

IET winter 2016
Semester-6
Digital Signal Processing

LAB 7-8

Objectives:

Understand different concepts of Z-transform

Prerequisites:

- Z-transform and its properties, Inverse z-transform, Concept of ROC

Explore Following Commands:

- syms
- ztrans
- zplan
- iztrans
- impz

Problems

1. Use MATLAB to obtain Symbolic Z-Transform of some basic signals.


- a. $X(n) = u(n)$
- b. $X(n) = nu(n)$
- c. $X(n) = (1+n) u(n)$
- d. $X(n) = \cos(\omega_0 n) u(n)$
- e. $X(n) = \sin(\omega_0 n) u(n)$
- f. $X(n) = a^n \cos(\omega_0 n) u(n)$
- g. $X(n) = a^n \sin(\omega_0 n) u(n)$
- h. $X(n) = n a^n u(n) ;$
- i. $X(n) = -n a^n u(-n - 1) ;$
- j. $X(n) = n (-1)^n u(n)$
- k. $X(n) = (n)^2 u(n)$

2. Use MATLAB to Plot poles and zeros of the Z-transform obtained for following signals.

a. $X(n) = \left(\frac{1}{2}\right)^n u(n) + \left(-\frac{1}{3}\right)^n u(n)$

b. $X(n) = \left(-\frac{1}{3}\right)^n u(n) - \left(\frac{1}{2}\right)^n u(-n-1)$

c. $X(n) = \left(\frac{1}{2}\right)^n u(-n)$

d. $X(n) = \{-1, 0, -1, 0, -1, 0, -1, 0, -1, \dots\}$


3. Use MATLAB to obtain Symbolic Inverse Z-Transform of some basic signals.

a. $X(z) = \left(\frac{1+3z^{-1}}{1-3z^{-1}+2z^{-2}}\right)$

b. $X(z) = \left(\frac{1+2z^{-1}}{1+z^{-2}}\right)$

c. $X(z) = \left(\frac{1+2z^{-1}+z^{-2}}{1+4z^{-1}+4z^{-2}}\right)$

4. I) Use MATLAB to obtain impulse response & step response of the systems specified below

II) Use MATLAB to obtain pole-zero plot of the systems specified in (a), (b), (c)

a. $Y(n) = 0.75 y(n-1) - 0.125 y(n-2) + x(n)$

b. $Y(n) = y(n-1) + x(n)$

c. $Y(n) = 0.7 y(n-1) - 0.1 y(n-2) + 2 x(n) - x(n-2)$