

Assignment - 1

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Q4) ans)

`function Perceptron()`

```
clear all, close all;
DataPoints = [-10 -10; -8 -2; -6 -12; -4 -4; 10 10; 8 2; 6 12; 4 4];
DataPoints = DataPoints';
DataLabel = [-1 -1 -1 -1 1 1 1 1];
class1Pts = DataPoints(:, DataLabel == -1);
class2Pts = DataPoints(:, DataLabel == 1);
plot (class1Pts(1, :), class2Pts (2, :), 'bo', class2Pts (1, :), class2Pts (2, :), 'rx');
W = findSepLine(class1Pts, class2Pts);
```

`end`

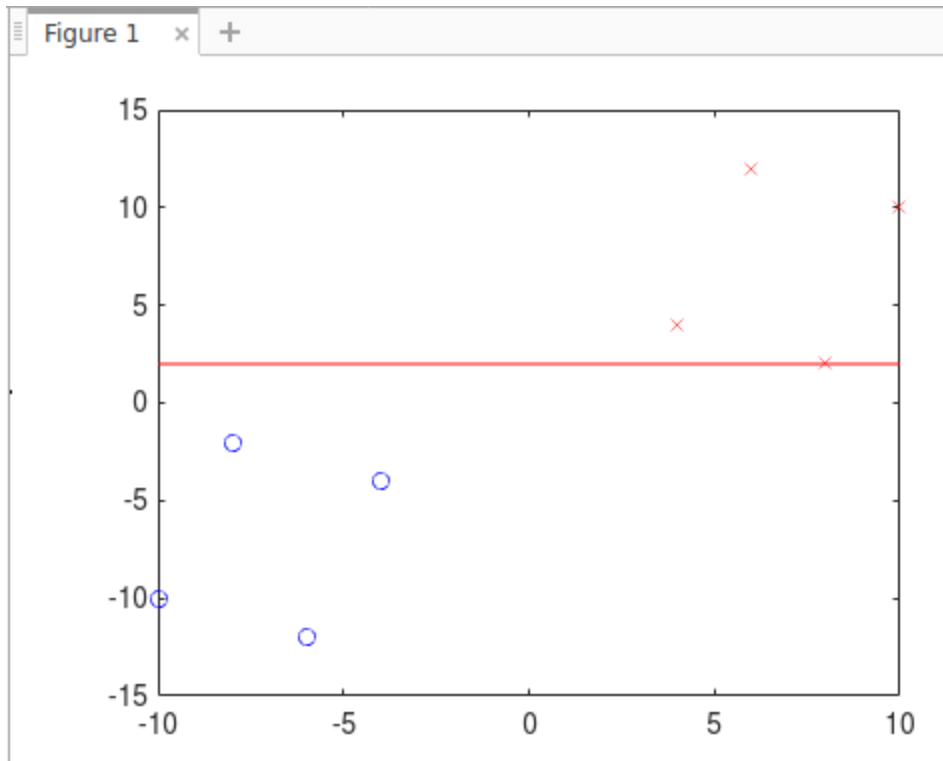
`function W = findSepLine (class1Pts, class2Pts)`

```
class1Pts = [1,1,1,1;class1Pts];
class2Pts = [1,1,1,1;class2Pts];
W = [0 1 -1]; %x = y line
xMin = min(class1Pts(2,:)); %x range for plotting the line
xMax = max(class2Pts(2,:));
xrange = xMin:0.01:xMax;
alpha = 0.005;
fprintf('Alpha : %f\n',alpha)
for i = 1:30
    % ax + by + c = 0
    a = W(2);
    b = W(3);
    c = W(1);
    y = (-a*xrange -c)/b; %Generate y points on the boundary
    clf;
    plot (class1Pts(2,:), class1Pts(3,:), 'bo', class2Pts(2,:), class2Pts(3,:), 'rx');
    hold on;
    plot (xrange, y,'r'); pause(5); %Plot the boundary
    %Pick misclassified samples from negative class
    predClass1 = class1Pts'*W'; %Predict class for negative class samples
```

```

    pickdmcSac1 = find(predClss1>0); %pick those which are wrongly predicted
as positive
    sumdxX1 = sum(pickdmcSac1, 2); %compute gradient contribution from
negative sample
    %Pick misclassified samples from positive class
    predClss2 = class2Pts'*W'; %Predict class for positive class samples
    pickdmcSac2 = find(predClss2<=0); %pick those which are predicted as
from negative class
    sumdxX2 = sum(-1*pickdmcSac2, 2); %compute gradient contribution from
negative samples
    errCst = sumdxX1 + sumdxX2 %compute gradient for both negative and
positive class
    W = W - alpha*errCst %apply gradient descent
    if (isempty(pickdmcSac1) && isempty(pickdmcSac2))
        %if no misclassified samples
        return;
    end
end
end
end

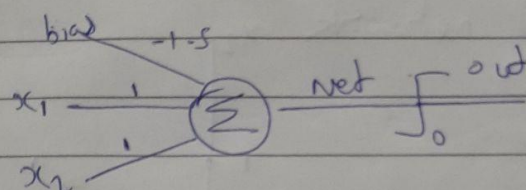
```





Assignment - 1

- 1 ans) Training a neural network means identifying parameter of a neuron. Lets take an eg, of a 'and' neural network

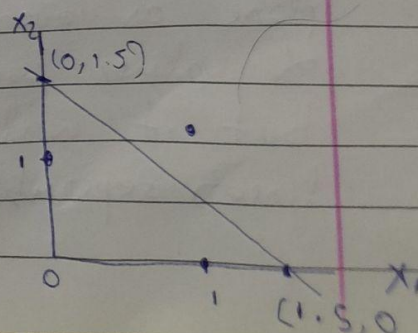


So from the diagram $-1.5, 1, 1$ are weights and threshold is also a parameter since we use it as a step function.

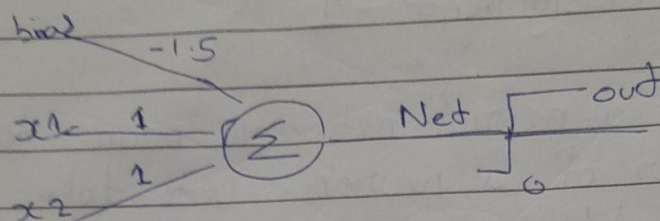
- 2 ans) A neuron can implement a line on a plane so it means its capacity is accordance to the data which is linearly separable, then a perceptron on a single neuron can always find a decision boundary and will always converge.

3 ans) AND neural network

x_1	x_2	o
0	0	0
0	1	0
1	0	0
1	1	1

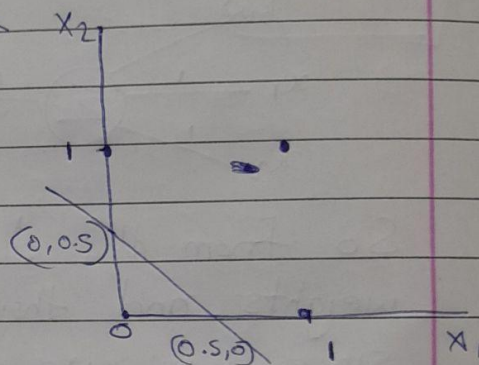


So decision boundary will be $x_1 + x_2 - 1.5 = 0$

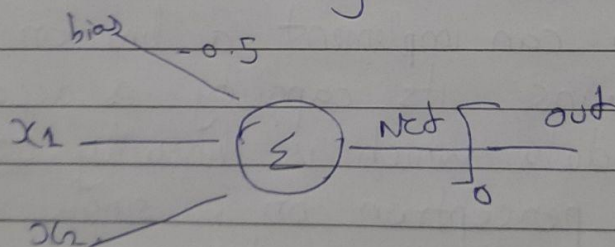


OR neural network

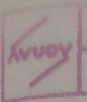
x_1	x_2	0
0	0	0
0	1	1
1	0	1
1	1	1



decision boundary will be $x_1 + x_2 - 0.5 = 0$



- 5 No, it will not give the best hyper plane as even though we change different λ values, we will get different line but it will not be the best. But for linear separable data it will always converge.



The best hyper plane is when boundary which maximizes the margin and that is given by the support vector machine (svm).

- 6 Since XOR is non-linear separable problem we would not be able to find $W \cdot X$ that separate training sample of two classes. So it will never converge.

Even if we change the activation function to more sophisticated sigmoid and neuron activation saturates at either close to 0 or 1, the gradient at these region is almost zero.

XOR neural network

$$\begin{aligned} A \oplus B &= A\bar{B} + \bar{A}B \\ &= \bar{A}B + A\bar{B} + A\bar{A} + B\bar{B} \\ &= A(\bar{A} + \bar{B}) + B(\bar{A} + \bar{B}) \\ &= (A+B)(\bar{A} + \bar{B}) \\ &= (A+B)(\overline{AB}) \end{aligned}$$

So from here we can see that XOR gate consist of OR, NAND and AND gate

Decision boundary now consist of:

$$\text{OR} \rightarrow 2A + 2B = 1$$

$$\text{NAND} \rightarrow A + B = 2$$

$$\text{AND} \rightarrow A + B = 1$$

