

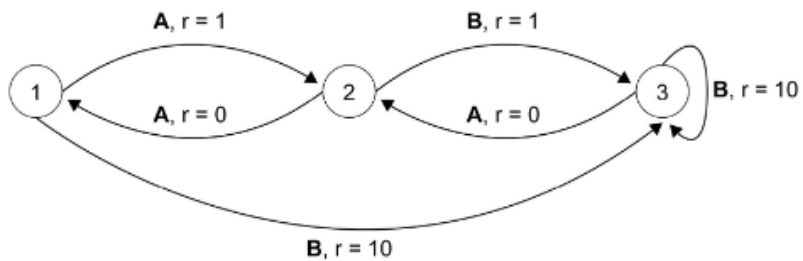
REINFORCEMENT LEARNING

LAB - 1

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Part I

Figure given below shows a simple example composed of three state and two actions



ans)

#code

from typing import Tuple

```
class Environment:
```

```
    def __init__(self):
```

```
        self._initial_state=1
```

```
        self._allowed_action=[0,1]
```

```
        self._states=[1,2,3]
```

```
        self._current_state=self._initial_state
```

```
    def step(self,action:int)->Tuple[int,int]:
```

```
        if action not in self._allowed_action:
```

```
            raise ValueError("Action is not allowed")
```

```
        reward=0
```

```
        if action==0 and self._current_state==1:
```

```
            self._current_state=2
```

```
            reward=1
```

```
            return (self._current_state,reward)
```

```

elif action==1 and self._current_state==1:
    self._current_state=3
    reward=10
    return (self._current_state,reward)
elif action==0 and self._current_state==2:
    self._current_state=1
    reward=0
    return (self._current_state,reward)
elif action==1 and self._current_state==2:
    self._current_state=3
    reward=1
    return (self._current_state,reward)
elif action==0 and self._current_state==3:
    self._current_state=2
    reward=0
    return (self._current_state,reward)
elif action==1 and self._current_state==3:
    self._current_state=3
    reward=10
    return (self._current_state,reward)

```

```

def reset(self)->int:
    self._current_state=self._initial_state
    return self._current_state

```

```

env=Environment()
state=env.reset()

```

```

actions=[0,0,1,1,0,1]

```

```

print(f"Initial state is {state}")

```

```

for action in actions:
    next_state, reward=env.step(action)
    print(f"From state {state} to state {next_state} with action {action}, reward: {reward}")

```

```
state=next_state
```

#Output

```
(base) deepak@g0takh0r:~/Sem6/RL (21AIE311)/Lab1$ python3 main.py
Initial state is 1
From state 1 to state 2 with action 0, reward: 1
From state 2 to state 1 with action 0, reward: 0
From state 1 to state 3 with action 1, reward: 10
From state 3 to state 3 with action 1, reward: 10
From state 3 to state 2 with action 0, reward: 0
From state 2 to state 3 with action 1, reward: 1
```

Part II

Creating a complex structure code with 5 states and 3 actions
ans)

#code

```
from typing import Tuple
```

```
class Environment:
```

```
    def __init__(self):
```

```
        self._initial_state=1
```

```
        self._allowed_action=[0,1,2]
```

```
        self._states=[1,2,3,4,5]
```

```
        self._current_state=self._initial_state
```

```
    def step(self,action:int)->Tuple[int,int]:
```

```
        if action not in self._allowed_action:
```

```
            raise ValueError("Action is not allowed")
```

```
        reward=0
```

```
        if action==0 and self._current_state==1:
```

```
            self._current_state=2
```

```
            reward=1
```

```
            return (self._current_state,reward)
```

```
        elif action==1 and self._current_state==1:
```

```
            self._current_state=3
```

```
            reward=1
```

```
        return (self._current_state,reward)
elif action==2 and self._current_state==1:
    self._current_state=1
    reward=0
    return (self._current_state,reward)
elif action==0 and self._current_state==2:
    self._current_state=1
    reward=0
    return (self._current_state,reward)
elif action==1 and self._current_state==2:
    self._current_state=3
    reward=1
    return (self._current_state,reward)
elif action==2 and self._current_state==2:
    self._current_state=2
    reward=0
    return (self._current_state,reward)
elif action==0 and self._current_state==3:
    self._current_state=2
    reward=0
    return (self._current_state,reward)
elif action==1 and self._current_state==3:
    self._current_state=4
    reward=1
    return (self._current_state,reward)
elif action==2 and self._current_state==3:
    self._current_state=3
    reward=0
    return (self._current_state,reward)
elif action==0 and self._current_state==4:
    self._current_state=3
    reward=0
    return (self._current_state,reward)
elif action==1 and self._current_state==4:
    self._current_state=5
```

```

        reward=10
        return (self._current_state,reward)
    elif action==2 and self._current_state==4:
        self._current_state=4
        reward=0
        return (self._current_state,reward)
    elif action==0 and self._current_state==5:
        self._current_state=4
        reward=0
        return (self._current_state,reward)
    elif action==1 and self._current_state==5:
        self._current_state=5
        reward=10
        return (self._current_state,reward)
    elif action==2 and self._current_state==5:
        self._current_state=3
        reward=0
        return (self._current_state,reward)

```

```

def reset(self)->int:
    self._current_state=self._initial_state
    return self._current_state

```

```

env=Environment()
state=env.reset()

```

```

actions=[0,2,0,1,2,1,2,0,1,2,1]

```

```

print(f"Intial state is {state}")

```

```

for action in actions:
    next_state, reward=env.step(action)
    print(f"From state {state} to state {next_state} with action {action}, reward: {reward}")
    state=next_state

```

#Output

```

(base) deepak@gotakh0r:~/Sem6/RL (21AIE311)/Lab1$ python3 lab1_part2.py
Initial state is 1
From state 1 to state 2 with action 0, reward: 1
From state 2 to state 2 with action 2, reward: 0
From state 2 to state 1 with action 0, reward: 0
From state 1 to state 3 with action 1, reward: 1
From state 3 to state 3 with action 2, reward: 0
From state 3 to state 4 with action 1, reward: 1
From state 4 to state 4 with action 2, reward: 0
From state 4 to state 3 with action 0, reward: 0
From state 3 to state 4 with action 1, reward: 1
From state 4 to state 4 with action 2, reward: 0
From state 4 to state 5 with action 1, reward: 10

```

Part III

Generalizing the problem with n state and m actions

ans)

Performing the same model demonstration as the first one

[#code](#)

from typing import Tuple

class Environment:

def __init__(self, _allowed_action, _states):

self.trf = {}

self._initial_state=1

self._allowed_action=_allowed_action

self._states=_states

self._current_state=self._initial_state

print("Enter the transition")

print("Format : current_state action next_state reward")

for i in range((len(_allowed_action)*len(_states))):

new=input().split(' ')

new=[int(x) for x in new]

s, a, n, r = new

self.trf[s,a]=(n, r)

def step(self, action:int)->Tuple[int,int]:

perform = self.trf[(self._current_state, action)] #matching the dictionary to perform

action

```

    if perform:
        n,r=perform
        self._current_state=n
        return (self._current_state,r)
    else:
        print("Error!!!")
        return 0

```

```

def reset(self)->int:
    self._current_state=self._initial_state
    return self._current_state

```

```

st=input("Enter the states : ").split()
st=[int(x) for x in st]
ac=input("Enter the actions : ").split()
ac=[int(x) for x in ac]
env=Environment(st,ac)

```

```

state=env.reset()

```

```

act=input("Enter the actions to be performed : ").split()
act=[int(x) for x in act]
actions=act

```

```

print(f"Initial state is {state}")

```

```

for action in actions:
    next_state, reward=env.step(action)
    print(f"From state {state} to state {next_state} with action {action}, reward: {reward}")
    state=next_state

```

#Output

```
(base) deepak@g0takh0r:~/Sem6/RL (21AIE311)/Lab1$ python3 gmain.py
Enter the states : 1 2 3
Enter the actions : 0 1
Enter the transition
Format : current_state action next_state reward
1 0 2 1
1 1 3 10
2 0 1 0
2 1 3 1
3 0 2 0
3 1 3 10
Enter the actions to be performed : 0 0 1 1 0 1
Initial state is 1
From state 1 to state 2 with action 0, reward: 1
From state 2 to state 1 with action 0, reward: 0
From state 1 to state 3 with action 1, reward: 10
From state 3 to state 3 with action 1, reward: 10
From state 3 to state 2 with action 0, reward: 0
From state 2 to state 3 with action 1, reward: 1
```