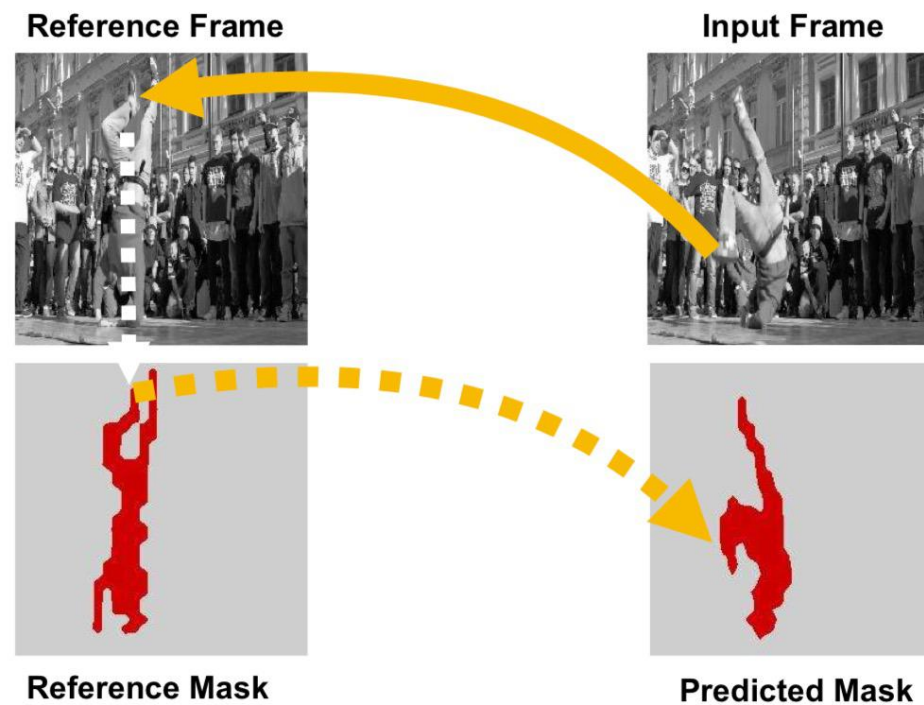
*Vondrick, Shrivastava, Fathi, Guadarrama, Murphy, ECCV 2018*



## Self-supervised Learning

- Video Example: Temporal Coherence of Color

**Tracking Emerges:** Only the first frame is given, colors indicate different instances



Tracking Emerges by Colorizing Videos

*Vondrick, Shrivastava, Fathi, Guadarrama, Murphy, ECCV 2018*

# Self-supervised Learning

- Video Example: Temporal Coherence of Color

**Segment Tracking:** Only the first frame is given, colors indicate different instances



Tracking Emerges by Colorizing Videos

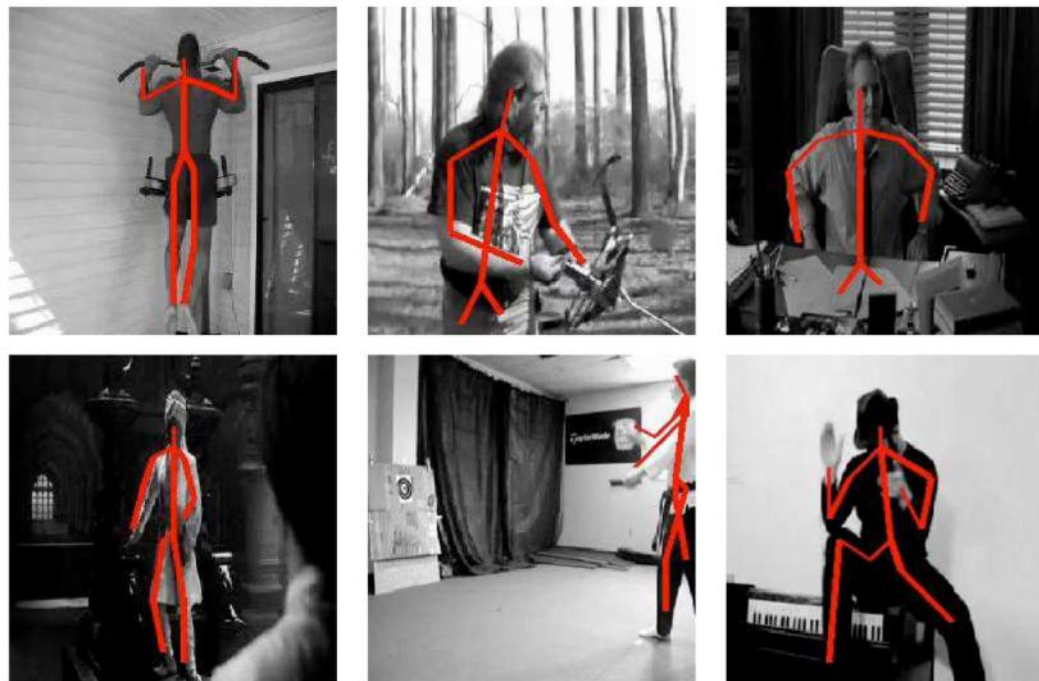
*Vondrick, Shrivastava, Fathi, Guadarrama, Murphy, ECCV 2018*



## Self-supervised Learning

- Video Example: Temporal Coherence of Color

**Pose Tracking:** Only the skeleton in the first frame is given



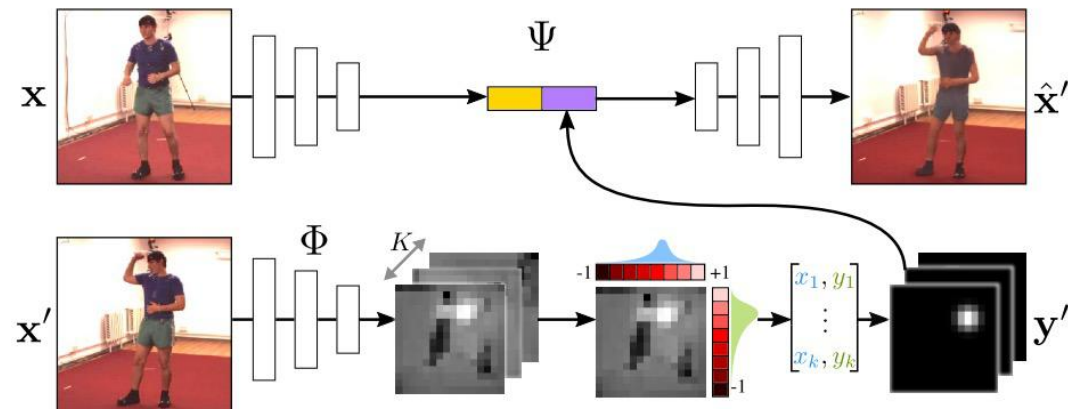
Tracking Emerges by Colorizing Videos

*Vondrick, Shrivastava, Fathi, Guadarrama, Murphy, ECCV 2018*

# Self-supervised Learning

- Video Example: Temporal Coherence of Color

Unsupervised Key-point Detection: Only paired images of the same object is given



- Achieve retargeting
- Disentangling Style and Geometry
- Invariant Localization



Unsupervised Learning of Object Landmarks through Conditional Image Generation

*Tomas Jakab, Ankush Gupta et al. NIPS, 2018.*

# Self-supervised Learning

- **Video + Sound Example**

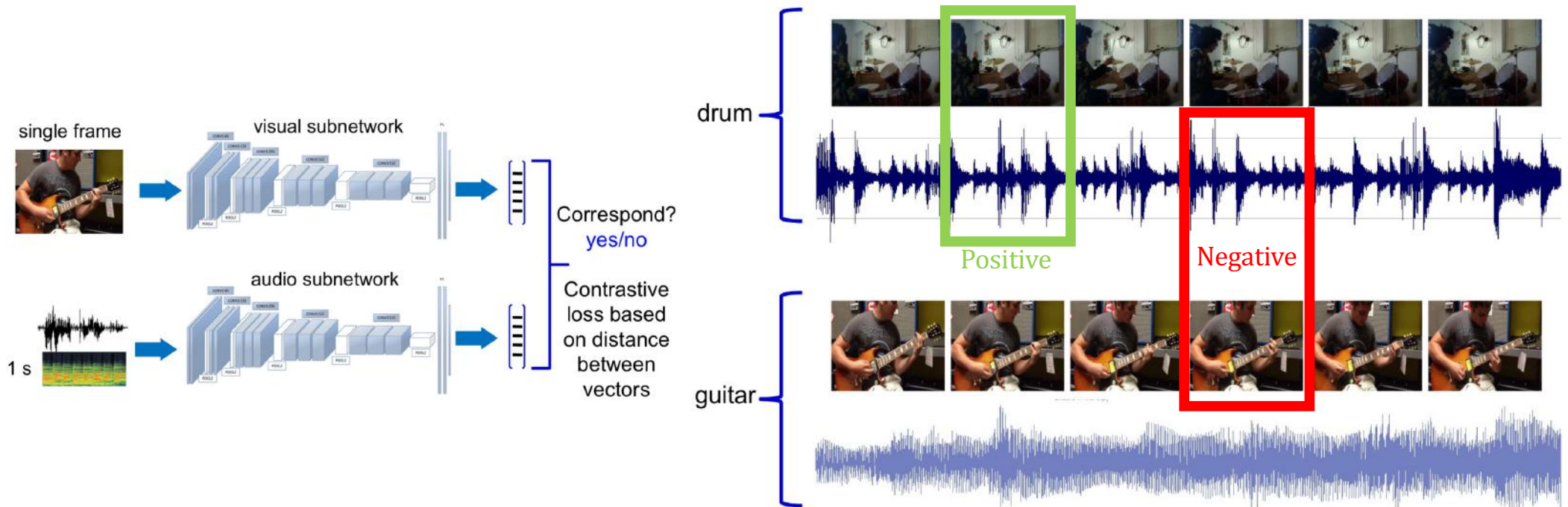


- Sound and frames are:
  - Semantically consistent
  - Synchronized
- Two types of proxy task:
  - Predict audio-visual correspondence
  - Predict audio-visual synchronization

# Self-supervised Learning

- Video + Sound Example: Audio-Visual Co-supervision

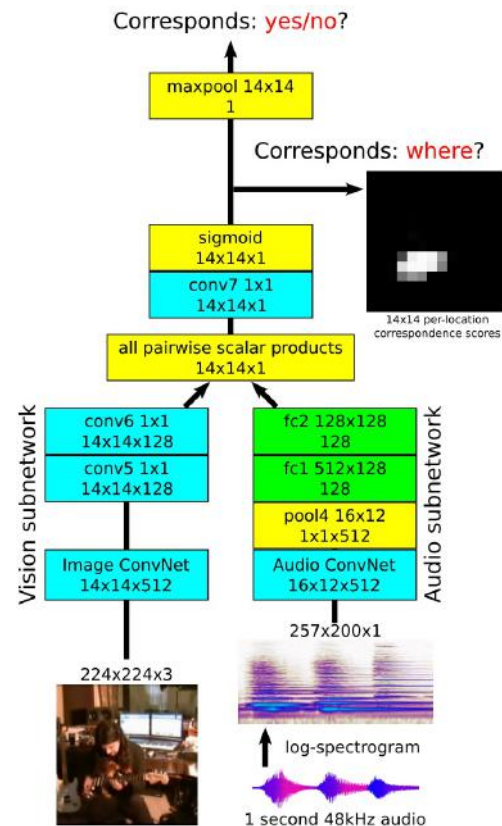
Train a network to predict if image and audio clip correspond



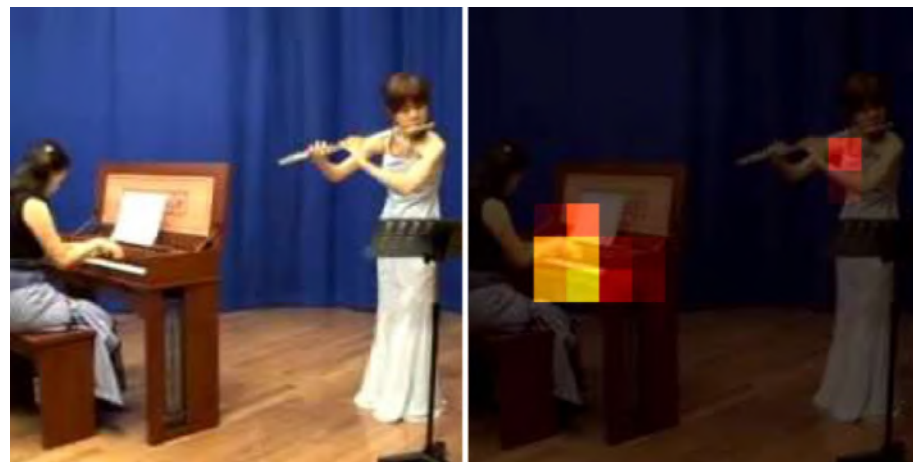


# Self-supervised Learning

## • Video + Sound Example: Audio-Visual Co-supervision

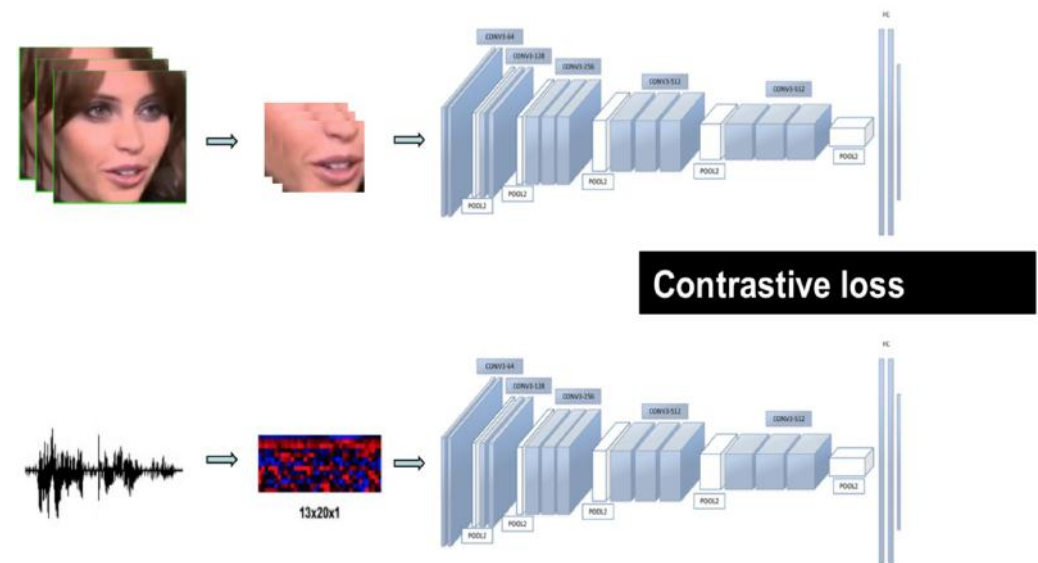
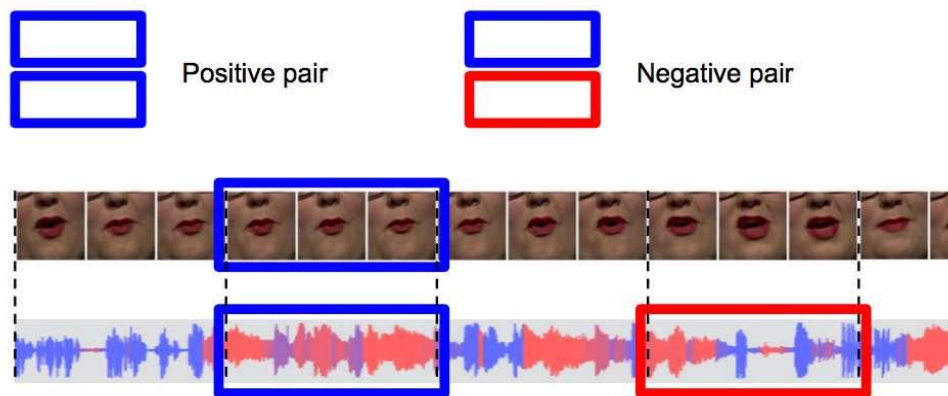


- Learn good visual features
- Learn good audio features
- Learn aligned audio-visual embeddings
- Learn to localize objects that sound
- Using learned features
  - Sound classification
  - Query on image to retrieve audio
  - Localizing objects with sound



# Self-supervised Learning

- Video + Sound Example: Audio-Visual Co-supervision



- Applications
  - Active speaker detection
  - Audio-to-video synchronization
  - Voice-over rejection
  - Visual features for lip reading

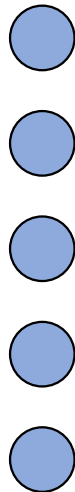
Out of time: Automatic lip sync in the wild. *Chung, Zisserman, 2016*

- Unsupervised Learning
- Semi-supervised Learning
- Weakly-supervised Learning
- Dual Learning
- Self-supervised Learning
- Self-augmented Learning



# Self-augmented Learning

Data in input only  
with known inverse mapping  $f'$   
(Learn the mapping  $f$  and output  $y$ )

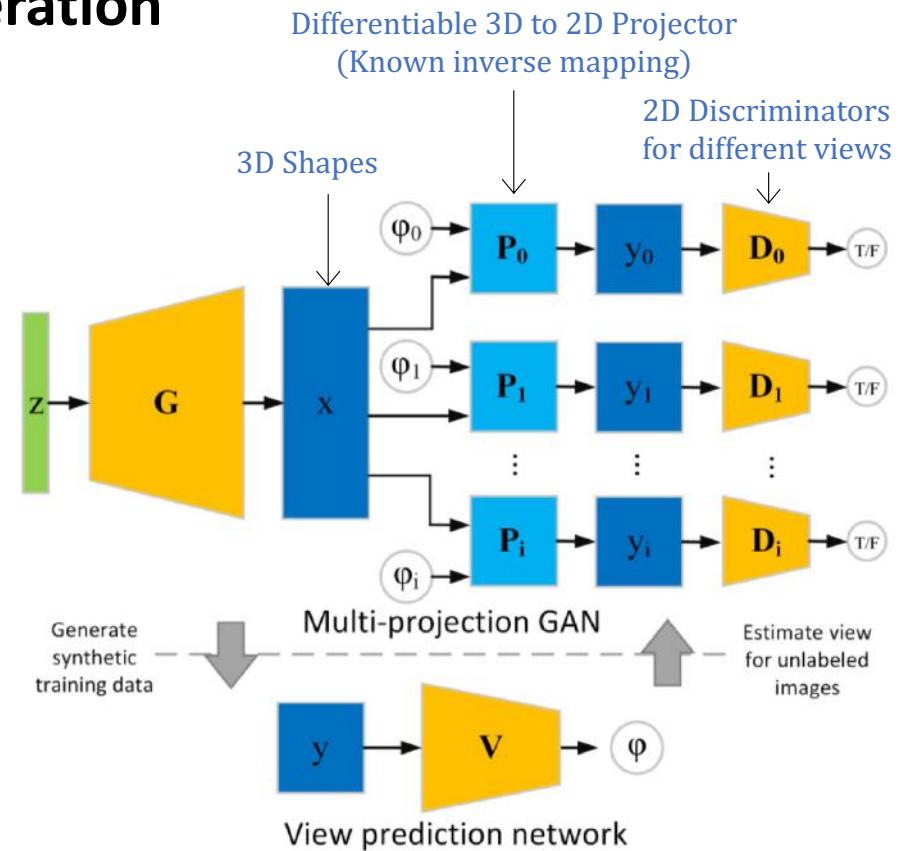
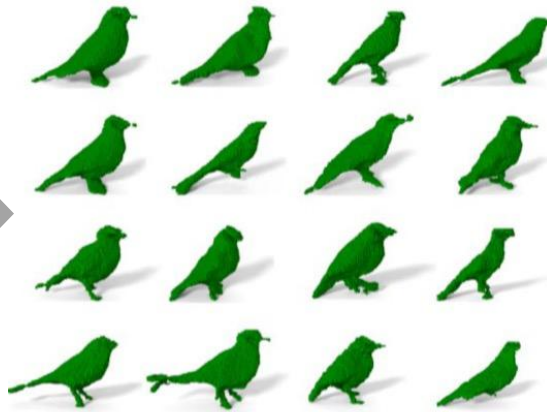


$$y = f(x), x = f'(y)$$

Self-augmented Learning

# Self-augmented Learning

- Example: Unsupervised 3D shape generation**



# Summary

- Unsupervised Learning
- Semi-supervised Learning
- Weakly-supervised Learning
- Dual Learning
- Self-supervised Learning
- Self-augmented Learning

# Thanks