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1. Write a MATLAB function program $[\mathbb{Q}, \mathbb{R}] = \mathsf{cgs}(\mathbb{V})$ to orthonormalize the columns of an $n \times m$ matrix V, $(n \geq m)$ by the Classical Gram Schmidt procedure so that Q is the isometry satisfying

$$span{Q(:,1)} = span{V(:,1)}
span{Q(:,1), Q(:,2)} = span{V(:,1), V(:,2)},
:
span{Q(:,1), Q(:,2), ..., Q(:,m)} = span{V(:,1), V(:,2), ..., V(:,m)}$$

and R is an upper triangular matrix such that $R(i,j) = \langle V(:,j), Q(:,i) \rangle$.

- 2. A slight modification of the above program leads to the Modified Gram Schmidt procedure for orthonormalizing the columns of V. Perform this modification to obtain another function program $[\mathbb{Q}, \mathbb{R}] = \mathtt{mgs}(\mathbb{V})$.
- 3. Write a function program [Q, R] = cgsrep(V) that performs Classified Gram Schmidt with reorthogonalization by making appropriate changes to your function program cgs.
 Take care to replace for loops by matrix-vector multiplications as far as possible in each of the above programs.
- 4. The purpose of this exercise is to solve the Least-Squares Problem (in short, LSP) Ax = b by different methods and compare the solutions. Here $A \in \mathbb{R}^{n \times m}$ and $b \in \mathbb{R}^n$, and usually n is much bigger than m.

Origin: Suppose that we have a data set (t_i, b_i) , for i = 1 : m, that have been obtained from some experiment. These data are governed by some unknown laws. So, the task is to come up with a model that best fits these data. A model is generated by a few functions, called model functions, ϕ_1, \ldots, ϕ_n . Therefore once a model is chosen, the task is to find a function p from the span of the model functions that best fits the data.

Suppose that the model functions ϕ_1, \ldots, ϕ_n are given. For $p \in \text{span}(\phi_1, \ldots, \phi_n)$, we have $p = x_1\phi_1 + \cdots + x_n\phi_n$ for some $x_j \in \mathbb{R}$. Now, forcing p to pass through the data (t_i, b_i) for i = 1 : m, we have $p(t_i) = b_i + r_i$, where r_i is the error. We want to choose that p for which the sum of the squares of the errors r_i is the smallest, that is, $\sum_{i=1}^m |r_i|^2$ is minimized.

Now $p(t_i) = b_i + r_i$ gives $x_1 \phi_1(t_i) + \cdots + x_n \phi_n(t_i) = b_i + r_i$. Thus in matrix notation,

$$\begin{bmatrix} \phi_1(t_1) & \cdots & \phi_n(t_1) \\ \phi_1(t_2) & \cdots & \phi_n(t_2) \\ \vdots & \cdots & \vdots \\ \phi_1(t_m) & \cdots & \phi_n(t_m) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix} + \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_m \end{bmatrix}.$$

This is of the form Ax = b + r and we have to choose $x \in \mathbb{R}^n$ for which the 2-norm of the residual vector $||r||_2$, is minimized. We write this as LSP Ax = b.

Your task is to find the polynomial of degree 19 that best fits the function $f(t) = \sin(\frac{\pi}{5}t) + \frac{t}{5}$ for $t_1 = -5, t_2 = -4.5, \dots, t_{23} = 6$. Set up the LSP Ax = b and determine the polynomial p whose coefficients are determined by x in three different ways:

- (a) By using the Matlab command
 >> A \ b
 This uses QR factorization to solve the LSP Ax = b. Call this polynomial p₁.
- (b) By setting up the normal equation $A^TAx = A^Tb$ and solving them for x. You will need to use the Cholesky method for this. Call this polynomial p_2 .
- (c) By solving the argumented system $\begin{bmatrix} I_n & A \\ A^T & 0 \end{bmatrix} \begin{bmatrix} -r \\ x \end{bmatrix} = \begin{bmatrix} b \\ 0 \end{bmatrix}$. Call this polynomial p_3 .

Set the formatting to format long e and compute the condition number of the coefficient matrix associated with each of the systems that you are solving. Which one is the most ill conditioned?

Compute the $||r||_2$ which gives the value of $\sqrt{\sum_{i=1}^{23} |p_j(t_i) - f(t_i)|^2} j = 1, 2, 3$ for each of these methods (again in format long e.). This is a measure of the goodness of the fit in each case. Which of the methods provide the best fit?