

Hao Dong

**Peking University** 



 $p_{data}$ 









$$\mathbf{x}^{j} \sim p_{data}$$
  
 $j = 1, 2, ... |\mathcal{D}|$ 

- dataset  $\mathcal{D}$
- data distribution  $p_{data}$
- model parameters  $\theta \in \mathcal{M}$

• How to represent (model) a data distribution? It can be an optimisation problem:

$$\min_{\theta \in \mathcal{M}} \mathcal{L}(p_{data}, p_{\theta})$$

Why parametric models?

They scale more efficiently with large dataset than non-parametric models.



#### $p_{data}$









$$\mathbf{x}^{j} \sim p_{data}$$
$$j = 1, 2, \dots |\mathcal{D}|$$

- dataset  $\mathcal{D}$
- data distribution  $p_{data}$
- model parameters  $\theta \in \mathcal{M}$

- We want to learn a probability distribution p(x) over x
- 1. Generation (sampling):  $\mathbf{x}_{new} \sim p(\mathbf{x})$
- **2. Density Estimation:** p(x) high if x looks like a cat
- 3. Unsupervised Representation Learning:

Discovering the underlying structure from the data distribution (e.g., ears, nose, eyes ...)



#### Recap: Challenges from Lecture 1

#### Representation ability

How to represent p(x)

For 1-D data x, the probability distribution p(x) is simple, e.g., Gaussian? For high-dimensional data  $\mathbf{x}=(x_1,x_2,\dots,x_n)$ , how do we learn the joint distribution  $p(x_1,x_2,\dots,x_n)$ ?

#### Learning method

How do we measure and minimise the distance between the estimated distribution p(x) (i.e.,  $p_x$ ) and the real distribution  $p_{data}$ ? we can now perform generative process and density estimation

#### Inference

How do we perform discriminative task?
i.e., invert the generative process



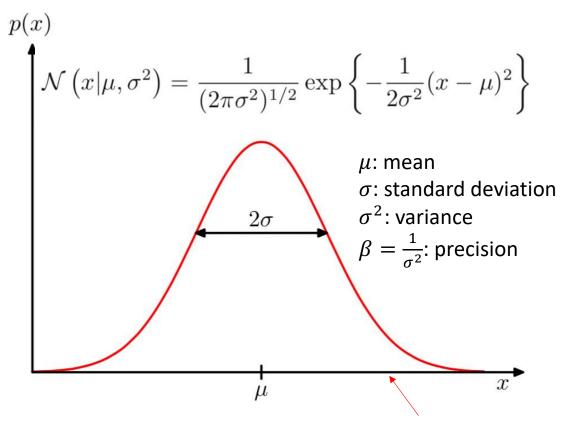
Problem of High-dimensional Data
 Less Parameters: Conditional Independence
 Less Parameters: Bayesian Network
 Naïve Bayes Classifier
 Discriminative vs. Generative Models
 Logistic Regression
 Deep Neural Networks
 Continuous Variables



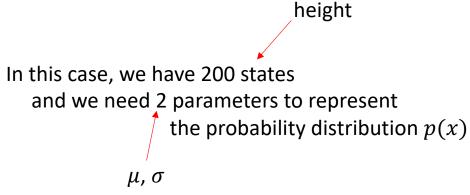
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How to represent the height distribution (age from 30cm to 230cm)



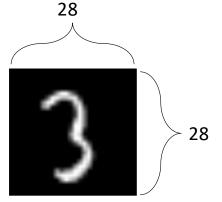
The probability of *x* to be this value





How to represent a high-dimensional data  $\mathbf{x} = (x_1, x_2, x_3, ..., x_n)$ 





So... how to represent  $p(x_1, x_2, ..., x_{784})$  ?

how many number of parameters?

In MNIST, an images have 28 \* 28 \* 1 = 784 binary values

#### **MNIST dataset**



• How to represent a high-dimensional data  $\mathbf{x} = (x_1, x_2, x_3, ..., x_n)$ 

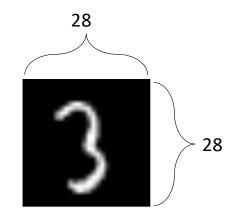
(Bernoulli random variables)

As x can be either 0 or 1, i.e., only 2 states

(Joint distribution)

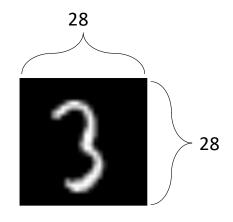
The number of possible state for  $p(x_1, x_2, ..., x_n)$  is  $\mathbf{2}^n$  which is far larger than the number of data sample

We need a super-large memory to store  $p(x_1,x_2,\dots,x_n)$  even we have such large memory, we do not have enough data to learn/model it





• How to represent a high-dimensional data  $\mathbf{x} = (x_1, x_2, x_3, ..., x_n)$ 



784 random binary variables

$$p(x_1, x_2, ..., x_n)$$
 has  $2^n$  states, then ...

How many number of parameters to model  $p(x_1, x_2, ..., x_n)$  ? :  $2^n$  -1?

Recap: Product Rule

$$p(x_1, x_2) = p(x_1)p(x_2|x_1)$$

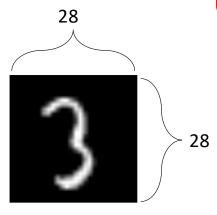
$$p(x_1, x_2, x_3) = p(x_1, x_2)p(x_3|x_1, x_2) = p(x_1)p(x_2|x_1)p(x_3|x_1, x_2)$$

•••

$$p(x_1, x_2, ..., x_n) = p(x_1)p(x_2|x_1)p(x_3|x_1, x_2) ... p(x_n|x_1, ..., x_{n-1})$$



• How to represent a high-dimensional data  $\mathbf{x} = (x_1, x_2, x_3, ..., x_n)$ 



784 random binary variables

$$p(x_1, x_2, ..., x_n) = p(x_1)p(x_2|x_1)p(x_3|x_1, x_2) ... p(x_n|x_1, ..., x_{n-1})$$

- $p(x_1)$  need 1 parameter, the probability of  $x_1$  to be 1 (as it is a binary variable)
- $p(x_2|x_1)$  need 2 parameters, i.e.,  $p(x_2|x_1=0)$  and  $p(x_2|x_1=1)$
- $p(x_3|x_1,x_2)$  need 4 parameters, i.e.,  $p(x_3|x_1=0,x_2=0)$ ,  $p(x_3|x_1=0,x_2=1)$  $p(x_3|x_1=1,x_2=0)$ ,  $p(x_3|x_1=1,x_2=1)$

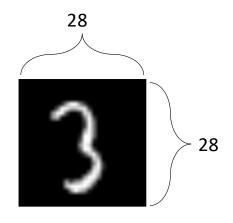
So ... The number of parameters to model  $p(x_1, x_2, ..., x_n)$  is:

$$1 + 2 + 4 + \dots + 2^{n-1} = 2^n - 1$$

(when variables are binary)



• How to represent a high-dimensional data  $\mathbf{x} = (x_1, x_2, x_3, ..., x_n)$ 



784 random binary variables

#### **Product Rule:**

$$p(x_1, x_2, ..., x_n) = p(x_1)p(x_2|x_1)p(x_3|x_1, x_2) ... p(x_n|x_1, ..., x_{n-1})$$

$$2^n \text{ states} \qquad \qquad 2^n - 1 \text{ parameters}$$

 $2^n - 1$  is exponential, the product rule does not help to reduce the num of parameters



• How to represent a high-dimensional data  $\mathbf{x} = (x_1, x_2, x_3, ..., x_n)$ 

#### In practice

- 1) The x can be continuous, i.e., infinite states
- 2) The number of x can be millions

#### For simplicity

We use binary x and MNIST for demo

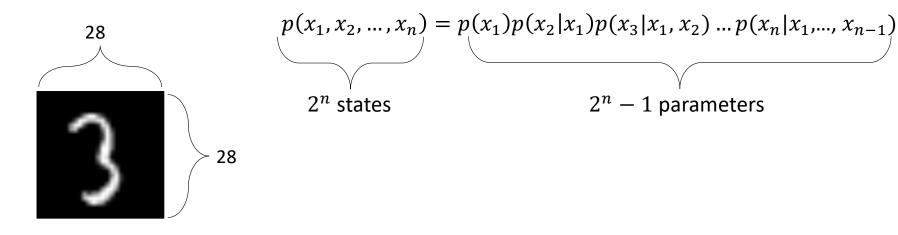


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• How to reduce the number of parameter to represent  $p(x_1, x_2, ..., x_n)$ ?

#### Product Rule does not help:



784 random binary variables



• How to reduce the number of parameter to represent  $p(x_1, x_2, ..., x_n)$ ?

**Recap:** If variables  $x_1, x_2$  are conditional independent given variable  $x_3$ , denotes as  $x_1 \perp x_2 \mid x_3$ 

$$p(x_1, x_2 | x_3) = p(x_1 | x_3) p(x_2 | x_3)$$

if not independent:

$$p(x_1, x_2 | x_3) = \frac{p(x_1, x_2, x_3)}{p(x_3)} = \frac{p(x_1, x_2, x_3)}{p(x_2, x_3)} \frac{p(x_2, x_3)}{p(x_3)} = p(x_1 | x_2, x_3) p(x_2 | x_3)$$

so we can have 
$$p(x_1|x_2,x_3)p(x_2|x_3) = p(x_1|x_3)p(x_2|x_3)$$
 if  $x_1 \perp x_2 \mid x_3$ 



• How to reduce the number of parameter to represent  $p(x_1, x_2, ..., x_n)$ ?

Given product rule:  $p(x_1, x_2, x_3, x_4) = p(x_1)p(x_2|x_1)p(x_3|x_1, x_2)p(x_4|x_1, x_2, x_3)$ 

If 
$$x_4 \perp x_2 \mid \{x_1, x_3\}$$
, we can simplify it as: 
$$p(x_1, x_2, x_3, x_4) = p(x_1)p(x_2 \mid x_1)p(x_3 \mid x_1, x_2)p(x_4 \mid x_1, x_2, x_3)$$

If 
$$x_2 \perp \{x_1, x_3\} \mid x_4$$
, we can simplify it as:  

$$p(x_1, x_2, x_3, x_4) = p(x_4, x_3, x_2, x_1) = p(x_4)p(x_3 \mid x_4)p(x_2 \mid x_3, x_4)p(x_1 \mid x_2, x_3, x_4)$$

$$= p(x_4)p(x_3 \mid x_4)p(x_2 \mid x_3, x_4)p(x_1 \mid x_2, x_3, x_4)$$



• How to reduce the number of parameter to represent  $p(x_1, x_2, ..., x_n)$ ?

In an **extreme case**, if  $x_{i+1} \perp \{x_1, x_2 \dots x_{i-1}\} \mid x_i$ , i.e., the next variable only related to the current variable (Markov model!)

$$p(x_1, x_2, x_3, x_4) = p(x_1)p(x_2|x_1)p(x_3|x_1, x_2)p(x_4|x_1, x_2, x_3)$$

$$= p(x_1)p(x_2|x_1)p(x_3|x_4, x_2)p(x_4|x_4, x_2, x_3)$$

$$= p(x_1)p(x_2|x_1)p(x_3|x_2)p(x_4|x_3)$$

If x are binary variables

$$2n-1$$
 parameters  $<< 2^n-1$  parameters

So ...

if conditional independencies exist, the number of parameter can be reduced!!



• How to reduce the number of parameter to represent  $p(x_1, x_2, ..., x_n)$ ?

In a MORE extreme case, if  $x_i$  are independent identical (IID)

$$p(x_1, x_2, x_3, x_4) = p(x_1)p(x_2|x_1)p(x_3|x_1, x_2)p(x_4|x_1, x_2, x_3)$$
  
=  $p(x_1)p(x_2|x_4)p(x_3|x_4, x_2)p(x_4|x_1, x_2, x_3)$   
=  $p(x_1)p(x_2)p(x_3)p(x_4)$ 

However, in practice, there exists "relationship" between variables the independence assumption is not practical...

e.g., the following random samples would not happen







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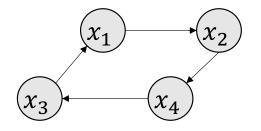
#### Key idea:

Joint distribution: 
$$p(x_1, x_2, ..., x_n) = p(x_1)p(x_2|x_1)p(x_3|x_1, x_2) ... p(x_n|x_1, ..., x_{n-1})$$

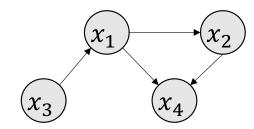
$$2^n - 1 \text{ parameters if } x \text{ are binary variables}$$

use conditional distribution instead of joint distribution to reduce the num of parameters

Bayesian network structure is a **Directed Acyclic Graph**, G = (V, E) where V means vertexes, E means edges



**Directed Cycle** 



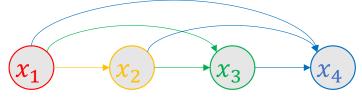
**Directed Acyclic Graph** 



#### Key idea:

Bayesian network structure is a **Directed Acyclic Graph**, G = (V, E)

Joint distribution:  $p(x_1, x_2, x_3, x_4) = p(x_1)p(x_2|x_1)p(x_3|x_1, x_2)p(x_4|x_1, x_2, x_3)$ 



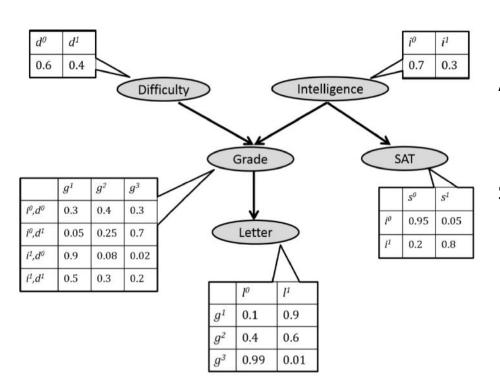
If  $x_{i+1} \perp \{x_1, x_2 \dots x_{i-1}\} \mid x_i$  $p(x_1, x_2, x_3, x_4) = p(x_1)p(x_2|x_1)p(x_3|x_4, x_2)p(x_4|x_4, x_2, x_3)$   $= p(x_1)p(x_2|x_1)p(x_3|x_2)p(x_4|x_3)$ 



**Less edges == Less parameters** 



#### Example



$$p(d, i, g, s, l) = p(d)p(i|d)p(g|d, i)p(s|d, i, g)p(l|d, i, g, s)$$

According to the left Bayesian Net, we have the independencies:

$$d \perp i$$
  $s \perp \{d, g\}$   $l \perp \{d, i, s\}$ 

So that ..

$$p(d, i, g, s, l) = p(d)p(i)p(g|i, d)p(s|i)p(l|g)$$



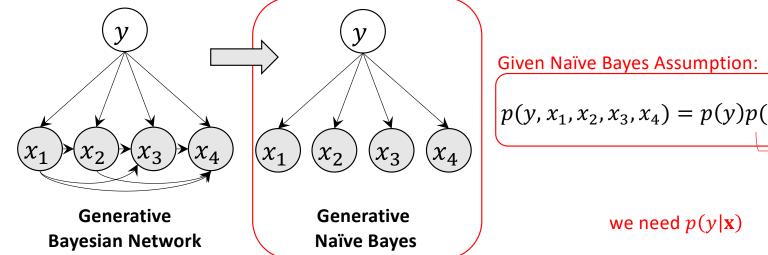
- Bayesian Network structure is a **Directed Acyclic Graph**, G = (V, E)
- Bayesian Network is given by (G, P), where P is a set of local conditional probability distributions for each node/vertex of G
- Compute the P using data samples to "learn" the Bayesian Network
- Bayesian Network is also known as Belief Network and Bayes Network



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## Naïve Bayes Classifier

- How Bayesian Network performs inferencing? i.e., discriminative tasks?
- Support we have a binary classification problem, label y=0,1, features  $\mathbf{x}=(x_1,x_2,x_3,x_4)$
- The probability distribution is  $p(y, x_1, x_2, x_3, x_4)$
- Naïve Bayes Classifier assume that  $x_i \perp \mathbf{x}_{-i} | y |$ , so that:



$$p(y, x_1, x_2, x_3, x_4) = p(y)p(x_1|y)p(x_2|y) p(x_3|y)p(x_4|y)$$

$$p(\mathbf{x}|y)$$



#### Naïve Bayes Classifier

$$p(y|\mathbf{x}) = \frac{p(\mathbf{x}, y)}{p(\mathbf{x})} = \frac{p(y)p(\mathbf{x}|y)}{p(\mathbf{x})} \propto p(y)p(\mathbf{x}|y)$$

$$\hat{y} = arg \max_{y} p(y|\mathbf{x}) = arg \max_{y} \frac{p(\mathbf{x}, y)}{p(\mathbf{x})} = arg \max_{y} p(y)p(\mathbf{x}|y)$$

Given Naïve Bayes Assumption:

$$p(\mathbf{x}|\mathbf{y}) = p(x_1|\mathbf{y})p(x_2|\mathbf{y}) p(x_3|\mathbf{y})$$



## Naïve Bayes Classifier

- Given  $p(\mathbf{x}|y) = p(x_1|y)p(x_2|y) p(x_3|y)$ , how to compute p(Y|X)?
- First, we can **estimate** the parameters from the training set:

	$x_1 = 0$	$x_1 = 1$	$x_2 = 0$	$x_2 = 1$	$x_3 = 0$	$x_3 = 1$	$x_4 = 0$	$x_4 = 1$
y = 0	3	5	5	2	0	8	7	4
y = 1	1	0	3	10	7	4	2	5

• 
$$p(Y = 0) = \frac{3+5+5+2+8+7+4}{(3+5+5+2+8+7+4)+(1+3+10+7+4+2+5)}$$

• 
$$p(x_1 = 0|Y = 0) = \frac{3}{3+5+5+2+8+7+4}$$

- •
- Second, **predict** the probability of a label given an input with **Bayes rule**:

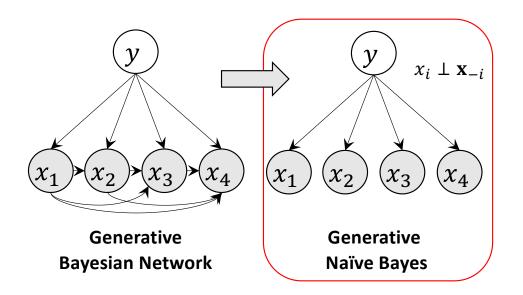
• 
$$p(Y = 0 | x_1, x_2, x_3, x_4) = \frac{p(Y=0) \prod_{i=1}^4 p(x_i | Y=0)}{\sum_{y=\{0,1\}} p(Y=y) \prod_{i=1}^4 p(x_i | Y=y)}$$



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Limitation

Are the independence assumptions reasonable ??





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#### Discriminative vs. Generative Models

 $\sim$  symmetry property p(X,Y)=p(Y,X)

- Given p(Y,X) = p(X|Y)p(Y) = p(Y|X)p(X)
- Discriminative: X → Y, we only need to estimate the conditional distribution P(Y|X)
   without learning to model P(X)
   simply input X then output Y



• Generative:  $Y \to X$ , we need both P(Y) and P(X|Y) to compute p(Y|X) via Bayes (see the Naïve Bayes Classifier as an example)

$$Y \longrightarrow X \qquad p(Y|X) = p(X|Y)p(Y)/p(X)$$



#### Discriminative vs. Generative Models

Given a random vector  $\mathbf{x} = (x_1, x_2, ..., x_n)$ , the product rules can give us:

$$p(y, \mathbf{x}) = p(y)p(x_1|y)p(x_2|y, x_1) \dots p(x_n|y, x_1, x_2, \dots, x_{n-1})$$
  
$$p(y, \mathbf{x}) = p(x_1)p(x_2|x_1)p(x_3|x_1, x_2) \dots p(y|x_1, x_2, \dots, x_{n-1})$$

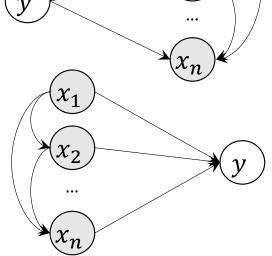
#### generative

p(y) is simple to estimate

but how to parametrise  $p(x_i|y, x_1,...,x_{i-1})$ ?

#### discriminative

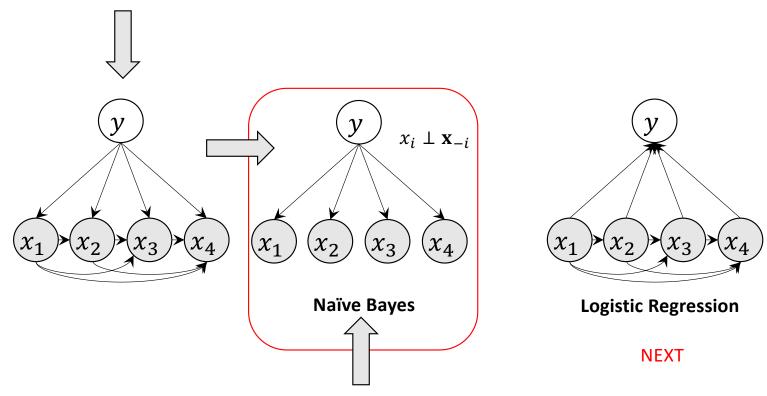
only need to parametrise  $p(y|x_1,...,x_{n-1})$ 





#### Discriminative vs. Generative Models

parametrise  $p(x_i|y, x_1,...,x_{i-1})$  without independent assumptions



parametrise  $p(x_i|y, x_1,...,x_{i-1})$  with independent assumptions



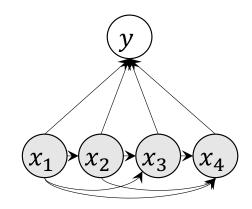
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## **Logistic Regression**

• Parameterise the p(Y|X) without independence assumptions

only need to parametrise  $p(y|x_1,...,x_{n-1})$ 



**Logistic Regression** 

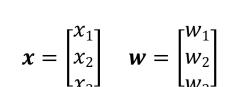


## **Logistic Regression**

• (only need to) parameterise the p(Y|X) without independence assumptions

$$p(Y = 1|\mathbf{x}, \mathbf{w}, b) = f(\mathbf{x}, \mathbf{w}, b)$$

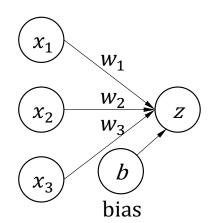
input layer output layer



 $z = x_1 w_1 + x_2 w_2 + x_3 w_3 + b$ 

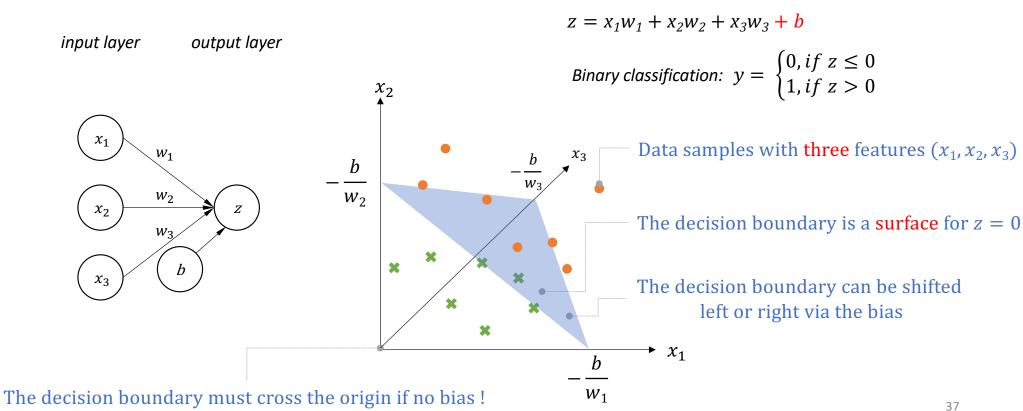
$$z = \mathbf{w}^T \mathbf{x} + b$$

$$z = \begin{bmatrix} w_1 & w_2 & w_3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + b$$





(only need to) parameterise the p(Y|X) without independence assumptions





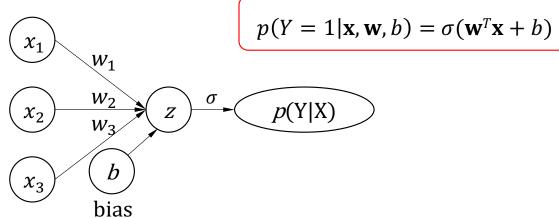
• (only need to) parameterise the p(Y|X) without independence assumptions

$$p(Y = 1|\mathbf{x}, \mathbf{w}, b) = f(\mathbf{x}, \mathbf{w}, b)$$

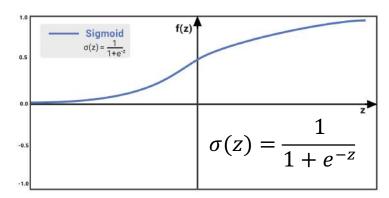
input layer output layer



 $z = \mathbf{w}^T \mathbf{x} + h$ 



#### Sigmoid/Logistic function





- Logistic regression does not require independence assumptions  $x_i \perp \mathbf{x}_{-i}$ , like Naïve Bayes
- Example, in spam classification,  $x_1 = 1$  ["bank" exists] and  $x_2 = 1$  ["account" exists]

If "bank" and "account" always appear together,

**Naïve Bayes** will **count this evidence twice**:

$$p(y, x_1, x_2, x_3) = p(y)p(x_1|y)p(x_2|y) p(x_3|y)$$
$$p(x_1|y) = p(x_2|y)$$

**Logistic regressive** can set either  $w_1$  or  $w_2$  to **zero** to ignore one of it!!



- Discriminative model is powerful, so what is the advantage of generative model?
  - Discriminative models p(Y|X) require all X are observed, fail to work if some inputs are missing!
  - Generative models  $p(Y|X) = \frac{p(Y,X)}{p(X)} = \frac{p(Y)p(X|Y)}{p(X)} \propto p(Y)p(X|Y)$ when some input are unobserved, still allow us to compute p(Y|X)e.g., Naive Bayes

	$x_1 = 0$	$x_1 = 1$	$x_2 = 0$	$x_2 = 1$	$x_3 = 0$	$x_3 = 1$	$x_4 = 0$	$x_4 = 1$
y = 0	3	5	5	2	0	8	7	4
y = 1	1	0	3	10	7	4	2	5

• 
$$p(Y = 0) = \frac{3+5+5+2+8+7+4}{(3+5+5+2+8+7+4)+(1+3+10+7+4+2+5)}$$
  
•  $p(x_1 = 0|Y = 0) = \frac{3}{3+5+5+2+8+7+4}$ 

• 
$$p(x_1 = 0|Y = 0) = \frac{3}{3+5+5+2+8+7+4}$$



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# Deep Neural Network

• Logistic regression parameterises the p(Y|X) without independence assumptions

$$p(Y = 1|\mathbf{x}, \mathbf{w}, b) = f(\mathbf{x}, \mathbf{w}, b)$$

but logistic regression is a **linear dependence** (between input and output)

which might be too simple

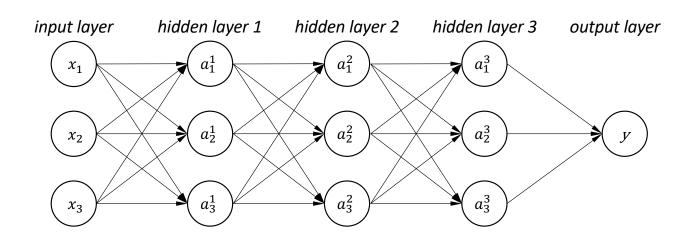
**Non-linear** dependence is better ...

$$p_{Neural}(Y = 1 | \mathbf{x}, \boldsymbol{\theta}) = f(\mathbf{x}, \boldsymbol{\theta})$$



# Deep Neural Network

More parameters and layers, better representation capacity ...



More powerful than logistic regression



## Deep Neural Network

Naïve Bayes

$$p(x_1, x_2, x_3, x_4) = p(x_1)p(x_2|x_1)p(x_3|x_1, x_2)p(x_4|x_1, x_2, x_3)$$

$$\approx p(x_1)p(x_2|x_1)p(x_3|x_1, x_2)p(x_4|x_1, x_2, x_3)$$

$$\approx p(x_1)p(x_2|x_1)p(x_3|x_2)p(x_4|x_3)$$

Deep Neural Network

$$p(x_1, x_2, x_3, x_4) = p(x_1)p(x_2|x_1)p(x_3|x_1, x_2)p(x_4|x_1, x_2, x_3)$$

$$\approx p(x_1)p(x_2|x_1)p_{Neural}(x_3|x_1, x_2)pNeu_{ral}(x_4|x_1, x_2, x_3)$$

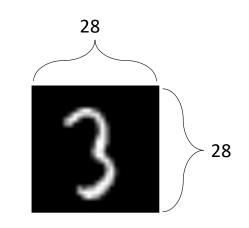


- Problem of High-dimensional Data
- Less Parameters: Conditional Independence
- Less Parameters: Bayesian Network
- Naïve Bayes Classifier
- Discriminative vs. Generative Models
- Logistic Regression
- Deep Neural Networks
- Continuous Variables

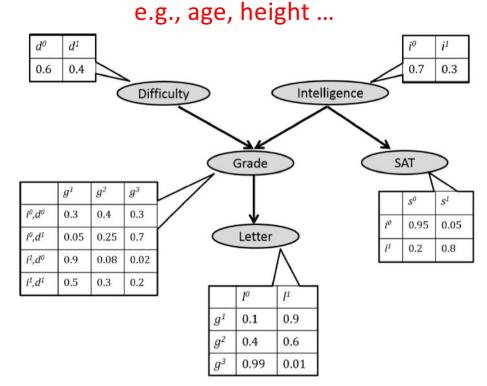


#### Discrete Variables

The below examples both use discrete variables, but there are many variables are continuous!



784 random binary variables





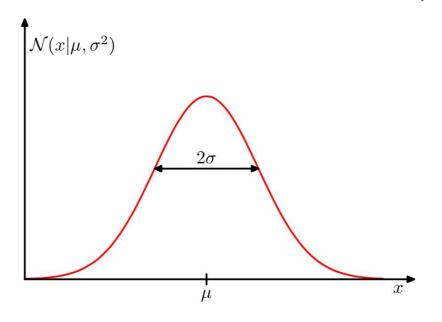
• Represent Continuous Variables

If x is a continuous variable, we can represent it with its **probability density function (PDF)** instead of a **table** anymore ..



#### Represent Continuous Variables

Consider x is a random **float-point** variable to represent "age", we can use 1-D Gaussian to parameterised the density.



$$\mathcal{N}(x|\mu,\sigma^2) = \frac{1}{(2\pi\sigma^2)^{1/2}} \exp\left\{-\frac{1}{2\sigma^2}(x-\mu)^2\right\}$$
$$\mathcal{N}(x|\mu,\sigma^2) > 0$$

 $\mu$ : mean

 $\sigma$ : standard deviation

 $\sigma^2$ : variance

$$\beta = \frac{1}{\sigma^2}$$
: precision

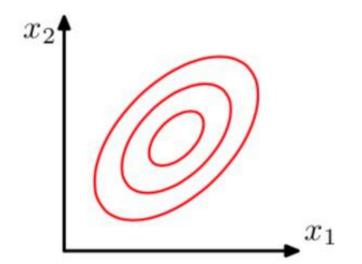


#### Represent Continuous Variables

Consider **x** is a random **float-point** vector to represent "age", "height", "weight" ..... it can be a **joint probability density function** 

we can use **D-dimensional Gaussian** to parameterize it

(a.k.a Multivariable Gaussian)



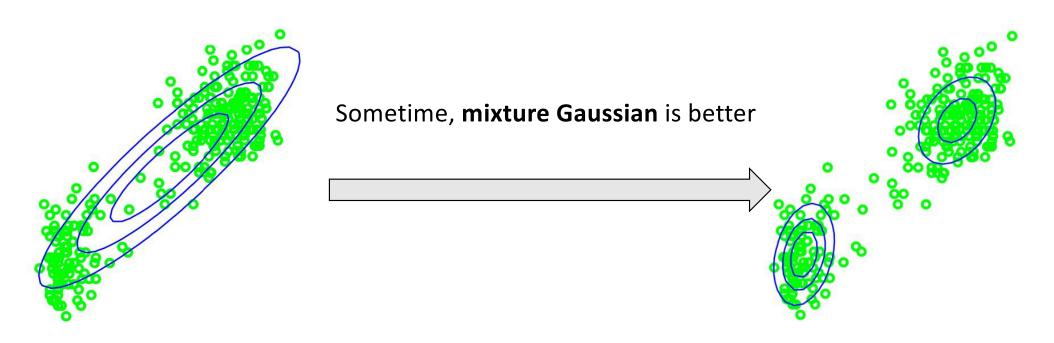
$$\mathcal{N}(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{D/2}} \frac{1}{|\boldsymbol{\Sigma}|^{1/2}} \exp\left\{-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^{\mathrm{T}} \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})\right\}$$

 $\mu$  is called the mean  $\Sigma$  is called the covariance  $|\Sigma|$  denotes the determinant of  $\Sigma$ 



## • Represent Continuous Variables

Consider x is a random float-point vector to represent "age", "height", "weight" .....





## **Data Representation**

Problem of High-dimensional Data
 Less Parameters: Conditional Independence
 Less Parameters: Bayesian Network
 Naïve Bayes Classifier
 Discriminative vs. Generative Models
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# **Thanks**