Introduction

- OCR Optical Character Recognition
- Technique for converting printed text into machine-encoded text.

Text Image

There exist several methods to design forms with fields to fields may be surrounded by bounding boxes, by light rectangles o methods specify where to write and, therefore, minimize the effect with other parts of the form. These guides can be located on a sit located below the form or they can be printed directly on the feat a separate sheet is much better from the point of view of the quobut requires giving more instructions and, more importantly, rest this type of acquisition is used. Guiding rulers printed on the used for this reason. Light rectangles can be removed more easily whenever the handwritten text touches the rulers. Nevertheless, the taken into account: The best way to print these light rectangles.

There exist several methods to design forms with fields to fields may be surrounded by bounding boxes, by light rectangles of methods specify where to write and, therefore, minimize the effect with other parts of the form. These guides can be located on a sit located below the form or they can be printed directly on the feat separate sheet is much better from the point of view of the quadrature giving more instructions and, more importantly, rest this type of acquisition is used. Guiding rulers printed on the used for this reason. Light rectangles can be removed more easily whenever the handwritten text touches the rulers. Nevertheless, be taken into account: The best way to print these light rectangles.

OCR Output

There exist <u>se-ueral</u> 1nethod11- to design forms with fields to 'fields 1nay be <u>s-urrounded</u> by bounding boxes. by light rectangles o methods specify whe (o write and. therelo re. 11iini1nize the effer with other parts of the Jonn. These guides can be located on a <u>s</u>, is located below the Jonn or they can be printed directly on the f< a separate sheet is 1nuch better fro1n the point of view of the guides but requires giving 1nore 'instructions and. 1nore i1 nportantly, rest this type of a -isitio11 is used. Gitiding rulers printed on the used jdr this Light rectangles can be re1noved 1nore easily whene delication into count: The best juay to print these light rectangles.

There exist several methods to design forms with fields to fields 1nay be surrounded by bounding boxes, by light rectangles o methods specify where to write and. therefore, mini1nize the effe, with other parts of the for1n. These guides can be Located on as, is Located below the form or they can be printed directly on the f< a separate sheet is much better from the point of view of the guc but requires giving 1nore instructions and, 1nore i1nportantly. rest this type of acquisition is used. Guiding rulers printed on the used for this reason. Light rectangles can be removed more easily whenever the handwritten te:it touches the rulers. Nevertheless... be taken into account: The best way to print these light rectangles.

Noisy Image

Clean Image

Objective

Using image processing and machine learning approaches create a predictive algorithm to clean up the noisy images of text

There exist several methods to design forms with fields to fields may be surrounded by bounding boxes, by light rectangles of methods specify where to write and, therefore, minimize the effect with other parts of the form. These guides can be located on a sit located below the form or they can be printed directly on the form a separate sheet is much better from the point of view of the quabut requires giving more instructions and, more importantly, rest this type of acquisition is used. Guiding rulers printed on the used for this reason. Light rectangles can be removed more easily whenever the handwritten text touches the rulers. Nevertheless, the taken into account: The best way to print these light rectangles can be removed.

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Clean Image

Business Use Case

Lot of old and fragile documents can be digitized in a readable format. Will improve OCR technique in accurately converting text image to live text.

Data set



Dirty images

- Grayscale images
- 8 bit images
- Contain Noise

There exist several methods to design forms with fields to fields may be surrounded by bounding boxes, by light rectangles o methods specify where to write and, therefore, minimize the effect with other parts of the form. These guides can be located on a sit located below the form or they can be printed directly on the fect a separate sheet is much better from the point of view of the qualitative form the point of view of the qualitative for this type of acquisition is used. Guiding rulers printed on the used for this reason. Light rectangles can be removed more easily whenever the handwritten text touches the rulers. Nevertheless, the taken into account: The best way to print these light rectangles.

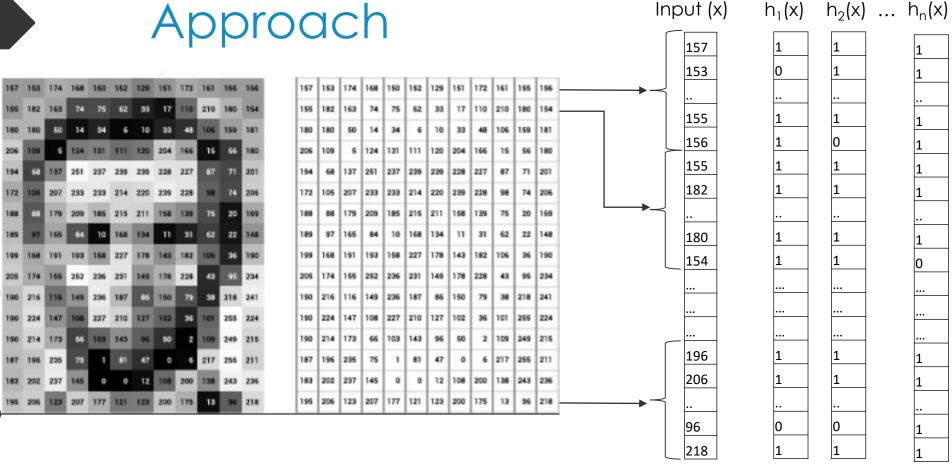


Clean images

- B&W images
- 1 bit images
- No Noise

There exist several methods to design forms with fields to fields may be surrounded by bounding boxes, by light rectangles o methods specify where to write and, therefore, minimize the effewith other parts of the form. These guides can be located on a sis located below the form or they can be printed directly on the few a separate sheet is much better from the point of view of the quabut requires giving more instructions and, more importantly, rest this type of acquisition is used. Guiding rulers printed on the used for this reason. Light rectangles can be removed more easily whenever the handwritten text touches the rulers. Nevertheless, be taken into account: The best way to print these light rectangles.

Approach



Step1: Use image processing techniques to create features – $h_1(x)$, $h_2(x)$...

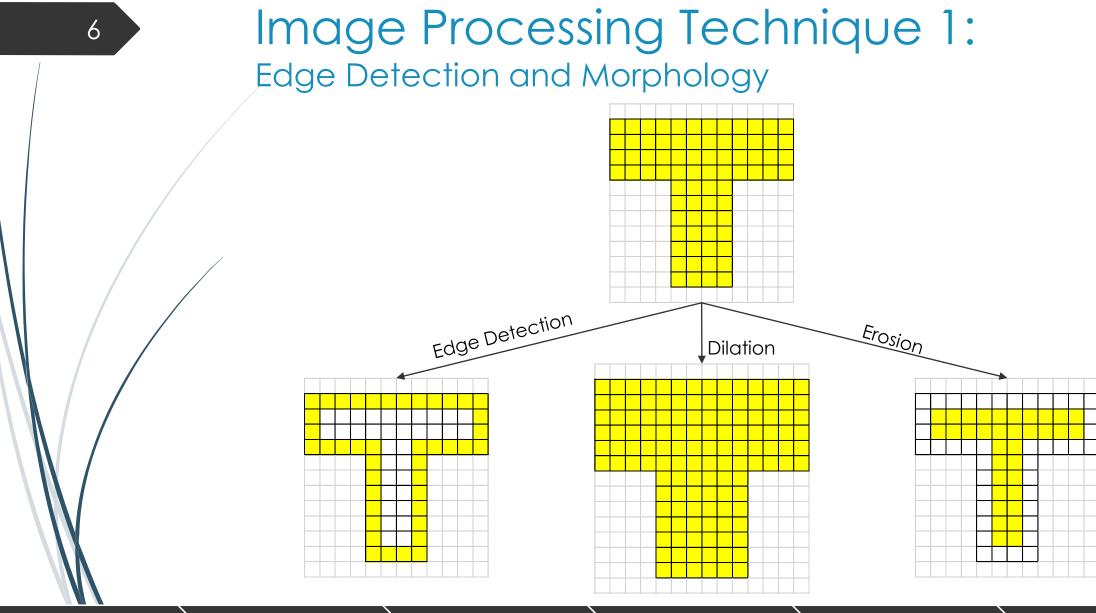
Step 2: Use machine learning techniques to find relationship b/w y and input variables

 $y = f(x, h_1(x), h_2(x), h_n(x)) + e$

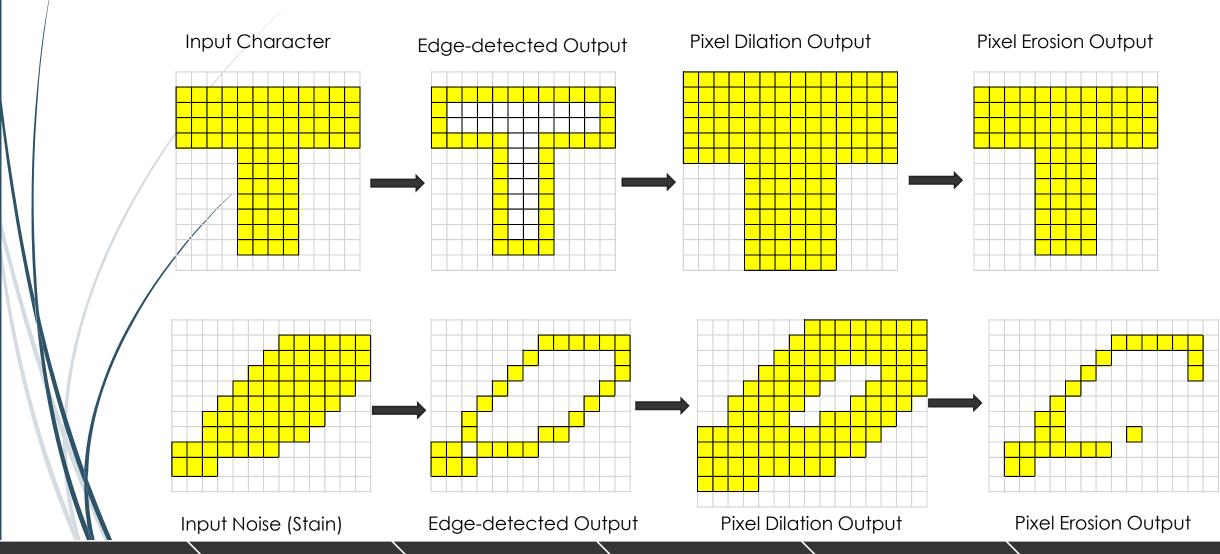
features

Output (y)

Edge Detection and Morphology



Motivation

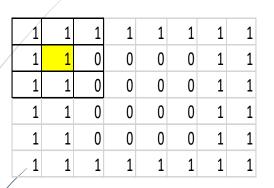


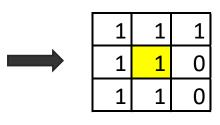
8

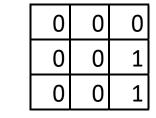
Algorithms Used

- Edge Detection Algorithm
 - Used biOps package
 - imgCanny() function does edge detection using the Canny algorithm
- Pixel Dilation
 - Created a function pixelDilation()
- Pixel Erosion
 - Created a function pixelErosion()

Pixel Dilation Algorithm









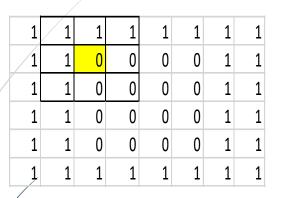


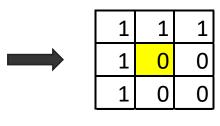
If $Sum > 0 \{ pixel = 0 \}$

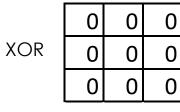


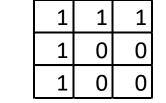
Sum = 2

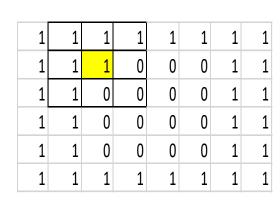
Pixel Erosion Algorithm











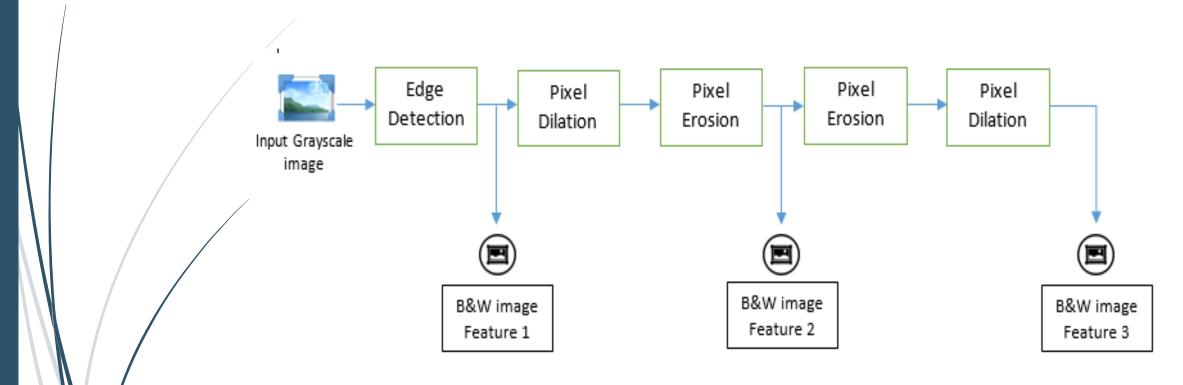
If Sum > 0 { pixel = 1}



Sum = 4

SUM

End-to-End Block Diagram



Adaptive Thresholding

Adaptive Thresholding

- Global thresholding works if background is relatively uniform
- Partition the original image into several sub images and utilize global thresholding techniques for each sub image

Adaptive Thresholding technique	R package (function)
Empirical Bayes thresholding	<u>EbayesThresh</u> (ebayesthresh)
Tree based thresholding	<u>treethresh</u> (treethresh)
wavelet thresholding	<u>treethresh</u> (threshold)
Local adaptive	EBImage (thresh)

Adaptive Thresholding

thresh(x, w=5, h=5, offset=0.01)

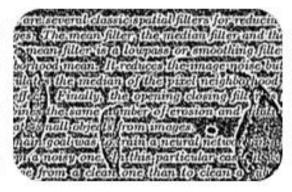
x: Image object,

w, h: width and height of moving rectangular window.

Offset: Thresholding object from the average value

are several classic spatial filters for reducinges. The mean filter, the median filter and the e-mean filter is a lowpass or smoothing filter borhood mean. It reduces the image noise but rulates the median of the pixel neighborhood effect. Finally, the opening closing filter is bines the same number of crosson and challate small objects from images. main goal was to train a neural network in a on a noisy one. In this particular case at a see from a clean one than to clean a see

Original



w=2, h=2

s are several classic spatial filters for reduciniges. The mean filter, the median filter and the
is mean filter is a lowpass or smoothing filter
abbricood mean. It reduces the image noise but
culding the median of the pixel neighborhood
effects. Finally, the opening closing filter is
bines the same effenber of erosion and states
at a mall objects from images.

w = 10, h = 10

Median Filtering



Median Filter Implementation



- Nonlinear digital filtering technique, often used to remove noise
- An image filter that replaces a pixel with the median value of the pixels surrounding it
- This technique wipes out small features, but maintains broad features
- The resultant image is the 'background' of the image

$$\frac{\mathbf{M} \mathbf{E} \mathbf{D} + \mathbf{I} \mathbf{A} \mathbf{N}}{2}$$

2-D Median Filter Algorithm

Consider the following matrix

$$\begin{bmatrix} 5 & 4 & 8 \\ 2 & 1 & 9 \\ 13 & 3 & 11 \end{bmatrix}$$

```
img = matrix(c(5,2,13,4,1,3,8,9,11),nrow=3,ncol = 3)
img
```

 Create an empty output matrix of the same size as that of the input matrix (in this case, a 3*3 matrix) as follows

```
#Create an empty output matrix of the same size as the input image
Y = matrix(0,nrow(img),ncol(img))
Y
```

2-D Median Filter Algorithm

 Pad the input matrix with zeros on all sides (based on the median filter width)

```
k=3 \\ n=floor(k/2) \\ \# Modify the input image matrix by padding 0s outside the input image matrix #to make it size having an additional n rows and n columns <math display="block">img\_modify = matrix(0,nrow(img)+2*n,ncol(img)+2*n) \\ img\_modify
```

 Place the input matrix (img), in the center of this newly created padded matrix as follows

```
#Copy the Original matrix to the zero/padded matrix
row_seq = seq(nrow(img))
col_seq = seq(ncol(img))

for (x in row_seq)
{
   for (y in col_seq)
   {
      img_modify[x+n,y+n] = img[x,y]
   }
}
img_modify
```

2-D Median Filter Algorithm

Consider a window of size 3 by 3 from the input matrix

$$\text{window} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 5 & 4 \\ 0 & 2 & 1 \end{bmatrix}$$

Sort of the window =
$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 2 & 4 & 5 \end{bmatrix}$$
 (Median is 0)

- Extend the algorithm to iterate through all combinations of a 3*3 window and record the output
- Final Output Y

```
> Y

[,1] [,2] [,3]

[1,] 0 2 0

[2,] 2 5 0

[3,] 0 0 0
```

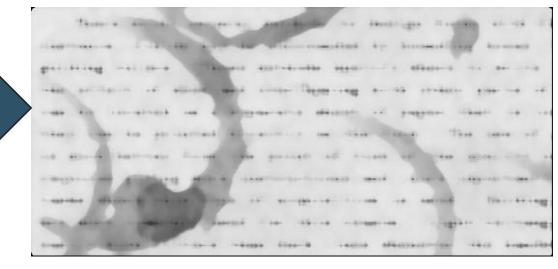
Median Filter – Image Processing

Input Image (with noise) median

There exist several methods to design forms with finstance, fields may be surrounded by bounding boxes, guiding rulers. These methods specify where to write the effect of skew and overlapping with other parts of can be located on a separate sheet of paper that is lotthey can be printed directly on the form. The use of is much better from the point of view of the quality or requires giving more instructions and, more importantly tasks where this type of acquisition is used. Guiding are more commonly used for this reason. Light rectangle easily with filters than dark lines whenever the handward of the surrounded by bounding boxes, is a surr

Background Image (Applying the filter – window size of 9)

Median Filter



Extract the foreground from the background

 Subtract the background from the original image and normalize the output image to have values between [0 1]

```
foreground = img - background
#In this case, we know that the writing is always darker than the background,
#so, our foreground should only show pixels that are darker than background
foreground[foreground > 0] = 0

#Normalizing the final results (pixels) to lie between 0-1
m1 = min(foreground)
m2 = max(foreground)
foreground = (foreground - m1) / (m2 - m1)
```

Processed Image

Input Image (with noise)

There exist several methods to design forms with fi instance, fields may be surrounded by bounding boxes, guiding rulers. These methods specify where to write the effect of skew and overlapping with other parts of can be located on a separate sheet of paper that is lothey can be printed directly on the form. The use of is much better from the point of view of the quality or requires giving more instructions and, more importantly tasks where this type of acquisition is used. Guiding are more commonly used for this reason. Light rectangle easily with filters than dark lines whenever the handwork.

Cleansed Image

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Identifying gaps between lines of text

The image with noise

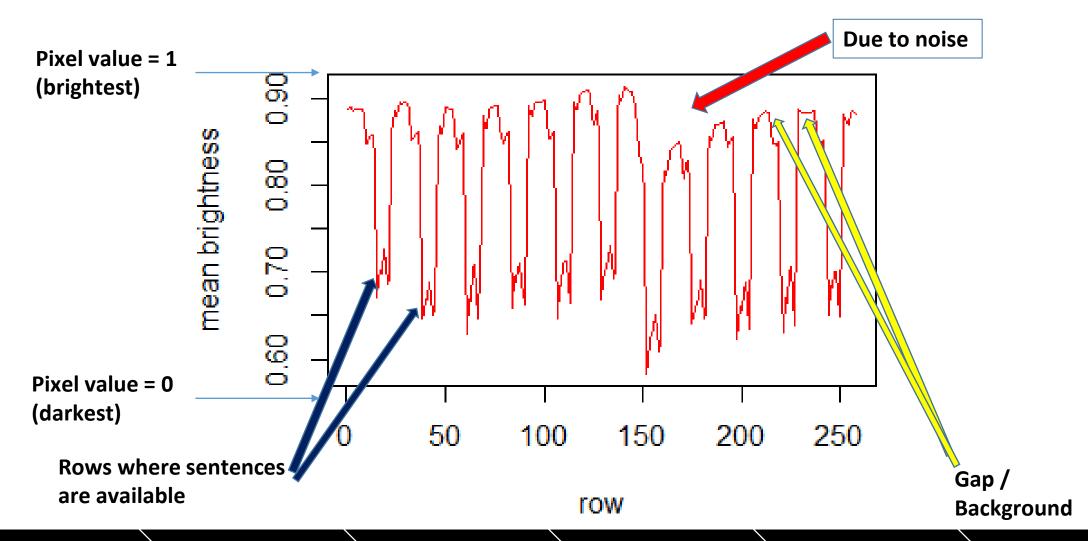
Line of sentence -

Blank spaces

Background

There exist several methods to design forms with fields to fields may be surrounded by bounding boxes, by light rectangles of methods specify where to write and, therefore, minimize the effect with other parts of the form. These guides can be located on a set is located below the form or they can be printed directly on the feat a separate sheet is much better from the point of view of the qualitative during the second part of t

Identifying mean pixel value for each row



Introduction

Edge Detection

Adaptive Thresholdin

Median Filtering

Feature Engineering

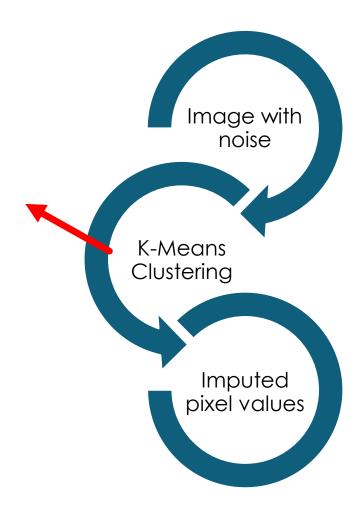
Ensemble

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Approach

K-Means clustering:

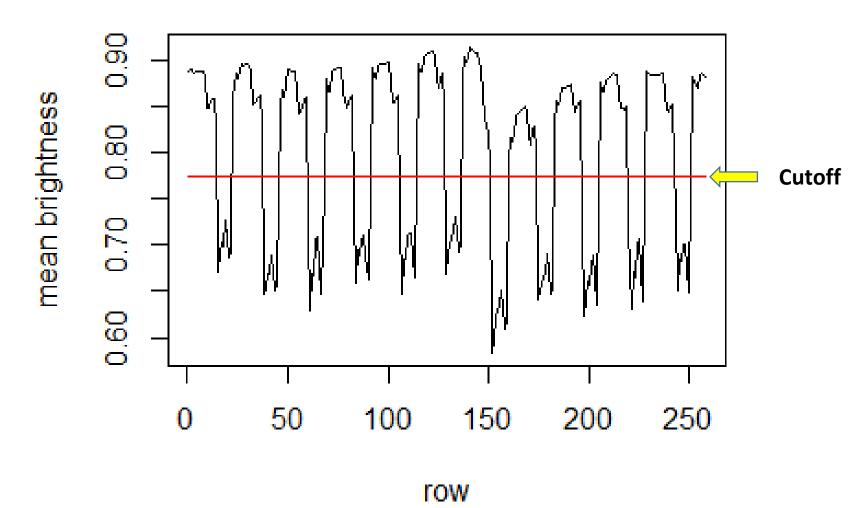
- Cluster size: 2
- Lower cluster: Lower pixel values
- Upper cluster: Higher pixel values



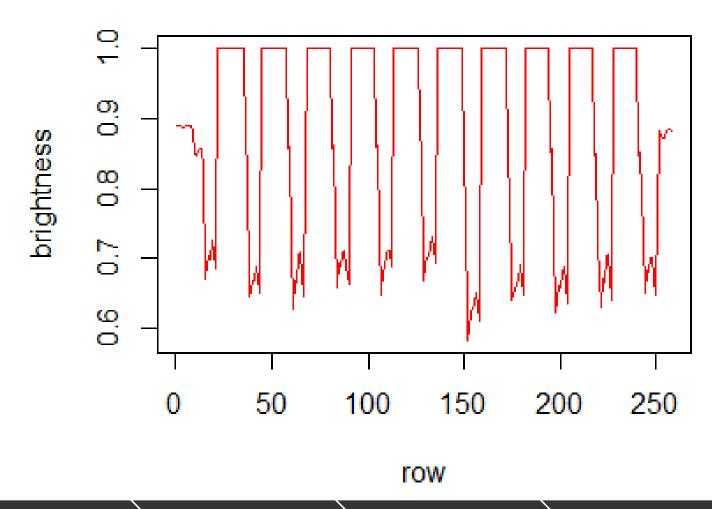
Introduction

Identifying cutoff

Cutoff = Mean of (Highest value of lower cluster)
AND (Lowest value of upper cluster)



Imputing background





Final image

There exist several methods to design forms with fields to fields may be surrounded by bounding boxes, by light rectangles of methods specify where to write and, therefore, minimize the effect with other parts of the form. These guides can be located on a sit is located below the form or they can be printed directly on the feat a separate sheet is much better from the point of view of the quadratures giving more instructions and, more importantly, rest this type of acquisition is used. Guiding rulers printed on the used for this reason. Light rectangles can be removed more easily whenever the handwritten text touches the rulers. Nevertheless, the taken into account: The best way to print these light rectangles.





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Final Image

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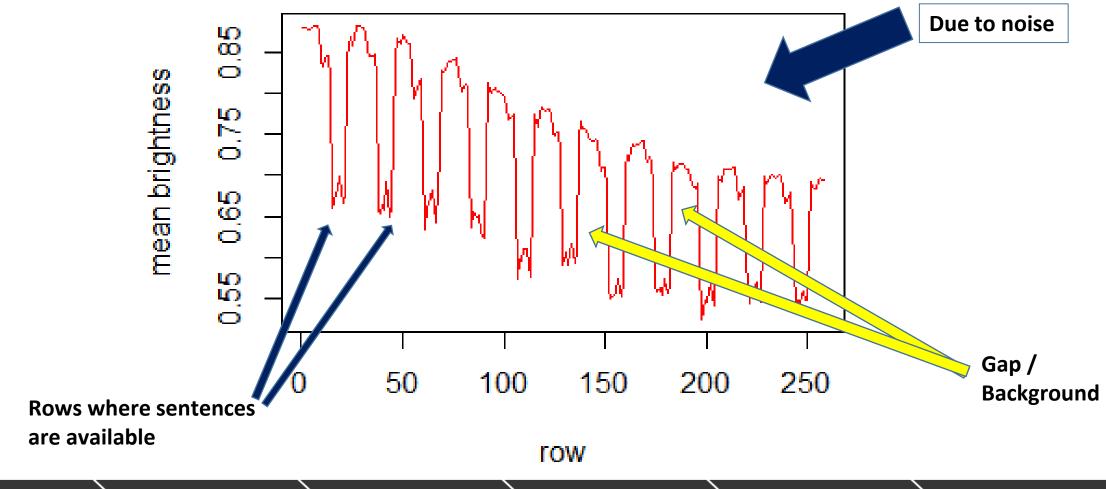
The image with noise

Line of sentence Blank spaces A new offline handwritten database for the Spanish language ish sentences, has recently been developed: the Spartacus database ish Restricted-domain Task of Cursive Script). There were two this corpus. First of all, most databases do not contain Spanish is a widespread major language. Another important reafrom semantic-restricted tasks. These tasks are commonly used use of linguistic knowledge beyond the lexicon level in the recogn

Background

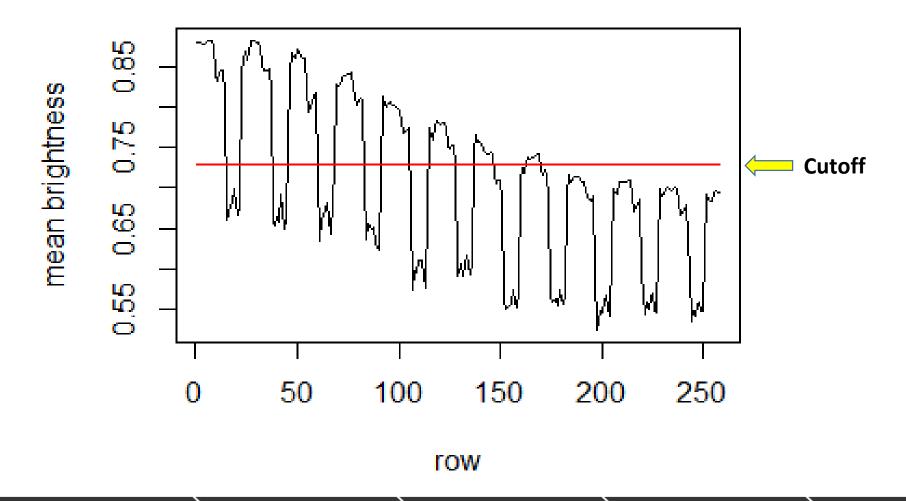
As the Spartacus database consisted mainly of short sentence paragraphs, the writers were asked to copy a set of sentences in f line fields in the forms. Next figure shows one of the forms used These forms also contain a brief set of instructions given to the

Identifying mean pixel value for each row

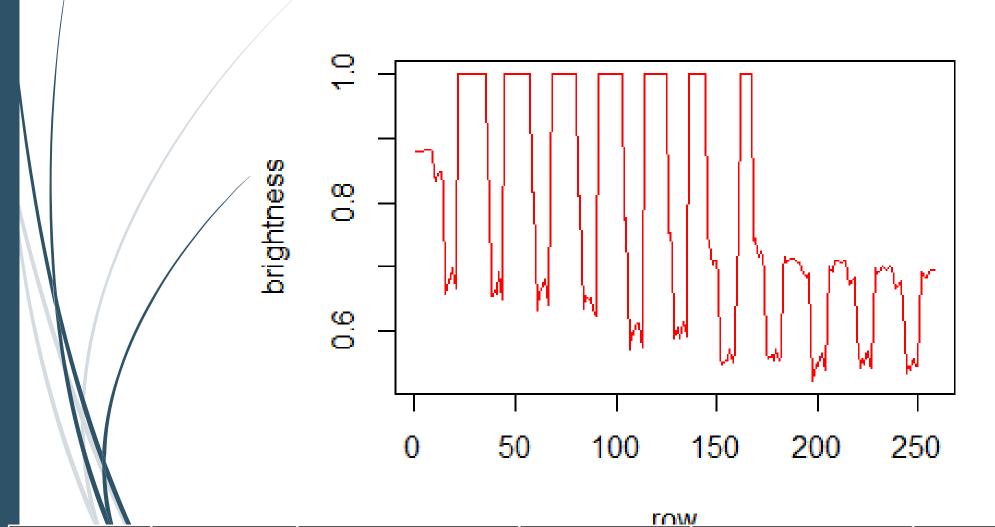


Identifying cutoff

Cutoff = Mean of (Highest value of lower cluster)
AND (Lowest value of upper cluster)



Imputing background



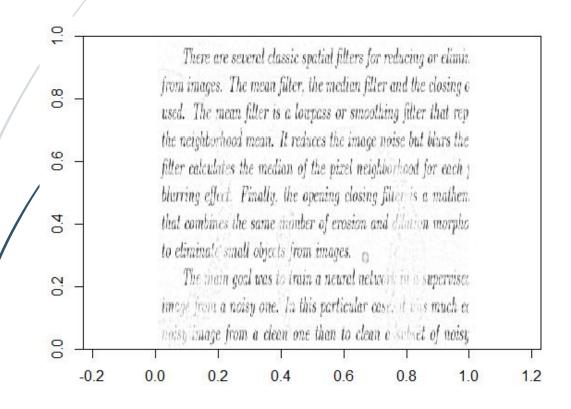
Final Image

A new offline handwritten database for the Spanish language ish sentences, has recently been developed: the Spartacus databases ish Restricted-domain Task of Cursive Script). There were two this corpus. First of all, most databases do not contain Spanish is a widespread major language. Another important real from semantic-restricted tasks. These tasks are commonly used use of linguistic knowledge beyond the legicon level in the recogn

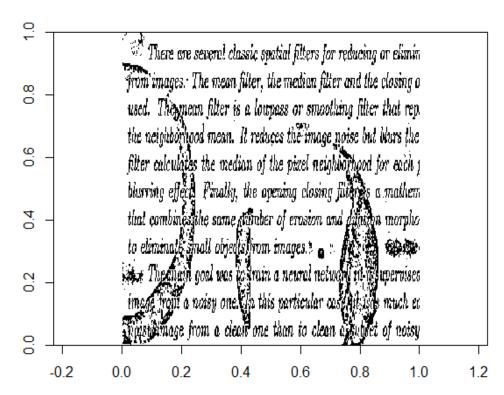
As the Spartacus database consisted mainly of short sentence paragraphs, the writers were asked to copy a set of sentences in f line fields in the forms. Next figure shows one of the forms used These forms also contain a brief set of instructions given to the Ensembling the results of different techniques - XGBoost

Individual Image Cleaning Algorithms Might Not Produce Optimum Results

Output from a Median Filter



Output from a Adaptive Thresholding



39 Process

There are several classic spatial filters for reducing or elimin from images. The mean filter, the median filter and the closing o used. The mean filter is a lowpass or smoothing filter that repute the neighborhood mean. It reduces the image noise but blurs the filter calculates the median of the pixel neighborhood for each plurring effect. Finally, the opening closing filter is a mathem that combines the same number of erosion and dilation morpho to eliminate small objects from images.

The main goal was to train a neural network in a supervised image from a noisy one. In this particular case, it was much ea noisy image from a clean one than to clean a subset of noisy Median Filter

Edge Detection

Adaptive Thresholding XGBoost

There are several classic spatial filters for reducing or elimin from images. The mean filter, the median filter and the closing o used. The mean filter is a lowpass or smoothing filter that repete the neighborhood mean. It reduces the image noise but blurs the filter calculates the median of the pixel neighborhood for each plurring effect. Finally, the opening closing filter is a mathem that combines the same number of erosion and dilation morpho to eliminate small objects from images.

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Featurization

Input

Predictors

Model

Target

Introduction

Edge Detection

Adaptive Thresholdin

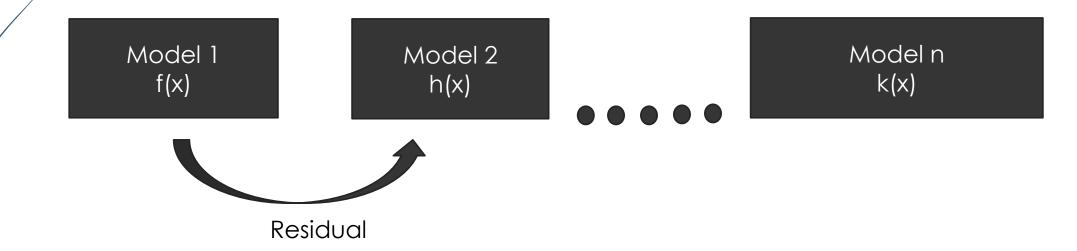
Median Filtering

Feature Engineering

Ensemble

Gradient Boosting

- A sequence of weak learners are used to produce more powerful predictions
- Later models focus on learning errors better



Adaptive Thresholding

Edge Detection

Algorithm

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For each image in the data, do:

Read dirty image & and convert it into a one column matrix



Read clean image & convert it into a one column matrix



Apply median filtering & convert the cleaned image into a one column matrix



Apply feature detection filter & convert the cleaned image into a one column matrix



Column bind all these features



Append it to the dataframe containing these features for the previous images

	Original	Featurization [‡]	Median [‡] Filtering	Target [‡]
1	0.8941176	0.8941176	1.0000000	1
2	0.8823529	0.8823529	1.0000000	1
3	0.8980392	0.8980392	1.0000000	1
4	0.9137255	0.9137255	1.0000000	1
5	0.8941176	0.8941176	1.0000000	1
6	0.9215686	0.9215686	1.0000000	1
7	0.9098039	0.9098039	1.0000000	1
8	0.8980392	0.8980392	1.0000000	1
9	0.9098039	0.9098039	1.0000000	1
10	0.8941176	0.8941176	1.0000000	1
11	0.9137255	0.9137255	1.0000000	1
12	0.9215686	0.9215686	1.0000000	1
13	0.9294118	0.9294118	1.0000000	1
14	0.9215686	0.9215686	1.0000000	1
15	0.9176471	0.9176471	1.0000000	1
16	0.9098039	0.9098039	1.0000000	1
17	0.9176471	0.9176471	1.0000000	1
18	0.9176471	0.9176471	1.0000000	1
19	0.9137255	0.9137255	1.0000000	1
20	0.9176471	0.9176471	1.0000000	1

For each image in the data, do:

Take a randomly selected sample from the data(250000 rows were selected)



Convert the data into a dense matrix with label being the cleaned image



Using cross validation, determine the optimum number of rounds for the xgboost model



Create the model with RMSE as the evaluation parameter



Predict for test images using this model



Convert the result into a matrix of the same dimensions as the original image

$\Leftrightarrow \Rightarrow$	a 7 F
	pred [‡]
1	0.9979517
2	0.9981245
3	0.9977194
4	0.9977194
5	0.9974357
6	0.9974357
7	0.9974357
8	0.9979517
9	0.9981074
10	0.9981245
- 11	0.9981074
12	0.9982852
13	0.9981245
14	0.9981245
15	0.9981074

Conclusion



There are several classic spatial filters for reducing or elimine from images. The mean filter, the median filter and the closing of used. The mean filter is a lowpass or smoothing filter that report the neighborhood mean. It reduces the image noise but blurs the filter calculates the median of the pixel neighborhood for each publishing effect. Finally, the opening closing filter is a mathematical that combines the same number of erosion and dilation morphoto to eliminate small objects from images.

The main goal was to train a neural network in a supervisea image from a noisy one. In this particular case, it was much ea noisy image from a clean one than to clean a subset of noisy

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