



Name : Deepak Kumar P Hanakesh

Class/Branch : CSE - 6A

Reg No. : IPE17CS044

Program No. / Experiment No.

Title : DM Assignment

Q1 what is a decision tree? Explain working of hunt's algorithm

Ans. A decision tree is a decision support tool and is a flow chart like tree structure, where each internal node denotes a test on a attribute, each branch represents a test on an attribute and an outcome of test

Hunt's Algorithm

let D_t be the set of training records that reach a node 't'

General Procedure.

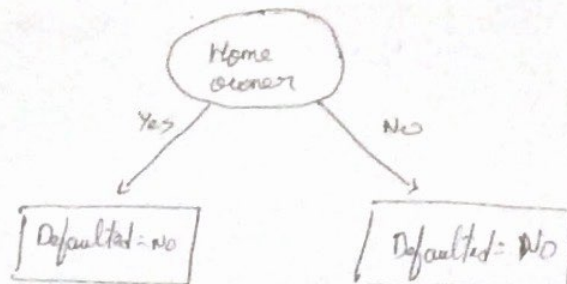
1. If D_t contains records that belong to the same class y_t , then t is a leaf node labelled as y_t
2. If D_t contains records that belong to more than one class, use an attribute test to split the data into smaller subsets. Recursively apply procedure to each subset.

Marks

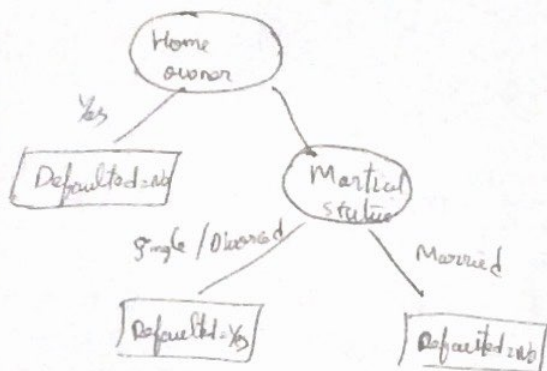
Staff Signature

Defaulted = No

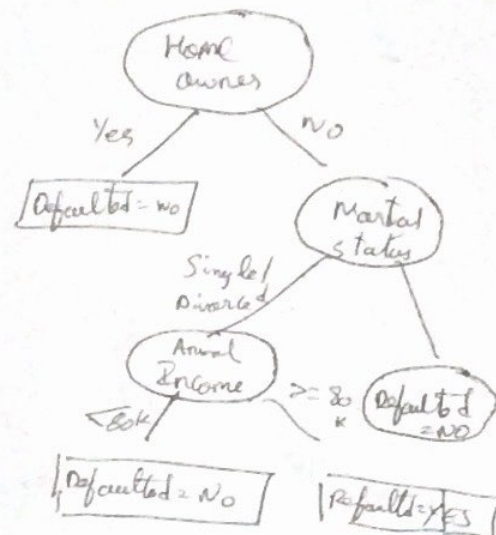
(a)



(b)



(c)



Q2
Ans

Case 1 Based on Home Owner

Defaults = $\frac{7}{10}$ for the class No

= $\frac{3}{10}$ for the class Yes

$$\text{Gini Index} = 1 - \sum_{i=0}^{C-1} [P(i|t)]^2$$

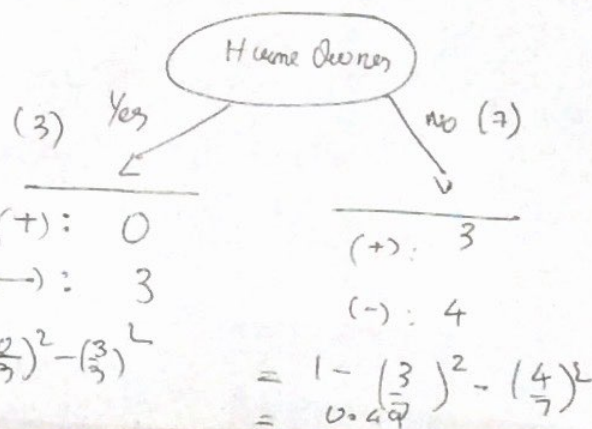
$$= 1 - \left(\frac{7}{10}\right)^2 - \left(\frac{3}{10}\right)^2$$

$$= 0.42$$

∴ Weighted

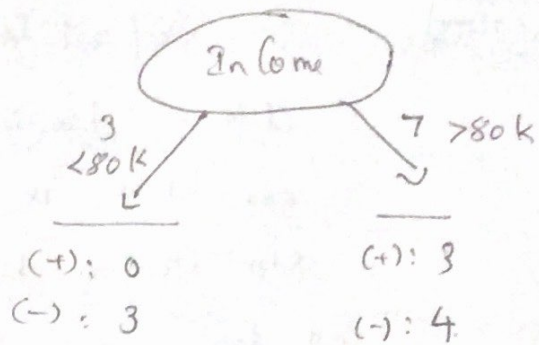
$$\text{Summed Gini} = \frac{3}{10} \times 0 + \frac{7}{10} \times (0.42)$$

$$\text{Summed Gini} = 0.294$$



1PE17S044) Case 2: Annual Income

Defaults: $\frac{7}{10}$ class No
 $\frac{3}{10}$ class Yes



∴ Weighted Summed

$$GI = \left(\frac{7}{10}\right) \times 0.49 + \left(\frac{3}{10}\right) \times 0$$

$$= 0.343$$

$$= 1 - \left(\frac{0}{3}\right)^2 - \left(\frac{3}{3}\right)^2 = 1 - \left(\frac{0}{7}\right)^2 - \left(\frac{4}{7}\right)^2$$

$$= 0.0$$

$$= 0.49$$

Q3 Explain the decision tree induction algorithm with the characteristics in details.

Ans Algorithm: A skeleton decision tree induction algorithm

if TreeGrowth (E, F)

if Stopping-Cond (E, F) = true then

leaf = Create Node()

leaf.label = Classify (E)

return leaf

else

root = Create Node()

root.test-Cond = find-best-split (E, F)

let $V = \{v \mid v \text{ is a possible outcome of root.test-Cond}\}$

for each $v \in V$ do

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$E_v = \{e \mid \text{root.test_end}(e) = v \text{ and } e \in E\}$

child = Tree Growth (E_v, F)

add child as descendant of root and label the edge (root \rightarrow child) as v

end for

end if

return root.

CreateNode(): function extends to the decision tree by creating a new node.

find_best_split(): function determining which attribute should be selected as the test condition for splitting the training set.

classify(): function determines the class label to be assigned to a leaf node.

Characteristics of Decision Tree Induction

1. Decision tree induction is a non parametric approach for building classification models.
2. Finding an optimal decision tree is an NP-Complete problem. Many algorithms a heuristic-based approach to guide the search in the vast hypothesis space.
3. Techniques developed for constructing decision trees are computationally expensive, making it possible to quickly construct

And its worst case is $O(w)$, w is maximum depth of tree.

4. Decision trees, especially smaller-sized trees, are relatively easy to interpret.
5. Decision tree algorithms are quite robust to presence of noise, especially when methods for avoiding overfitting.

Q4 Write a note on Bayesian Network

Ans.

A Bayesian belief network (BBN) or Bayesian network provides a graphical representation of the probabilistic relationship among a set of random variables.

Two key elements of a Bayesian Network:

1. A directed acyclic graph encoding the dependence relationships among a set of variables
2. A probability table associating each node to its immediate parent nodes.

Q5)

a) $P(B = \text{good}, F = \text{empty}, S = \text{yes})$

Sol) Given

$$P(A = \text{empty} \mid B = \text{good}, F = \text{empty}) = 0.8$$

and

$$P(S = \text{yes} \mid B = \text{good}, F = \text{empty}) = 1 \quad P(S = \text{No} \mid B = \text{good}, F = \text{empty})$$

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$$\therefore P(B = \text{good}, F = \text{empty}, G = \text{empty}, S = \text{yes}) = 0.8 \times 0.2 = 0.16$$

or b) $P(B = \text{Bad}, F = \text{empty}, G = \text{not empty}, S = \text{no})$

Sol Given,

$$P(G = \text{not empty} \mid B = \text{bad}, F = \text{empty}) = 1 - P(\text{not empty} \mid \text{bad empty})$$

$$= 1 - 0.9 = 0.1$$

$$P(S = \text{no} \mid B = \text{bad}, F = \text{empty}) = 1.0$$

$$\therefore P(B = \text{bad}, F = \text{empty}, G = \text{not empty}, S = \text{no}) = 1 \times 0.1 = 0.1$$

or c) Given $B = \text{bad}$,
To find, $P(\text{start} = \text{Yes})$

$$\therefore P(S = \text{no} \mid B = \text{bad}) = P(S = \text{no} \mid B = \text{bad}, F = \text{not empty}) \times P(F = \text{not empty})$$

$$+ P(S = \text{no} \mid B = \text{bad}, F = \text{empty}) \times P(F = \text{empty})$$

$$= 0.9 \times 0.8 + 1.0 \times 0.2 = 0.92$$

\therefore The probability that the car will start given battery is bad

$$= 1 - P(S = \text{no} \mid B = \text{bad})$$

$$= 1 - 0.92$$

$$= 0.08$$

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Q6 Explain Rule Based classifier with examples

Ans • A rule based classifier is a technique for classifying records using a collection of "if... then..." rules

- The rules for the model are represented in a disjunctive normal form $R = (r_1 \vee r_2 \vee \dots \vee r_k)$, where R is known as the rule set and r_i 's are the classification rules or disjuncts.

Examples:

r_1 : (Gives Birth = no) \wedge (Aerial Creature = yes) \rightarrow Birds

r_2 : (Gives Birth = no) \wedge (Aquatic Creature = yes) \rightarrow Fishes

r_3 : (Gives Birth = yes) \wedge (Body Temperature =
 warm -
 Blooded) \rightarrow Mammals

r_4 : (Gives Birth = no) \wedge (Aerial Creature = no) \rightarrow Reptiles

r_5 : (Aquatic Creature = semi) \rightarrow Amphibians.

Each classification rule can be expressed as

r_i : (condition i) $\rightarrow y_i$

The LHS of rule is rule antecedent or precondition

07 What are ¹⁰⁵¹⁷⁵⁰⁴⁴ different characteristics of lazy learners. Explain any one in details with a practical application.

Characteristics

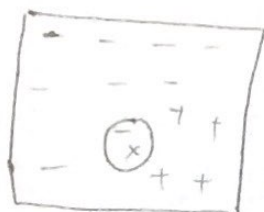
- Lazy learners such as nearest neighbor classifiers do not require model building. However, classifying a test example can be quite expensive because we need to compute the proximity values individually between the test and training examples.
- Nearest-neighbor classifiers make their predictions on local information, eager learners like decision trees and rule based classifiers attempt to find a global model that fits the model space.
- nearest neighbor classifiers can produce arbitrarily shaped decision boundaries, such boundaries provide a more flexible model representation compared to decision tree. These boundaries of nearest neighbor classifier also have high variability because they depend on composition of training examples.
- Nearest neighbor classifiers can produce wrong predictions unless appropriate proximity measure and data preprocessing steps are taken.

Example: Suppose we want to classify a group of people based on attributes such as height and weight. The height attribute has a low variability, ranging from 1.5 m to 1.85 m, whereas weight attribute may vary from 90 lb to 250 lb. If the scale of attributes are not taken into consideration, the proximity measure may be dominated by differences in the weights of a person.

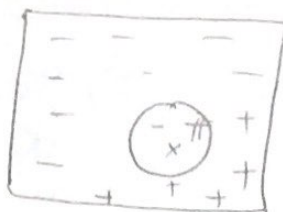
Q8 What is KNN? Explain with example. may only vote & weighted vote

The K-nearest neighbors of a given example x refer to the K points that are closest to x .

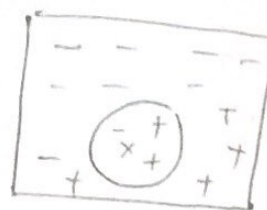
Eg:



1 - nearest neighbor



2 - nearest neighbor



3 - nearest neighbor

K-NN of a record x are data point from its nearest neighbor list, and compute distance between two points.

$$d(p, q) = \sqrt{\sum_i (p_i - q_i)^2}$$

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Once the nearest Neighbor list is obtained, test example is classified based on majority class of its nearest neighbors.

$$\text{Majority Voting, } y' = \underset{v}{\operatorname{argmax}} \sum_{(x_i, y_i) \in D_z} I(v = y_i)$$

where v is class label

y_i is class label for one of the nearest neighbors

$I()$ - indicator function that returns 1 if argument is true otherwise false.

Using distance-weighted voting scheme, the class label can be determined as

Distance-Weighted Voting,

$$y' = \underset{v}{\operatorname{argmax}} \cdot \sum_{(x_i, y_i) \in D_z} w_i \times I(v = y_i)$$

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Record	A	B	C	Class
1	0	0	0	T
2	0	0	1	-
3	0	1	1	-
4	0	1	1	-
5	0	0	1	+
6	1	0	1	+
7	1	0	1	-
8	1	0	1	-
9	1	1	1	+
10	1	0	1	+

Estimate the
Conditional Probabilities
 $P(A|+)$ $P(A|-)$
 $P(B|+)$ $P(B|-)$
 $P(C|+)$ $P(C|-)$

Ans,

$$P(A) = 5/10$$

$$P(\bar{A}) = 5/10$$

$$P(B) = 3/10$$

$$P(\bar{B}) = 7/10$$

$$P(C) = 9/10$$

$$P(\bar{C}) = 1/10$$

We know that,

$$P(A|B) = \frac{P(A, B)}{P(B)} = \frac{P(A \cap B)}{P(B)}$$

$$P(A|+) = \frac{P(A, +)}{P(+)} = \frac{3/10}{5/10} = \frac{3}{5} = 0.6$$

$$P(B|+) = \frac{P(B, +)}{P(+)} = \frac{1/10}{5/10} = 0.2$$

$$P(C|+) = \frac{P(C, +)}{P(+)} = \frac{4/10}{5/10} = \frac{4}{5} = 0.8$$

$$P(A|-) = \frac{P(A, -)}{P(-)} = \frac{2/10}{5/10} = \frac{2}{5} = 0.4$$

$$P(B|-) = \frac{P(B, -)}{P(-)} = \frac{2/10}{5/10} = \frac{2}{5} = 0.4$$

$$P(C|-) = \frac{P(C, -)}{P(-)} = \frac{5/10}{1/10} = \frac{5}{1} = 1.0$$

10) Explain rule ordering schemes in details.

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Sol

Rule Ordering:

After generating the rule set, C4.5 rules uses the class-based ordering scheme to order the extracted rules that predict the same class are grouped together into the same subset. The total description length for each subset is computed and the classes are arranged in increasing order of their total description. The class that has smallest description length is given the highest priority because it is expected to contain the best set of rules.

• The total description length for a class is given by $L_{\text{exception}} + g \times L_{\text{model}}$.

→ $L_{\text{exception}}$ is no. of bits needed to encode the misclassified examples.

→ L_{model} is no. of bits needed to encode the model.

→ g is tuning parameter with default = 0.5

The value of the tuning parameter is small if the model contains many redundant attributes.