

Image Completion Using Low Tensor Tree Rank and Total Variation Minimization

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Outline

- related work
 - Total variation
 - The state-of-art tensor completion with smooth constraint
- proposed optimization model
 - proposed algorithm
 - solution
- Simulation
 - Color image completion
- Conclusion

Tensor tree format

Specially , for the root D we have $A^{(D)} = U_D \in \mathbb{R}^{I \times 1} (k_D = 1)$.

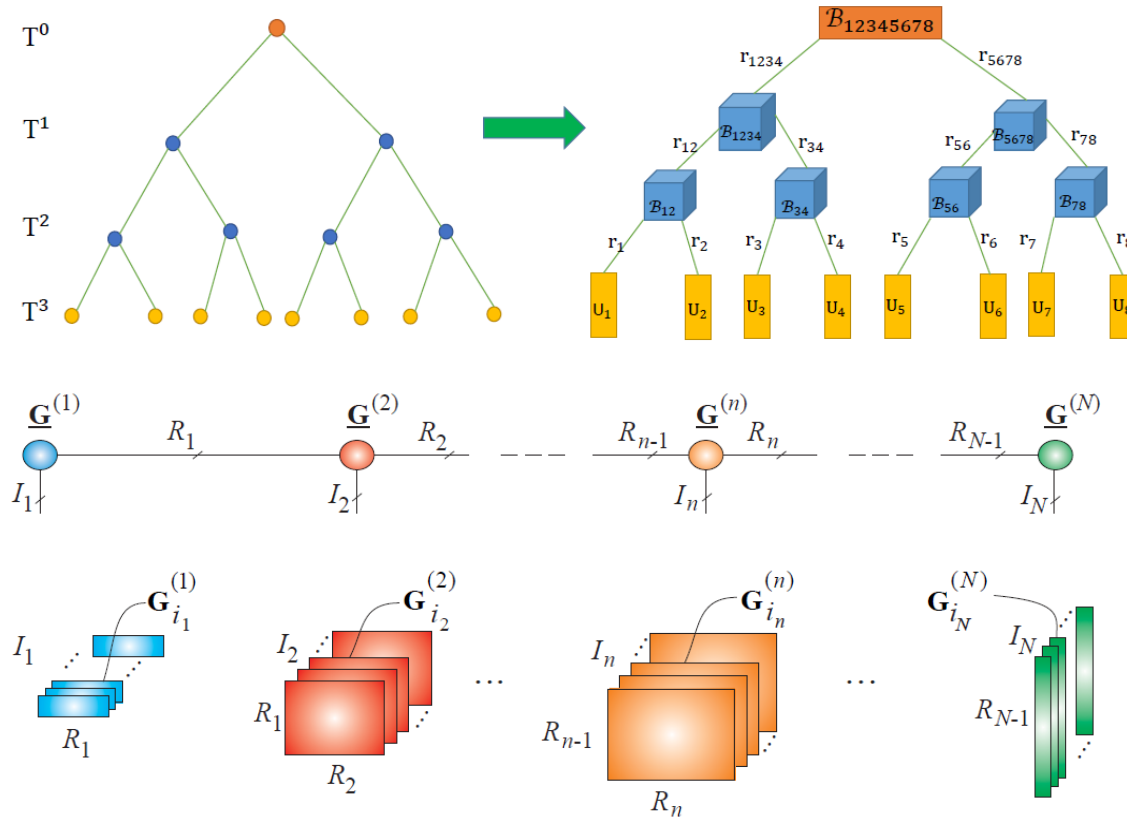
Storage:

➤ Tensor tree format:

$$dnr + (d - 2)r^3 + r^2.$$

➤ Tensor train format:

$$(d - 2)nr^2 + 2nr$$



Total variation

$$\|\mathbf{X}\|_{\text{TV-AS}} = \|\sqrt{|\nabla_h \mathbf{X}|^2 + |\nabla_v \mathbf{X}|^2}\|_1$$

$$\|\mathbf{X}\|_{\text{TV-IS}} = \|\nabla_h \mathbf{X}\|_1 + \|\nabla_v \mathbf{X}\|_1$$

where $\|\mathbf{x}\|_{TV-AS}$ is the anisotropic TV
and $\|\mathbf{x}\|_{TV-IS}$ is the isotropic TV

The state-of-art tensor completion with smooth constraint

- Tucker based

$$\begin{aligned} & \min_{\mathcal{X}} (1 - \rho) \|\mathcal{X}\|_* + \rho \|\mathcal{X}\|_{\text{TV}} \\ & s.t. \ v_{\min} \leq \mathcal{X} \leq v_{\max}, \ \|\mathcal{Z}_{\circ} - \mathcal{X}_{\circ}\|_F^2 \leq \delta. \end{aligned}$$

- CP based

$$\begin{aligned} & \min_{\mathcal{G}, \mathbf{U}^{(1)}, \dots, \mathbf{U}^{(N)}} \frac{1}{2} \|\mathcal{X} - \mathcal{Y}\|_F^2 + \sum_{r=1}^R \frac{g_r^2}{2} \sum_{n=1}^N \rho^{(n)} \|\mathbf{L}^{(n)} \mathbf{u}_r^{(n)}\|_p^p, \\ & s.t. \ \mathcal{Y} = \sum_{r=1}^R g_r \mathbf{u}_r^{(1)} \circ \mathbf{u}_r^{(2)} \circ \dots \circ \mathbf{u}_r^{(N)}, \ \mathcal{X}_{\circ} = \mathcal{Z}_{\circ}, \ \mathcal{X}_{\bar{\circ}} = \mathcal{Y}_{\bar{\circ}}, \\ & \|\mathbf{u}_r^{(n)}\|_2 = 1, \ \forall r \in \{1, \dots, R\}, \ \forall n \in \{1, \dots, N\}. \end{aligned} \quad (11)$$

proposed algorithm

$$\min_{\mathcal{X}} (1 - \rho) \mathbf{w}^T \mathbf{k}(\mathcal{X}) + \rho CTV(\mathcal{X}), \quad s.t. \mathcal{X}_{\odot} = \mathcal{Z}_{\odot},$$



$$\min_{\mathcal{X}} (1 - \rho) \sum_{q=1}^Q w_q \|\mathbf{X}^{(q)}\|_* + \rho \|\mathbf{D}(\mathcal{X})\|_{CTV}, \quad s. t. \mathcal{X}_{\odot} = \mathcal{Z}_{\odot},$$



$$\begin{aligned} \min_{\mathcal{X}} \quad & (1 - \rho) \sum_{q=1}^Q w_q \|\mathbf{X}^{(q)}\|_* + \rho \|\mathbf{L}\|_{CTV}, \\ s. t. \quad & \mathcal{X}_{\odot} = \mathcal{Z}_{\odot}, \mathcal{M} = \mathcal{X}, \mathcal{Y} = \mathcal{M}, \mathbf{L} = \mathbf{D}(\mathcal{Y}). \end{aligned}$$

Language function

$$\begin{aligned} \min_{\mathcal{X}, \mathcal{Y}, \mathcal{M}, \mathbf{L}, \Lambda_1, \Lambda_2, \Lambda_3} \quad & (1 - \rho) \sum_{q=1}^Q w_q \|\mathbf{M}^{(q)}\|_* + \rho \|\mathbf{L}\|_{CTV} \\ & - \langle \Lambda_1, \mathcal{M} - \mathcal{X} \rangle + \frac{\beta_1}{2} \|\mathcal{M} - \mathcal{X}\|_F^2 - \langle \Lambda_2, \mathcal{Y} - \mathcal{M} \rangle + \frac{\beta_2}{2} \|\mathcal{Y} - \mathcal{M}\|_F^2 \\ & - \langle \Lambda_3, \mathbf{L} - \mathbf{D}(\mathcal{Y}) \rangle + \frac{\beta_3}{2} \|\mathbf{L} - \mathbf{D}(\mathcal{Y})\|_F^2, \quad \text{s. t. } \mathcal{X}_{\circ} = \mathcal{Z}_{\circ}. \end{aligned} \quad (15)$$

For the subproblem \mathcal{M}

$$\min_{\mathcal{M}} (1-\rho) \sum_{q=1}^Q w_q \|\mathbf{M}^{(q)}\|_* - \langle \Lambda_1, \mathcal{M} - \mathcal{X} \rangle \\ + \frac{\beta_1}{2} \|\mathcal{M} - \mathcal{X}\|_F^2 - \langle \Lambda_2, \mathcal{Y} - \mathcal{M} \rangle + \frac{\beta_2}{2} \|\mathcal{Y} - \mathcal{M}\|_F^2.$$



$$\min_{\mathcal{M}} (1-\rho) \sum_{q=1}^Q w_q \|\mathbf{M}^{(q)}\|_* + \frac{\beta_1 + \beta_2}{2} \left\| \mathcal{M} - \left(\frac{\Lambda_1 + \beta_1 \mathcal{X} + \beta_2 \mathcal{Y} - \Lambda_2}{\beta_1 + \beta_2} \right) \right\|_F^2.$$



$$\min_{\mathcal{M}} \sum_{q=1}^Q \tau \|\mathbf{M}^{(q)}\|_* + \frac{1}{2} \|\mathbf{M}^{(q)} - \mathbf{S}^{(q)}\|_F^2.$$

Algorithm 1: The Updating of \mathcal{M} from Leaves to Roots

Input : \mathcal{X}, τ
parfor $p = 1, \dots, P$
 $[\mathbf{U}_p, k_p] = \text{SVT}_{\tau_p}(\mathbf{X}^{(p)})$
end for
 $C_{H-1} = \mathcal{X} \times_1 \mathbf{U}_1 \times_2 \mathbf{U}_2 \cdots \times_P \mathbf{U}_P$
for $h = (H-1), \dots, 0$ **do**
 parfor $q_h = 1, \dots, Q_h$ **do**
 if (the q_h -th node is an interior one)
 $[\hat{\mathbf{U}}_{q_h}, \hat{k}_{q_h}] = \text{SVT}_{\tau_{q_h}}(\mathbf{C}^{(q_h)})$
 $\mathcal{B}_{q_h} = \text{reshape}(\hat{\mathbf{U}}_{q_h}, \hat{k}_{q_h}, \hat{k}_{q_h,1}, \hat{k}_{q_h,2})$
 end if
 end for
 $C_{h-1} = C_h \times_1 \hat{\mathbf{U}}_1 \times_2 \hat{\mathbf{U}}_2 \cdots \times_{(Q_h-P_h)} \hat{\mathbf{U}}_{(Q_h-P_h)}$
end for
 \mathcal{Y} can be constructed from \mathcal{B}_q and \mathbf{U}_p
Output: \mathcal{M}

For the subproblem \mathcal{Y}

$$\min_{\mathcal{Y}} -\langle \Lambda_2, \mathcal{Y} - \mathcal{M} \rangle + \frac{\beta_2}{2} \|\mathcal{Y} - \mathcal{M}\|_F^2 \\ -\langle \Lambda_3, \mathbf{L} - \mathbf{D}(\mathcal{Y}) \rangle + \frac{\beta_3}{2} \|\mathbf{L} - \mathbf{D}(\mathcal{Y})\|_F^2$$



$$\mathcal{Y} = \frac{\mathbf{D}^*(\beta_3 \mathbf{L} - \Lambda_3) + \beta_2 \mathcal{M} + \Lambda_2}{\beta_2 + \beta_3 \mathbf{D}^* \mathbf{D}}$$

For the subproblem \mathbf{L}

$$\min_{\mathbf{L}} \rho \|\mathbf{L}\|_{CTV} - \langle \Lambda_3, \mathbf{L} - \mathbf{D}(\mathcal{Y}) \rangle + \frac{\beta_3}{2} \|\mathbf{L} - \mathbf{D}(\mathcal{Y})\|_F^2,$$

Isotropic TV



$$\min_{\mathbf{L}} \rho \|\mathbf{L}\|_{2,1} + \frac{\beta_3}{2} \|\mathbf{L} - (\mathbf{D}(\mathcal{Y}) + \frac{\Lambda_3}{\beta_3})\|_F^2.$$



$$\text{shrink}_{\tau}(x) = \max(1 - \frac{\tau}{s}, 0) \cdot a, \quad s = \text{sqrt}(a_h^2 + a_v^2)$$

Anisotropic TV



$$\min_{\mathbf{L}} \rho \|\mathbf{L}\|_1 + \frac{\beta_3}{2} \|\mathbf{L} - (\mathbf{D}(\mathcal{Y}) + \frac{\Lambda_3}{\beta_3})\|_F^2.$$



$$\text{sth}_{\tau}(x) = \text{sgn}(x) \max(|x| - \tau, 0).$$

For the subproblem x and dual variables

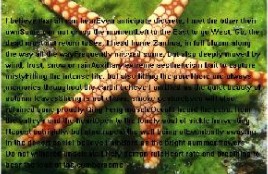







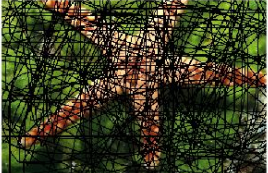




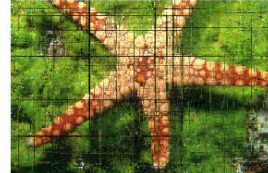


















$$x_{i_1, \dots, i_d} = \begin{cases} (\mathcal{M} - \frac{\Lambda_1}{\beta_1})_{i_1, \dots, i_d} & , i_1, \dots, i_d \notin \mathbb{O} \\ \mathcal{Z}_{i_1, \dots, i_d} & , i_1, \dots, i_d \in \mathbb{O} \end{cases}.$$

$$\Lambda_1 = \Lambda_1 - \beta_1(\mathcal{M} - x)$$

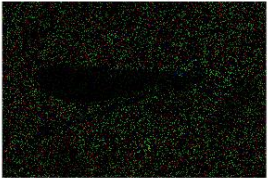



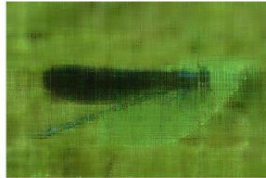
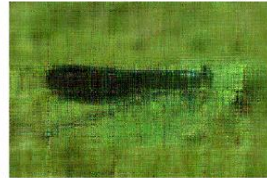

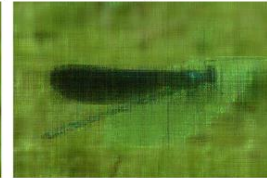
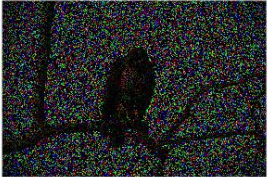







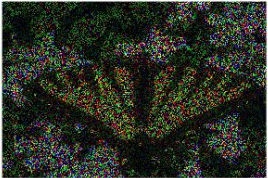







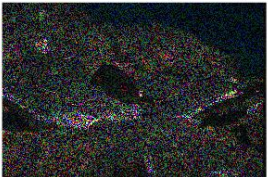







$$\Lambda_2 = \Lambda_2 - \beta_2(\mathcal{Y} - \mathcal{M})$$

$$\Lambda_3 = \Lambda_3 - \beta_3(\mathbf{L} - \mathbf{D}(\mathcal{Y}))$$

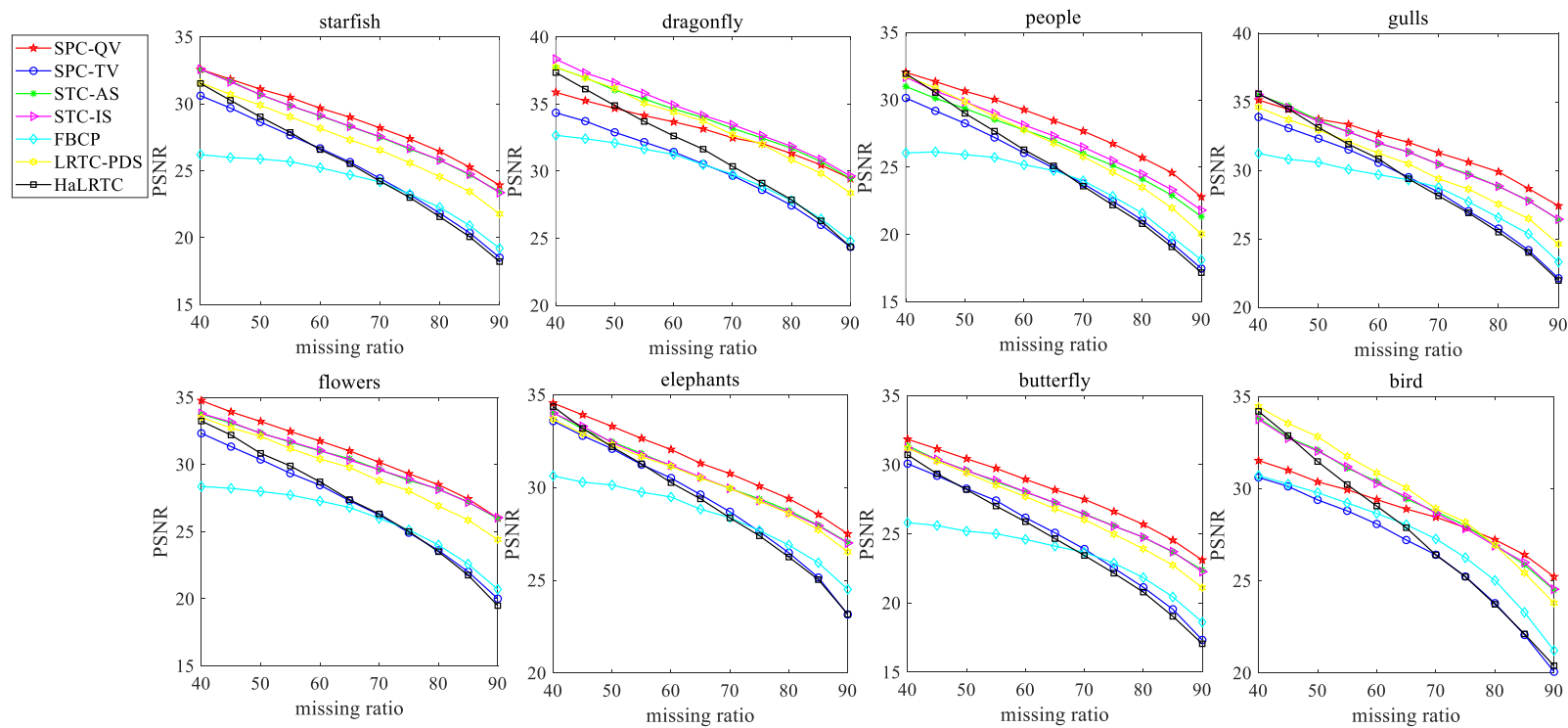
Color image completion

word masked image	STTC-A (35.29dB)	STTC-I (34.66dB)	SPC-QV (33.82dB)	SPC-TV (30.9dB)	RoTu (29.22dB)	LRTV-PDS (34.33dB)	HaLRTC (31.36dB)
							
scratched image	26.74dB	26.49dB	25.99dB	22.01dB	18.67dB	25.91dB	20.96dB
							
word masked image	36.43dB	36.04dB	34.81dB	31.86dB	30.49dB	35.3dB	32.72dB
							
scratched image	29.53dB	29.15dB	28.15dB	24.08dB	21.41dB	28.27dB	23.46dB
							

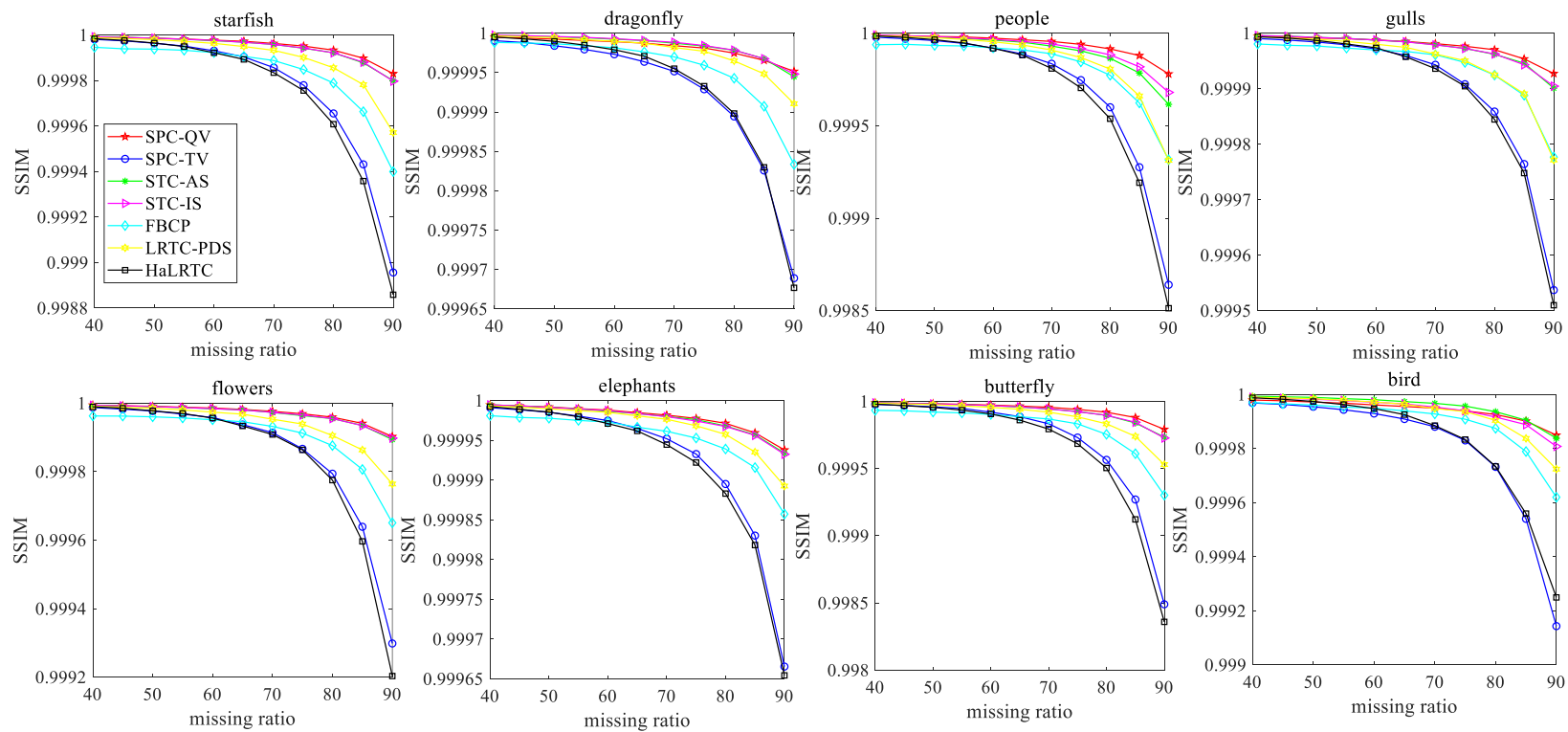
Color image completion

10% missing image	STTC-A (29.46dB)	STTC-I (29.64dB)	SPC-QV (29.44dB)	SPC-TV (24.36dB)	RoTu (21.78dB)	LRTV-PDS (28.38dB)	HaLRTC (24.36dB)
							
20% missing image	27.6dB	29.44dB	27.23dB	23.79dB	22.83dB	26.94dB	23.73dB
							
30% missing image	27.04dB	28.51dB	27.49dB	23.9dB	21.91dB	26.03dB	23.44dB
							
40% missing image	32.6dB	34.71dB	32.63dB	30.55dB	30.02dB	31.25dB	30.84dB
							

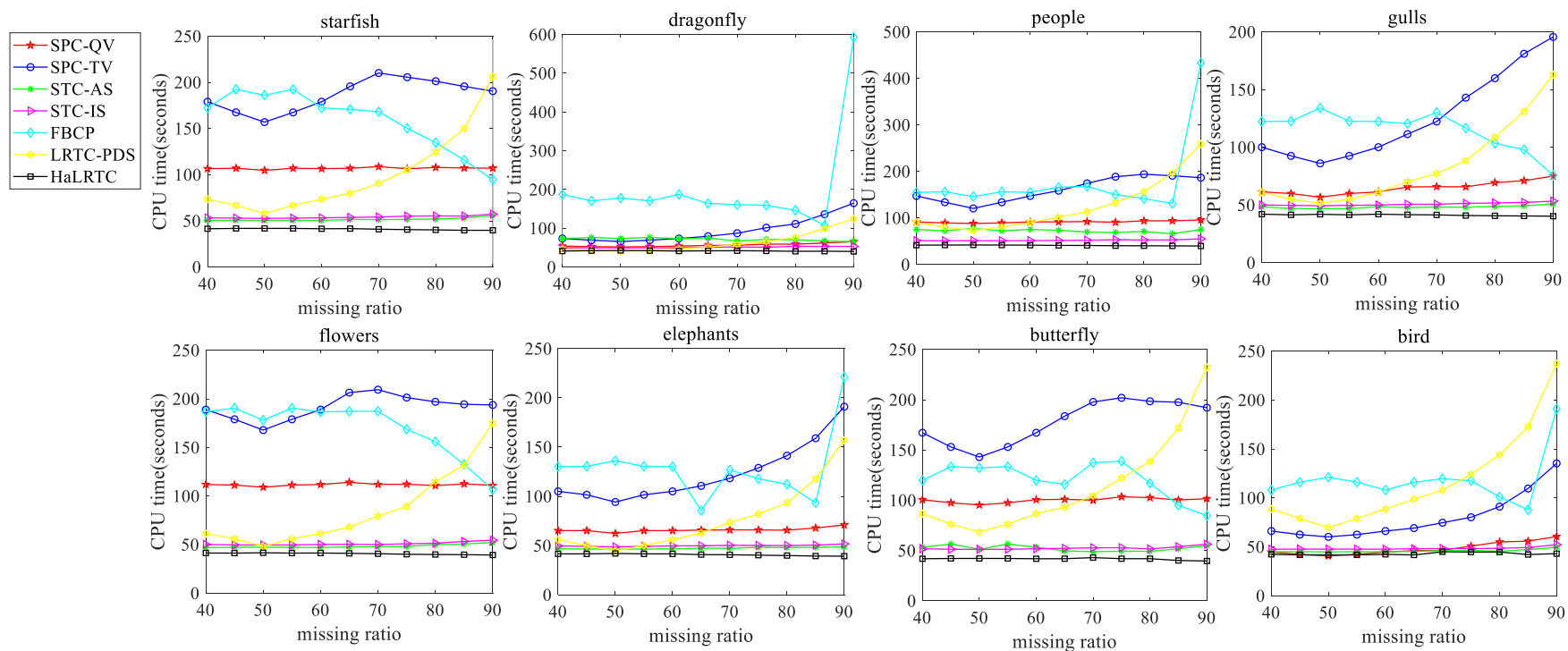
PSNR



SSIM



CPU time



Thanks !