Participant #:		Task:	Session #:		Date: //_	
		Post Ta	sk Questi	onnaire		
	-	-		mpleting each ovided stateme		circle the
Task Difficu	ılt <u>y</u>					
It was easy f	or me to con	nplete this tas	k.			
1	2	3	4	5	6	7
Strongly Disagree	Disagree	Somewhat Disagree	Neutral	Somewhat Agree	Agree	Strongly Agree
I am not fatig	gued from co	ompleting this	task.			
1	2	3	4	5	6	7
Strongly Disagree	Disagree	Somewhat Disagree	Neutral	Somewhat Agree	Agree	Strongly Agree
Interaction	with Robot					
The robot wa	as easy for m	ne to operate.				
1	2	3	4	5	6	7
Strongly Disagree	Disagree	Somewhat Disagree	Neutral	Somewhat Agree	Agree	Strongly Agree
It was easy f	or me to issu	ie my intende	d command	s.		
1	2	3	4	5	6	7
Strongly Disagree	Disagree	Somewhat Disagree	Neutral	Somewhat Agree	Agree	Strongly Agree
I had to think	about how	to accomplish	the task us	ing the robot.		
1	2	3	4	5	6	7
Strongly Disagree	Disagree	Somewhat Disagree	Neutral	Somewhat Agree	Agree	Strongly Agree
I had a clear	view of the	objects in the	testing envi	ronment.		
1	2	3	4	5	6	7
Strongly	Disagree	Somewhat	Neutral	Somewhat	Agree	Strongly

	Agree						
Robot Assistance: The robot assistance was present during this task. True False							
The autonomous assistance helped me complete the task.							
1 2 3 4 5 6	7						
Strongly Disagree Somewhat Neutral Somewhat Agree Disagree Disagree Agree	Strongly Agree						
I preferred doing the task with assistance.							
1 2 3 4 5 6	7						
Strongly Disagree Somewhat Neutral Somewhat Agree Disagree Disagree Agree	Strongly Agree						
If you would have liked assistance at any time during task execution, please de when and what type of assistance you would have preferred:	escribe						
Learning affects:							
I feel proficient in controlling the robot using this interface.							
1 2 3 4 5 6	7						
Strongly Disagree Somewhat Neutral Somewhat Agree Disagree Disagree Agree	Strongly Agree						
I feel proficient in controlling the robot with this control operational mode.							
1 2 3 4 5 6							
	7						