# IET Winter 2016 Semester-6 Digital Signal Processing

# LAB3

## **Objectives:**

Understand different concepts of linear and circular convolution along with its applications.

#### **Prerequisites:**

- Linear Convolution
- 2D Convolution
- Circular Convolution

### **Problems**

1. Explore command **conv2** in Matlab. Take input of 2 Matrix from user and Find 2D convolution of the same. Also explore the properties of **conv2** command and analyze the result.

For an example

$$A = \begin{bmatrix} 17 & 24 & 1 & 8 & 15 \\ 23 & 5 & 7 & 14 & 16 \\ 4 & 6 & 13 & 20 & 22 \\ 10 & 12 & 19 & 21 & 3 \\ 11 & 18 & 25 & 2 & 9 \end{bmatrix} \qquad B = \begin{bmatrix} 1 & 3 & 1 \\ 0 & 5 & 0 \\ 2 & 1 & 2 \end{bmatrix}$$

- 2. Application of 2D convolution on image processing applications
  - a) Take a standard test image "Lenna.png" from shared folder. Explore following commands and apply for given image.
    - imread
    - rgb2gray
    - imshow
  - b) Now in order to perform 2D convolution, Given image becomes first input as matrix and second input will be a sets of kernel matrix performing different operations on image which are mentioned below:

## **List of different kernels:**

In image processing, a kernel, convolution matrix, or mask is a small matrix useful for averaging, sharpening, embossing, edge-detection, and more. This is accomplished by means of convolution between a kernel and an image.

Average (blur, smooth) 3x3 convolution kernel

$$A = \begin{bmatrix} 1/9 & 1/9 & 1/9 \\ 1/9 & 1/9 & 1/9 \\ 1/9 & 1/9 & 1/9 \end{bmatrix}$$

Sharpen 3x3 convolution kernel

$$S = \begin{bmatrix} 0 & -1 & 0 \\ -1 & 5 & -1 \\ 0 & -1 & 0 \end{bmatrix}$$

Edge detection 3x3 convolution kernel

$$\mathsf{E} = \begin{bmatrix} 0 & -1 & 0 \\ -1 & 4 & -1 \\ 0 & -1 & 0 \end{bmatrix}$$

$$\mathsf{E} = \begin{bmatrix} 0 & -1 & 0 \\ -1 & 4 & -1 \\ 0 & -1 & 0 \end{bmatrix} \qquad \mathsf{E}_\mathsf{H} = \begin{bmatrix} 0 & 0 & 0 \\ -1 & 2 & -1 \\ 0 & 0 & 0 \end{bmatrix} \qquad \mathsf{E}_\mathsf{V} = \begin{bmatrix} 0 & -1 & 0 \\ 0 & 2 & 0 \\ 0 & -1 & 0 \end{bmatrix}$$

$$\mathsf{E}_{\mathsf{V}} = \begin{bmatrix} 0 & -1 & 0 \\ 0 & 2 & 0 \\ 0 & -1 & 0 \end{bmatrix}$$

Gradient detection 3x3 convolution kernel

$$G_{H} = \begin{bmatrix} -1 & -1 & -1 \\ 0 & 0 & 0 \\ 1 & 1 & 1 \end{bmatrix} \qquad G_{V} = \begin{bmatrix} -1 & 0 & 1 \\ -1 & 0 & 1 \\ -1 & 0 & 1 \end{bmatrix}$$

$$G_{V} = \begin{bmatrix} -1 & 0 & 1 \\ -1 & 0 & 1 \\ -1 & 0 & 1 \end{bmatrix}$$

Sobel Operator 3x3 convolution kernel

$$S_{H} = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & 0 \\ -1 & -2 & -1 \end{bmatrix} \qquad S_{V} = \begin{bmatrix} 1 & 0 & -1 \\ 2 & 0 & -2 \\ 1 & 0 & -1 \end{bmatrix}$$

$$S_V = \begin{bmatrix} 1 & 0 & -1 \\ 2 & 0 & -2 \\ 1 & 0 & -1 \end{bmatrix}$$

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3. Develop a MATLAB function to obtain circular convolution of two sequences. Use definition of circular convolution to obtain the output sequence. Verify the function for following sequence. Write a script file to use the developed function.

1. 
$$x_1(n) = \{1,-1,-2,3,-1\}$$
 and  $x_2(n) = \{1,2,3\}$ 

2. 
$$x_1(n) = \{1, 2, 1, 2\}$$
 and  $x_2(n) = \{3, 2, 1, 4\}$ 

3. 
$$x_1(n) = \cos\left(\frac{2\pi n}{N}\right)$$
 and  $x_2(n) = \sin\left(\frac{2\pi n}{N}\right)$ ,  $0 \le n \le N - 1$ .for N=8

4. Write a MATLAB program to find circular convolution of two sequences using Matrix Multiplication method.

4. 
$$x_1(n) = \{1,-1,-2,3,-1\}$$
 and  $x_2(n) = \{1,2,3\}$ 

5. 
$$x_1(n) = \{1, 2, 1, 2\}$$
 and  $x_2(n) = \{3, 2, 1, 4\}$ 

6. 
$$x_1(n) = \cos\left(\frac{2\pi n}{N}\right)$$
 and  $x_2(n) = \sin\left(\frac{2\pi n}{N}\right)$ ,  $0 \le n \le N - 1$ .for N=8