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Statistical Inference for a New Class of Multivariate Pareto Distributions

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Various solutions to the parameter estimation problem of a recently introduced multivariate Pareto distribution are developed and exemplified numerically. Namely, a density of the aforementioned multivariate Pareto distribution with respect to a dominating measure, rather than the corresponding Lebesgue measure, is specified and then employed to investigate the maximum likelihood estimation (MLE) approach. Also, in an attempt to fully enjoy the common shock origins of the multivariate model of interest, an adapted variant of the expectation-maximization (EM) algorithm is formulated and studied. The method of moments is discussed as a convenient way to obtain starting values for the numerical optimization procedures associated with the MLE and EM methods.

Keywords Common shock model; Expectation-maximization algorithm; Maximum likelihood estimation; Method of moments; Multivariate Pareto distribution.

Mathematics Subject Classification 62F10; 62H12; 60E05.

1. Introduction

Fix a measurable space (Ω, \mathcal{F}) and $n \in \mathbf{Z}_+$, and let $\mathbf{Y} = (Y_0, Y_1, \dots, Y_n)' : \Omega \to \mathbf{R}^{n+1}$ denote an (n+1)-dimensional random vector possessing mutually independent Pareto-distributed coordinates $Y_i \backsim \mathrm{Pa}(\mu_i, \sigma_i, \alpha_i), \ i = 0, 1, \dots, n$ (" \backsim " stands for "distributed" throughout), such that, for $\sigma_i \in \mathbf{R}_+$ and $\alpha_i \in \mathbf{R}_+$, we have that

$$\overline{F}_{Y_i}(y) = \mathbf{P}[Y_i > y] = \left(1 + \frac{y_i - \mu_i}{\sigma_i}\right)^{-\alpha_i}, \text{ with } y > \mu_i \in \mathbf{R}.$$
 (1.1)

Then, for $\mu_0 = 0$, $\sigma_0 = 1$, $\alpha_{0j} = \alpha_0 + \alpha_j$, j = 1, ..., n, and a map $T : \mathbf{R}^{n+1} \to \mathbf{R}^n$, the random vector $\mathbf{X} = T(\mathbf{Y})$, with the coordinates $X_j = \min(\sigma_j Y_0 + \mu_j, Y_j) \backsim \mathrm{Pa}(\mu_j, \sigma_j, \alpha_{0j})$, is in Asimit et al. (2010) referred to as a multivariate Pareto distribution

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having arbitrarily parameterized Pareto of the second kind margins (see Arnold, 1983), and a dependence structure, described by the Marshall and Olkin copula (see Marshall and Olkin, 1967). Various applications of the just-mentioned multivariate Pareto distribution in, for example, actuarial mathematics and/or operational research stem from its "common shock"-based formation (see, loc. cit., as well as Asimit et al., 2010).

The multivariate Pareto distribution above, which was in Asimit et al. (2010) denoted by $Pa_n(\mu, \sigma, \alpha, \alpha_0)$, with the vectors of parameters $\mu = (\mu_1, \dots, \mu_n)' \in \mathbb{R}^n$, $\sigma = (\sigma_1, \dots, \sigma_n)' \in \mathbb{R}^n_+$, $\alpha = (\alpha_1, \dots, \alpha_n)' \in \mathbb{R}^n_+$, and a scalar-valued "dependence" parameter $\alpha_0 > 0$, proved to be quite analytically tractable and thus allowed for a comprehensive study of a number of its properties. More specifically, we derived explicit expressions for, for example, the decumulative distribution functions (ddfs), the probability density functions (pdfs), and the conditional as well as joint moments, proved certain characteristic results, and developed pricing formulas. A discussion of the appropriate inferential statistics techniques for $Pa_n(\mu, \sigma, \alpha, \alpha_0)$ seems therefore to suggest itself.

Our interest in this article is therefore to find estimates of μ , σ , α , and α_0 . Speaking plainly, the problem is not trivial. Indeed, notice that the maximum likelihood estimation (MLE) seems not at first glance applicable because the ddf of $\mathbf{X} \backsim \mathrm{Pa}_n(\mu, \sigma, \alpha, \alpha_0)$, which is given by (see, loc. cit.)

$$\overline{F}_{\mathbf{X}}(x_1, \dots, x_n) = \left(1 + \max_{j=1,\dots,n} \frac{x_j - \mu_j}{\sigma_j}\right)^{-\alpha_0} \prod_{j=1}^n \left(1 + \frac{x_j - \mu_j}{\sigma_j}\right)^{-\alpha_j}, \tag{1.2}$$

with $x_j > \mu_j$, $j = 1, \ldots, n$, is not absolutely continuous with respect to the Lebesgue measure on \mathbf{R}^n . Furthermore, even the moment-based estimation can become somewhat intricate if, say, the expectation and/or variance are not finite, which can certainly be the case, for example, we readily have that if $\alpha_{0j} \leq 1$, then $\mathbf{E}[X_j]$ is infinite. It is worthwhile noticing that the aforementioned statistical inconvenience is often an advantage, and it is in fact quite desirable in practical applications for modeling "particularly heavy" financial risks and/or losses.

In the rest of the article, we attempt to provide possible ways to tackle the parameters estimation issue. To this end, in Section 2.2 we specify a density of $\mathbf{X} \backsim \mathrm{Pa}_n(\boldsymbol{\mu}, \boldsymbol{\sigma}, \boldsymbol{\alpha}, \alpha_0)$ with respect to a dominating measure, instead of the Lebesgue measure, which makes the MLE method feasible, and we discuss the expectation-maximization (EM) algorithm to estimate the parameters in Section 2.3. Section 3 reveals a numerical study and concludes the article. The proofs are relegated to the Appendix.

2. Main Results

2.1. Basic Properties

In Asimit et al. (2010), we showed that, for j = 1, ..., n,

- The distribution of X_i is $Pa(\mu_i, \sigma_i, \alpha_{0i})$.
- The mathematical expectation of X_j is, for $\alpha_{0j} > 1$,

$$\mathbf{E}[X_j] = \mu_j + \frac{\sigma_j}{\alpha_{0j} - 1}.$$

• The variance of X_i is, for $\alpha_{0i} > 2$,

$$\mathbf{Var}[X_j] = \frac{\alpha_{0j}\sigma_j^2}{(\alpha_{0j} - 1)^2(\alpha_{0j} - 2)}.$$

• The covariance between X_j and X_k is, for $j \neq k$, $\alpha_{0j} > 1$, $\alpha_{0k} > 1$, and $\alpha_{0jk} = \alpha_0 + \alpha_j + \alpha_k > 2$,

$$\mathbf{Cov}[X_j, X_k] = \frac{\alpha_0 \sigma_j \sigma_k}{(\alpha_{0j} - 1)(\alpha_{0k} - 1)(\alpha_{0jk} - 2)}.$$

• Pearson's correlation coefficient between X_j and X_k is, for $j \neq k$, $\alpha_{0j} > 2$, $\alpha_{0k} > 2$, and $\alpha_{0jk} > 2$,

$$\mathbf{Corr}[X_j, X_k] = \frac{\alpha_0}{\alpha_{0jk} - 2} \sqrt{\frac{(\alpha_{0j} - 2)(\alpha_{0k} - 2)}{\alpha_{0j}\alpha_{0k}}}.$$
 (2.1)

Furthermore, for $1 \le j \ne k \le n$ and $x_k > \mu_k$, the conditional ddf of $X_j \mid X_k = x_k$, as well as the conditional expectation $\mathbf{E}[X_j \mid X_k = x_k]$ were also derived in Asimit et al. (2010).

As it has been mentioned, the multivariate Pareto distribution of interest in this article possesses Pareto of the second kind margins and Marshall-Olkin copula-based dependence structure (see Nelsen, 1999, p. 46). For the sake of the analysis in Section 2.3, we further complement (2.1) with the following two well-known robust measures of association, that is, Kendall's Tau and Spearman's Rho (see Nelsen, 1999, p. 133 and 136; for the proofs).

Lemma 2.1. Let $\mathbf{X} \backsim Pa_n(\boldsymbol{\mu}, \boldsymbol{\sigma}, \boldsymbol{\alpha}, \alpha_0)$ follow the multivariate Pareto distribution of interest, and let $1 \leq j \neq k \leq n$. Then it can be shown that,

• Spearman's rank correlation coefficient between X_i and X_k is

$$\rho[X_j, X_k] = 3\alpha_0/(2(\alpha_{0j} + \alpha_{0k}) - \alpha_0), \text{ and}$$
 (2.2)

• Kendall's tau rank correlation coefficient between X_i and X_k is

$$\tau[X_i, X_k] = \alpha_0 / (\alpha_{0i} + \alpha_{0k} - \alpha_0). \tag{2.3}$$

2.2. Density and Likelihood

It is not difficult to see that the pdf does not everywhere exist for ddf (1.2). We skip negligible technical details and only note in passing that the ddf consists of both absolutely continuous and singular components. Thereby, with a fixed index $(n) \in \{1, ..., n\}$, such that

$$z_{(n)} = \max_{j=1,\dots,n} (x_j - \mu_j)/\sigma_j,$$
 (2.4)

and $\alpha_{(0n)}$ and $\sigma_{(n)}$ denoting the shape and scale parameters corresponding to the just introduced coordinate $z_{(n)}$, we have that the pdf for the absolutely continuous part is

$$f_{\mathbf{X}}(x_1,\ldots,x_n) = \frac{\alpha_{(0n)}}{\sigma_{(n)}} \left(1+z_{(n)}\right)^{-(\alpha_{(0n)}+1)} \prod_{j=1,\ j\neq (n)}^n \frac{\alpha_j}{\sigma_j} \left(1+\frac{x_j-\mu_j}{\sigma_j}\right)^{-(\alpha_j+1)}, \quad (2.5)$$

where $x_j > \mu_j$. In addition, for distinct $j_1, \ldots, j_k \in \{1, 2, \ldots, n\}$ and a fixed $k \le n$, the probabilities for the singular component are given by

$$\mathbf{P}\left[\frac{X_{j_1} - \mu_{j_1}}{\sigma_{j_1}} = \dots = \frac{X_{j_k} - \mu_{j_k}}{\sigma_{j_k}}\right] = \frac{\alpha_0}{\alpha_0 + \sum_{i=1}^k \alpha_{j_i}}.$$
 (2.6)

We further specify a probability density function of the multivariate Pareto distribution with respect to a dominating measure, rather than to the Lebesgue measure on \mathbf{R}^n (see, e.g., Hanagal, 1996; Proschan and Sullo, 1976; for similar approaches). To this end, for $r=2,\ldots,n$, let $\mathcal{I}_r=\{i_1,\ldots,i_r\}\subseteq\{1,\ldots,n\}=\mathcal{I}_n$, and $\{j_1,\ldots,j_{n-r}\}=\mathcal{I}_n\setminus\mathcal{I}_r$. Also, for $\mathcal{C}\subseteq\mathbf{R}^n$, let us define

$$g_{\mathcal{I}_r}(\mathcal{C}) = \left\{ \left(z_{(n)}, x_{j_1}, ..., x_{j_{n-r}} \right) : \mathbf{x} \in \mathcal{C} \text{ and } \frac{x_{i_1} - \mu_{i_1}}{\sigma_{i_1}} = \cdots = \frac{x_{i_r} - \mu_{i_r}}{\sigma_{i_r}} = z_{(n)} \right\},$$

with $z_{(n)}$ given in (2.4). Then for v_n denoting the n -dimensional Lebesgue measure, it is possible to introduce another measure $v >> v_n$ (in words, "v dominates v_n "), such that

$$\nu(\mathcal{C}) = \nu_n(\mathcal{C}) + \sum_{\substack{r = 2, \dots, n \\ \mathcal{I}_r \subseteq \mathcal{I}_n}} \nu_{n-r+1} \left(g_{\mathcal{I}_r} \left(\mathcal{C} \bigcap \left\{ \mathbf{x} \in \mathbf{R}^n : x_i > \mu_i, \ i = 1, \dots, n \right\} \right) \right)$$
(2.7)

for any C in the Borel σ -algebra \mathcal{B}^n in \mathbf{R}^n .

Furthermore, let $\mathbf{x} = (x_1, \dots, x_n)' \in \mathbf{R}^n$ be a realization of $\mathbf{X} \backsim \operatorname{Pa}_n(\boldsymbol{\mu}, \boldsymbol{\sigma}, \boldsymbol{\alpha}, \alpha_0)$. We then introduce a number of auxiliary indexes as functions of \mathbf{x} , for $j = 1, \dots, n$, $k = 1, \dots, n$, and "#" denoting the "cardinality" of a set, that is, let

$$v_{j} = v_{j}(\mathbf{x}) = \begin{cases} 1, & (x_{j} - \mu_{j})/\sigma_{j} < z_{(n)} \\ 0, & \text{otherwise} \end{cases},$$

$$s = s(\mathbf{x}) = \begin{cases} 1, & \exists j \neq k : (x_{j} - \mu_{j})/\sigma_{j} = (x_{k} - \mu_{k})/\sigma_{k} = z_{(n)} \\ 0, & \text{otherwise} \end{cases},$$

and

$$r = r(\mathbf{x}) = \# \left\{ j \in \{1, \dots, n\} : \frac{x_j - \mu_j}{\sigma_j} = z_{(n)} \right\}.$$

(When no confusion is possible, we omit the argument " \mathbf{x} ," and we write v_j , s, and r instead of $v_j(\mathbf{x})$, $s(\mathbf{x})$, and $r(\mathbf{x})$, respectively.)

Theorem 2.1. The density of $\mathbf{X} \backsim Pa_n(\boldsymbol{\mu}, \boldsymbol{\sigma}, \boldsymbol{\alpha}, \alpha_0)$ with respect to $\boldsymbol{\nu}$ is given by

$$f_{\mathbf{X}}(x_1,\ldots,x_n) = \alpha_0^s (1+z_{(n)})^{-\alpha_0+r-1} \prod_{j=1}^n \left(\frac{\alpha_j}{\sigma_j}\right)^{\nu_j} \left(\frac{\alpha_{0j}}{\sigma_j}\right)^{(1-s)(1-\nu_j)}$$

$$\times \left(1 + \frac{x_j - \mu_j}{\sigma_j}\right)^{-(\alpha_j + 1)},\,$$

where $x_j > \mu_j \in \mathbf{R}, \ j = 1, ..., n$.

Before sketching the MLE method, it is worthwhile noticing the particular forms of the bivariate and trivariate pdf.

Corollary 2.1. The pdf of $\mathbf{X} \backsim Pa_2(\boldsymbol{\mu}, \boldsymbol{\sigma}, \boldsymbol{\alpha}, \alpha_0)$ is given by

$$f_{\mathbf{X}}(\mathbf{x}) = \begin{cases} \frac{\alpha_{j}\alpha_{0i}}{\sigma_{1}\sigma_{2}} \left(1 + \frac{x_{i} - \mu_{i}}{\sigma_{i}}\right)^{-(\alpha_{0i} + 1)} \left(1 + \frac{x_{j} - \mu_{j}}{\sigma_{j}}\right)^{-(\alpha_{j} + 1)}, & \frac{x_{i} - \mu_{i}}{\sigma_{i}} > \frac{x_{j} - \mu_{j}}{\sigma_{j}} > 0\\ and & i \neq j \in \{1, 2\}\\ \alpha_{0} \left(1 + z_{(2)}\right)^{-(\alpha_{0} + \alpha_{1} + \alpha_{2} + 1)}, & \frac{x_{1} - \mu_{1}}{\sigma_{1}} = \frac{x_{2} - \mu_{2}}{\sigma_{2}} = z_{(2)} > 0 \end{cases}$$

$$(2.8)$$

while for $\mathbf{X} \backsim Pa_3(\boldsymbol{\mu}, \boldsymbol{\sigma}, \boldsymbol{\alpha}, \alpha_0)$ and $\{i, j, k\} = \{1, 2, 3\}$, it holds that

$$f_{\mathbf{X}}(\mathbf{x}) = \begin{cases} \frac{\alpha_{i}\alpha_{j}\alpha_{0k}}{\sigma_{1}\sigma_{2}\sigma_{3}} \left(1 + \frac{x_{k} - \mu_{k}}{\sigma_{k}}\right)^{-(\alpha_{0k} + 1)} \left(1 + \frac{x_{i} - \mu_{i}}{\sigma_{i}}\right)^{-(\alpha_{i} + 1)} \left(1 + \frac{x_{j} - \mu_{j}}{\sigma_{j}}\right)^{-(\alpha_{j} + 1)}, \\ \frac{x_{k} - \mu_{k}}{\sigma_{k}} > \max\left\{\frac{x_{i} - \mu_{i}}{\sigma_{i}}, \frac{x_{j} - \mu_{j}}{\sigma_{j}}\right\} > 0 \\ \frac{\alpha_{i}\alpha_{0}}{\sigma_{i}} \left(1 + z_{(3)}\right)^{-(\alpha_{0} + \alpha_{j} + \alpha_{k} + 1)} \left(1 + \frac{x_{i} - \mu_{i}}{\sigma_{i}}\right)^{-(\alpha_{i} + 1)}, \\ \frac{x_{k} - \mu_{k}}{\sigma_{k}} = \frac{x_{j} - \mu_{j}}{\sigma_{j}} = z_{(3)} > \frac{x_{i} - \mu_{i}}{\sigma_{i}} > 0 \\ \alpha_{0} \left(1 + z_{(3)}\right)^{-(\alpha_{0} + \alpha_{1} + \alpha_{2} + \alpha_{3} + 1)}, \quad \frac{x_{1} - \mu_{1}}{\sigma_{1}} = \frac{x_{2} - \mu_{2}}{\sigma_{2}} = \frac{x_{3} - \mu_{3}}{\sigma_{3}} = z_{(3)} > 0 \end{cases}$$

Theorem 2.1 establishes an absolutely continuous pdf, which can be used to develop the MLE for the multivariate Pareto distribution of interest, as it is shown in the sequel.

Let $(\mathbf{X}_i)_{i=1}^m$ be *m*-independent copies of $\mathbf{X} \backsim \operatorname{Pa}_n(\boldsymbol{\mu}, \boldsymbol{\sigma}, \boldsymbol{\alpha}, \alpha_0)$, with the realization of, say, \mathbf{X}_i , being denoted by $\mathbf{x}_i = (x_{1,i}, \dots, x_{n,i})'$, and let, for $j = 1, \dots, n$,

$$u_0 = \sum_{i=1}^{m} s(\mathbf{x}_i), \quad u_j = \sum_{i=1}^{m} v_j(\mathbf{x}_i), \quad w_j = \sum_{i=1}^{m} (1 - s(\mathbf{x}_i)) (1 - v_j(\mathbf{x}_i)).$$

Let $z_{(n)i} = \max_{j=1,\dots,n} (x_{j,i} - \mu_j)/\sigma_j$, for a fixed $i = 1,\dots,m$. The following statement is a clear consequence of Theorem 2.1 and is therefore given without proof.

Corollary 2.2. The log-likelihood function for the $Pa_n(\mu, \sigma, \alpha, \alpha_0)$ sample $(\mathbf{X}_i)_{i=1}^m$ is

$$\ln \mathcal{L}(\boldsymbol{\mu}, \boldsymbol{\sigma}, \boldsymbol{\alpha}, \alpha_0; \mathbf{x}_1, \dots, \mathbf{x}_m) = u_0 \ln \alpha_0 + \sum_{i=1}^m (r(\mathbf{x}_i) - \alpha_0 - 1) \ln(1 + z_{(n)i})$$
 (2.9)

$$+\sum_{j=1}^{n}\left(u_{j}\ln\alpha_{j}+w_{j}\ln\alpha_{0j}-\left(u_{j}+w_{j}\right)\ln\sigma_{j}-\left(\alpha_{j}+1\right)\sum_{i=1}^{m}\ln\left(1+\frac{x_{j,i}-\mu_{j}}{\sigma_{j}}\right)\right),$$

which simplifies to the findings of Hanagal (1996) for $\mu_i = \sigma_i \equiv 1$.

At this point, the ideal solution is of course to estimate all (3n + 1) parameters of $Pa_n(\mu, \sigma, \alpha, \alpha_0)$ applying the just derived log-likelihood. However, this can become rather

cumbersome (if not impossible) if, say, μ and σ are unknown, since in such a case, we have that, for example, s and v_j are unknown as well. Remarkably, it is possible to tackle the aforementioned complication by following an alternative route to estimating the parameters of interest, that we in fact do in Section 2.3

To complement the current discussion, we further outline a number of seemingly useful observations, which can be of importance to practitioners under specific constraints. To start off, we note that the obvious estimates for μ_j are $\hat{\mu}_j = \min_{i=1,...,m} x_{j,i}$, where j=1,...,n, and we thus have to actually estimate (2n+1) parameters, only, with further simplifications sometimes possible.

Indeed, an interesting special case in this respect is the one when the multivariate Pareto distribution of interest possesses identically distributed margins, or, more generally, when $\sigma_j \equiv \sigma$. Then we readily observe that the v, s, and r functions do not depend on the values of σ , and therefore a system of (n+2) nonlinear equations must be solved to obtain the estimates of σ , α_0 , and α . The system is given below, and it is not solvable analytically

$$\begin{cases} \sum_{i=1}^{m} \left(\sum_{j=1}^{n} \left(\alpha_{j} + 1 \right) \frac{x_{j,i} - \hat{\mu}_{j}}{\sigma + x_{j,i} - \hat{\mu}_{j}} - \left(r \left(\mathbf{x}_{i} \right) - \alpha_{0} - 1 \right) \frac{z_{(n)i}}{1 + z_{(n)i}} \right) - \sum_{j=1}^{n} \left(u_{j} + w_{j} \right) = 0, \\ \frac{u_{0}}{\alpha_{0}} - \sum_{i=1}^{m} \ln \left(1 + z_{(n)i} \right) + \sum_{j=1}^{n} \frac{w_{j}}{\alpha_{0j}} = 0, \text{ and} \\ \frac{u_{j}}{\alpha_{j}} + \frac{w_{j}}{\alpha_{0j}} - \sum_{i=1}^{m} \ln \left(1 + \frac{x_{j,i} - \hat{\mu}_{j}}{\sigma} \right) = 0, \text{ for each } j = 1, \dots, n \end{cases}$$

In a variety of practical applications, it may be convenient to estimate μ and σ using the marginal (univariate) estimation discussed in, for example, Arnold (1983), and to utilize the log-likelihood function obtained in Corollary 2.2 to find the estimates of α_0 and α . Thereby, assuming that we have the estimates $\hat{\mu}$ and $\hat{\sigma}$, we readily end up with the system

$$\begin{cases} \frac{u_0}{\alpha_0} - \sum_{i=1}^m \ln\left(1 + z_{(n)i}\right) + \sum_{j=1}^n \frac{w_j}{\alpha_{0j}} = 0, \text{ and} \\ \frac{u_j}{\alpha_j} + \frac{w_j}{\alpha_{0j}} - \sum_{i=1}^m \ln\left(1 + \frac{x_{j,i} - \hat{\mu}_j}{\hat{\sigma}_j}\right) = 0, \text{ for each } j = 1, \dots, n \end{cases}$$
(2.10)

which can be solved numerically for α_0 and α in order to obtain $\hat{\alpha}_0$ and $\hat{\alpha}$.

Furthermore, we may want to estimate μ and σ , as well as $(\alpha_{0j})_{j=1}^n$ using marginal (univariate) estimation techniques, and to estimate α_0 with the help of (2.9) thereafter. In such a case, with $(\hat{\alpha}_{0j})_{j=1}^n$ denoting the estimates of $(\alpha_{0j})_{j=1}^n$, the only equation to solve is

$$\frac{u_0}{\alpha_0} - \sum_{i=1}^m \ln\left(1 + z_{(n)i}\right) + \sum_{i=1}^n \left(\sum_{i=1}^m \ln\left(1 + \frac{x_{j,i} - \hat{\mu}_j}{\hat{\sigma}_j}\right) - \frac{u_j}{\hat{\alpha}_{0j} - \alpha_0}\right) = 0.$$
 (2.11)

In the next subsection, we discuss an alternative method, which allows to estimate the parameters of interest simultaneously. To this end, we note in passing that in the context of the map $\mathbf{X} = T(\mathbf{Y})$, the random vector $\mathbf{Y} \in \mathbf{R}^{n+1}$ is a latent variable, and only $\mathbf{X} \in \mathbf{R}^n$ is practically observed. This interpretation, as well as the unimodal nature of the multivariate Pareto distribution considered herein, strongly hint at the appropriateness of the method. In the rest of the article, we keep our discussion restricted to the bivariate and trivariate cases to make the exposition simple and to circumvent notational inconveniences inevitably arising when the general case is considered.

2.3. Expectation-maximization Algorithm

The general version of the EM algorithm was described and analyzed by Dempster et al. (1977) (see also Wu, 1983) as an alternative to solving complex MLE problems. Karlis (2003) realized the method in the context of the multivariate exponential distribution of Marshall and Olkin, which is an example of a multivariate common shock model with exponential margins. As the multivariate Pareto distribution of interest clearly allows for a missing data interpretation, the utilization of the EM algorithm is quite natural.

To start off, we readily note that in the bivariate case, the missing data are represented by the latent random vector $\mathbf{Y} = (Y_0, Y_1, Y_2)'$, whereas the random vector $\mathbf{X} = T(\mathbf{Y}) = (X_1, X_2)' \backsim \operatorname{Pa}_2(\boldsymbol{\mu}, \boldsymbol{\sigma}, \boldsymbol{\alpha}, \alpha_0)$ denotes the practically observable variables of interest. Consequently, the complete data are in that case a five-dimensional random vector possessing the pdf $f_{\mathbf{X},\mathbf{Y}}(\mathbf{x},\mathbf{y};\boldsymbol{\theta})$ with $\boldsymbol{\theta} = (\boldsymbol{\mu}, \boldsymbol{\sigma}, \boldsymbol{\alpha}, \alpha_0)' \in \boldsymbol{\Theta} \subset \mathbf{R}^7$. The EM algorithm then iteratively improves the initial estimate $\boldsymbol{\theta}^{(0)}$ by constructing new estimates $\boldsymbol{\theta}^{(k+1)}$, $k \in \mathbf{N}$, that do not decrease the complete data expected analog of (2.9).

More specifically, denoting, as before, by $(\mathbf{X}_i)_{i=1}^m$ and $\mathbf{x}_i = (x_{1,i}, x_{2,i})'$, the *m*-independent copies of $\mathbf{X} \backsim \operatorname{Pa}_2(\boldsymbol{\mu}, \boldsymbol{\sigma}, \boldsymbol{\alpha}, \alpha_0)$ and the realization of say \mathbf{X}_i , respectively, the complete data expected log-likelihood is naturally formulated as

$$Q\left(\boldsymbol{\theta}; \mathbf{x}_{1}, \dots, \mathbf{x}_{m}, \boldsymbol{\theta}^{(k)}\right) = \mathbf{E}\left[\ln \prod_{i=1}^{m} f_{\mathbf{X}_{i}, \mathbf{Y}}\left(\mathbf{X}_{i}, \mathbf{Y}; \boldsymbol{\theta}\right) \mid \mathbf{X}_{i} = \mathbf{x}_{i}, \boldsymbol{\theta}^{(k)}\right]$$

$$= \int_{\mathbf{R}^{3}} \sum_{i=1}^{m} \ln f_{\mathbf{X}_{i}, \mathbf{Y}}\left(\mathbf{x}_{i}, \mathbf{y}; \boldsymbol{\theta}\right) f_{\mathbf{Y} \mid \mathbf{X}_{i} = \mathbf{x}_{i}, \boldsymbol{\theta}^{(k)}}\left(\mathbf{y}\right) d\mathbf{y}, \quad (2.12)$$

and it must be calculated for every k = 0, 1, ... The estimate $\theta^{(k+1)}$ is then determined as the expected log-likelihood maximizer, that is, given $\theta^{(k)}$, we have that

$$\boldsymbol{\theta}^{(k+1)} = \arg \max_{\boldsymbol{\theta} \in \boldsymbol{\Theta}} Q\left(\boldsymbol{\theta}; \mathbf{x}_1, \dots, \mathbf{x}_m, \boldsymbol{\theta}^{(k)}\right). \tag{2.13}$$

We note in passing that it is well accepted to refer to (2.12) and (2.13) as the "E" and "M" steps, respectively. The two steps are repeated until a convergence criterion has been achieved.

In view of the recurrent nature of the EM algorithm, the k = 0 case, which corresponds to the initial expected log-likelihood $Q\left(\boldsymbol{\theta}; \mathbf{x}_1, \dots, \mathbf{x}_m, \boldsymbol{\theta}^{(0)}\right)$, requires a somewhat special treatment. Speaking literally, the problem boils down to determining the starting value $\boldsymbol{\theta}^{(0)}$ to then allow for the evaluation of the consequent estimates. In this respect, we suggest to utilize the empirical variates of the appropriate mean, variance, Pearson's correlation, as well as of Spearman's and/or Kendall's coefficients of association to trigger the method of moments (MM) estimation technique. We can thereby obtain, for example, the estimates of α_0 ,

$$\hat{\alpha}_{0} = \frac{c \left(\hat{\alpha}_{01} + \hat{\alpha}_{02} - 2\right)}{1 + c}, \text{ with } c = \widehat{\mathbf{Corr}}[X_{1}, X_{2}] \sqrt{\frac{\hat{\alpha}_{01}\hat{\alpha}_{02}}{(\hat{\alpha}_{01} - 2)(\hat{\alpha}_{02} - 2)}},$$

$$\hat{\alpha}_{0\rho} = \frac{2 \left(\hat{\alpha}_{01} + \hat{\alpha}_{02}\right) \hat{\rho}[X_{1}, X_{2}]}{3 + \hat{\rho}[X_{1}, X_{2}]}, \text{ and } \hat{\alpha}_{0\tau} = \frac{\left(\hat{\alpha}_{01} + \hat{\alpha}_{02}\right) \hat{\tau}[X_{1}, X_{2}]}{1 + \hat{\tau}[X_{1}, X_{2}]},$$

using the empirical values of Pearson's correlation, Spearman's ρ , and Kendall's τ , respectively. In the similar fashion, the entire $\theta = (\mu, \sigma, \alpha, \alpha_0)'$ can be found using appropriate MM equations, and it is thereafter used as $\theta^{(0)}$ to start with the EM algorithm.

Explicit expressions for (2.12) are generally rarely derivable. In the context of the multivariate Pareto distribution of interest, the derivation is however possible with an effort.

Lemma 2.2. Let $\mathbf{X} \backsim Pa_2(\boldsymbol{\mu}, \boldsymbol{\sigma}, \boldsymbol{\alpha}, \alpha_0)$ be the observable random vector, and let $Y_0 \backsim Pa(0, 1, \alpha_0)$ and $Y_j \backsim Pa(\mu_j, \sigma_j, \alpha_j)$, j = 1, 2 denote the latent variables. In addition, let $z(x_j) = (x_j - \mu_j)/\sigma_j$. The conditional pdf of $\mathbf{Y} = (Y_0, Y_1, Y_2)'$ on $\mathbf{X} = (X_1, X_2)'$ is

$$f_{\mathbf{Y}|\mathbf{X}}\left(\mathbf{y}\,|\mathbf{x}\right) = \begin{cases} \frac{\alpha_{0}\alpha_{i}}{\alpha_{0i}}\left(1+y_{0}\right)^{-\alpha_{0}-1}\left(1+z(x_{i})\right)^{\alpha_{0}}, & y_{j} = x_{j}, y_{i} = x_{i} \quad and \quad y_{0} > z(x_{i})\\ \frac{\alpha_{0}\alpha_{i}}{\sigma_{i}\alpha_{0i}}\left(1+y_{0}\right)^{\alpha_{i}}\left(1+\frac{y_{i}-\mu_{i}}{\sigma_{i}}\right)^{-\alpha_{i}-1}, & y_{j} = x_{j}, y_{i} > x_{i} \quad and \quad y_{0} = z(x_{i}) \end{cases},$$

for $z(x_i) > z(x_i)$, $i \neq j \in \{1, 2\}$, and

$$f_{\mathbf{Y}|\mathbf{X}}(\mathbf{y}|\mathbf{x}) = \frac{\alpha_1 \alpha_2}{\sigma_1 \sigma_2} (1 + y_0)^{\alpha_1 + \alpha_2} \left(1 + \frac{y_1 - \mu_1}{\sigma_1} \right)^{-\alpha_1 - 1} \left(1 + \frac{y_2 - \mu_2}{\sigma_2} \right)^{-\alpha_2 - 1},$$

for
$$z(x_1) = z(x_2) = y_0 < \min\{(y_1 - \mu_1)/\sigma_1, (y_2 - \mu_2)/\sigma_2\}.$$

We further employ Lemma 2.2 to estimate the parameters of the multivariate Pareto distribution of interest. To this end, for $i=1,\ldots,m$, let us redenote by $\mathbf{x}_i=(x_{1,i},x_{2,i})'$ a realization of the bivariate Pareto of the second kind random vector \mathbf{X}_i , which is an independent copy of $\mathbf{X} \backsim \operatorname{Pa}_2(\boldsymbol{\mu},\boldsymbol{\sigma},\boldsymbol{\alpha},\alpha_0)$, and let $(\mathbf{X}_i)_{i=1}^m$ be a sequence of such copies. As we have already noted, the estimation of the parameters of Pa_2 is not indeed trivial. The EM algorithm with its time-consuming M-step does not contribute to the tractability, either. Therefore, we suggest an adapted variant of the algorithm to estimate the vector $\boldsymbol{\theta}^* = (\boldsymbol{\alpha},\alpha_0)'$. We note in passing that the obvious estimate for $\boldsymbol{\mu} = (\mu_1,\mu_2)'$ is $\hat{\boldsymbol{\mu}} = (\hat{\mu}_1,\hat{\mu}_2)'$, such that $\hat{\mu}_j = \min_{i=1,\ldots,m} x_{j,i}, \quad j=1,2$, and we estimate the vector $\boldsymbol{\sigma} = (\sigma_1,\sigma_2)'$ separately employing marginal (univariate) estimation techniques.

Namely, the (k + 1)th step of the adapted EM algorithm utilized in the sequel is

E step - Evaluate $Q(\boldsymbol{\alpha}, \alpha_0; \mathbf{x}_1, \dots, \mathbf{x}_m, \boldsymbol{\alpha}^{(k)}, \alpha_0^{(k)})$ using identity (2.12) and Lemma 2.2. M1 step - Obtain the maximum likelihood estimates $\boldsymbol{\alpha}^{(k+1)}, \alpha_0^{(k+1)}$ of $\boldsymbol{\alpha}$ and α_0 à la (2.13). M2 step - Use the estimates from the M1-step above to update the marginal maximum likelihood estimate $\boldsymbol{\sigma}^{(k+1)} = (\sigma_1^{(k+1)}, \sigma_2^{(k+1)})'$ of $\boldsymbol{\sigma} = (\sigma_1, \sigma_2)'$.

The aforementioned three steps are repeated until a convergence criterion has been reached.

Recall that, for j=1, 2 and $i=1, \ldots, m$, we have that $X_{j,i}=\min\left(\sigma_{j}Y_{0,i}+\mu_{j},Y_{j,i}\right)$. To facilitate the exposition of the main result herein, let $z_{j,i}^{(k)}=\left(x_{j,i}-\hat{\mu}_{j}\right)/\sigma_{j}^{(k)}$ and also $z_{(2)i}^{(k)}=\max_{j}z_{j,i}^{(k)}$. In addition, denote by $w_{0}^{(k)}, \ w_{1}^{(k)}$, and $w_{2}^{(k)}$ the cardinalities of the sets $S_{0}^{(k)}=\left\{i:z_{1,i}^{(k)}=z_{2,i}^{(k)}\right\}$, $S_{1}^{(k)}=\left\{i:z_{1,i}^{(k)}>z_{2,i}^{(k)}\right\}$, and $S_{2}^{(k)}=\left\{i:z_{1,i}^{(k)}<z_{2,i}^{(k)}\right\}$, respectively.

Theorem 2.2. The expected log-likelihood for the (k + 1)th, $k \in \mathbb{N}$, E step is

$$Q(\boldsymbol{\alpha}, \alpha_{0}; \mathbf{x}_{1}, \dots, \mathbf{x}_{m}, \boldsymbol{\alpha}^{(k)}, \alpha_{0}^{(k)})$$

$$\propto m \ln (\alpha_{0}\alpha_{1}\alpha_{2}) - \alpha_{0} \left(\sum_{i=1}^{m} \ln \left(1 + z_{(2)i}^{(k)} \right) + \frac{\alpha_{2}^{(k)} w_{2}^{(k)}}{\alpha_{0}^{(k)} \alpha_{02}^{(k)}} + \frac{\alpha_{1}^{(k)} w_{1}^{(k)}}{\alpha_{0}^{(k)} \alpha_{01}^{(k)}} \right)$$

$$- \sum_{j=1}^{2} \alpha_{j} \left(\sum_{i=1}^{m} \ln \left(1 + z_{j,i}^{(k)} \right) + \frac{\alpha_{0}^{(k)} w_{j}^{(k)}}{\alpha_{j}^{(k)} \alpha_{0j}^{(k)}} + \frac{w_{0}^{(k)}}{\alpha_{j}^{(k)}} \right). \tag{2.14}$$

Theorem 2.2 clearly establishes the E step of the adapted EM algorithm. Thereby, the next statement follows straightforwardly, and it establishes the consequent M1 step.

Corollary 2.3. The (k + 1)th, $k \in \mathbb{N}$, step estimates of the coordinates of $\theta^* = (\alpha, \alpha_0)'$ are conveniently obtained as

$$\begin{split} &\alpha_0^{(k+1)} = m \left(\sum_{i=1}^m \ln \left(1 + z_{(2)i}^{(k)} \right) + \frac{\alpha_1^{(k)} w_1^{(k)}}{\alpha_0^{(k)} \alpha_{01}^{(k)}} + \frac{\alpha_2^{(k)} w_2^{(k)}}{\alpha_0^{(k)} \alpha_{02}^{(k)}} \right)^{-1}, \\ &\alpha_1^{(k+1)} = m \left(\sum_{i=1}^m \ln \left(1 + z_{1,i}^{(k)} \right) + \frac{\alpha_0^{(k)} w_1^{(k)}}{\alpha_1^{(k)} \alpha_{01}^{(k)}} + \frac{w_0^{(k)}}{\alpha_1^{(k)}} \right)^{-1}, \ and \\ &\alpha_2^{(k+1)} = m \left(\sum_{i=1}^m \ln \left(1 + z_{2,i}^{(k)} \right) + \frac{\alpha_0^{(k)} w_2^{(k)}}{\alpha_2^{(k)} \alpha_{02}^{(k)}} + \frac{w_0^{(k)}}{\alpha_2^{(k)}} \right)^{-1}. \end{split}$$

At last, to establish the M2 step of the adapted EM algorithm, the system

$$\sigma_j^{(k+1)} \sum_{i=1}^m \left(\sigma_j^{(k+1)} + x_{j,i} - \hat{\mu}_j \right)^{-1} = \frac{m \alpha_{0j}^{(k+1)}}{\alpha_{0j}^{(k+1)} + 1}, \ j = 1, 2,$$
 (2.15)

is solved numerically for $\sigma_j^{(k+1)}$ employing $\alpha_{0j}^{(k+1)}$, j=1, 2, evaluated at the M1 step.

Note 2.1. Noticeably, Corollary 2.3 extends to the trivariate case in a similar fashion. Namely, let $\{j,l,q\}=\{1,2,3\}$ and denote by $w_j^{(k)},w_{jl}^{(k)}$, and $w_0^{(k)}$ the cardinalities of the sets $S_j^{(k)}=\left\{i:z_{j,i}^{(k)}>\max\{z_{l,i}^{(k)},z_{q,i}^{(k)}\}\right\}$, $S_{jl}^{(k)}=\left\{i:z_{j,i}^{(k)}=z_{l,i}^{(k)}>z_{q,i}^{(k)}\right\}$, and $S_0^{(k)}=\left\{i:z_{1,i}^{(k)}=z_{2,i}^{(k)}=z_{3,i}^{(k)}\right\}$, respectively. Then the (k+1)th step estimates of the coordinates of $\boldsymbol{\theta}^*=(\boldsymbol{\alpha},\alpha_0)'$ arise as

$$\begin{split} &\alpha_0^{(k+1)} = m \left(\sum_{i=1}^m \ln \left(1 + z_{(3)i}^{(k)} \right) + \frac{1}{\alpha_0^{(k)}} \sum_{j=1}^3 \frac{\alpha_j^{(k)} w_j^{(k)}}{\alpha_{0j}^{(k)}} \right)^{-1}, \\ &\alpha_j^{(k+1)} = m \left(\sum_{i=1}^m \ln \left(1 + z_{j,i}^{(k)} \right) + \frac{1}{\alpha_j^{(k)}} \left(\frac{\alpha_0^{(k)} w_j^{(k)}}{\alpha_{0j}^{(k)}} + w_{jl}^{(k)} + w_{jq}^{(k)} + w_0^{(k)} \right) \right)^{-1}, \end{split}$$

Table 1 Estimated parameters for the simulated bivariate Pareto $\mathbf{X} \backsim \operatorname{Pa}_2(\boldsymbol{\mu}, \boldsymbol{\sigma}, \boldsymbol{\alpha}, \alpha_0)$, with $\boldsymbol{\mu} = (1, 2)', \ \boldsymbol{\sigma} = (2, 3)', \ \boldsymbol{\alpha} = (2, 2)', \ \alpha_0 = 2$

		Multivariate	Adapted				
Parameters Pearson's Corr		Spearman's ρ	Kendall's τ	MLE	EM		
\hat{lpha}_0	2.18480	2.09250	2.08020	2.03579	2.04602		
\hat{lpha}_1	1.80185	1.89415	1.90645	1.95086	1.95178		
\hat{lpha}_2	1.99119	2.08349	2.09579	2.14020	2.04601		
$\hat{\sigma}_1$		2.0102	25		2.01722		
$\hat{\sigma}_2$		3.1221	.5		3.04672		
$\hat{\mu}_1$	1.0000029						
	2.0002214						
$\frac{\hat{\mu}_2}{\chi^2}$	27.9646	17.6281	17.1714	17.2520	14.2909		

where j = 1, 2, 3.

After our derivations herein had been accomplished, we found a work by Kundu and Dey (2009), in which yet somewhat different approach to the EM algorithm was followed in the context of a bivariate Weibull distribution. More specifically, in the aforementioned article, the orderings among the coordinates of $\mathbf{Y} = (Y_0, Y_1, Y_2)'$, rather than the coordinates themselves, were considered a missing information. The two results are however isomorphic.

3. A Numerical Illustration

3.1. Bivariate Case

To exemplify and compare the various estimation methods presented above, we have generated bivariate Pareto random vectors $\mathbf{X}_i \sim \text{Pa}_2(\boldsymbol{\mu}=(1,\ 2)',\boldsymbol{\sigma}=(2,\ 3)',\boldsymbol{\alpha}=(2,\ 2)',\alpha_0=2),\ i=1,\ldots,m=5,000$, and we have then applied the multivariate MLE (see Section

Table 2
The AE, MSE, and AI indexes for the adapted EM method with varying sample size and $\mathbf{X} \backsim \mathrm{Pa}_2(\boldsymbol{\mu}, \boldsymbol{\sigma}, \boldsymbol{\alpha}, \alpha_0)$, where $\boldsymbol{\mu} = (1, 1)', \ \boldsymbol{\sigma} = (1, 1)', \ \boldsymbol{\alpha} = (2, 2)', \ \alpha_0 = 2$

	m = 1,000, $AI = 1,697$		m = 2,000, $AI = 1651$		m = 3,000, $AI = 1,568$		m = 4,000, $AI = 1,515$	
	AE	MSE	AE	MSE	AE	MSE	AE	MSE
μ_1	1.0001	6×10^{-8}	1.0001	2×10^{-8}	1.00006	10^{-8}	1.00005	10^{-9}
μ_2	1.0002	9×10^{-8}	1.0001	2×10^{-8}	1.00006	10^{-8}	1.00005	10^{-8}
σ_1	1.0010	0.0190	1.0119	0.0166	1.0089	0.0120	1.0017	0.0047
σ_2	1.0141	0.0230	1.0144	0.0214	1.0171	0.0095	1.0014	0.0069
α_1	2.0178	0.1060	2.1578	0.1643	2.0870	0.0772	2.0578	0.0536
α_2	2.2152	0.3095	2.0327	0.1836	2.1368	0.0831	2.0439	0.0420
α_0	1.9557	0.0836	1.9424	0.0373	1.9682	0.0239	1.9411	0.0205

Table 3
The AE, MSE, and AI indexes for the adapted EM method with varying α_0 and $\mathbf{X} \sim \text{Pa}_2(\boldsymbol{\mu}, \boldsymbol{\sigma}, \boldsymbol{\alpha}, \alpha_0)$, where $\boldsymbol{\mu} = (1, 1)'$, $\boldsymbol{\sigma} = (1, 1)'$, $\boldsymbol{\alpha} = (2, 2)'$, and m = 4,000

	$\alpha_0 = 1,$ $AI = 686$		$\alpha_0 = 1.5,$ AI = 1, 047		$\alpha_0 = 2,$ AI = 1,515		$\alpha_0 = 2.5,$ AI = 2, 122	
	AE	MSE	AE	MSE	AE	MSE	AE	MSE
$\overline{\mu_1}$	1.00008	1×10^{-8}	1.0001	2×10^{-8}	1.00006	10^{-8}	1.00004	10^{-9}
μ_2	1.00007	1×10^{-8}	1.0001	2×10^{-8}	1.00006	10^{-8}	1.00006	10^{-8}
σ_1	1.0039	0.0046	0.9916	0.0052	1.0017	0.0047	1.0219	0.0098
σ_2	0.9994	0.0063	1.0195	0.0101	1.0014	0.0069	1.0029	0.0130
α_1	2.0342	0.0247	2.0083	0.0276	2.0578	0.0536	2.0228	0.0543
α_2	2.0329	0.0340	2.0119	0.0499	2.0912	0.0420	2.0912	0.0987
α_0	0.9803	0.0041	1.4533	0.0093	1.9411	0.0205	2.4223	0.0404

2.2), as well as the MM and the adapted EM (see Section 2.3) methods to estimate μ , σ , α , and α_0 . To rank the various estimation techniques, we have used the well-known Pearson's χ^2 test (see Greenwood and Nikulin, 1996 for details).

As expected in our case, the χ^2 test at a significance level of 0.01 has rejected the Pearson's correlation-based MM method, only. This is not surprising, bearing in mind the expression for the conditional expectation, derived in Corollary 3.1 of Asimit et al. (2010), that is, the linear correlation is not a good measure of dependence for the multivariate Pareto distribution of interest. To rank among other estimation techniques, we have employed the χ^2 values (see Table 1; the lower–the better). Other entries of the table are briefly explained below.

Table 4 The AE, MSE, and AI indexes for the adapted EM method with varying sample sizes and $\mathbf{X} \sim \text{Pa}_3(\boldsymbol{\mu}, \boldsymbol{\sigma}, \boldsymbol{\alpha}, \alpha_0)$, where $\boldsymbol{\mu} = (1, 1, 1)', \ \boldsymbol{\sigma} = (1, 1, 1)', \ \boldsymbol{\alpha} = (2, 2, 2)', \text{ and } \alpha_0 = 2$

	m = 1,000, AI = 1,789		m = 2,000, AI = 1,642		m = 3,000, AI = 1,618		m = 3,500, AI = 1,541	
	AE	MSE	AE	MSE	AE	MSE	AE	MSE
$\overline{\mu_1}$	1.0002	7×10^{-8}	1.0001	10^{-8}	1.00005	10^{-8}	1.00007	10^{-8}
μ_2	1.0002	9×10^{-8}	1.0001	2×10^{-8}	1.00007	10^{-8}	1.00007	10^{-8}
μ_3	1.0002	8×10^{-8}	1.0001	3×10^{-8}	1.00006	10^{-8}	1.00004	10^{-8}
σ_1	0.9749	0.0298	1.0019	0.0212	1.0174	0.0072	1.0023	0.0040
σ_2	1.0205	0.0389	0.9941	0.0181	1.0070	0.0136	0.9944	0.0139
σ_3	1.0057	0.0339	1.0122	0.0149	1.0132	0.0113	0.9989	0.0043
α_1	2.0531	0.2025	2.1319	0.1773	2.0590	0.0517	2.0284	0.0501
α_2	2.2112	0.3228	2.1021	0.1415	2.1211	0.1074	1.9915	0.0600
α_3	2.1902	0.2850	1.9654	0.1055	2.1401	0.1006	2.0716	0.0625
α_0	1.8670	0.0611	1.8740	0.0367	1.9148	0.0284	1.8910	0.0280

The obvious estimates of μ_1 and μ_2 have been obtained as $\hat{\mu}_1 = 1.0000029$ and $\hat{\mu}_2 = 2.0002214$, and these values have been used in all three estimation techniques. The estimates of σ_1 and σ_2 have been developed as solutions of the marginal MLE system of equations—in the context of the MM and the multivariate MLE methods, and as iteratively updated solutions of the marginal MLE system—in the context of the adapted EM algorithm. The advantage of the latter technique is reflected in the corresponding χ^2 values. Similarly, the adapted EM algorithm seems to have outperformed the MM and the multivariate MLE when estimating α_0 , α_1 , and α_2 .

Next in order to verify the performance of the proposed EM method as opposed to sample size, we have kept $\mu_1 = \mu_2 = 1$, $\sigma_1 = \sigma_2 = 1$, and $\alpha_1 = \alpha_2 = \alpha_0 = 2$ fixed and let the sample size vary. Also, as the starting values did not influence the Average Estimates (AEs), we have further fixed $\sigma_1 = \sigma_2 = \alpha_1 = \alpha_2 = \alpha_0 = 1.5$ as initial values. The stopping criterion hinged on the difference between parameters' consecutive values (stop if less than 10^{-6} in absolute value). Based on 100 replications, we thereby obtained the AE and the mean squared error (MSE) for each parameter, as well as the average number of iterations (AI), required. The results are depicted in Table 2, and we notice that the estimation naturally improves with sample size.

To elucidate the influence of the dependence on the outputs of the adapted EM algorithm, we let the values of α_0 vary, and set $\mu_1 = \mu_2 = 1$, $\sigma_1 = \sigma_2 = 1$ and $\alpha_1 = \alpha_2 = 2$. In this respect, Table 3 seems to imply that the weaker the dependence is, the more effective the EM algorithm becomes.

3.2. Trivariate Case

To conclude, we have also applied the EM method in the trivariate case with varying sample sizes and fixed $\mu_1 = \mu_2 = \mu_3 = 1$, $\sigma_1 = \sigma_2 = \sigma_3 = 1$ and $\alpha_1 = \alpha_2 = \alpha_3 = \alpha_0 = 2$. The outcomes are depicted in Table 4, and they are comparable with these in Table 2.

Appendix: Proofs

Proof of Theorem 2.1. According to (2.7), we readily have that, for any C in the Borel σ -algebra \mathcal{B}^n in \mathbf{R}^n ,

$$\mathbf{P}[\{\mathbf{X} \in \mathcal{C}\}] = \int_{\mathcal{C}} f_{\mathbf{X}} d\nu = \int_{\mathcal{C}} f_{\mathbf{X}} d\nu_n + \sum_{r=2}^n \int_{\mathcal{C}} f_{\mathbf{X}} d\nu_{n-r+1}.$$

Therefore, to treat the right most side, and for each r = 2, ..., n and $\mathcal{T}_r = \mathcal{I}_n \setminus \mathcal{I}_r$, we start with the probability

$$\mathbf{P}\left[\left\{\mathbf{X} > \mathbf{x}\right\} \bigcap \left\{\frac{X_{i_1} - \mu_{i_1}}{\sigma_{i_1}} = \cdots = \frac{X_{i_r} - \mu_{i_r}}{\sigma_{i_r}}\right\}\right] \\
\stackrel{!}{=} \mathbf{P}\left[\bigcap_{l \in \mathcal{T}_r} \left\{Y_l > x_l\right\} \bigcap_{j=1}^r \left\{Y_0 \le \frac{Y_{i_j} - \mu_{i_j}}{\sigma_{i_j}}\right\} \bigcap \left\{Y_0 > z_{(n)}\right\}\right] \\
\stackrel{!}{=} \left(\prod_{l \in \mathcal{T}_r} \overline{F}_{Y_l}(x_l)\right) \int_{z_{(n)}}^{\infty} f_{Y_0}(y_0) \left(\prod_{j=1}^r \int_{\sigma_{i_j} y_0 + \mu_{i_j}}^{\infty} f_{Y_{i_j}}(y_j) \, dy_j\right) dy_0$$

$$\begin{split} &= \left(\prod_{l \in \mathcal{T}_r} \overline{F}_{Y_l}\left(x_l\right)\right) \int\limits_{z_{(n)}}^{\infty} \alpha_0 \left(1 + y_0\right)^{-\left(\alpha_0 + \sum_{j=1}^r \alpha_{i_j} + 1\right)} dy_0 \\ &= \frac{\alpha_0}{\alpha_0 + \sum_{j=1}^r \alpha_{i_j}} \left(1 + z_{(n)}\right)^{-\left(\alpha_0 + \sum_{j=1}^r \alpha_{i_j}\right)} \prod\limits_{l \in \mathcal{T}_r} \left(1 + \frac{x_l - \mu_l}{\sigma_l}\right)^{-\alpha_l}, \end{split}$$

where $\underline{1}$ is because, for $\sigma_j \in \mathbf{R}_+$, $\mu_j \in \mathbf{R}$ and j = 1, ..., n, we have that

$$\frac{\min(\sigma_j Y_0 + \mu_j, Y_j) - \mu_j}{\sigma_j} = \min\left(Y_0, \frac{Y_j - \mu_j}{\sigma_j}\right),\,$$

and $\underline{\underline{2}}$ holds by independence. The corresponding density is then obtained (recall the dimension of the measure ν_{n-r+1}) by differentiating with respect to $z_{(n)}$, as well as with respect to each x_l with $l \in \mathcal{T}_r$, as

$$f(x_1,\ldots,x_n)=\alpha_0\left(1+z_{(n)}\right)^{-\left(\alpha_0+\sum_{j=1}^r\alpha_{i_j}+1\right)}\prod_{l\in\mathcal{T}}\frac{\alpha_l}{\sigma_l}\left(1+\frac{x_l-\mu_l}{\sigma_l}\right)^{-(\alpha_l+1)},$$

which along with (2.5) and keeping in mind (2.7) and the Radon–Nikodym theorem completes the proof.

Proof of Lemma 2.2. It is clear that the ddf of the complete data random vector is conveniently written as

$$\mathbf{P}[\{Y > y\} \cap \{X > x\}]
= \mathbf{P}[Y_0 > \max(z(x_1), z(x_2), y_0)] \mathbf{P}[Y_1 > \max(x_1, y_1)] \mathbf{P}[Y_2 > \max(x_2, y_2)],$$

where $y_j > \mu_j$ and $x_j > \mu_j$, j = 1, 2, as well as $y_0 > 0$. Consequently various orderings of $z(x_1)$, $z(x_2)$ and y_0 must be treated separately. More specifically, utilizing (2.8), we readily have that, for example, for $z(x_1) = z(x_2) = y_0$ and thus $y_0 < \min\left(\frac{y_1 - \mu_1}{\sigma_1}, \frac{y_2 - \mu_2}{\sigma_2}\right)$, the conditional pdf of interest reduces to

$$f_{\mathbf{Y}|\mathbf{X}}(\mathbf{y}|\mathbf{x}) = f_{Y_0}(y_0) f_{Y_1}(y_1) f_{Y_2}(y_2) (f_{\mathbf{X}}(\mathbf{x}))^{-1},$$

as required.

A somewhat more tedious case is the one where $z(x_1) \neq z(x_2)$ and $y_0 > \max(z(x_1), z(x_2))$, which implies that $x_j = y_j$, j = 1, 2. Then the ddf to be considered is

$$\mathbf{P}[\{\mathbf{Y} > \mathbf{y}\} \cap \{\mathbf{X} > \mathbf{x}\} \cap \{X_1 = Y_1\} \cap \{X_2 = Y_2\} \cap \{Y_0 > \max\{z(X_1), z(X_2)\}\}] \\
= \mathbf{P}[\{Y_0 > y_0\} \cap \{\sigma_1 Y_0 + \mu_1 > Y_1 > x_1\} \cap \{\sigma_2 Y_0 + \mu_2 > Y_2 > x_2\}] \\
= \int_{y_0}^{\infty} f_{Y_0}(u_0) \left(\prod_{j=1}^{2} \int_{x_j}^{\sigma_j u_0 + \mu_j} f_{Y_j}(u_j) du_j \right) du_0 \\
= \int_{y_0}^{\infty} f_{Y_0}(u_0) \prod_{j=1}^{2} \left(\overline{F}_{Y_j}(x_j) - \overline{F}_{Y_j}(\sigma_j u_0 + \mu_j) \right) du_0$$

$$= \overline{F}_{Y_0}(y_0) \overline{F}_{Y_1}(x_1) \overline{F}_{Y_2}(x_2) + H_0(y_0) + H_1(y_0, x_1) + H_2(y_0, x_2),$$

which thus yields

$$f_{\mathbf{Y}|\mathbf{X}}(\mathbf{y}|\mathbf{x}) = f_{Y_0}(y_0) f_{Y_1}(x_1) f_{Y_2}(x_2) (f_{\mathbf{X}}(\mathbf{x}))^{-1},$$

and it in turn disintegrates as expected keeping in mind (2.8).

The proof of the remaining two expressions is knocked out in an entirely similar fashion, and it is thus left to the reader. This completes the proof of the lemma. \Box

Proof of Theorem 2.1. By definition and utilizing Lemma 2.2, we have that

$$\begin{split} & Q(\boldsymbol{\alpha}, \alpha_{0}; \mathbf{x}_{1}, \dots, \mathbf{x}_{m}, \boldsymbol{\alpha}^{(k)}, \alpha_{0}^{(k)}) \\ & = \mathbf{E} \bigg[\sum_{i=1}^{m} \ln f_{\mathbf{X}_{i}, \mathbf{Y}} \left(\mathbf{X}_{i}, \ \mathbf{Y}; \ \boldsymbol{\sigma}^{(k)}, \boldsymbol{\alpha}, \alpha_{0} \right) \, \big| \ \mathbf{X}_{i} = \mathbf{x}_{i}, \ \boldsymbol{\theta}^{(k)} \bigg] \\ & = \mathbf{E} \bigg[\left(\sum_{i=1}^{m} \ln \left(f_{Y_{0}}(Y_{0}) \, f_{Y_{1}} \left(X_{1,i} \right) \, f_{Y_{2}} \left(X_{2,i} \right) \right) \right) \mathbf{1} \, \left\{ \begin{aligned} z_{1,i}^{(k)} & \neq z_{2,i}^{(k)}, \ Y_{j} = X_{j,i}, \ j = 1, 2 \\ Y_{0} &> \max \left\{ z_{1,i}^{(k)}, z_{2,i}^{(k)} \right\} \end{aligned} \right\} \\ & \quad \left| \ \mathbf{X}_{i} = \mathbf{x}_{i}, \ \boldsymbol{\theta}^{(k)} \right] \\ & \quad \left| \mathbf{X}_{i} = \mathbf{x}_{i}, \ \boldsymbol{\theta}^{(k)} \right] \\ & \quad \left| \ \mathbf{X}_{i} = \mathbf{x}_{i}, \ \boldsymbol{\theta}^{(k)} \right] \\ & \quad \left| \ \mathbf{X}_{i} = \mathbf{x}_{i}, \ \boldsymbol{\theta}^{(k)} \right] \\ & \quad \left| \ \mathbf{X}_{i} = \mathbf{x}_{i}, \ \boldsymbol{\theta}^{(k)} \right] \\ & \quad \left| \ \mathbf{X}_{i} = \mathbf{x}_{i}, \ \boldsymbol{\theta}^{(k)} \right] \\ & \quad \left| \ \mathbf{X}_{i} = \mathbf{x}_{i}, \ \boldsymbol{\theta}^{(k)} \right] \\ & \quad \left| \ \mathbf{X}_{i} = \mathbf{x}_{i}, \ \boldsymbol{\theta}^{(k)} \right] \\ & \quad \left| \ \mathbf{X}_{i} = \mathbf{x}_{i}, \ \boldsymbol{\theta}^{(k)} \right] \\ & \quad \left| \ \mathbf{X}_{i} = \mathbf{x}_{i}, \ \boldsymbol{\theta}^{(k)} \right] \\ & \quad \left| \ \mathbf{X}_{i} = \mathbf{x}_{i}, \ \boldsymbol{\theta}^{(k)} \right] . \end{aligned}$$

Further, according to Lemma 2.2, three distinct cases must be considered. Namely, for, for example, $z_{2,i}^{(k)} > z_{1,i}^{(k)}$, $i=1,\ldots,m$, we have that

$$Q_{1}(\boldsymbol{\alpha}, \alpha_{0}; \mathbf{x}_{1}, \dots, \mathbf{x}_{m}, \boldsymbol{\alpha}^{(k)}, \alpha_{0}^{(k)})$$

$$= \mathbf{E} \left[\left(\sum_{i=1}^{m} \ln \left(f_{Y_{0}}(Y_{0}) f_{Y_{1}}(X_{1,i}) f_{Y_{2}}(X_{2,i}) \right) \right) \mathbf{1} \left\{ \begin{array}{l} Y_{0} > z_{2,i}^{(k)} > z_{1,i}^{(k)}, \\ X_{j,i} = Y_{j}, j = 1, 2 \end{array} \right\}$$

$$\left| \mathbf{X}_{i} = \mathbf{x}_{i}, \boldsymbol{\theta}^{(k)} \right]$$

$$\begin{split} &+ \mathbf{E} \bigg[\left(\sum_{i=1}^{m} \ln \left(f_{Y_0} \left(Y_0 \right) \frac{f_{Y_1} \left(X_{1,i} \right)}{\sigma_2^{(k)}} f_{Y_2} \left(Y_2 \right) \right) \right) \mathbf{1} \left\{ Y_0 = z_{2,i}^{(k)} > z_{1,i}^{(k)}, \\ & Y_2 > X_{2,i}, X_{1,i} = Y_1 \right\} \\ &= \sum_{\substack{i = 1, \dots, m \\ z_{2,i}^{(k)} > z_{1,i}^{(k)}}} \int \ln \left(\alpha_0 \left(1 + y_0 \right)^{-\alpha_0 - 1} \frac{\alpha_1 \alpha_2}{\sigma_1^{(k)} \sigma_2^{(k)}} \left(1 + z_{1,i}^{(k)} \right)^{-\alpha_1 - 1} \left(1 + z_{2,i}^{(k)} \right)^{-\alpha_2 - 1} \right) \\ &\times \frac{\alpha_0^{(k)} \alpha_2^{(k)}}{\sigma_0^{(k)}} \left(1 + z_{2,i}^{(k)} \right)^{\alpha_0^{(k)}} \left(1 + y_0 \right)^{-\alpha_0^{(k)} - 1} \mathbf{1} \{ y_0 > z_{2,i}^{(k)} \} dy_0 \\ &+ \sum_{\substack{i = 1, \dots, m \\ z_{2,i}^{(k)} > z_{1,i}^{(k)}}} \int \ln \left(\frac{\alpha_0}{\sigma_2^{(k)}} \left(1 + z_{2,i}^{(k)} \right)^{-\alpha_0 - 1} \frac{\alpha_1 \alpha_2}{\sigma_1^{(k)} \sigma_2^{(k)}} \left(1 + z_{1,i}^{(k)} \right)^{-\alpha_1 - 1} \right. \\ &\times \left(1 + \frac{y_2 - \hat{\mu}_2}{\sigma_2^{(k)}} \right)^{-\alpha_2 - 1} \right) \\ &\times \frac{\alpha_0^{(k)} \alpha_2^{(k)}}{\sigma_2^{(k)} \alpha_0^{(k)}} \left(1 + z_{2,i}^{(k)} \right)^{\alpha_2^{(k)}} \left(1 + \frac{y_2 - \hat{\mu}_2}{\sigma_2^{(k)}} \right)^{-\alpha_2^{(k)} - 1} \mathbf{1} \{ y_2 > x_{2,i} \} dy_2 \\ &\propto \sum_{\substack{i = 1, \dots, m \\ z_{2,i}^{(k)} > z_{1,i}^{(k)}}} \left(\ln \left(\alpha_0 \alpha_1 \alpha_2 \right) - \left(\alpha_0 + \alpha_2 \right) \ln \left(1 + z_{2,i}^{(k)} \right) - \alpha_1 \ln \left(1 + z_{1,i}^{(k)} \right) \\ &- \frac{\alpha_0 \alpha_2^{(k)}}{\alpha_0^{(k)} \alpha_0^{(k)}} - \frac{\alpha_2 \alpha_0^{(k)}}{\alpha_2^{(k)} \alpha_0^{(k)}} \right), \end{split}$$

neglecting the terms that do not depend on α_0 and/or α .

A similar expression follows, for example, by symmetry, for the opposite case, where $z_{2,i}^{(k)} < z_{1,i}^{(k)}$, that is, we have that

$$\begin{aligned} Q_{2}(\boldsymbol{\alpha}, \alpha_{0}; \mathbf{x}_{1}, \dots, \mathbf{x}_{m}, \boldsymbol{\alpha}^{(k)}, \alpha_{0}^{(k)}) \\ &= \sum_{\substack{i = 1, \dots, m \\ z_{2,i}^{(k)} < z_{1,i}^{(k)}}} \left(\ln \left(\alpha_{0} \alpha_{1} \alpha_{2} \right) - \left(\alpha_{0} + \alpha_{1} \right) \ln \left(1 + z_{1,i}^{(k)} \right) - \alpha_{2} \ln \left(1 + z_{2,i}^{(k)} \right) \right. \\ &\left. - \frac{\alpha_{0} \alpha_{1}^{(k)}}{\alpha_{0}^{(k)} \alpha_{01}^{(k)}} - \frac{\alpha_{1} \alpha_{0}^{(k)}}{\alpha_{1}^{(k)} \alpha_{01}^{(k)}} \right). \end{aligned}$$

Finally, for $z_{2,i}^{(k)} = z_{1,i}^{(k)}$, we readily obtain that

$$Q_{3}(\boldsymbol{\alpha}, \alpha_{0}; \mathbf{x}_{1}, \dots, \mathbf{x}_{m}, \boldsymbol{\alpha}^{(k)}, \alpha_{0}^{(k)})$$

$$= \mathbf{E} \left[\left(\sum_{i=1}^{m} \ln \left(f_{Y_{0}}(Y_{0}) f_{Y_{1}}(Y_{1}) f_{Y_{2}}(Y_{2}) \right) \right) \mathbf{1} \left\{ \begin{array}{l} Y_{0} = z_{1,i}^{(k)} = z_{2,i}^{(k)} \\ Y_{0} < \max \left\{ \frac{Y_{1} - \hat{\mu}_{1}}{\sigma_{1}^{(k)}}, \frac{Y_{2} - \hat{\mu}_{2}}{\sigma_{2}^{(k)}} \right\} \right\} \right]$$

$$\mid \mathbf{X}_{i} = \mathbf{x}_{i}, \quad \boldsymbol{\theta}^{(k)} \right]$$

$$\propto \sum_{\substack{i = 1, \dots, m \\ z_{2}^{(k)} = z_{i,i}^{(k)}}} \left(\ln (\alpha_{0}\alpha_{1}\alpha_{2}) - (\alpha_{0} + \alpha_{1} + \alpha_{2}) \ln \left(1 + z_{(2)i}^{(k)} \right) - \frac{\alpha_{1}}{\alpha_{1}^{(k)}} - \frac{\alpha_{2}}{\alpha_{2}^{(k)}} \right).$$

The expected log-likelihood of interest then follows as

$$Q(\boldsymbol{\alpha}, \alpha_0; \mathbf{x}_1, \dots, \mathbf{x}_m, \boldsymbol{\alpha}^{(k)}, \alpha_0^{(k)}) = \sum_{i=1}^3 Q_i(\boldsymbol{\alpha}, \alpha_0; \mathbf{x}_1, \dots, \mathbf{x}_m, \boldsymbol{\alpha}^{(k)}, \alpha_0^{(k)}),$$

which reduces to (2.14) as required and hence completes the proof.

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