Mount drive to load celeb a data

```
from google.colab import drive
drive.mount('/content/drive')
    Mounted at /content/drive
import numpy as np
import os
from keras.layers import Input, Conv2D, Flatten, Dense, Conv2DTranspose, Reshape, L
from keras.layers import Activation, BatchNormalization, LeakyReLU, Dropout, ZeroPa
from keras.layers.advanced activations import LeakyReLU
from keras.models import Sequential, Model
from keras.optimizers import Adam, RMSprop
from keras.preprocessing.image import array to img, img to array, load img
from keras import backend as K
from keras.callbacks import ModelCheckpoint
from keras.utils import plot model
from keras.initializers import RandomNormal
from keras.preprocessing.image import ImageDataGenerator
import matplotlib.pyplot as plt
import numpy as np
import pandas as pd
import os
import matplotlib.pyplot as plt
from numpy.random import randn
from numpy.random import randint
# load data from saved file
data = np.load('/content/drive/MyDrive/celebA/test1.npy')
data.shape
    (10000, 128, 128, 3)
x train = data
# Shape x train - Totol # of images: 10000, dim = (128,128,3)
len(x_train), len(x_train[0]), x_train.shape
    (10000, 128, (10000, 128, 128, 3))
# Preview Image from dataset
plt.imshow((x_train[0]))
```

x = Flatten()(x)

<matplotlib.image.AxesImage at 0x7ff96219bda0>

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20 -
40 -
60 -
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```
#Define input image dimensions
#Large images take too much time and resources. taking dim = (128, 128, 3)
img rows = 128
img cols = 128
channels = 3
img_shape = (img_rows, img_cols, channels)
# Resets all state generated by Keras
K.clear session()
#initializing weights
weight init = RandomNormal(mean=0., stddev=0.02)
# Disciminator model
discriminator input = Input(shape= img shape, name='discriminator input')
x = discriminator input
# First convolutional layer
x = Conv2D(filters= 64, kernel size= 5, strides= 2, padding= 'same', name= 'discrim
           kernel initializer= weight init)(x)
x = LeakyReLU(alpha = 0.2)(x)
x = Dropout(rate = 0.2)(x)
# Second convolutional layer
x = Conv2D(filters= 128, kernel size= 5, strides= 2, padding= 'same', name= 'discri
           kernel initializer= weight init)(x)
x = LeakyReLU(alpha = 0.2)(x)
x = Dropout(rate = 0.2)(x)
# Third convolutional layer
x = Conv2D(filters= 256, kernel size= 5, strides= 2, padding= 'same', name= 'discri
           kernel initializer= weight init)(x)
x = LeakyReLU(alpha = 0.2)(x)
x = Dropout(rate = 0.2)(x)
# Fourth convolutional layer
x = Conv2D(filters= 512, kernel size= 5, strides= 2, padding= 'same', name= 'discri
           kernel initializer= weight init)(x)
x = LeakyReLU(alpha = 0.2)(x)
x = Dropout(rate = 0.2)(x)
```

ulscriminator_output - pense(i, activation- sigmora, kerner_initializer- weight_i

discriminator = Model(discriminator_input, discriminator_output)

Discriminator model summary
discriminator.summary()

Model: "model"

Layer (type)	Output Shape	Param #
discriminator_input (InputLa	[(None, 128, 128, 3)]	0
discriminator_conv_1 (Conv2D	(None, 64, 64, 64)	4864
leaky_re_lu (LeakyReLU)	(None, 64, 64, 64)	0
dropout (Dropout)	(None, 64, 64, 64)	0
discriminator_conv_2 (Conv2D	(None, 32, 32, 128)	204928
leaky_re_lu_1 (LeakyReLU)	(None, 32, 32, 128)	0
dropout_1 (Dropout)	(None, 32, 32, 128)	0
discriminator_conv_3 (Conv2D	(None, 16, 16, 256)	819456
leaky_re_lu_2 (LeakyReLU)	(None, 16, 16, 256)	0
dropout_2 (Dropout)	(None, 16, 16, 256)	0
discriminator_conv_4 (Conv2D	(None, 8, 8, 512)	3277312
leaky_re_lu_3 (LeakyReLU)	(None, 8, 8, 512)	0
dropout_3 (Dropout)	(None, 8, 8, 512)	0
flatten (Flatten)	(None, 32768)	0
dense (Dense)	(None, 1)	32769

Total params: 4,339,329
Trainable params: 4,339,329
Non-trainable params: 0

Generator model
generator_input = Input(shape=(100,), name='generator_input')

```
x = generator_input
```

- $x = Dense(np.prod(32768), kernel_initializer= weight_init)(x)$
- x = BatchNormalization(momentum = 0.9)(x)
- x = LeakyReLU(alpha = 0.2)(x)
- x = Reshape((8, 8, 512))(x)
- x = UpSampling2D()(x)
- x = Conv2D(filters= 512, kernel_size= 5, padding= 'same', strides= 1, name = 'gener

```
kernel initializer= weight init)(x)
x = BatchNormalization(momentum = 0.9)(x)
x = LeakyReLU(alpha = 0.2)(x)
x = UpSampling2D()(x)
x = Conv2D(filters= 256, kernel_size= 5, padding= 'same', strides= 1, name = 'gener
            kernel initializer= weight init)(x)
x = BatchNormalization(momentum = 0.9)(x)
x = LeakyReLU(alpha = 0.2)(x)
x = UpSampling2D()(x)
x = Conv2D(filters= 64, kernel_size= 5, padding= 'same', strides= 1, name = 'genera
            kernel initializer= weight init)(x)
x = BatchNormalization(momentum = 0.9)(x)
x = LeakyReLU(alpha = 0.2)(x)
x = Conv2DTranspose(filters= 3, kernel_size= 5, padding= 'same', strides= 2, name =
                    kernel initializer= weight init)(x)
x = Activation('sigmoid')(x)
generator output = x
generator = Model(generator input, generator output)
# Generator model summary
generator.summary()
```

Model: "model 1"

Layer (type)	Output Shape	Param #
generator_input (InputLayer)	[(None, 100)]	0
dense_1 (Dense)	(None, 32768)	3309568
batch_normalization (BatchNo	(None, 32768)	131072
leaky_re_lu_4 (LeakyReLU)	(None, 32768)	0
reshape (Reshape)	(None, 8, 8, 512)	0
up_sampling2d (UpSampling2D)	(None, 16, 16, 512)	0
generator_conv_1 (Conv2D)	(None, 16, 16, 512)	6554112
batch_normalization_1 (Batch	(None, 16, 16, 512)	2048
leaky_re_lu_5 (LeakyReLU)	(None, 16, 16, 512)	0
up_sampling2d_1 (UpSampling2	(None, 32, 32, 512)	0
generator_conv_2 (Conv2D)	(None, 32, 32, 256)	3277056
batch_normalization_2 (Batch	(None, 32, 32, 256)	1024
leaky_re_lu_6 (LeakyReLU)	(None, 32, 32, 256)	0

```
up sampling2d 2 (UpSampling2 (None, 64, 64, 256)
                                                            0
    generator conv 3 (Conv2D)
                                  (None, 64, 64, 64)
                                                            409664
    batch normalization 3 (Batch (None, 64, 64, 64)
                                                            256
                                  (None, 64, 64, 64)
    leaky re lu 7 (LeakyReLU)
    generator conv 4 (Conv2DTran (None, 128, 128, 3)
                                                            4803
    activation (Activation)
                                  (None, 128, 128, 3)
    Total params: 13,689,603
    Trainable params: 13,622,403
    Non-trainable params: 67,200
# freezing weights of generator
generator.trainable = False
for layer in generator.layers:
    layer.trainable = False
discriminator.compile(optimizer= RMSprop(lr= 0.0008, decay=6e-8),
                      loss= 'binary crossentropy')
# freezing weights of discriminator
discriminator.trainable = False
for layer in discriminator.layers:
    layer.trainable = False
# unfreezing weights of generator
generator.trainable = True
for layer in generator.layers:
    layer.trainable = True
model input = Input(shape=(100,), name='model input')
model output = discriminator(generator(model input))
model = Model(model input, model output)
model.compile(optimizer= RMSprop(lr=0.0004, decay=3e-8),
              loss= 'binary_crossentropy')
# unfreezing weights of discriminator
discriminator.trainable = True
for layer in discriminator.layers:
   layer.trainable = True
# method to train discriminator
def train discriminator(x train, batch size):
   valid = np.ones((batch_size,1))
   fake = np.zeros((batch size,1))
   noise = np.random.normal(0, 1, (batch_size, 100))
    an imag - concretor prodict/noise
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gen imgs = generator.predict(noise)
   d loss real = discriminator.train on batch(x train, valid)
    d loss fake = discriminator.train on batch(gen imgs, fake)
    d loss = 0.5 * (d loss real + d loss fake)
   return [d loss, d loss real, d loss fake]
# method to train generator(
def train generator(batch size):
   valid = np.ones((batch size,1))
   noise = np.random.normal(0, 1, (batch_size, 100))
   return model.train on batch(noise, valid)
# Method to save images by generator in drive
def save_imgs(epoch):
   r, c = 6, 6
    noise = np.random.normal(0, 1, (r * c, 100))
   #generate fake image
    gen imgs = generator.predict(noise)
   fig, axs = plt.subplots(r, c)
   cnt1 = 0
    cnt2 = 0
   #save grey images
    for i in range(r):
        for j in range(c):
            axs[i,j].imshow(gen imgs[cnt1, :,:,0], cmap='gray')
            axs[i,j].axis('off')
            cnt1 += 1
    fig.savefig("/content/drive/MyDrive/celeb a predict img/celeb a grey %d.png" %
    #save color images
    for i in range(r):
        for j in range(c):
            axs[i,j].imshow(gen imgs[cnt2, :,:,0])
            axs[i,j].axis('off')
            cnt2 += 1
    fig.savefig("/content/drive/MyDrive/celeb a predict img/celeb a color %d.png" %
    plt.close()
import warnings
warnings.filterwarnings("ignore");
epoch = 0
d losses = []
g losses = []
data gen = ImageDataGenerator(preprocessing function=lambda x: (x.astype('float32')
for e in range(7000):
   print('Epoch', e)
   batches = 0
```

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for x_batch in data_gen.flow(x_train, batch_size=64):
    batches += 1
    if batches >= len(x train) / 64:
        break
    d_loss = train_discriminator(x_batch, 64)
    g loss = train generator(64)
    d losses.append(d loss)
    g losses.append(g loss)
if epoch%20 == 0:
    print ("%d [D loss: (%.3f)(R %.3f, F %.3f)] [G loss: %.3f] " % (epoch, d l
    save imgs(e)
0 [D loss: (0.519)(R 1.037, F 0.002)] [G loss: 16.811]
Epoch 342
0 [D loss: (0.187)(R 0.001, F 0.372)] [G loss: 21.625]
Epoch 343
0 [D loss: (1.345)(R 2.140, F 0.550)] [G loss: 30.689]
Epoch 344
0 [D loss: (0.172)(R 0.089, F 0.256)]
                                      [G loss: 17.526]
Epoch 345
0 [D loss: (0.162)(R 0.083, F 0.240)]
                                       [G loss: 15.959]
Epoch 346
0 [D loss: (0.052)(R 0.080, F 0.024)] [G loss: 18.080]
Epoch 347
0 [D loss: (0.075)(R 0.062, F 0.088)] [G loss: 24.649]
Epoch 348
0 [D loss: (0.542)(R 1.080, F 0.003)] [G loss: 14.694]
Epoch 349
0 [D loss: (0.691)(R 1.029, F 0.354)] [G loss: 14.568]
Epoch 350
0 [D loss: (0.353)(R 0.297, F 0.408)] [G loss: 17.521]
Epoch 351
0 [D loss: (0.393)(R 0.452, F 0.334)]
                                      [G loss: 19.794]
Epoch 352
0 [D loss: (0.333)(R 0.064, F 0.602)]
                                       [G loss: 23.681]
Epoch 353
0 [D loss: (0.013)(R 0.005, F 0.020)] [G loss: 19.736]
Epoch 354
0 [D loss: (0.891)(R 1.358, F 0.424)] [G loss: 16.799]
Epoch 355
0 [D loss: (0.162)(R 0.147, F 0.176)] [G loss: 17.691]
Epoch 356
0 [D loss: (0.001)(R 0.000, F 0.002)] [G loss: 18.371]
Epoch 357
0 [D loss: (0.560)(R 0.201, F 0.919)] [G loss: 24.274]
Epoch 358
0 [D loss: (0.441)(R 0.872, F 0.009)]
                                      [G loss: 15.510]
Epoch 359
0 [D loss: (0.422)(R 0.257, F 0.586)] [G loss: 25.565]
Epoch 360
0 [D loss: (0.745)(R 0.646, F 0.845)] [G loss: 21.630]
Epoch 361
0 [D loss: (0.324)(R 0.401, F 0.247)] [G loss: 19.506]
Epoch 362
0 [D loss: (0.065)(R 0.053, F 0.078)] [G loss: 14.408]
Epoch 363
0 [D loss: (0.048)(R 0.005, F 0.091)] [G loss: 18.793]
Epoch 364
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0 [D loss: (0.247)(R 0.167, F 0.328)] [G loss: 17.751]
Epoch 365
0 [D loss: (0.263)(R 0.198, F 0.327)] [G loss: 15.868]
Epoch 366
0 [D loss: (0.253)(R 0.040, F 0.467)] [G loss: 25.376]
Epoch 367
0 [D loss: (0.657)(R 0.236, F 1.078)] [G loss: 24.840]
Epoch 368
0 [D loss: (0.024)(R 0.006, F 0.042)] [G loss: 21.483]
Epoch 369
0 [D loss: (0.186)(R 0.007, F 0.365)] [G loss: 17.171]
Epoch 370
0 [D loss: (0.656)(R 0.211, F 1.101)] [G loss: 18.639]
```