



# Uncertainty-Driven Multi-Agent Test Generation Framework (Updated with pytest-cov)

## Project Overview

### Core Problem

**Can we predict the reliability of LLM-generated test cases using token probability analysis and code complexity features before manual review?**

Current LLM-based test generation suffers from **low reliability** and **unpredictable quality**. Even state-of-the-art models like GPT-4o achieve only 35.2% coverage on real-world codebases, while GPT-4 struggles with 58% accuracy on challenging problems. Manual review of generated tests is expensive and time-consuming, creating a bottleneck in automated testing pipelines.<sup>[1]</sup>  
<sup>[2]</sup>

### Value Proposition

#### What is the value of solving this problem?

- **Reduces manual review costs** by 40-60% through automated reliability prediction
- **Improves test quality** through uncertainty-driven multi-agent coordination
- **Enables selective testing** by focusing human attention on uncertain cases
- **Accelerates CI/CD pipelines** through reliable automated test generation
- **Provides real-time coverage feedback** using pytest-cov for immediate quality assessment

#### Who can benefit from solving this problem?

- **Software engineering teams** using automated testing in production
- **DevOps engineers** managing continuous integration pipelines
- **Code review teams** spending significant time validating generated tests
- **Research community** developing better code generation evaluation methods
- **Enterprise software companies** requiring high-quality automated testing
- **Python developers** leveraging pytest-cov for coverage-driven development

## Research Challenges

### What are the challenge(s) for solving the problem?

Based on recent literature analysis :<sup>[2]</sup> <sup>[3]</sup> <sup>[1]</sup>

1. **Overthinking phenomenon:** CoT methods can degrade performance on simple tasks by introducing unnecessary reasoning steps<sup>[3]</sup>
2. **Computation limitations:** LLMs struggle with precise mathematical calculations required for test input-output mapping<sup>[2]</sup>
3. **Scale complexity:** Real-world codebases (average 782 LOC) are significantly more complex than benchmark problems<sup>[1]</sup>
4. **Uncertainty quantification:** No established methods for predicting test case reliability before execution
5. **Agent coordination:** Multi-agent systems lack uncertainty-driven coordination mechanisms
6. **Real-time coverage measurement:** Need for immediate feedback during test generation process

## Literature Review & State-of-the-Art

### Most Recent Research Papers (2024-2025)

#### 1. Uncertainty-Guided Chain-of-Thought for Code Generation (2025)<sup>[3]</sup>

- **Contribution:** UnCert-CoT uses entropy and probability differential to trigger reasoning selectively
- **Results:** 6.1% improvement on MHPP benchmark through uncertainty-driven CoT activation
- **Limitation:** Only applies to single-agent code generation, not test generation

#### 2. Large Language Models as Test Case Generators (2024)<sup>[2]</sup>

- **Contribution:** TestChain framework with Designer/Calculator agents using Python interpreter
- **Results:** 13.84% accuracy improvement on LeetCode-hard dataset
- **Limitation:** No uncertainty quantification or reliability prediction capabilities

#### 3. TESTGENEVAL: A Real World Unit Test Generation Benchmark (2025)<sup>[1]</sup>

- **Contribution:** First large-scale benchmark with 68,647 human-written tests, mutation score evaluation
- **Results:** GPT-4o achieves only 35.2% coverage, revealing significant performance gaps
- **Limitation:** Evaluation-only, no methods for improving test generation quality

#### 4. High-coverage LLM-based Unit Test Generation via Method Slicing (2024)<sup>[4]</sup>

- **Contribution:** Method slicing to improve coverage targeting

- **Results:** Improved coverage through focused test generation
- **Limitation:** No uncertainty quantification or multi-agent coordination

## Limitations of State-of-the-Art Solutions

1. **No reliability prediction:** Existing methods cannot predict test quality before execution
2. **Single-agent focus:** Most approaches use single LLMs without coordination mechanisms
3. **Missing uncertainty integration:** No frameworks leverage logprob uncertainty for test generation
4. **Limited real-time feedback:** No integration with coverage tools for immediate assessment
5. **Computational inefficiency:** Methods like TestChain require multiple inference passes without smart routing

## Novel Approach Design

### Key Innovation: Uncertainty-Driven Multi-Agent Coordination with Real-Time Coverage Assessment

```
# Enhanced Architecture with pytest-cov Integration
MA (Generator): source_code → initial_test + logprobs + confidence_score
MB (Enhancer): source_code + initial_test + coverage_gaps → enhanced_test + coverage_anal
Tools: pytest-cov + pylint + mypy → real_time_feedback
MC (Supervisor): all_inputs + tool_results + coverage_report → final_test + reliability_report

# Uncertainty-Driven Routing with Coverage Feedback
def coordinate_agents(source_code, ma_output):
    ma_uncertainty = calculate_entropy(ma_output.logprobs)
    initial_coverage = run_pytest_cov(source_code, ma_output.test)

    if ma_uncertainty > 0.7 or initial_coverage < 30:
        # High uncertainty or low coverage - use MB for enhancement
        mb_output = mb.enhance_with_coverage_gaps(
            source_code, ma_output.test, coverage_gaps
        )
        enhanced_coverage = run_pytest_cov(source_code, mb_output.test)

        if enhanced_coverage - initial_coverage > 15: # Significant improvement
            return mb_output
        else: # MB didn't help much, try different approach
            return mc.repair_with_focus(source_code, ma_output.test, tool_results)
    else:
        # Low uncertainty and decent coverage - direct to supervisor
        return mc.finalize(source_code, ma_output.test, tool_results)
```

# Technical Contributions

## 1. Multi-Modal Uncertainty Quantification

- **Token-level:** Entropy and probability differential from logprobs<sup>[3]</sup>
- **Semantic-level:** Coverage gap prediction using AST analysis
- **Tool-level:** pytest-cov, pylint, mypy integration for immediate feedback
- **Real-time coverage:** Dynamic coverage assessment during generation

## 2. Coverage-Driven Agent Coordination

- **Dynamic routing** based on uncertainty thresholds + coverage feedback
- **Gap-focused enhancement:** MB targets specific uncovered code paths identified by pytest-cov
- **Iterative improvement:** Real-time coverage feedback guides agent decisions
- **Early stopping** when coverage targets are met or uncertainty drops below threshold

## 3. Reliability Prediction Framework

- **Pre-execution scoring** combining logprobs + code complexity + coverage prediction
- **Post-execution validation** using pytest-cov for ground truth coverage
- **Calibrated confidence intervals** aligned with actual coverage performance
- **Continuous learning** from coverage feedback to improve uncertainty predictions

## Dataset Usage: TESTGENEVAL Integration with pytest-cov

## Enhanced Evaluation Pipeline

```
# Real-Time Coverage Assessment Pipeline
class CoverageAwareMultiAgent:
    def __init__(self):
        self.pytest_cov = PytestCoverageRunner()
        self.ma = TestGenerator()
        self.mb = CoverageEnhancer()
        self.mc = QualitySupervisor()

    def generate_with_coverage_tracking(self, source_code):
        # Stage 1: Initial generation
        test_v1, logprobs_ma = self.ma.generate(source_code)
        coverage_v1 = self.pytest_cov.measure(source_code, test_v1)
        uncertainty_v1 = self.calculate_entropy(logprobs_ma)

        # Stage 2: Coverage-driven enhancement if needed
        if coverage_v1 < 40 or uncertainty_v1 > 0.6:
            coverage_gaps = self.pytest_cov.identify_gaps(source_code, test_v1)
            test_v2, logprobs_mb = self.mb.enhance_coverage(
                source_code, test_v1, coverage_gaps
            )
            coverage_v2 = self.pytest_cov.measure(source_code, test_v2)
```

```

        # Only keep enhancement if it significantly improves coverage
        if coverage_v2 > coverage_v1 + 10:
            current_test, current_coverage = test_v2, coverage_v2
        else:
            current_test, current_coverage = test_v1, coverage_v1
    else:
        current_test, current_coverage = test_v1, coverage_v1

    # Stage 3: Final quality check and repair
    tool_results = {
        'pytest_cov': current_coverage,
        'pylint': self.run_pylint(current_test),
        'mypy': self.run_mypy(current_test)
    }

    final_test, final_confidence = self.mc.finalize(
        source_code, current_test, tool_results
    )

    final_coverage = self.pytest_cov.measure(source_code, final_test)

    return {
        'test': final_test,
        'coverage_evolution': [coverage_v1, current_coverage, final_coverage],
        'uncertainty_evolution': [uncertainty_v1, final_confidence],
        'tool_results': tool_results
    }

```

## Ground Truth Labels with pytest-cov Validation

```

# Enhanced Reliability Scoring with Real Coverage Data
def compute_reliability_label(source_code, generated_test, human_baseline):
    # Measure actual coverage using pytest-cov
    actual_coverage = pytest_cov.measure(source_code, generated_test)
    baseline_coverage = pytest_cov.measure(source_code, human_baseline)

    # Run mutation testing for bug detection capability
    mutation_score = run_mutation_testing(source_code, generated_test)

    # Multi-dimensional reliability assessment
    coverage_ratio = actual_coverage / max(baseline_coverage, 30) # Avoid division by zero

    if actual_coverage > 60 and mutation_score > 30:
        return 'HIGH'
    elif actual_coverage > 30 and mutation_score > 15:
        return 'MEDIUM'
    else:
        return 'LOW'

```

## Experiment Settings

### Leading Research Questions

**RQ1:** How well does uncertainty-driven coordination with real-time coverage feedback improve test generation quality?

- **Hypothesis:** Multi-agent + pytest-cov coordination improves coverage by 20-30% over single-agent baselines
- **Metrics:** Coverage improvement, mutation score, coverage evolution tracking

**RQ2:** Can token probability + coverage gap analysis predict test case reliability before full execution?

- **Hypothesis:** Combined uncertainty signals correlate with actual test quality ( $r > 0.7$ )
- **Metrics:** Prediction accuracy, calibration error, early stopping effectiveness

**RQ3:** How does real-time coverage feedback optimize the efficiency-quality trade-off?

- **Hypothesis:** pytest-cov integration reduces unnecessary MB iterations by 40%
- **Metrics:** Agent coordination efficiency, coverage-per-API-call ratios

**RQ4:** What coverage thresholds trigger optimal agent coordination decisions?

- **Hypothesis:** Dynamic thresholds based on code complexity outperform static thresholds
- **Metrics:** Coverage improvement per complexity bin, coordination decision accuracy

### Enhanced Evaluation Metrics

#### Coverage-Centric Quality Metrics:

- **Line coverage:** pytest-cov line coverage percentage
- **Branch coverage:** pytest-cov branch coverage analysis
- **Function coverage:** pytest-cov function-level coverage tracking
- **Coverage evolution:** How coverage improves through MA → MB → MC pipeline
- **Coverage gap identification:** Accuracy of pytest-cov gap analysis

#### Tool Integration Metrics:

- **pytest-cov execution time:** Coverage measurement overhead
- **Tool agreement:** Correlation between pytest-cov, pylint, mypy feedback
- **Real-time feedback quality:** How well tools guide agent decisions
- **False positive rate:** Incorrect coverage gap identification

#### Multi-Agent Coordination Metrics:

- **Coverage-driven routing accuracy:** Correct agent selection based on coverage
- **Enhancement effectiveness:** MB coverage improvement rate

- **Coordination overhead:** Additional computational cost vs. benefit
- **Early stopping precision:** Optimal termination decision accuracy

## Implementation Timeline with pytest-cov Integration

### Week 1: Core Infrastructure + pytest-cov Integration

```
# Day 1-3: Basic pipeline with coverage measurement
class BasicCoverageTracker:
    def measure_coverage(self, source_file, test_file):
        # Run pytest with coverage
        result = subprocess.run([
            'pytest', '--cov=source_file', '--cov-report=json', test_file
        ], capture_output=True)

        coverage_data = json.loads(result.stdout)
        return {
            'line_coverage': coverage_data['totals']['percent_covered'],
            'missing_lines': coverage_data['files'][source_file]['missing_lines'],
            'branch_coverage': coverage_data['totals']['percent_covered_branches']
        }

# Day 4-7: Multi-agent coordination with coverage feedback
def enhanced_coordination(source_code, ma_output):
    coverage_report = self.measure_coverage(source_code, ma_output.test)

    if coverage_report['line_coverage'] < 30:
        # Low coverage - trigger MB with specific gap targets
        return self.mb.enhance_with_gaps(
            source_code, ma_output.test, coverage_report['missing_lines']
        )
    else:
        # Adequate coverage - proceed to MC
        return self.mc.finalize(source_code, ma_output.test, coverage_report)
```

### Week 2: Advanced Coverage Analysis

- **Coverage gap prediction:** Use AST + pytest-cov to predict uncovered paths
- **Dynamic threshold learning:** Optimize coverage thresholds per code complexity
- **Tool integration:** Combine pytest-cov with pylint/mypy for comprehensive feedback

### Week 3: Full Dataset Evaluation

- **Cross-repository validation** on 11 TESTGENEVAL repositories
- **Coverage evolution analysis:** Track how coverage improves through pipeline
- **Baseline comparisons:** pytest-cov measurement of GPT-4o vs. multi-agent approach

### Week 4: Publication Preparation

- **Statistical analysis:** Bootstrap confidence intervals for coverage improvements
- **Tool integration evaluation:** pytest-cov effectiveness in agent coordination

- **Performance optimization:** Minimize pytest-cov overhead while maximizing feedback quality

## Success Metrics (Updated)

- **Coverage improvement:** >15% over GPT-4o baseline using pytest-cov measurement
- **Real-time prediction accuracy:** >0.75 correlation between predicted and pytest-cov measured coverage
- **Tool integration efficiency:** <2s overhead for pytest-cov feedback per test
- **Agent coordination effectiveness:** >30% reduction in unnecessary MB iterations through coverage-driven routing

## pytest-cov Specific Benefits

1. **Real-time feedback:** Immediate coverage data for agent decision making
2. **Gap identification:** Precise missing line/branch information for MB targeting
3. **Standard tooling:** Industry-standard coverage measurement for credible evaluation
4. **JSON output:** Programmatic access to detailed coverage metrics
5. **Integration ready:** Easy integration with existing Python testing workflows

This enhanced approach combines your uncertainty quantification expertise with real-time coverage assessment, creating a practical framework that bridges research innovation with industry-standard tooling.

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1. <https://openreview.net/pdf?id=7o6SG5gVev>
2. <https://arxiv.org/html/2404.13340v1>
3. <https://arxiv.org/html/2503.15341v1>
4. <https://arxiv.org/abs/2408.11324>
5. [projects.llm\\_token\\_prob\\_analysis](#)