

**Your Ultimate Guide To Landing  
Top AI roles**



2.16.1

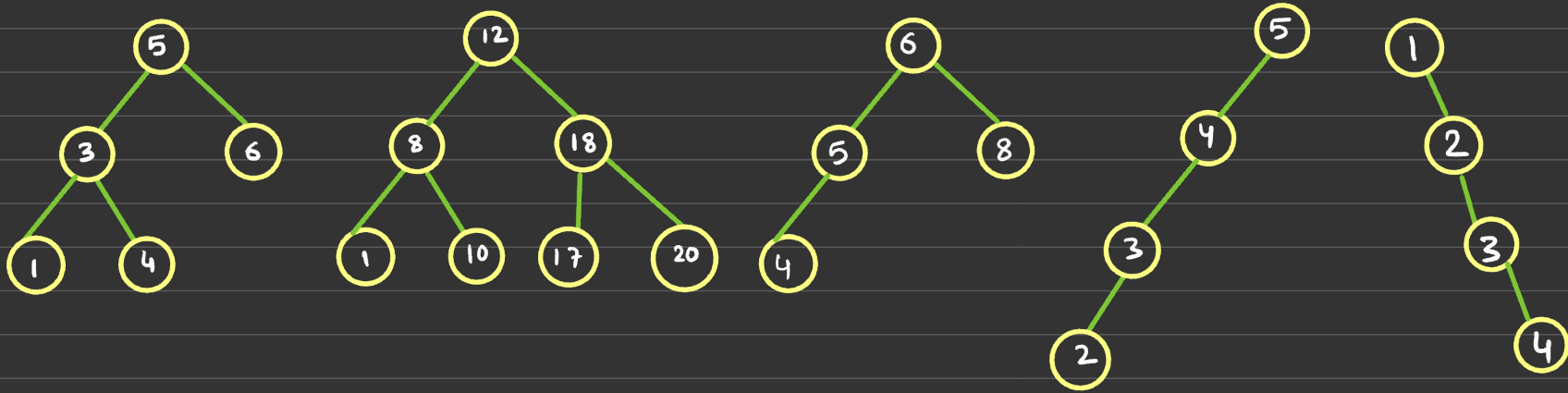
# Binary Search Tree

DECODE  
AimL

→ A binary Search Tree (BST) is a binary tree such that

- ① all left subtree elements should be less than root data
- ② all right subtree elements should be greater than root data.

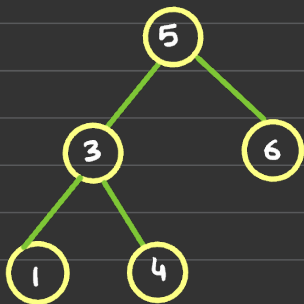
→ This property should be satisfied at every node in the tree.



## Properties of BST

- If we perform Inorder Traversal of a BST, it will get all the elements in increasing order
- In a BST, leftmost element will be the least and rightmost element will be the greatest element.
- No of BST possible with  $n$  distinct keys

$$\# \text{ BST} = \frac{{}^{2n}C_n}{n+1}$$



Inorder: 1, 3, 4, 5, 6

# BST Implementation in Python



```
Class TreeNode:  
    def __init__(self, value):  
        self.value = value  
        self.left = None  
        self.right = None
```



Node structure

## key operations in a BST

### ① Insertion

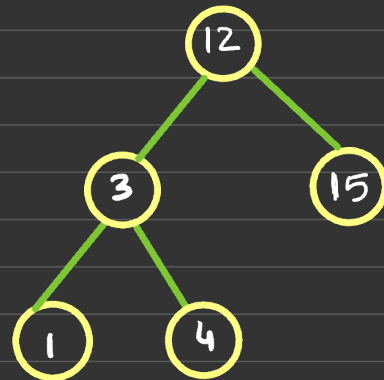
→ Insert a key in a BST

### ② Search

→ Search for a key in a BST

### ③ Deletion

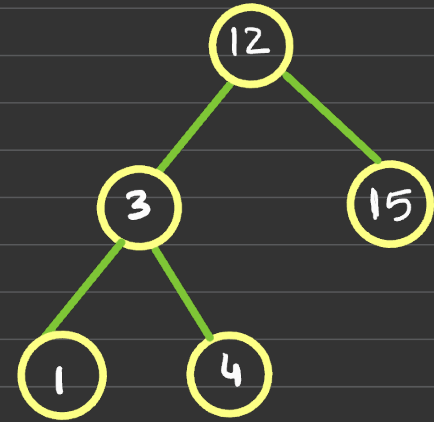
→ Delete a key in a BST



## Search in a BST

```
def search(root, key):
    if root is None:
        return root
    if root.key == key:
        return root
    if key > root.key:
        return search(root.right, key)
    return search(root.left, key)
```

→ Search Key → 4



### \* Time & Space Complexity

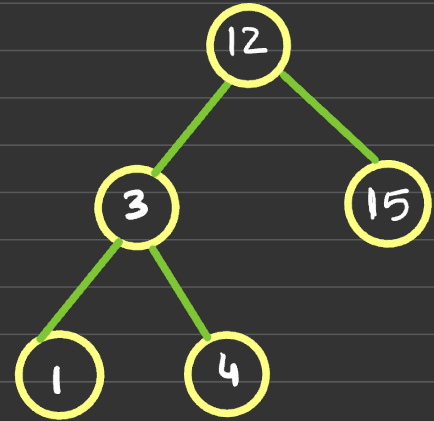
Time Complexity =  $O(n)$

Space Complexity =  $O(n)$

## Insertion in a BST

```
def insert(root, key):
    if root is None:
        return Node(key)
    if key < root.key:
        root.left = insert(root.left, key)
    elif key > root.key:
        root.right = insert(root.right, key)
    return root
```

→ Insert key → 8



### \* Time & Space Complexity

Time Complexity =  $O(n)$

Space Complexity =  $O(n)$

## Deletion in a BST

→ When deleting a node, there are 3 cases

① Node has no children (leaf node)

→ Just remove it

② Node has 1 child

→ Replace the node with its child

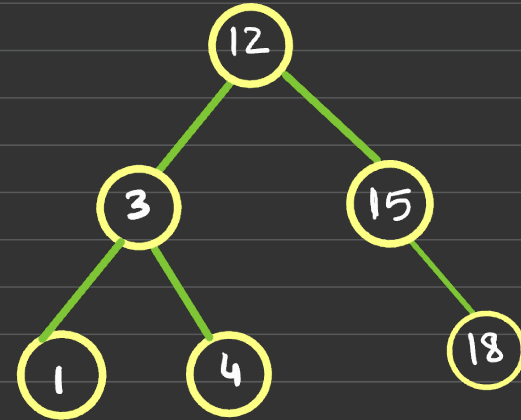
③ Node has 2 children

→ Find the inorder Successor (smallest node in right subtree)  
or inorder predecessor (largest in left subtree)

→ Swap the value with the target Node.

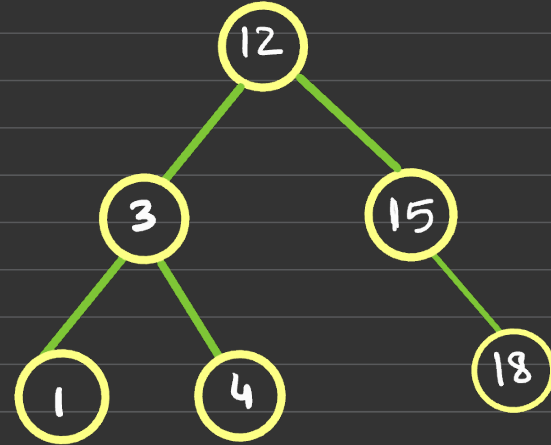
→ Delete that Successor/Predecessor.

→ Delete key → 18



## Deletion in a BST

```
def deleteNode(root, key):
    if root is None:
        return root
    if key < root.key:
        root.left = deleteNode(root.left, key)
    elif key > root.key:
        root.right = deleteNode(root.right, key)
    else: # node found
        if root.left == None:
            return root.right
        elif root.right == None:
            return root.left
        # Case I or II
        temp = inorderPredecessor(root.left)
        root.key = temp.key
        root.left = deleteNode(root.left, temp.key)
        # Case III
    return root
```





## \* Time & Space Complexity

Time Complexity =  $O(n)$

Space Complexity =  $O(n)$

## Binary Tree Vs Binary search Tree

→ If Tree is balanced. means height  $(h) = \log n$ .

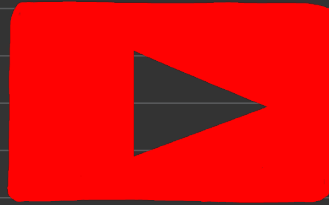
	Binary Tree	BST
Insert	$O(\log n)$	$\log(n)$
Search	$O(n)$	$\log(n)$
Delete	$O(\log n)$	$\log(n)$

Next Lecture

↳ AVL Tree



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