

# Detailed Human Action Understanding from Unlabeled Videos

Chen Sun



BROWN

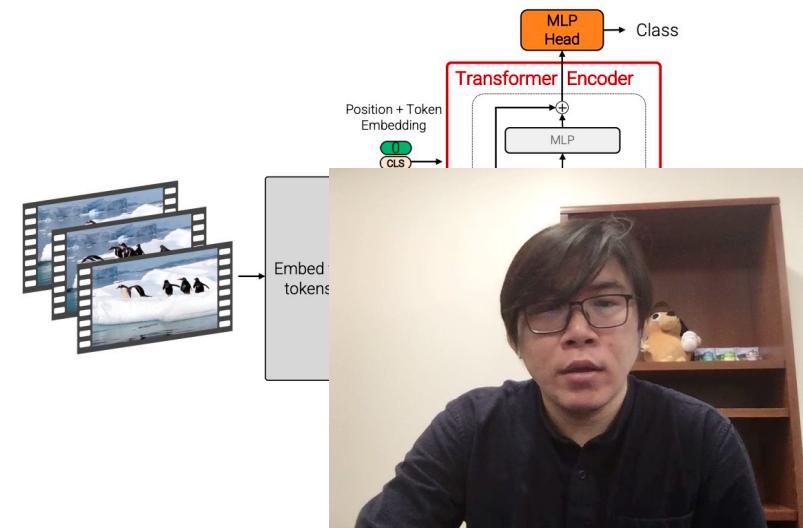
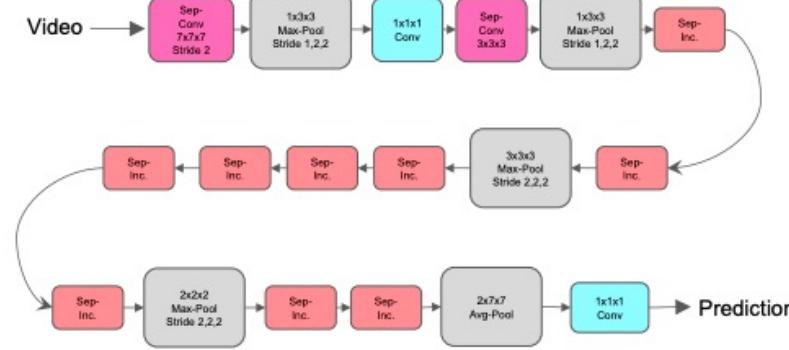
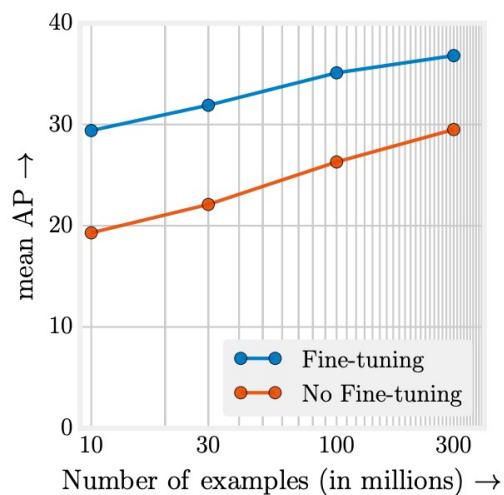
Google Research



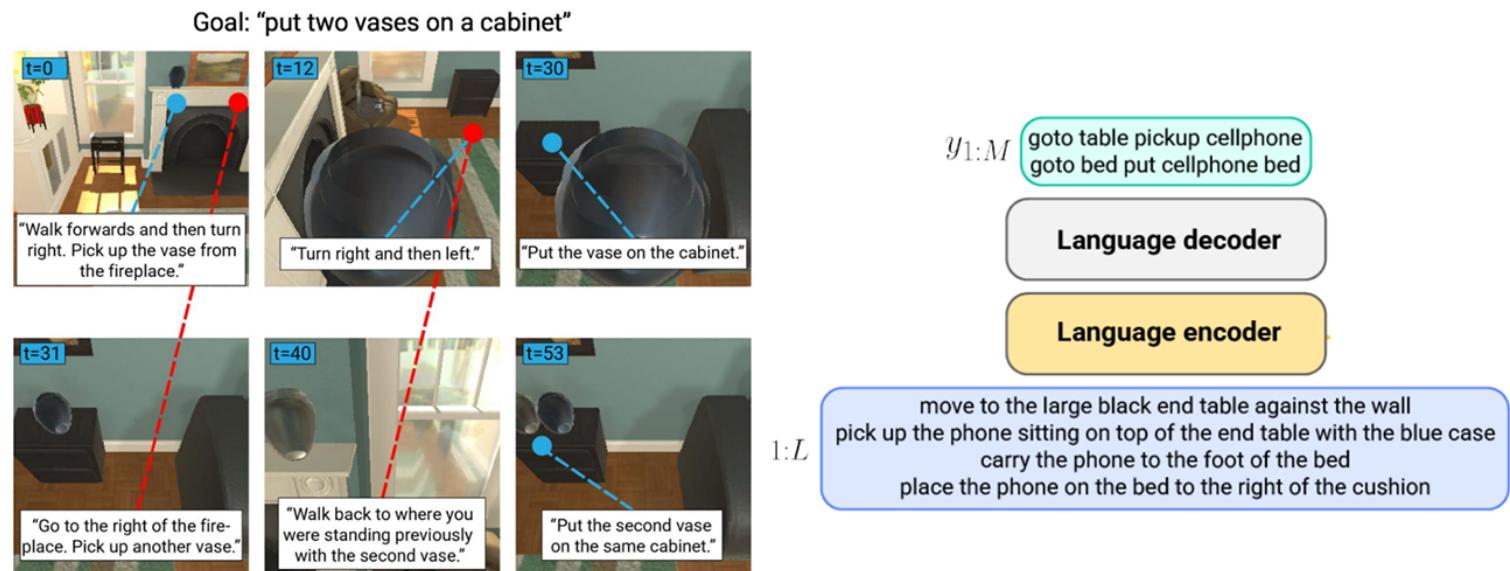
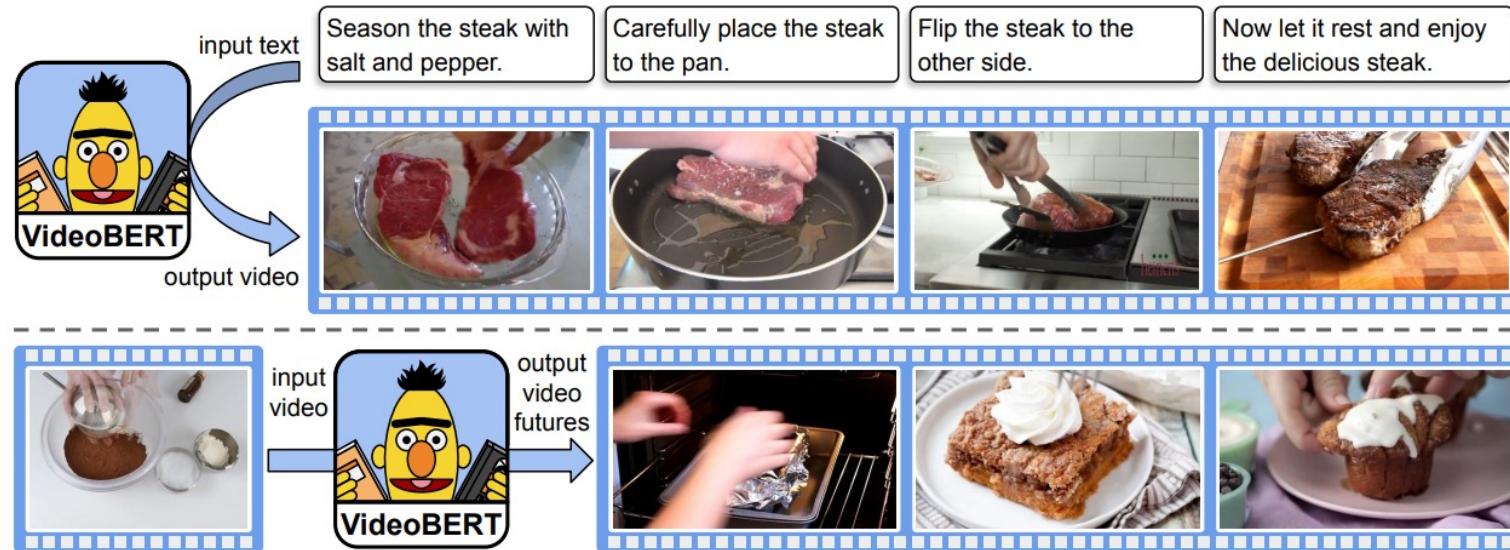
# My Research at Google: Large-scale Visual Understanding



**Left: Stand, Watch; Middle: Stand, Play instrument; Right: Sit, Play instrument**



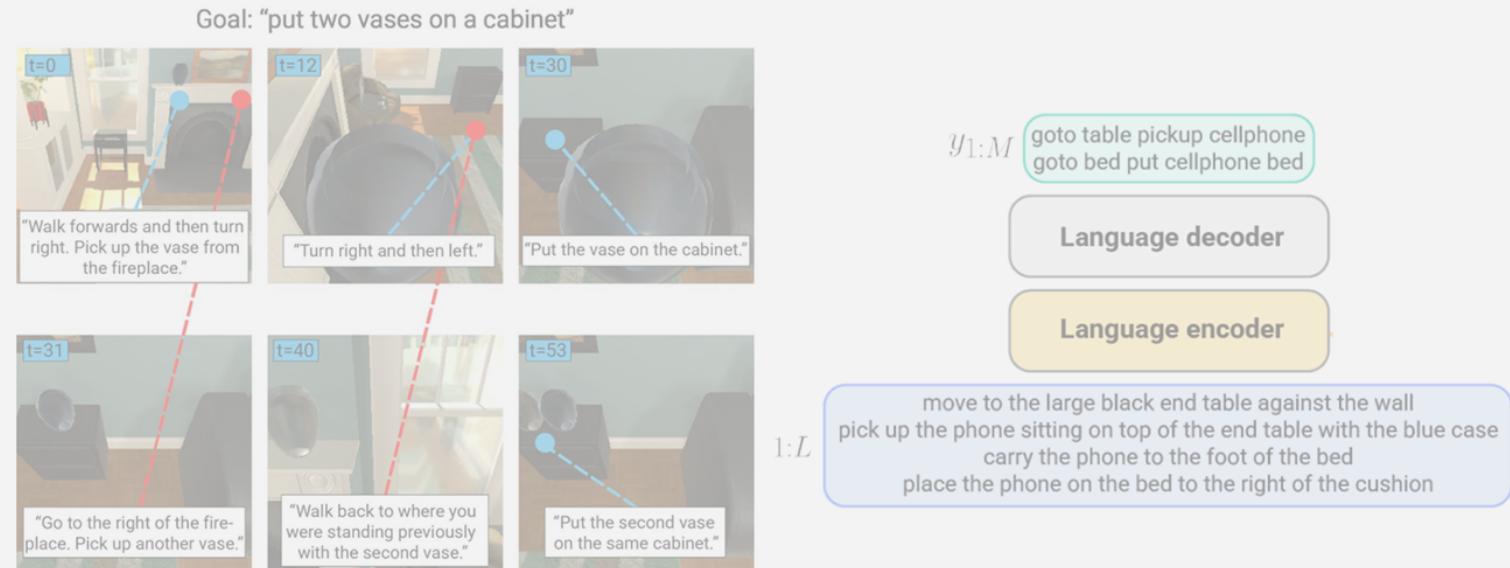
# My Research at Brown: Structured Video Understanding



# My Research at Brown: Structured Video Understanding



## We are hiring PhD students!



# What can we learn from videos?



A frame from the Atomic Visual Actions (AVA) dataset



# What can we learn from videos?



A frame from the Atomic Visual Actions (AVA) dataset

Object detection:

*Person, silverware, food*

Action detection:

*Sit, eat, talk*

Human-object interaction:

*Person hold fork / eat food*

Near-future prediction:

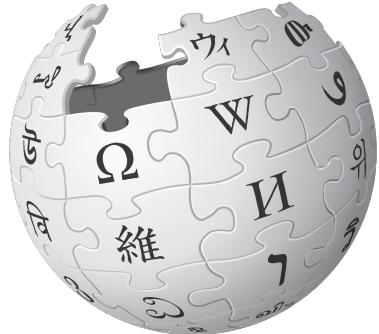
*Stand*



# Encyclopedia of Multimedia Contents



Place the ingredients onto a bowl of hot steamed rice.



## Ferguson years (1986–2013)

Main article: *History of Manchester United F.C. (1986–2013)*



Alex Ferguson managed the team between 1986 and 2013.



Ryan Giggs is the most decorated player in English football history.<sup>[62]</sup>

Alex Ferguson and his assistant Archie Knox arrived from Aberdeen on the day of Atkinson's dismissal,<sup>[41]</sup> and guided the club to an 11th-place finish in the league.<sup>[42]</sup> Despite a second-place finish in 1987–88, the club was back in 11th place the following season.<sup>[43]</sup> Reportedly on the verge of being dismissed, victory over Crystal Palace in the 1990 FA Cup Final replay (after a 3–3 draw) saved Ferguson's career.<sup>[44][45]</sup> The following season, Manchester United claimed their first UEFA Cup Winners' Cup title. That triumph allowed the club to compete in the European Super Cup for the very first time, where United beat European Cup holders Red Star Belgrade 1–0 in the final at Old Trafford. A second consecutive League Cup final appearance in 1992 saw the club win that competition for the first time as well, following a 1–0 win against Nottingham Forest at Wembley Stadium.<sup>[46]</sup> In 1993, the club won its first league title since 1967, and a year later, for the first time since 1957, it won a second consecutive title – alongside the FA Cup – to complete the first "Double" in the club's history.<sup>[47]</sup> United then became the first English club to do the Double twice when they won both competitions again in 1995–96,<sup>[48]</sup> before retaining the league title once more in 1996–97 with a game to spare.<sup>[47]</sup>

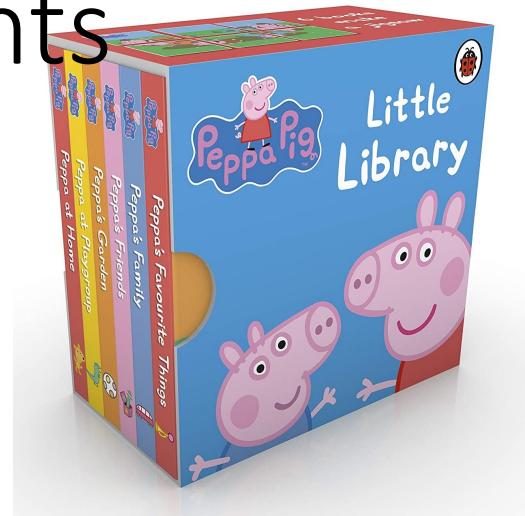
In the 1998–99 season, Manchester United became the first team to win the Premier League, FA Cup and UEFA Champions League – "The Treble" – in the same season.<sup>[49]</sup> Losing 1–0 going into injury time in the 1999 UEFA Champions League Final, Teddy Sheringham and Ole Gunnar Solskjær scored late goals to claim a dramatic victory over Bayern Munich, in what is considered one of the greatest comebacks of all time.<sup>[49]</sup> The club then became the only British team to ever win the Intercontinental Cup after beating Palmeiras 1–0 in Tokyo.<sup>[50]</sup> Ferguson was subsequently knighted for his services to football.<sup>[51]</sup>

Manchester United won the league again in the 1999–2000 and 2000–01 seasons, becoming only the fourth club to win the English title three times in a row. The team finished third in 2001–02, before regaining the title in 2002–03.<sup>[52]</sup> They won the 2003–04 FA Cup, beating Millwall 3–0 in the final at the Millennium Stadium in Cardiff to lift the trophy for a record 11th time.<sup>[54]</sup> In the 2005–06 season, Manchester United failed to qualify for the knockout phase of the UEFA Champions League for the first time in over a decade,<sup>[55]</sup> but recovered to secure a second-place league finish and victory over Wigan Athletic in the 2006 Football League Cup Final. The club regained the Premier League in the 2006–07 season, before completing the European double in 2007–08 with a 6–5 penalty shoot-out victory over Chelsea in the 2008 UEFA Champions League Final in Moscow to go with their 17th English league title. Ryan Giggs made a record 759th appearance for the club in that game, overtaking previous record holder Bobby Charlton.<sup>[56]</sup> In December 2008, the club became the first British team to win the FIFA Club World Cup and followed this with the 2008–09 Football League Cup, and its third successive Premier League title.<sup>[57]</sup> Forward Cristiano Ronaldo was sold to Real Madrid for a world record £80 million.<sup>[58]</sup> In 2010, Manchester United defeated Aston Villa 2–1 at Wembley to retain their successful defence of a knockout cup competition.<sup>[60]</sup>

After finishing as runner-up to Chelsea in the 2009–10 season, United achieved a record 19th league title in 2010–11, securing the championship with a 1–1 away win against West Ham United at Upton Park.<sup>[61]</sup> This was extended to 20 league titles in 2012–13, securing the championship with a 3–0 home win against Aston Villa on 22 April 2013.

## 2013–present

On 8 May 2013, Ferguson announced that he was to retire as manager at the end of the football season, but would remain at the club as a director and club ambassador.<sup>[63][64]</sup> He retired as the club's director in 2015.<sup>[65][66]</sup> The club announced the next day that Everton manager David Moyes would replace him from 1 July, having signed a six-year contract.<sup>[67][68][69]</sup> Ryan Giggs took over as manager in August 2014, but was sacked after a poor season in which the club failed to defend their Premier League title and failed to qualify for the UEFA Champions League for the first time since 1996.<sup>[70]</sup> They also failed to qualify for the Europa League, meaning that it was the first time Manchester United had not qualified for a European competition since 1990.<sup>[71]</sup> On 19 May 2014, it was announced that Giggs would leave the club at the end of the season.



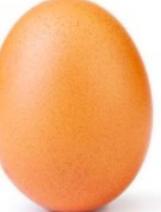
Bryan Robson was the captain of Manchester United for 12 years, longer than any other player.<sup>[36]</sup>



Front three: Manchester United's treble medals of the

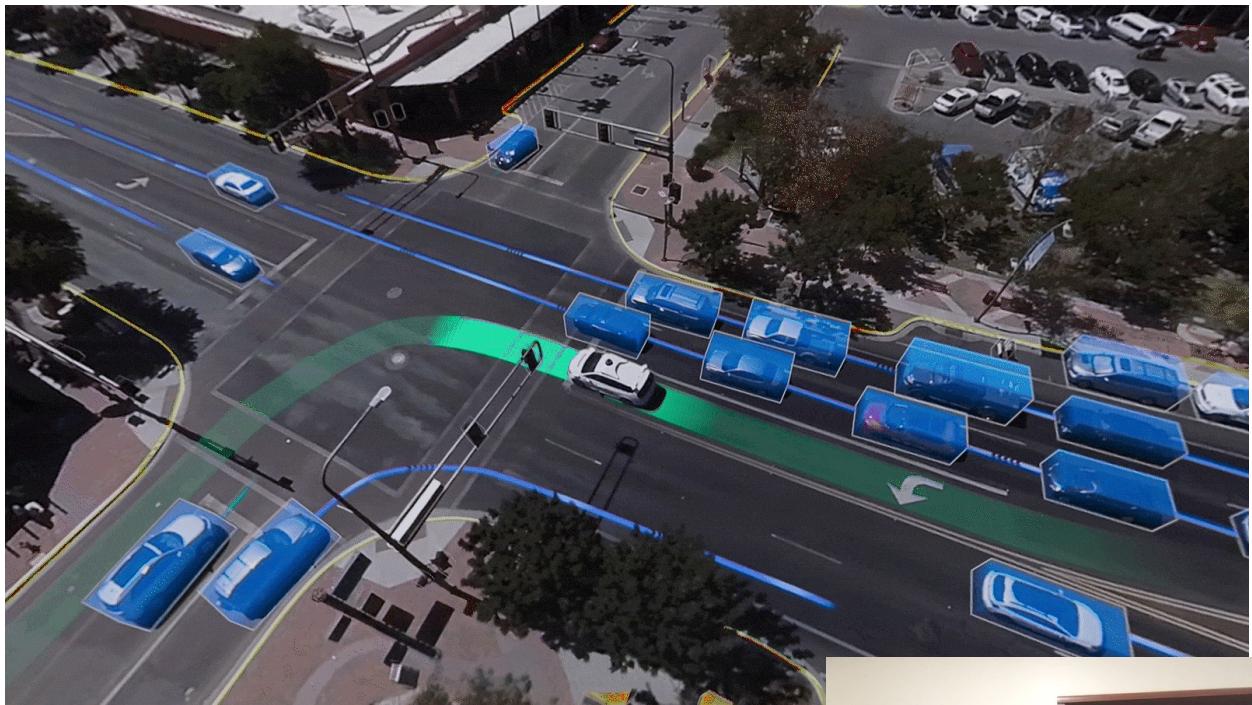


# What else can we learn from videos?

How to Turn  into:



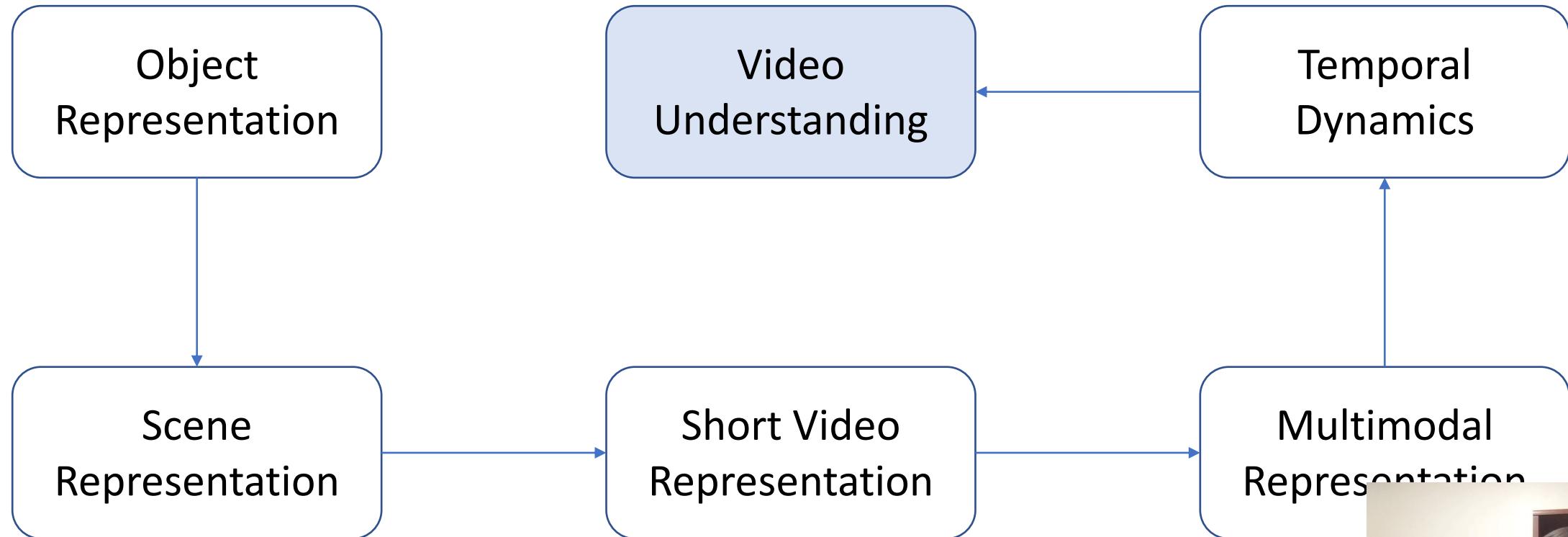
# What else can we learn from videos?



Transfer what has  
been learned from  
passive observations



# A RoadMap Towards Video Understanding



*Hard to label all of them*

*Need to learn from unlabeled videos!!*



# Scene-level Contrastive Learning

View 1: Augmented image



View 2: Augmented image



Similar

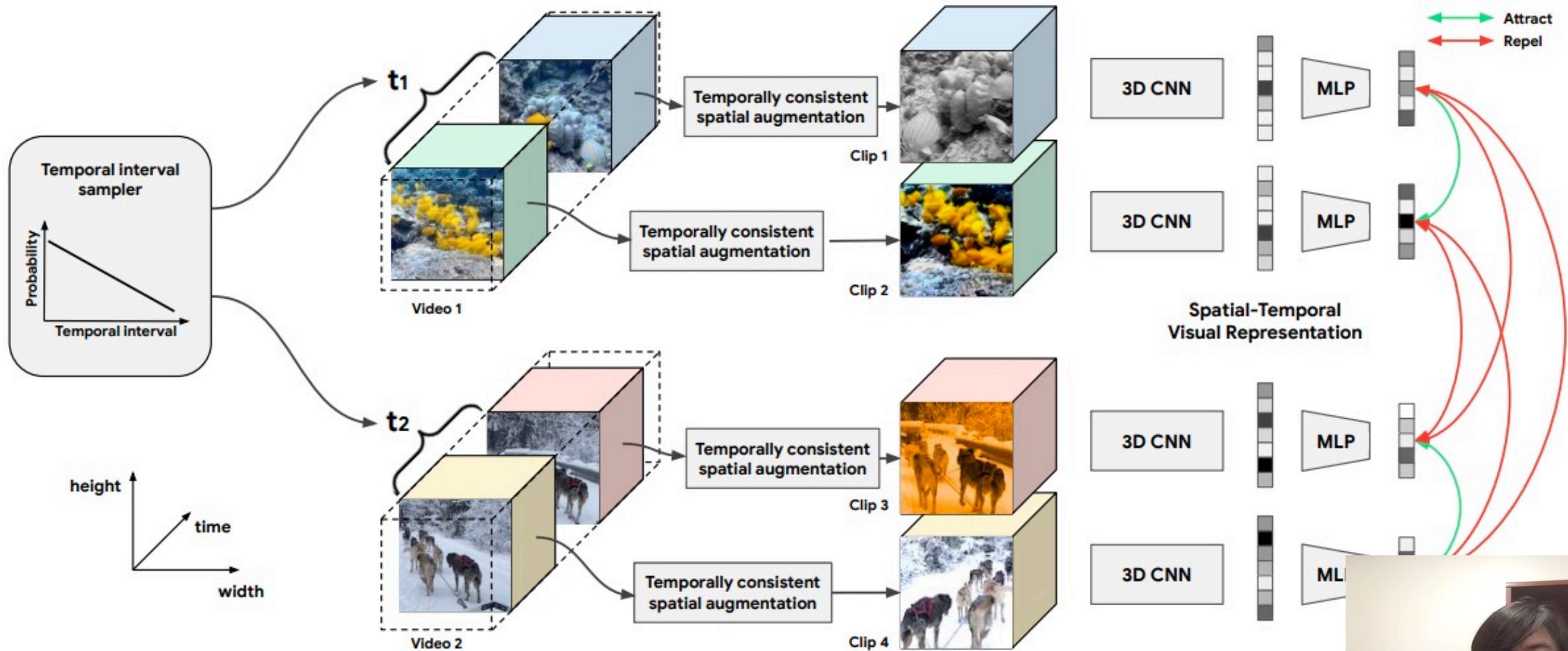
Different

*DistInst  
CPC  
CMC  
SimCLR  
MoCo*

...



# Contrastive Learning for Videos



Qian and Meng et al., Spatiotemporal Contrastive Video Representation Learning, CV



# What should consist positive pairs?

For images:  
Preserve objects



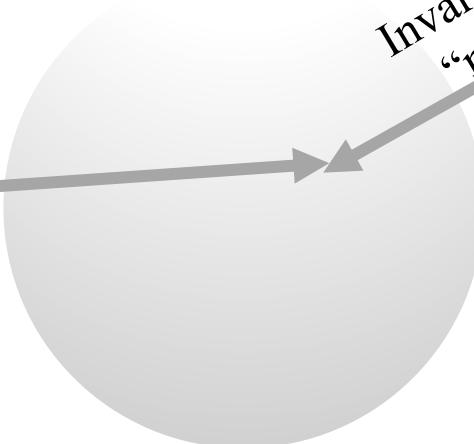
For videos:  
?



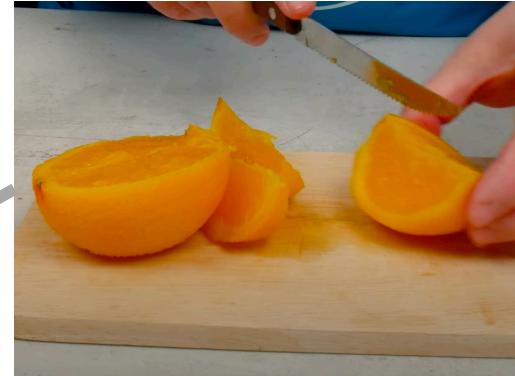
# Natural views introduce undesired invariances



View 1:  $v^t$



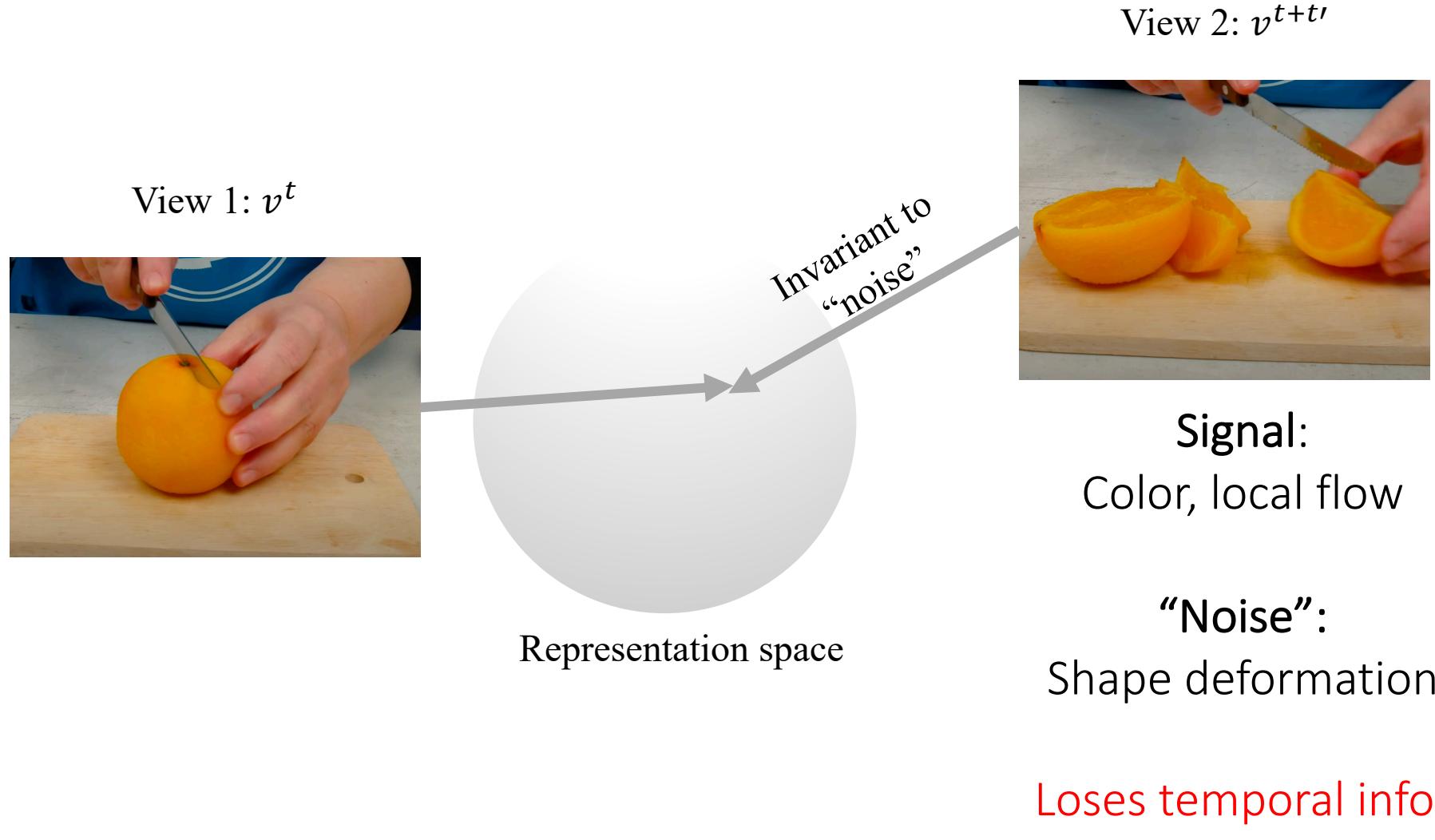
Invariant to  
“noise”



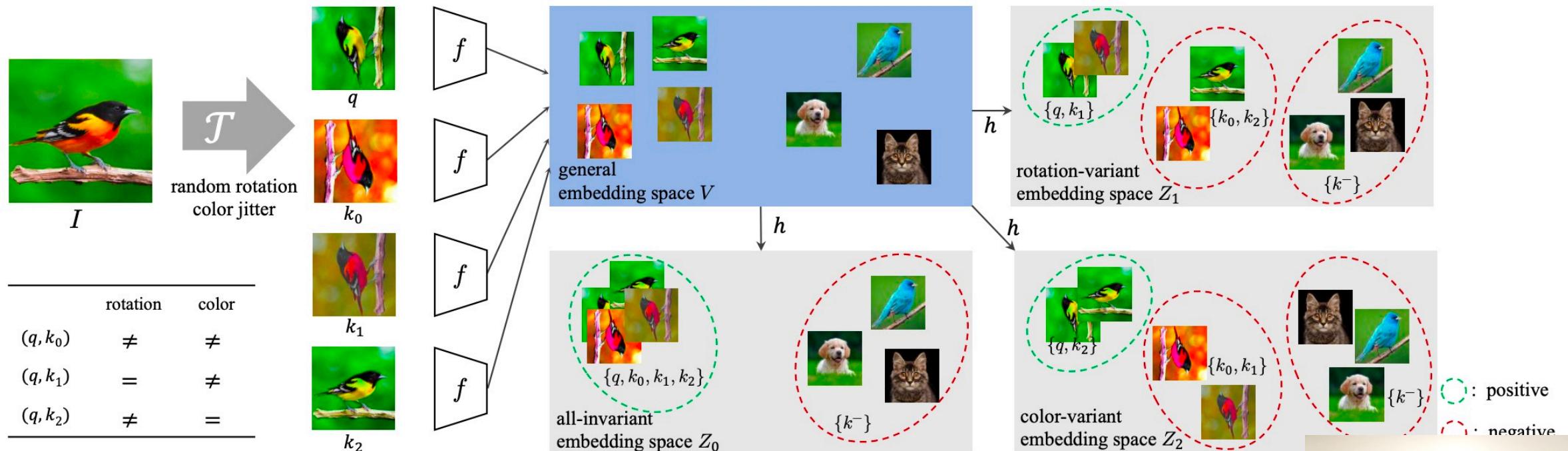
View 2:  $v^{t+t'}$



# Natural views introduce undesired invariances



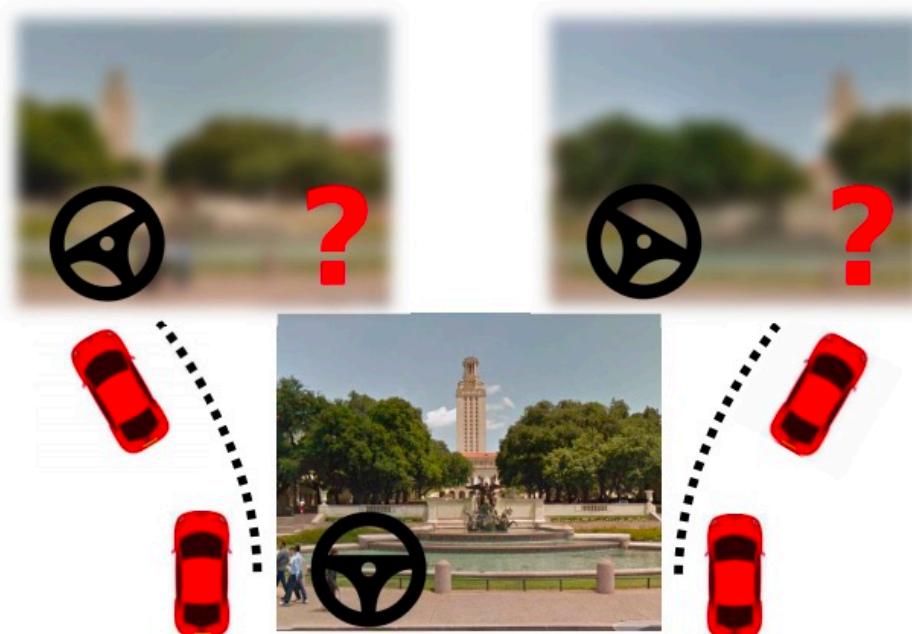
# Solution 1: Construct many pairs of views



May not scale well



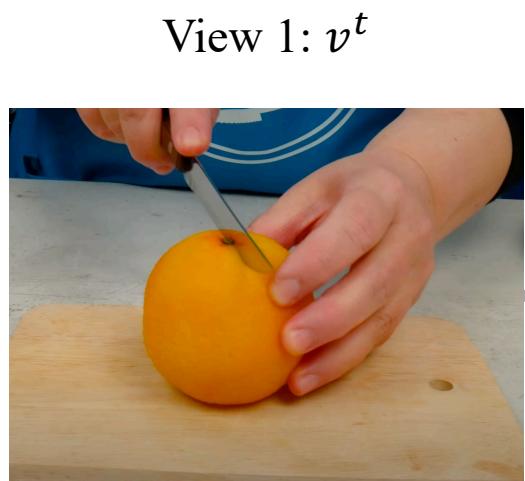
# Solution 2: Equivariant representations



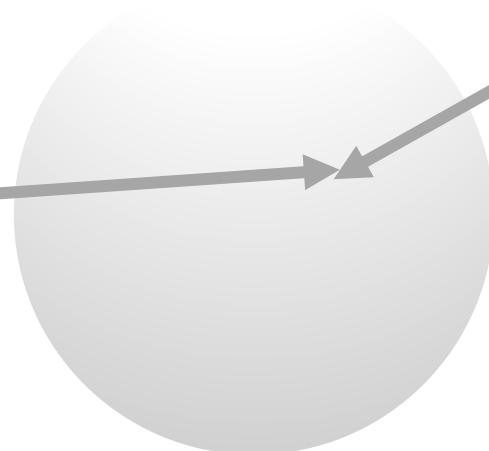
Not necessary for many tasks



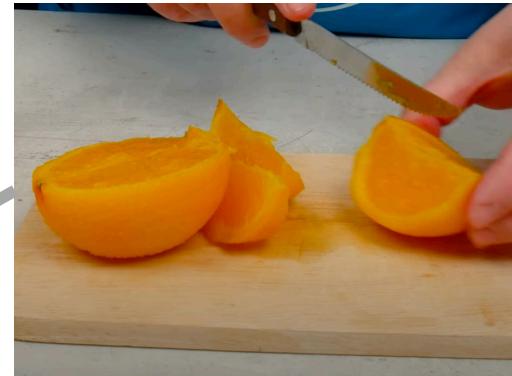
# Our solution: Simply encode the augmentations



View 1:  $v^t$



Representation space



View 2:  $v^{t+t'}$



# Our solution: Simply encode the augmentations

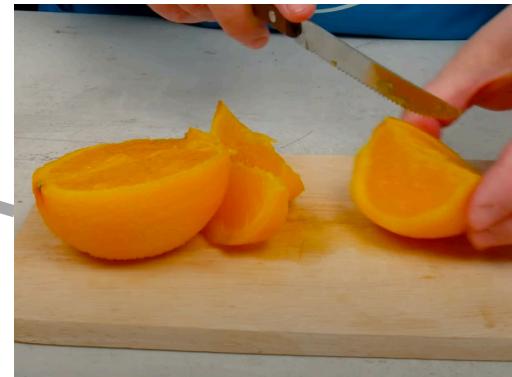
View 1:  $v^t$



Representation space

*Rewind( $t'$ )*

View 2:  $v^{t+t'}$



Learn an implicit  
“prediction” model of  $t'$

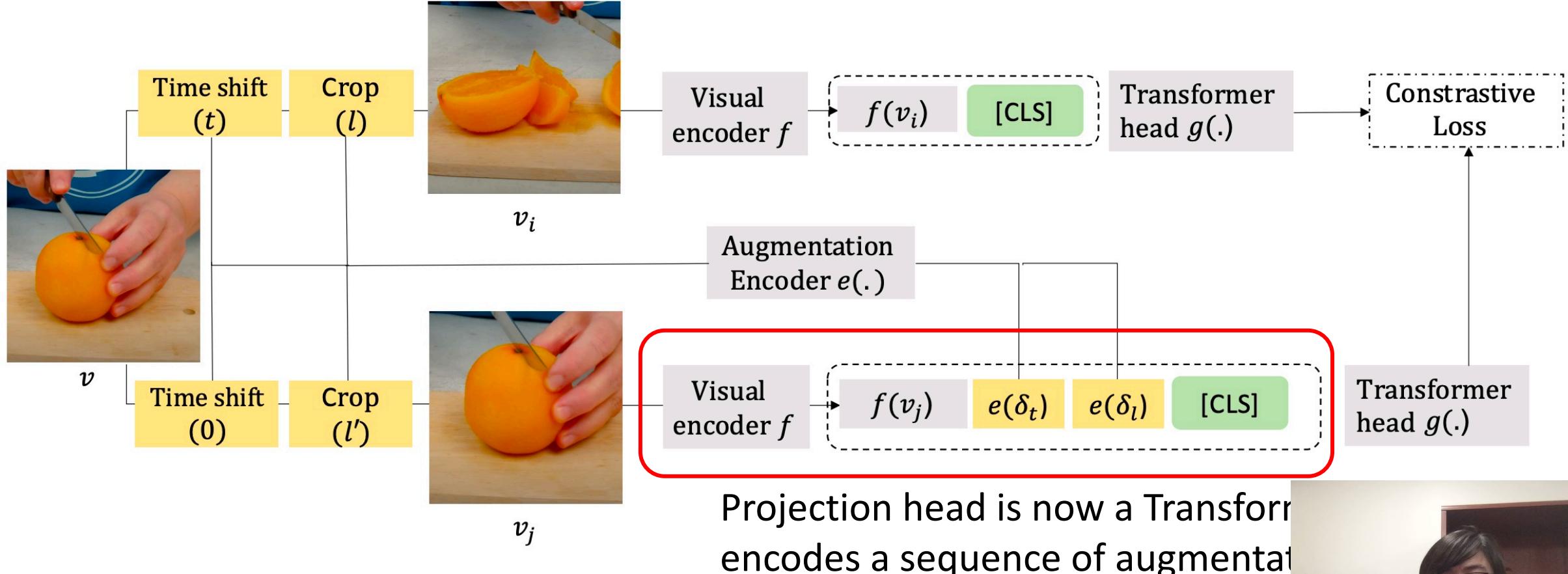
**Shared** and **predictable**  
information can be  
preserved:  
color, shape, etc.

Unpredictable is still  
“noise”  
car

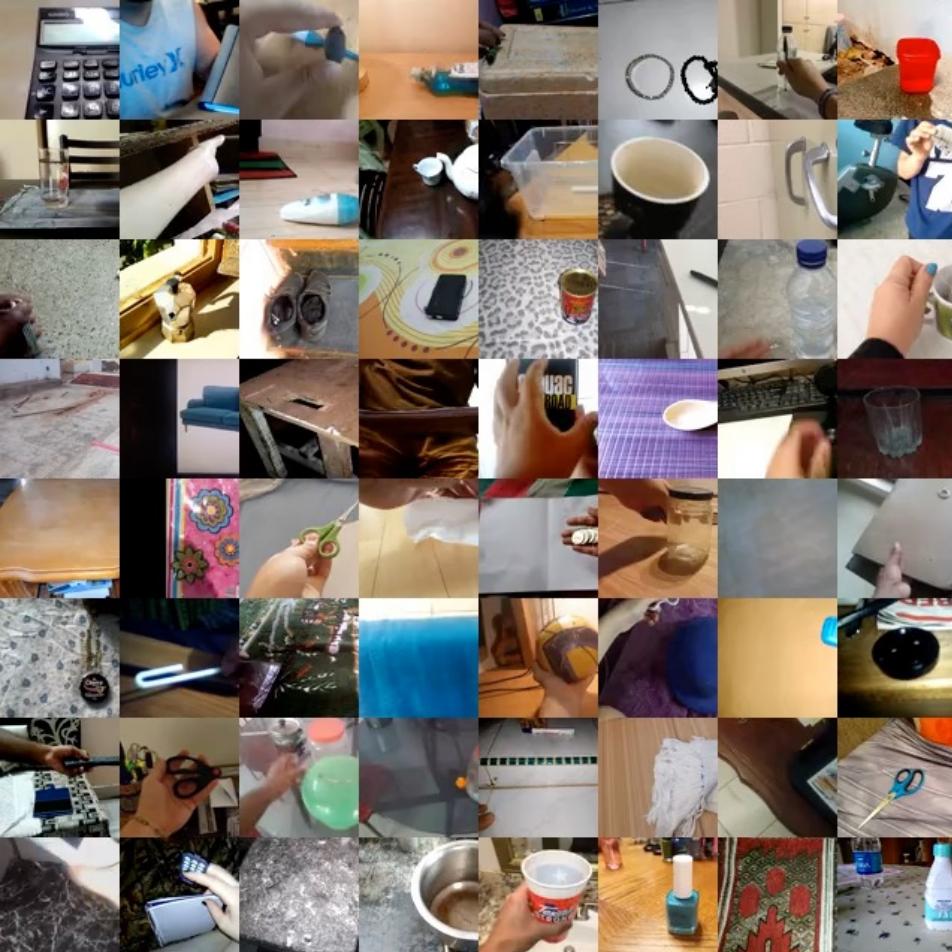
Special cases: view-invariant coding, view-predictive coding



# Composable AugmenTation Encoding (CATE)



# The Something-Something Dataset



## Classes

Putting something on a surface	4,081
Moving something up	3,750
Covering something with something	3,530
Pushing something from left to right	3,442
Moving something down	3,242
Pushing something from right to left	3,195
Uncovering something	3,004
Taking one of many similar things on the table	2,969

Fine-grained actions that rely on  
the arrow of time



# Augmentation encoding is helpful

Encoded	$\tau$	Dropout	Top-1 Acc.	Top-5 Acc.
No	-	-	26.5	55.9
Crop	$\delta_{x,y}$	✗	27.2	56.7
Crop	$\delta_{x,y}$	✓	28.1	58.0
Time	$\text{sgn}(\delta_t)$	✗	28.1	57.9
Time	$\delta_t$	✗	31.3	62.4
Time	$\delta_t$	✓	31.2	61.4

Encode Time	$\tau$	Time Offset Acc.
✗	-	5.7
✓	$\text{sgn}(\delta_t)$	65.7
✓	$\delta_t$	<b>99.9</b>

Table 5: **Time Shift Classification on SSv1**. Encoding time significantly helps on this proxy task, validating the intuition that our model retains useful time information.



# Augmentation encoding is composable

Enc. Crop	Enc. Time	Top-1 Acc.	Top-5 Acc.
✗	✗	26.5	55.9
✓	✗	28.1	58.0
✗	✓	31.2	61.4
✓	✓	<b>32.2</b>	<b>62.4</b>

Table 2: **Composing spatial (crop) and temporal encodings** for Something-Something v1. Each individual encoding outperforms the no encoding baseline (SimCLR++). Composing them together yields the best performance.



# Per-class comparison (temporal aug.)

Arrow of time  
barely matters:

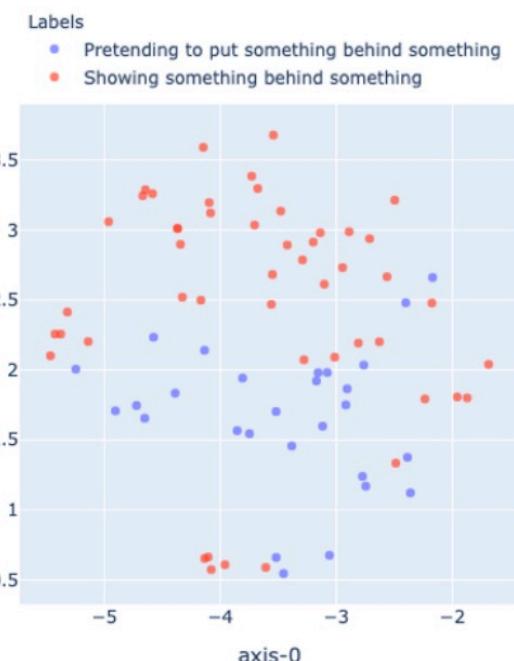
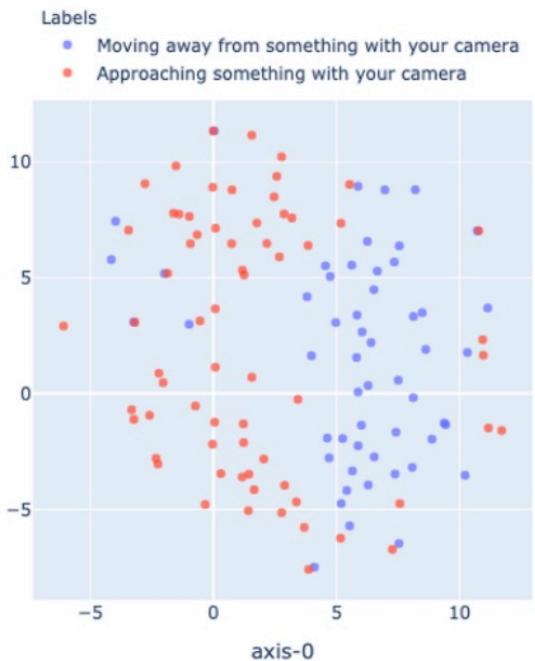
Label	$\Delta AP$
Lifting something up completely, then letting it drop down	21.0
Pulling two ends of something so that it gets stretched	19.8
Moving something and something closer to each other	18.5
Taking one of many similar things on the table	17.2
Pushing something so that it almost falls off but doesn't	16.7
Poking something so lightly that it doesn't move	-4.6
Pretending to pour something out of something	-5.4
Poking a stack of something without the stack collapsing	-5.5
Pretending to spread air onto something	-7.8

Table 4: Classes that benefit the most and the least with **time encoding** on SSv1. We sort the classes by their differences on Average Precision.

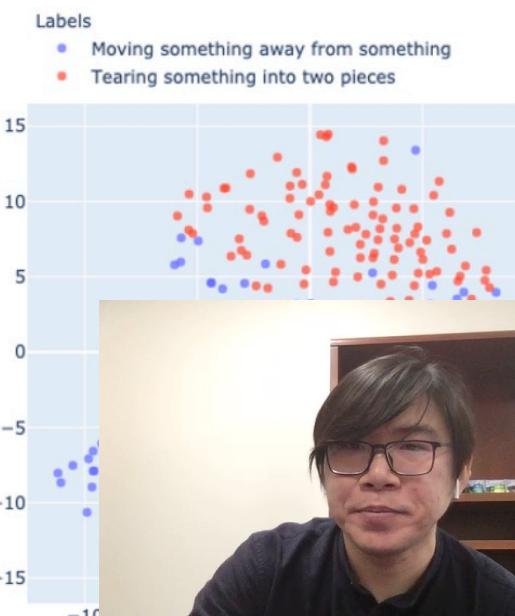
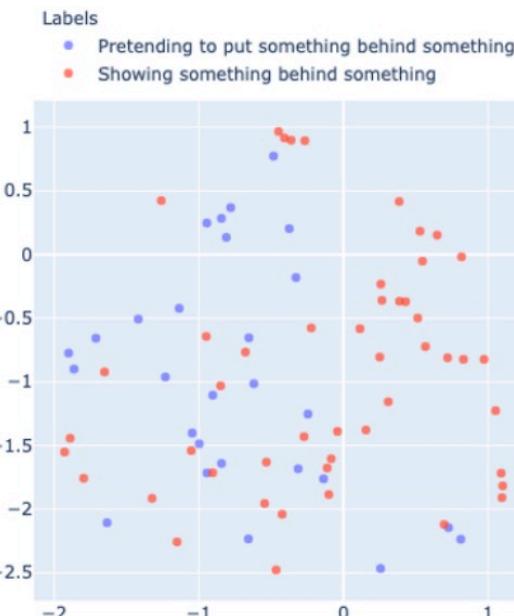
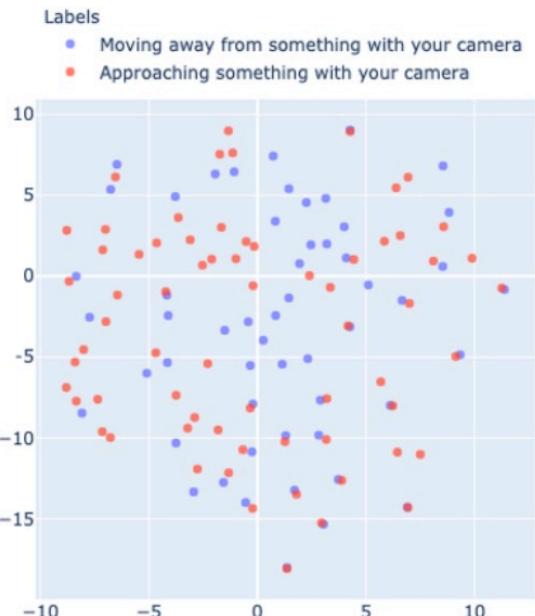


# t-SNE

CATE



No encoding



# Comparison on other benchmarks

Method	top 1	top 5	top 10	top 20	top 50
OPN [32]	19.9	28.7	34.0	40.6	51.6
SpeedNet [5]	13.0	28.1	37.5	49.5	65.0
VCP [34]	19.9	33.7	42.0	50.5	64.4
Temporal SSL [25]	26.1	48.5	59.1	69.6	82.8
MemDPC <sup>†</sup> [18]	40.2	63.2	71.9	78.6	-
CATE	<b>54.9</b>	<b>68.3</b>	<b>75.1</b>	<b>82.3</b>	<b>89.9</b>

Table A6: Nearest neighbor retrieval evaluation on UCF-101 split 1.  $\dagger$ : with Flow

Method	top 1	top 5	top 10	top 20	top 50
VCP [34]	6.7	21.3	32.7	49.2	73.3
MemDPC <sup>†</sup> [18]	15.6	37.6	52.0	65.3	-
CATE	<b>33.0</b>	<b>56.8</b>	<b>69.4</b>	<b>82.1</b>	<b>92.8</b>

Table A7: Nearest neighbor retrieval evaluation on HMDB-51 split 1.  $\dagger$ : with Flow



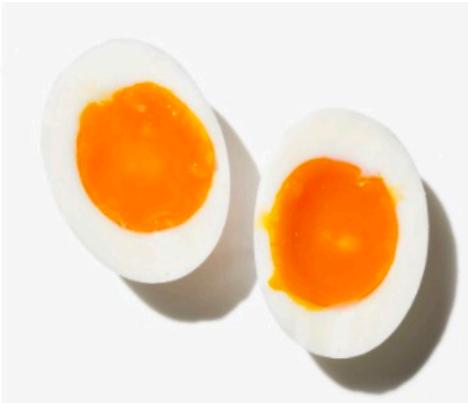
# Checkpoints are released!

<https://github.com/google-research/google-research/tree/master/cate>



# The egg problem

$$f\left( \text{egg}, \text{boil} \right) =$$



A more compact representation for videos:

**Actions as object state transitions**  
(Action recognition, object tracking, ...,  
Visual Commonsense)



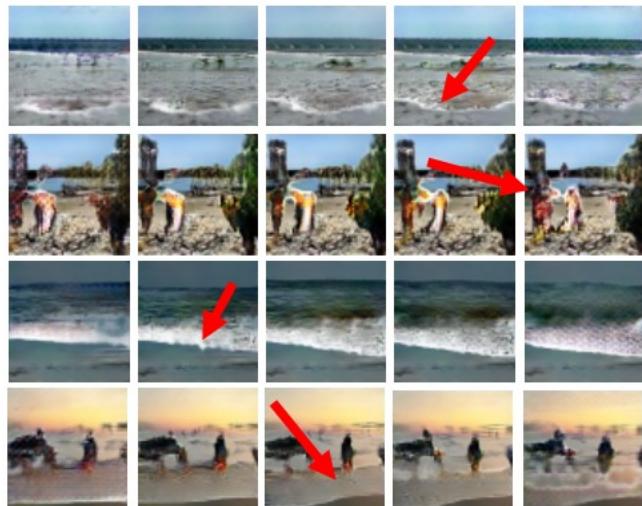
# But why?

- Towards Long Video Understanding
  - Only use “key moments”
  - Video summarization
- Structured Representation
  - Objects
  - Their state transitions over time (visual dynamics)
- Modeling temporal dynamics is itself important

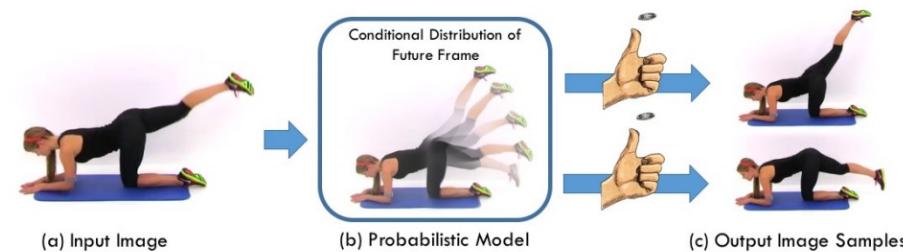


# How to predict the future?

Generate images...



Vondrick et al., 2016

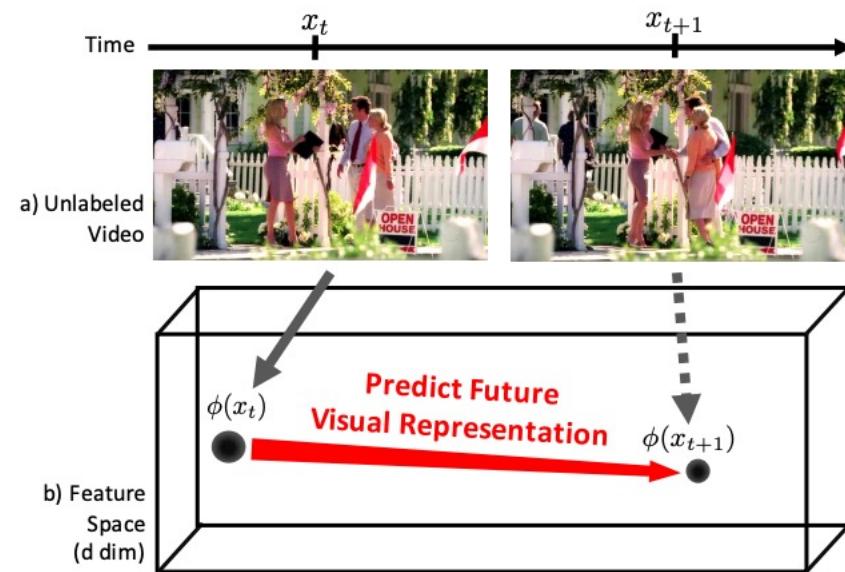


Xue et al., 2016

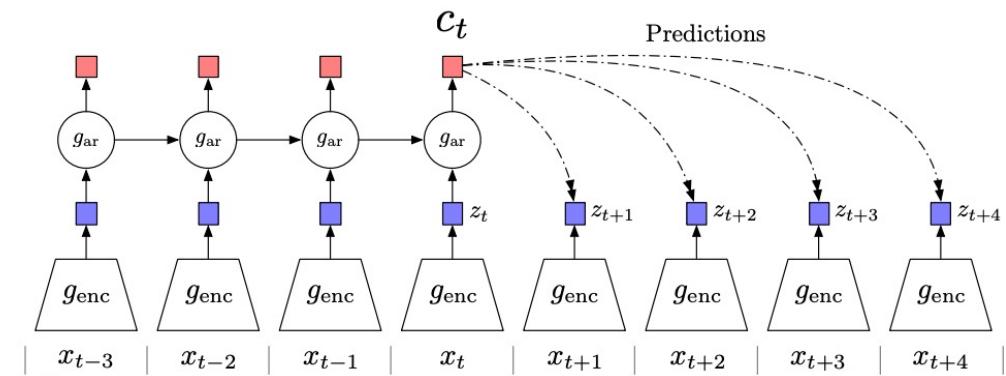


# How to predict the future?

Generate representations...



Vondrick et al., 2015



van den Oord et al., 2018

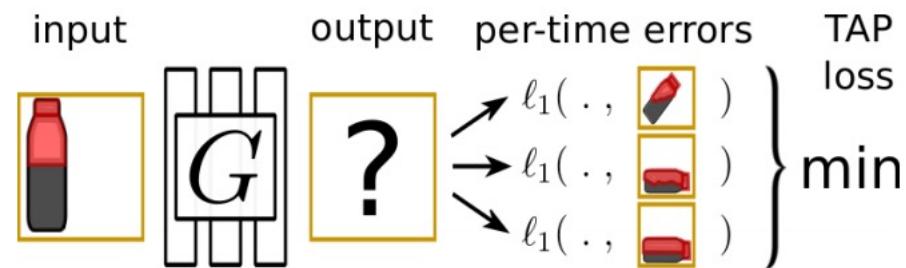


# Problem solved?

Not quite...

Predict at fixed offset into future = deal with high uncertainty!

Could let network output most predictable moment in near future



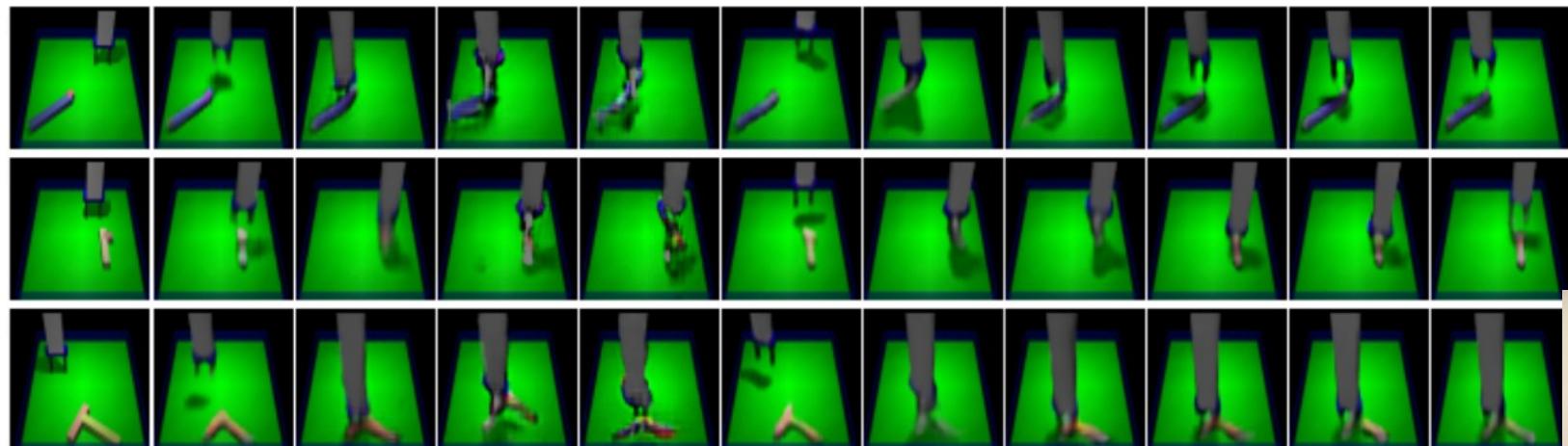
Jayaraman et al., 2018



# Okay, problem solved now?

Not quite...

Very short-term prediction – a few seconds into future at most  
Limited to simple, low-level visual data



Jayaraman et al., 2018



# The ideal future prediction

Dynamic, rather than at a fixed offset into the future

High-level, e.g., mixing eggs and flour → rolling out dough

Unsupervised, to take advantage of large unlabeled datasets

(a) Time =  $t$



“go ahead and  
pour the cream in”



# Better future predictions



...



“rinse off  
scallions”

“add soy sauce  
to the chicken”

...

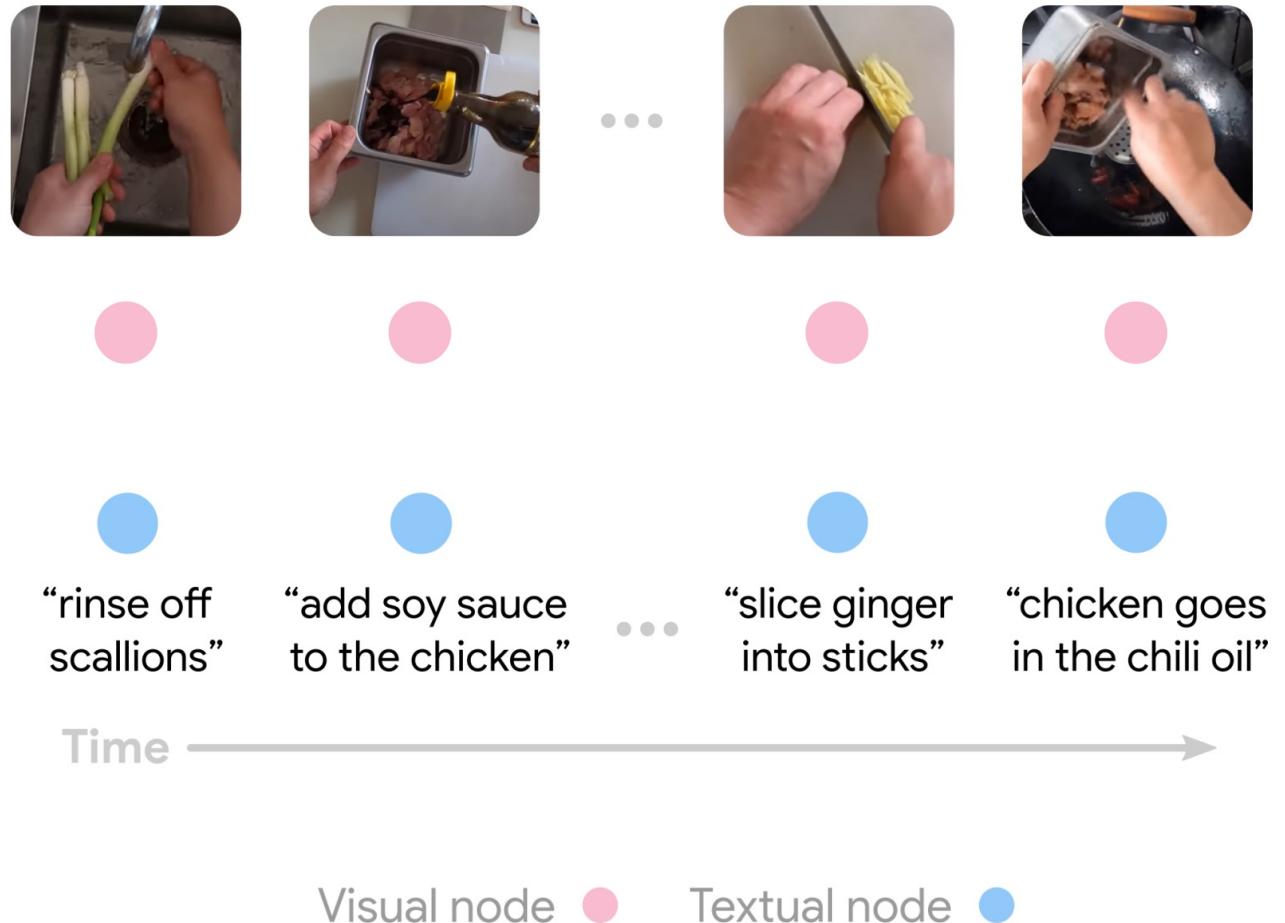
“slice ginger  
into sticks”

“chicken goes  
in the chili oil”

Time



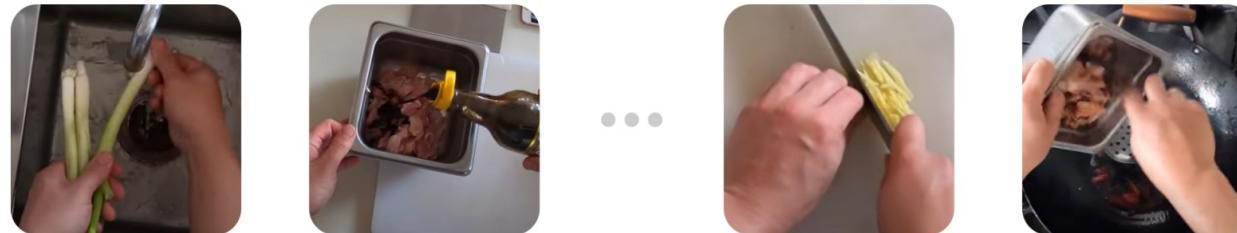
# Better future predictions



Epstein, Wu, Schmid, and Sun, Learning Temporal Dynamics from Cycles in Narrated Vide



# Cycling through video



“rinse off  
scallions”

“add soy sauce  
to the chicken”

...

“slice ginger  
into sticks”

“chicken goes  
in the chili oil”

Time



Start node



Visual node



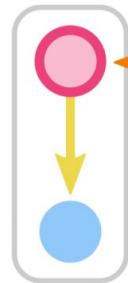
Textual node



# Cycling through video



...



“rinse off  
scallions”

“add soy sauce  
to the chicken”

...

“slice ginger  
into sticks”

“chicken goes  
in the chili oil”

Time



Start node



Visual node



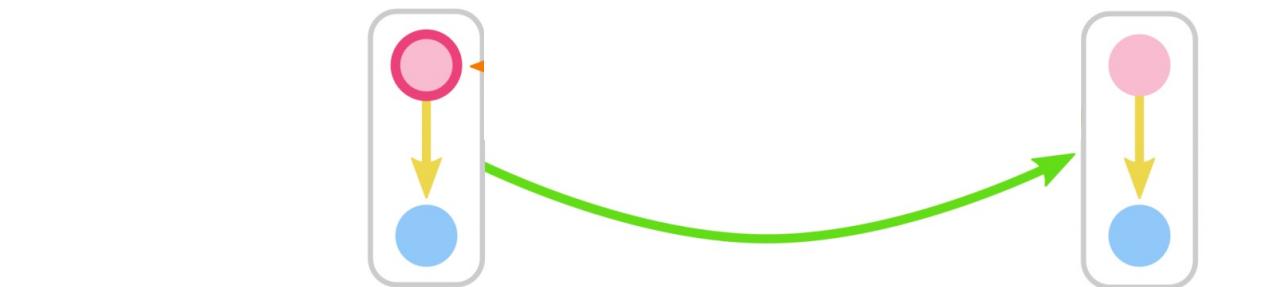
Textual node



Cross modal



# Cycling through video



“rinse off  
scallions”

“add soy sauce  
to the chicken”

...

“slice ginger  
into sticks”

“chicken goes  
in the chili oil”

Time

Start node



Visual node



Textual node



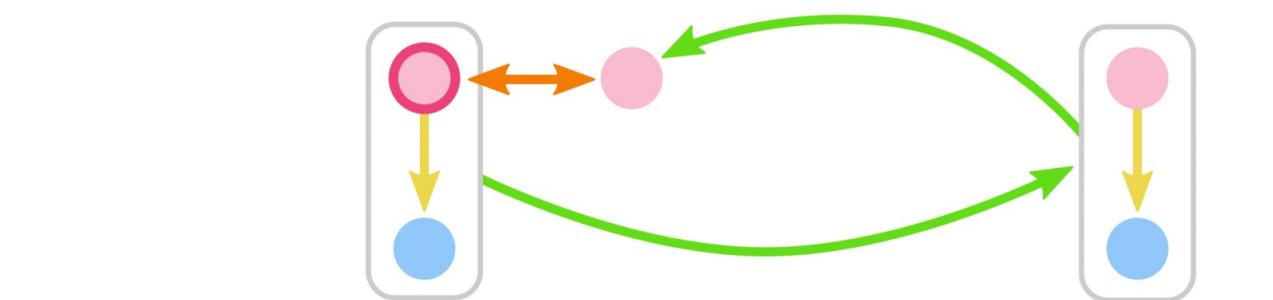
Cross modal



Temporal



# Cycling through video



Time →

Start node ○ Visual node ● Textual node ●

Cross modal → Temporal → Loss ←→



# Cycling through video - intuition

(a) Time =  $t$



“go ahead and  
pour the cream in”

(b) Time =  $t+1$



“go ahead and  
pour the cream in”

(c) Time =  $t+22$



“we'll be back  
in 30 minutes”

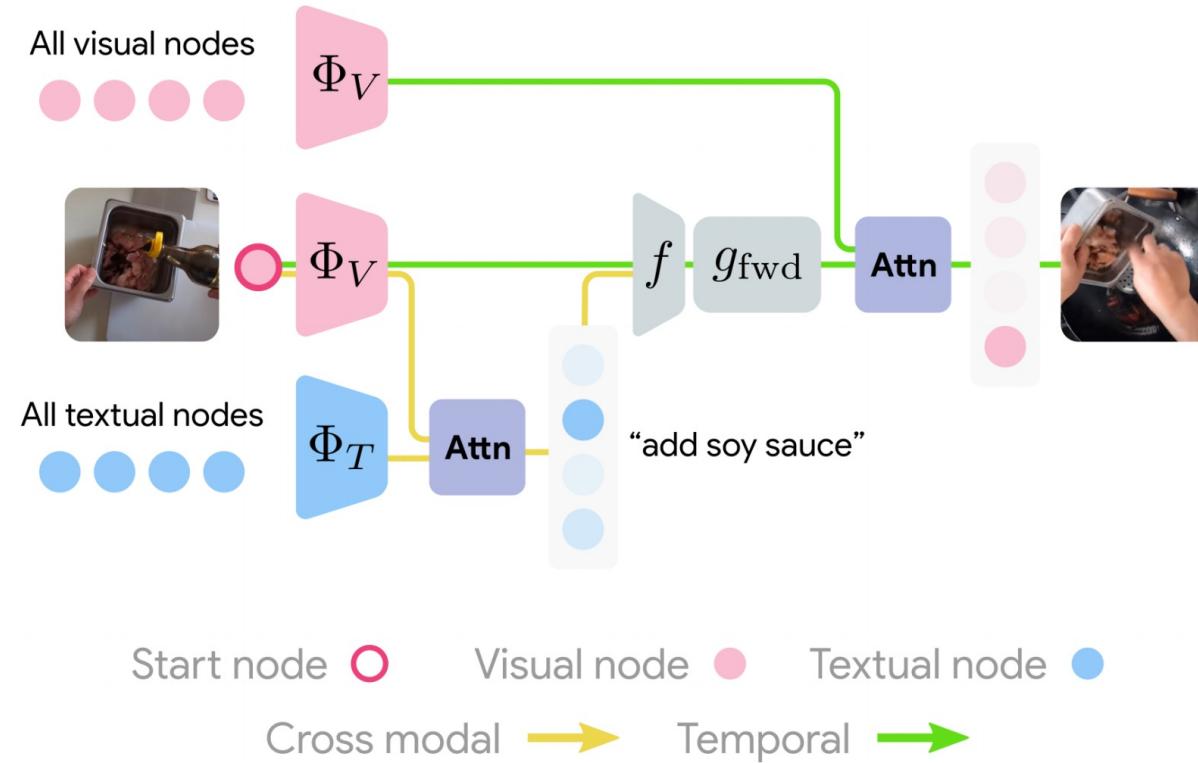
(d) Time =  $t+35$



“we have soft-serve  
ice cream”



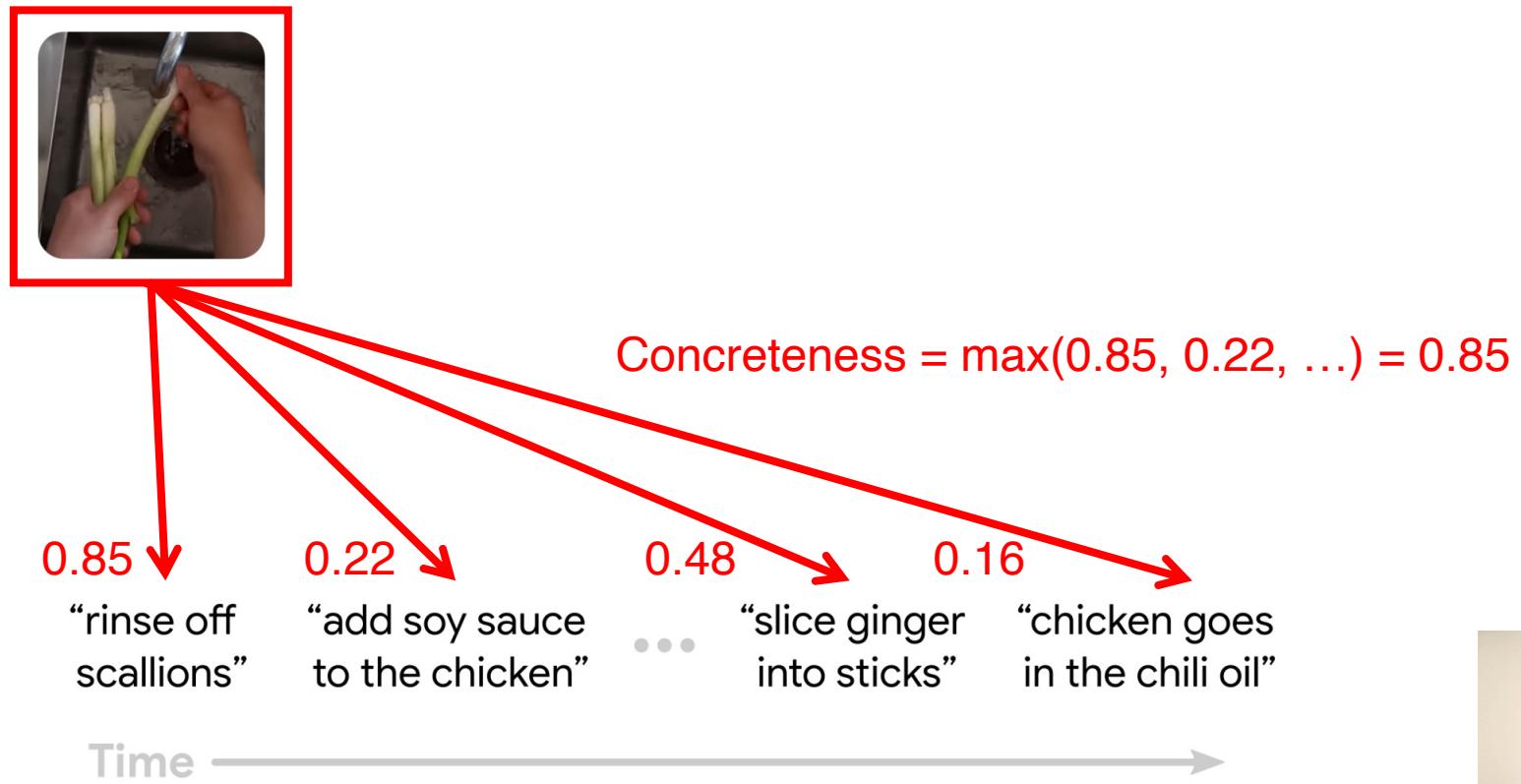
# Cycling through video - implementation



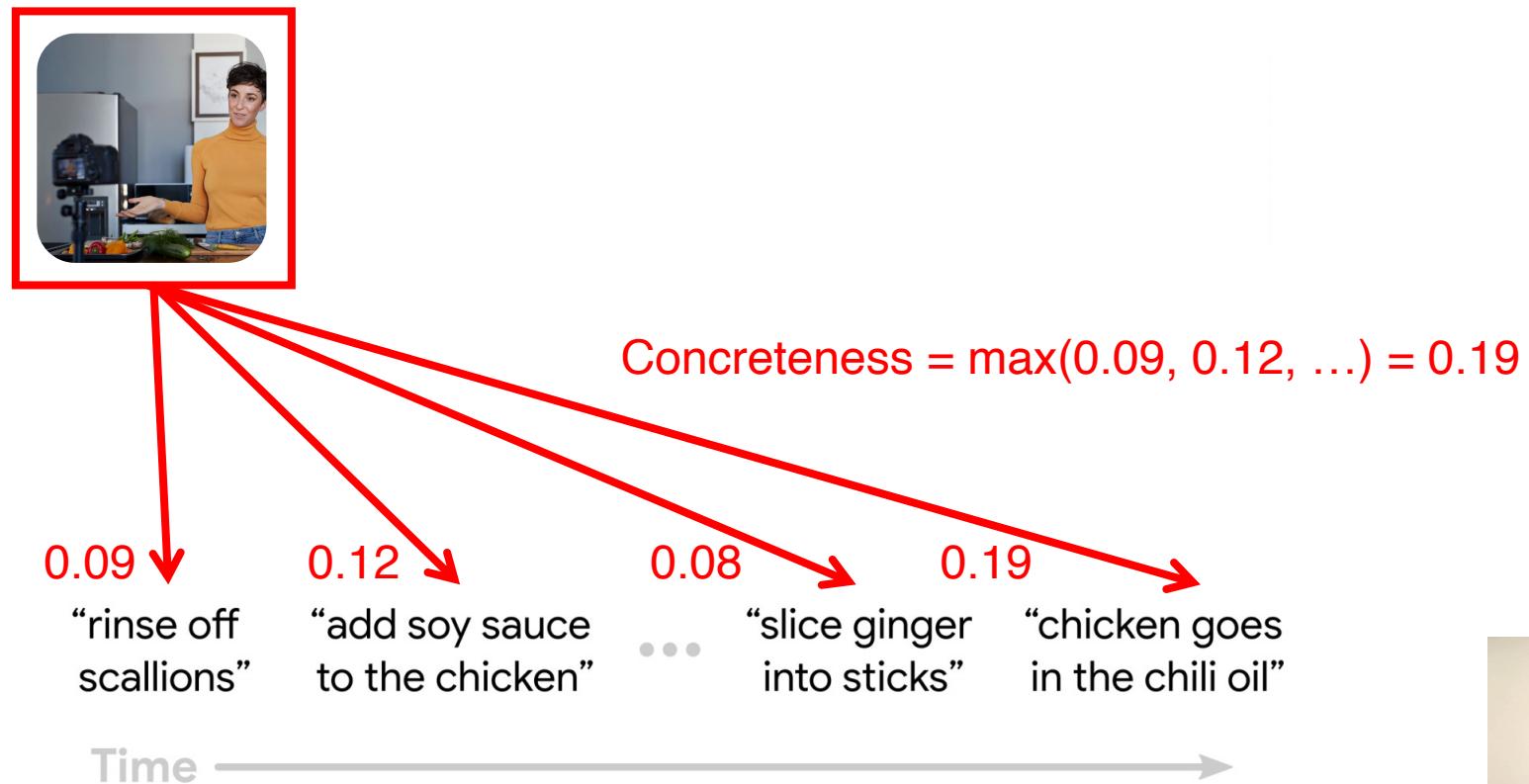
Epstein, Wu, Schmid, and Sun, Learning Temporal Dynamics from Cycles in Narrated Video



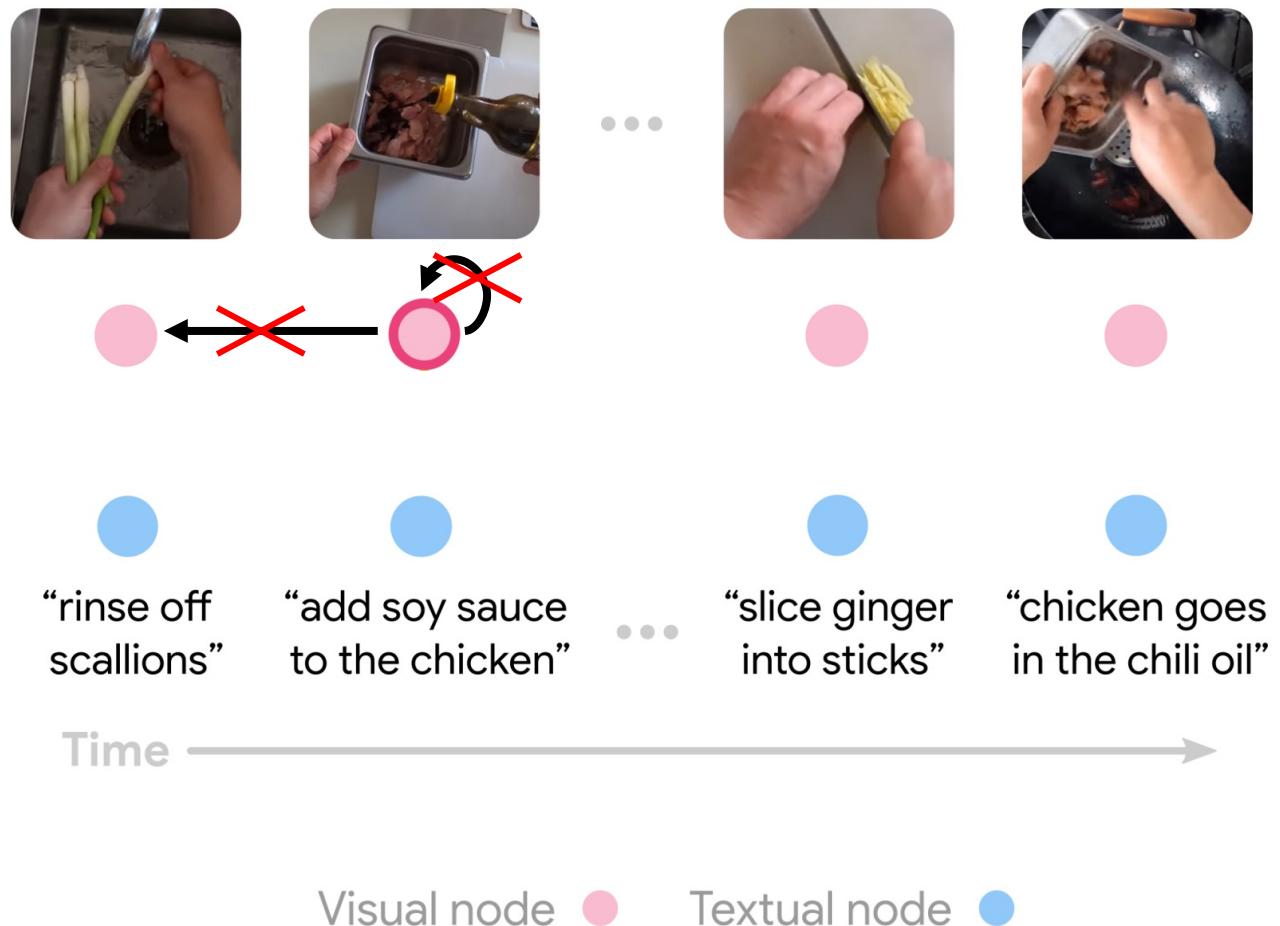
# Selecting start nodes



# Selecting start nodes



# Constraining temporal attention



# Discovering cycles in video

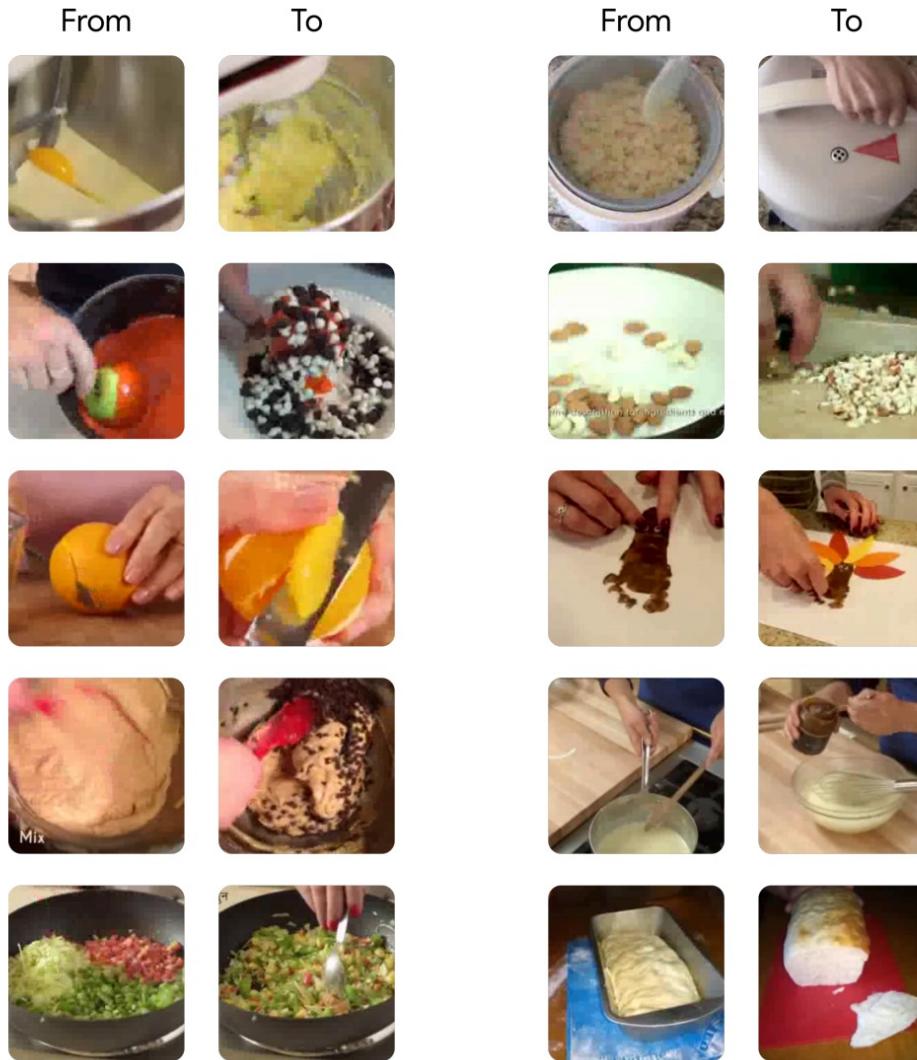
Start node	Cross-modal	Forward node	Cross-modal	Backward node
“knead the dough until slightly sticky”		“place dough in lightly greased bowl”		“knead the dough until slightly sticky”
“get the pan hot, adding oil”		“cook until onions are translucent”		“get the pan hot, adding oil”
“pour into graham cracker crust”		“place strawberries half inch from edge”		“pour into graham cracker crust”



# Finding cycles

Start node	Cross-modal	Forward node	Cross-modal	Backward node
	"spoon the batter into the loaf"		"bake until toothpick comes out clean"	
	"add the diced tomatoes"		"give it a quick stir to combine"	
	"cream butter in a large bowl"		"scoop batter into liners"	

# Discovering transitions in video



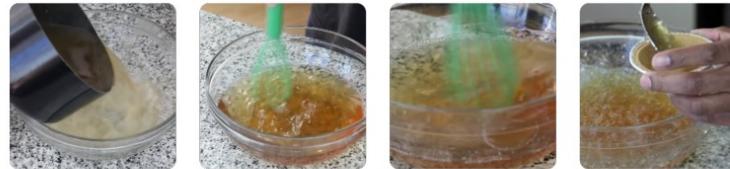
# Temporally ordering image collections



1 2 3 4 5



1 3 5 2 6



4 7 8 9

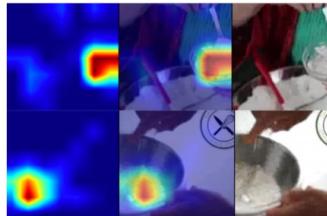


1 2 3 5 4

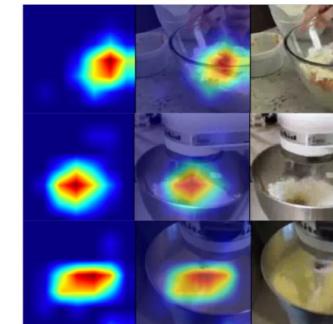


# Action and object neurons emerge

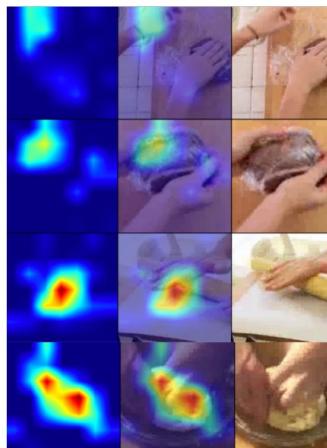
flour neuron ( $\rho=0.172$ )



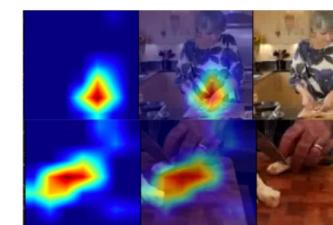
mix neuron ( $\rho=0.155$ )



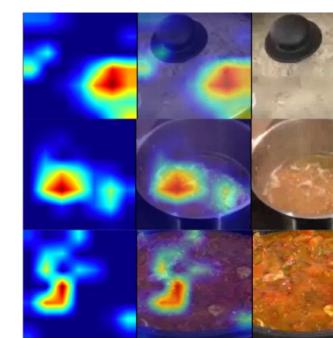
dough neuron ( $\rho=0.164$ )



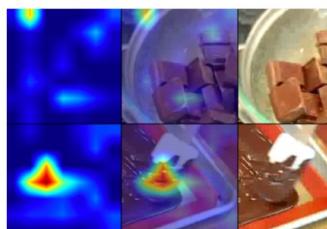
cut neuron ( $\rho=0.150$ )



boil neuron ( $\rho=0.131$ )



chocolate neuron ( $\rho=0.147$ )



# Vision-Language Navigation

ALFRED

Goal: "Rinse off a mug and place it in the coffee maker"



# VLN as a Benchmark

- Natural testbed for multimodal representations
  - Joint model visual observations, language instructions, etc.
  - From passive observation to active exploration
- The Transfer Learning Game
  - What to teach an agent before entering an environment?
  - Language and object grounding
  - Not always ideal to learn “end-to-end” and “from scratch”



# Focus One: language representations

$x_{1:L}$

move to the large black end table against the wall  
pick up the phone sitting on top of the end table with the blue case  
carry the phone to the foot of the bed  
place the phone on the bed to the right of the cushion

$y_{1:M}$

goto table pickup cellphone  
goto bed put cellphone bed

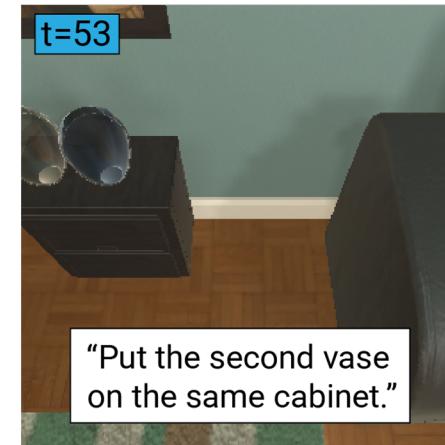
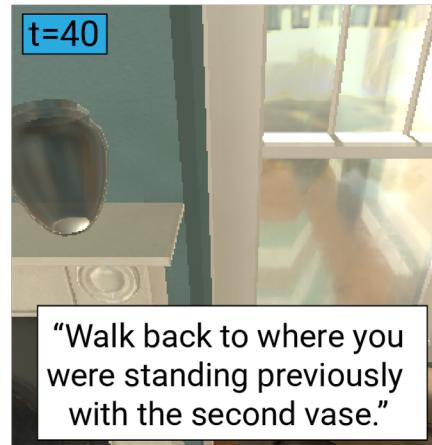
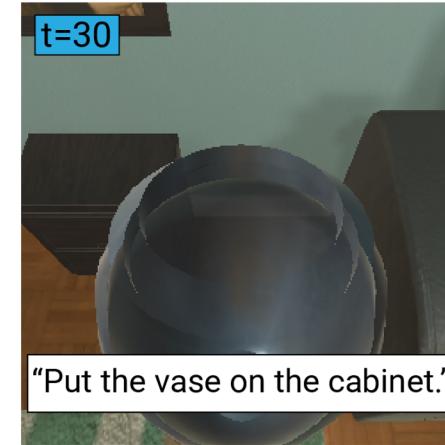
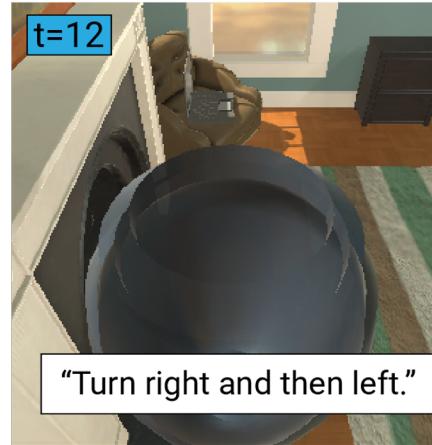
Often easier to collect

Can be “pre-trained” without a specific environment.



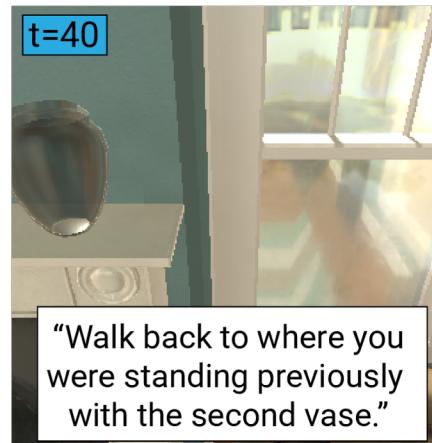
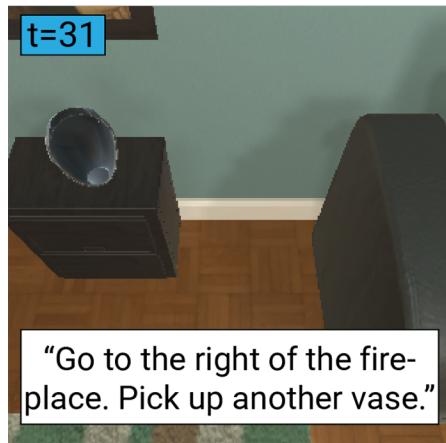
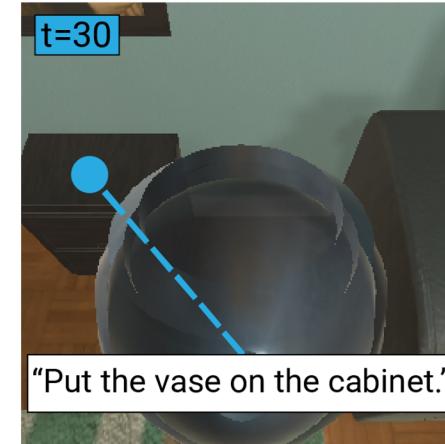
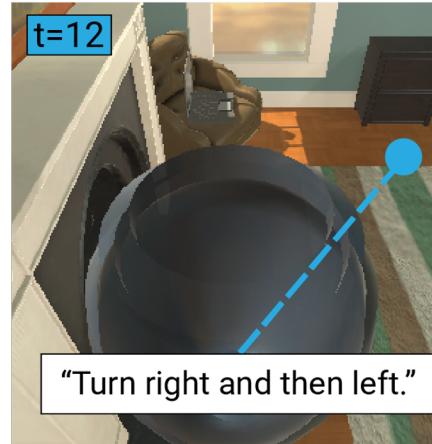
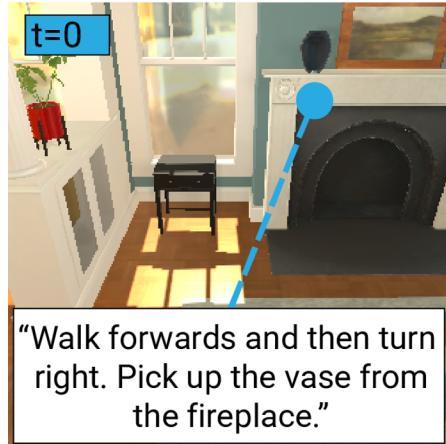
# Focus Two: Long-term dependencies

Goal: “put two vases on a cabinet”



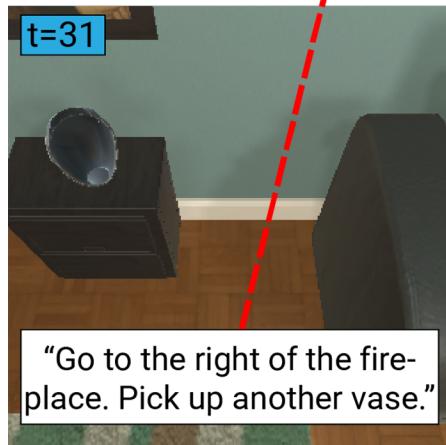
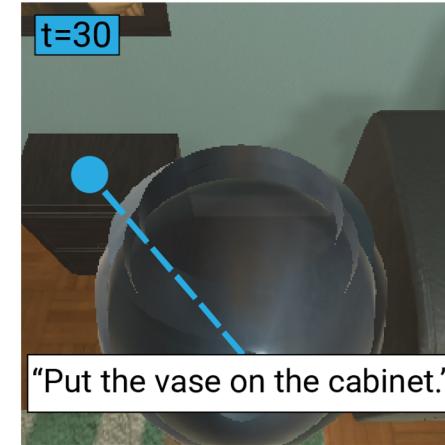
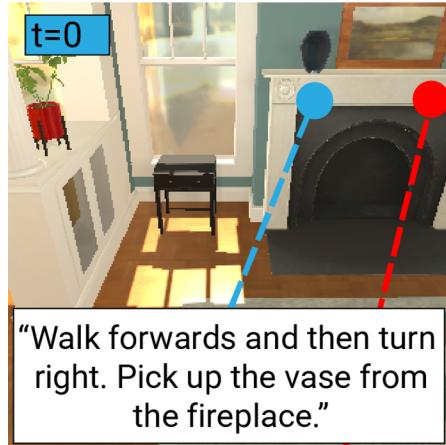
# Focus Two: Long-term dependencies

Goal: “put two vases on a cabinet”



# Focus Two: Long-term dependencies

Goal: “put two vases on a cabinet”



# Results: comparison with state-of-the-art

Model	Validation		Test	
	Seen	Unseen	Seen	Unseen
Shridhar <i>et al.</i> [50]	3.70	0.00	3.98	0.39
Nguyen <i>et al.</i> [58]	N/A	N/A	12.39	4.45
Singh <i>et al.</i> [52]	19.15	3.78	22.05	5.30
E.T. (ours)	33.78	3.17	28.77	5.04
E.T. (ours) + synth. data	<b>46.59</b>	<b>7.32</b>	<b>38.42</b>	<b>8.57</b>
Human	-	-	-	91.00

Comparison with state-of-the-art models.



# Self-attention to capture long-term dependency

Previous visual frames:



$t = 8$



$t = 18$

Attention to previous frames:



Current observation:



$t = 19$

*the agent needs to  
bring the apple back to  
the microwave*

**Goal:** Grab an apple, cook it and put it in the sink. **Instructions:** Turn to your left twice so that you are facing the fridge. Open the fridge, grab an apple from the shelf and close the fridge door. Walk to the left of the fridge to face the microwave. Put the apple in the microwave and cook it for a few seconds before taking it back out and closing the microwave. Turn to face your left. Put the apple in the sink.



# Code and checkpoints are released!

<https://github.com/alexpashevich/E.T.>



# Summary

- Many interesting tasks for detailed video understanding
  - Video is encyclopedia of multimedia contents!
  - From manual annotation to “automatic” supervision
    - Self-supervised: Contrastive Learning
    - Cross-modal supervised: Cross-modal cycle consistency
  - Many interesting applications of detailed video understanding
    - Structured multimodal representations for navigation
    - Better interpretable, more generalizable models



# Collaborators

