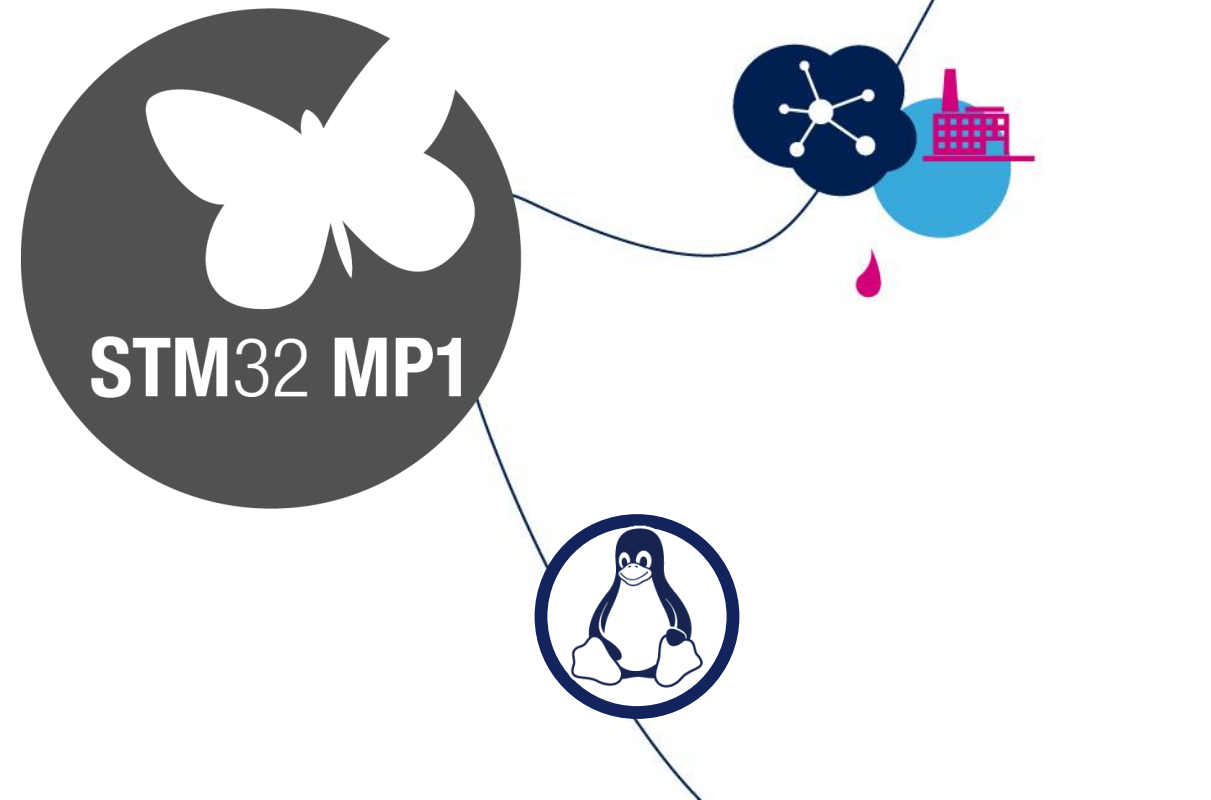


# *Simple Linux application with Developer Package*



## Lab Objective

- Reboot the board and observe a kernel boot log
- Use the already installed SDK
- Compile in Linux a simple hello world application
- Run the hello world application on the target

## Lab Objective

- Reboot the board and observe a kernel boot log
- Use the already installed SDK
- Compile in Linux a simple hello world application
- Run the hello world application on the target

Linux command on the host

```
root@stm32mp1: /#
```

Linux command on the target



theory



practice

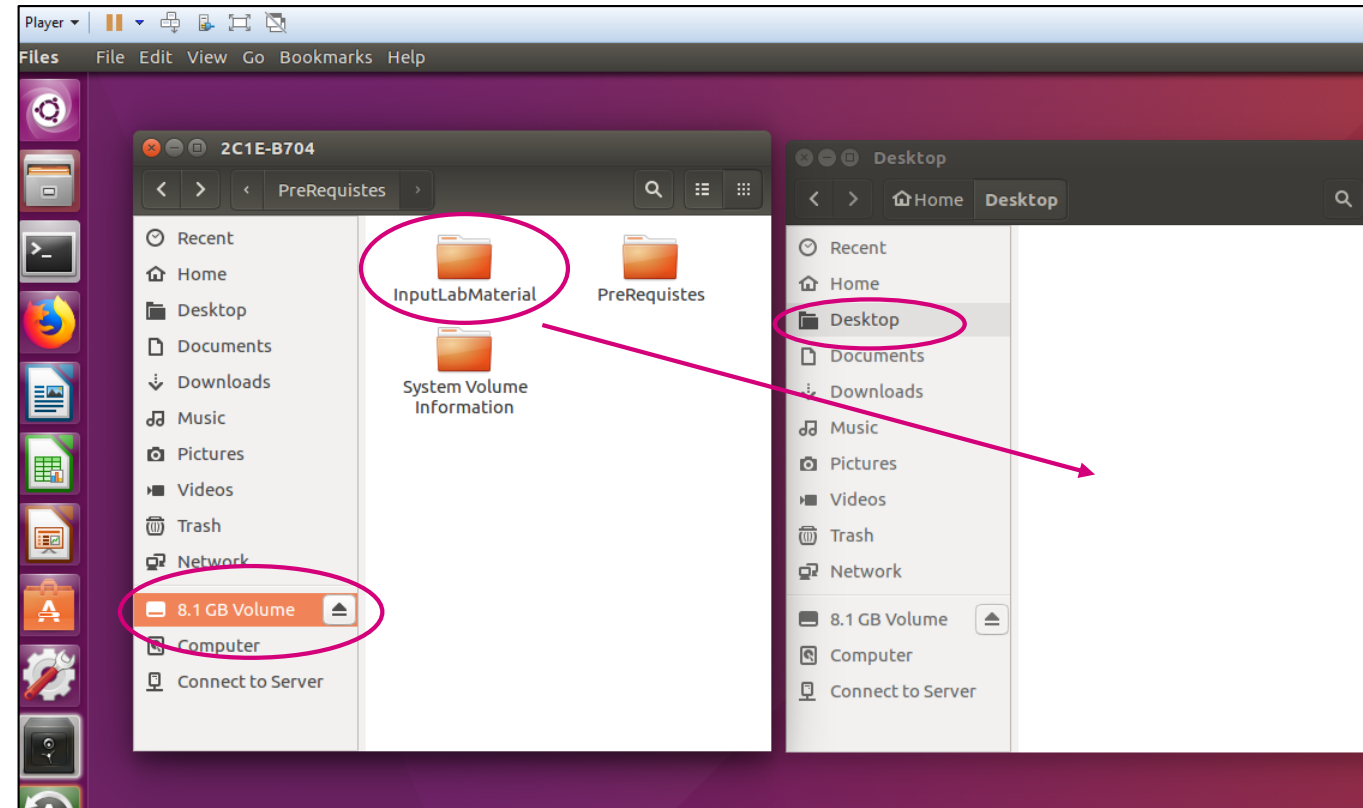


# Lab *Developer Package*

4

## Prerequisite for all the workshop labs

- 1) Start Linux Host
  - 2) Copy the workshop material to Linux Host desktop from a USB stick
- If the USB stick does not auto attach, select it via the VM “Player/Removable Devices”
  - Drag and Drop *InputLabMaterial* and *WorkshopSlides* folders to `$HOME/Desktop/`





## Hardware setup

- In the next steps, we will setup the hardware
- Contents:
  - 1 x STM32MP157C-DK2 development board
  - 1 x microSD card
  - 1 x micro USB cable
  - 1 x USB-C cable



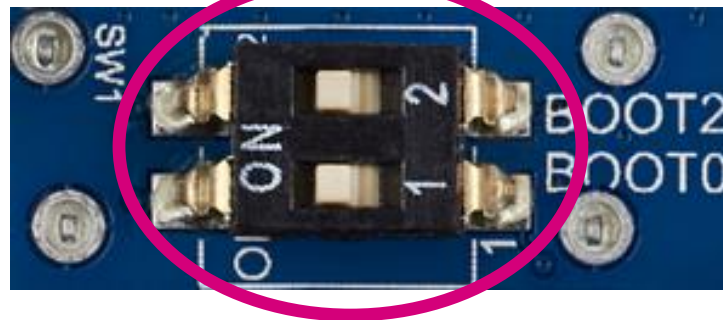


# Lab *Developer Package*

6

## Prerequisites - boot switch

- Make sure the boot switch is in the position '11'  
(SD card selected as boot device)

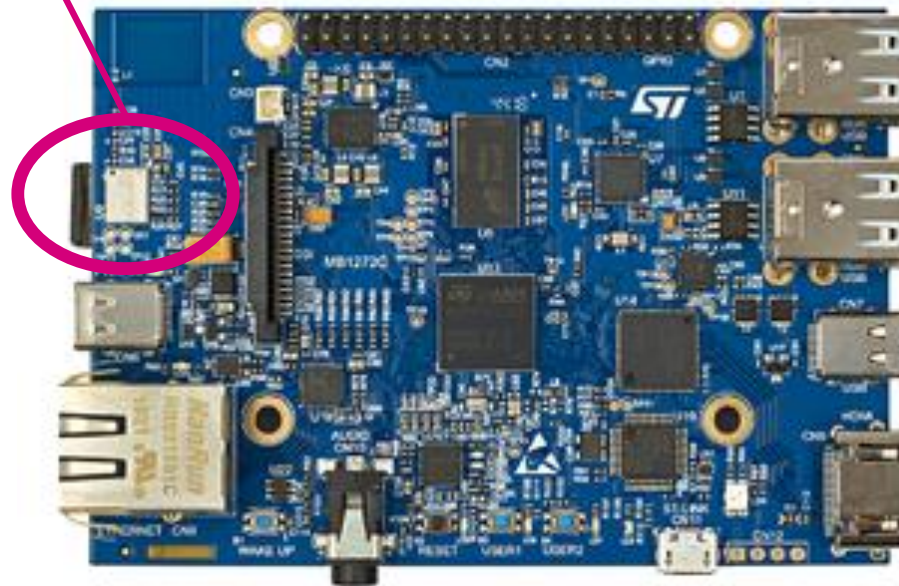




# Lab *Developer Package* 7

## Prerequisites - SD card

- Make sure the SD card is plugged in



*Note: the top view with the display removed*

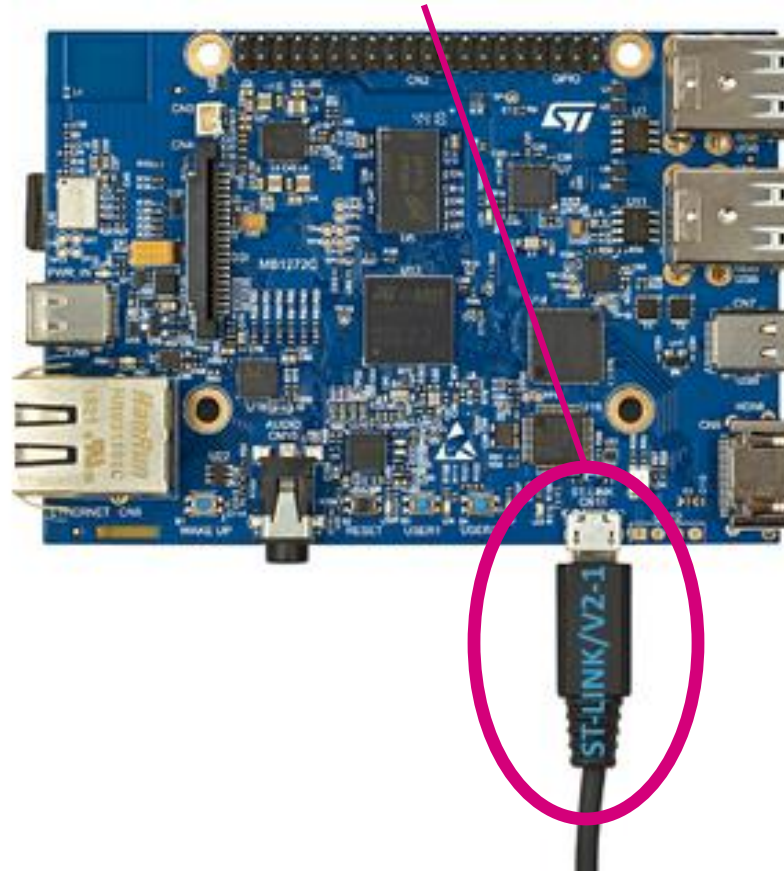




# Lab *Developer Package* 8

## Prerequisites - ST-LINK

- Connect the host PC to the on-board ST-LINK/V2 using a micro USB cable



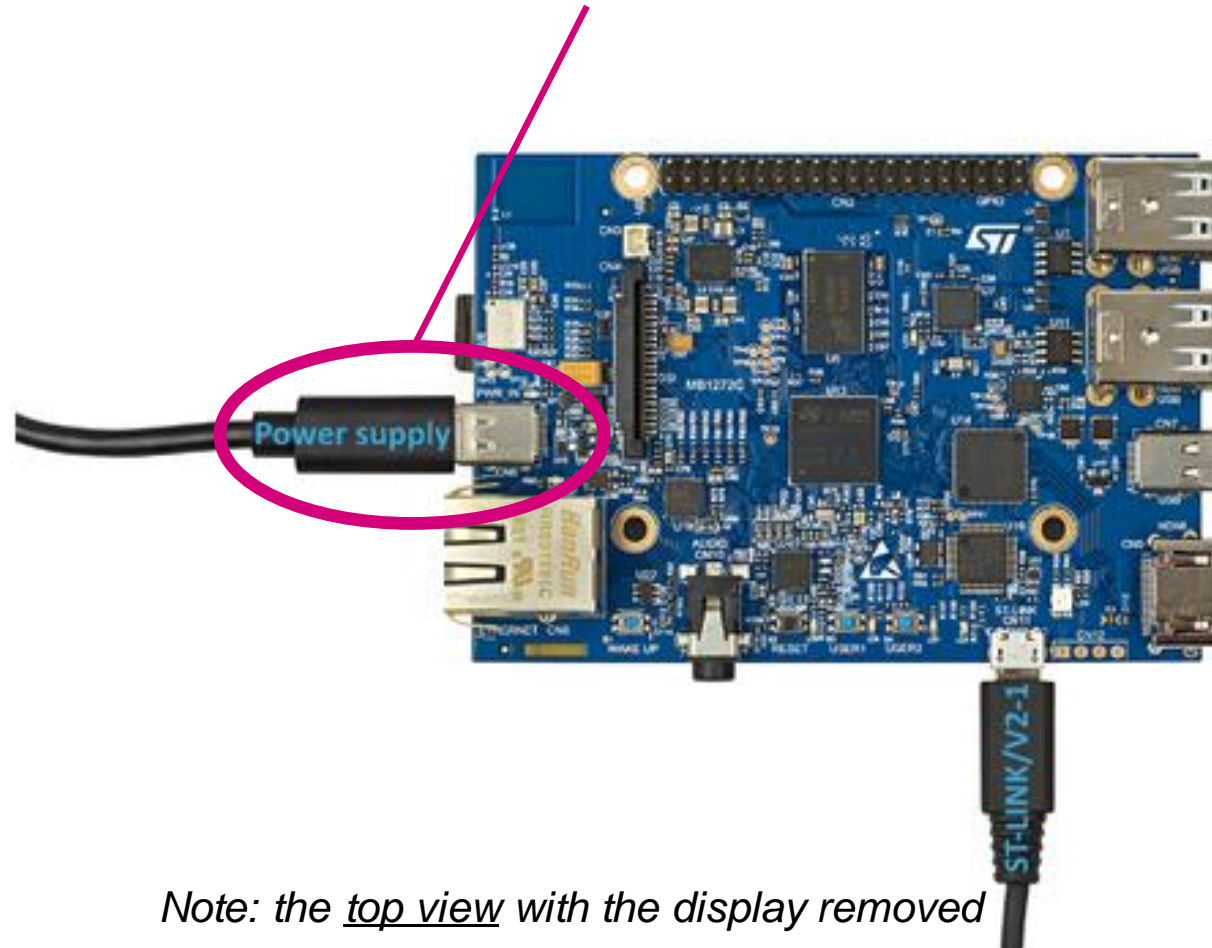




# Lab *Developer Package* 9

## Prerequisites - USB-C power supply

- Connect USB-C cable to power supply the development board



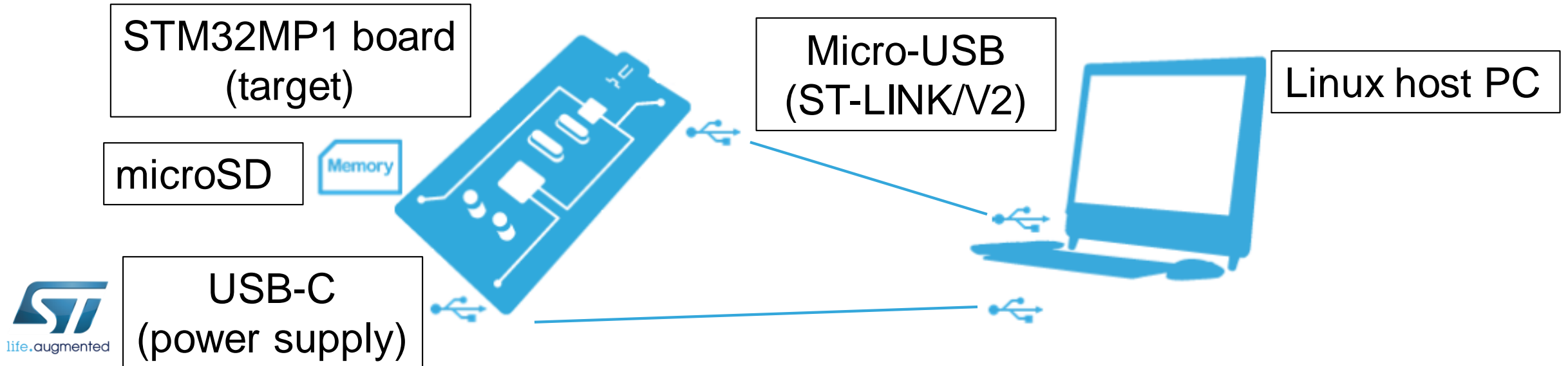


# Lab *Developer Package*

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## Prerequisites - summary

- Make sure the boot switch is in the position '11' (SD card selected as boot device)
- Make sure the SD card is plugged in
- Connect the host PC to the on-board ST-LINK/V2 using a micro USB cable
- Connect USB-C cable to power supply the development board





# Lab *Developer Package*

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## Power supply information

- STM32MP157C-DK2 development board can be powered using USB Type-C or USB Type-A from laptop for demo purpose
- Be very careful this mode is limited in terms of power  
It can NOT work for high power use cases
- Red LED may indicate not enough power supply
- For nominal behavior of dk2 board, it is recommended to connect the USB Type-C™ to USB Type-C™ cable to a 5V/3A power supply

- If the board power supply doesn't supply enough current (3A), the red LED indicates the issue following the rules below:

blink	console message	boot process
2 times	WARNING 500mA power supply detected Current too low, use a 3A power supply!	Continue and red LED stays ON
3 times	WARNING 1500mA power supply detected Current too low, use a 3A power supply!	Continue and red LED stays ON
forever	ERROR USB TYPE-C connection in unattached mode Check that USB TYPE-C cable is correctly plugged	stop
forever	USB TYPE-C charger not compliant with USB specification	stop

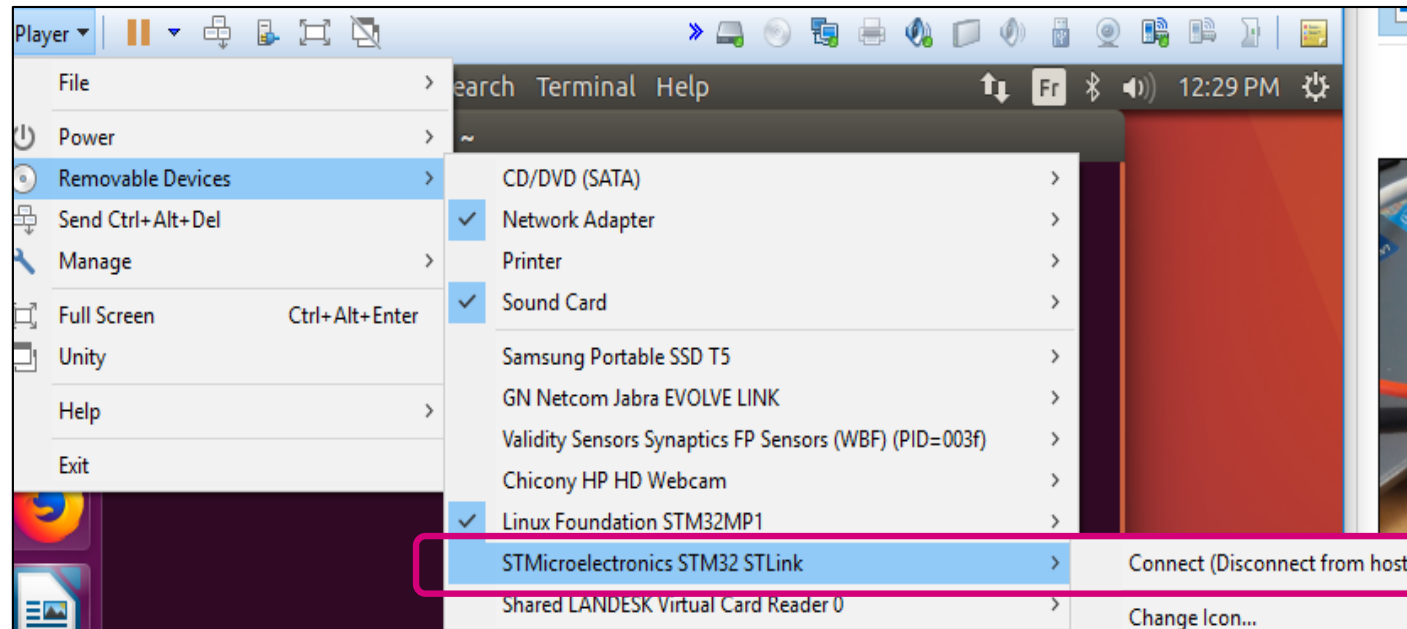


# Lab *Developer Package*

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## Enable USB ST-Link probe on Linux host

- Connect with the ST-Link debugger/programmer to the Linux host

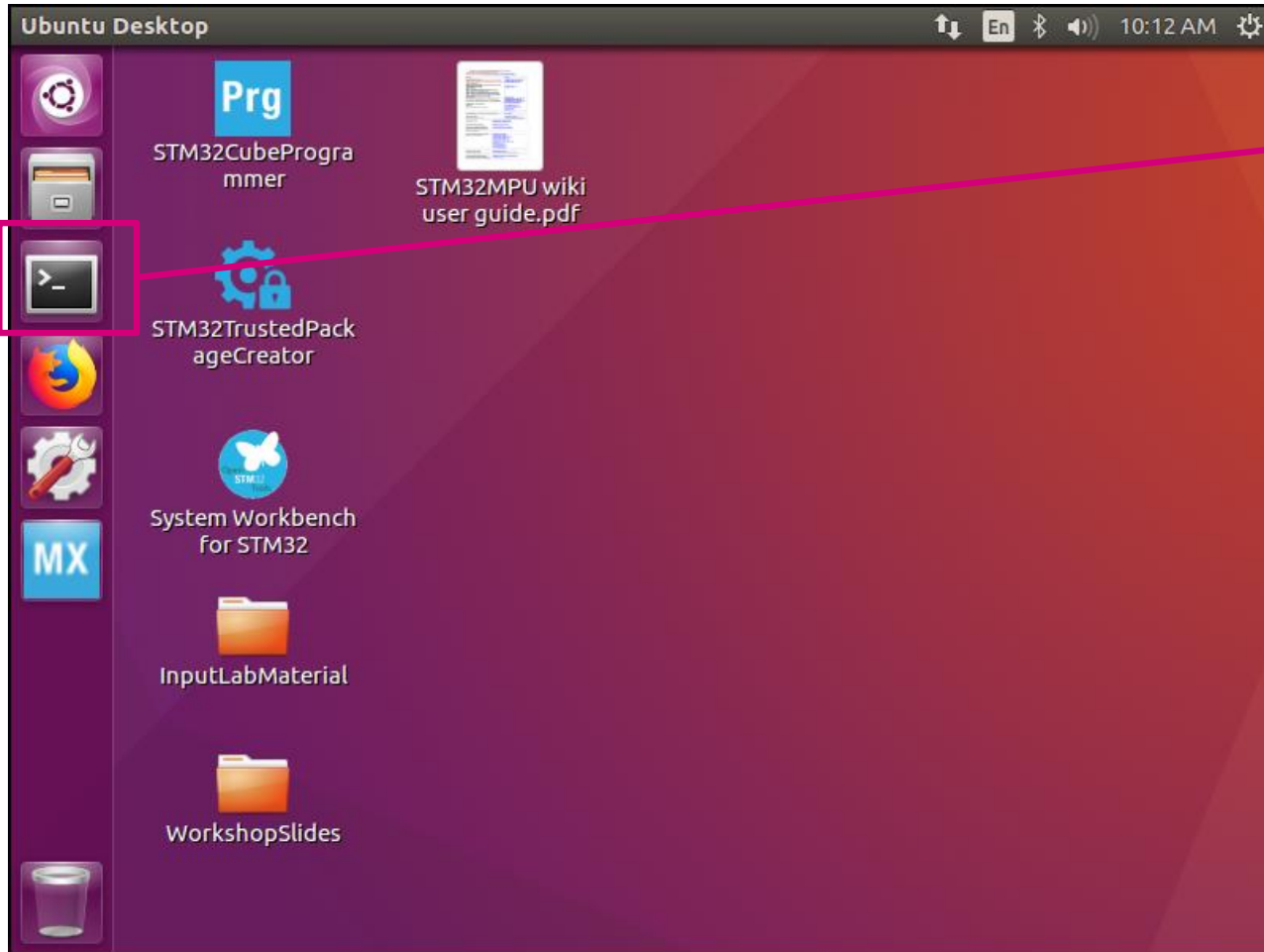




# Lab *Developer Package*

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## Launch a new terminal



- Launch a new terminal on Linux host

Hint:

You can use the keyboard shortcut

`<CTRL><ALT>T`



# Lab *Developer Package*

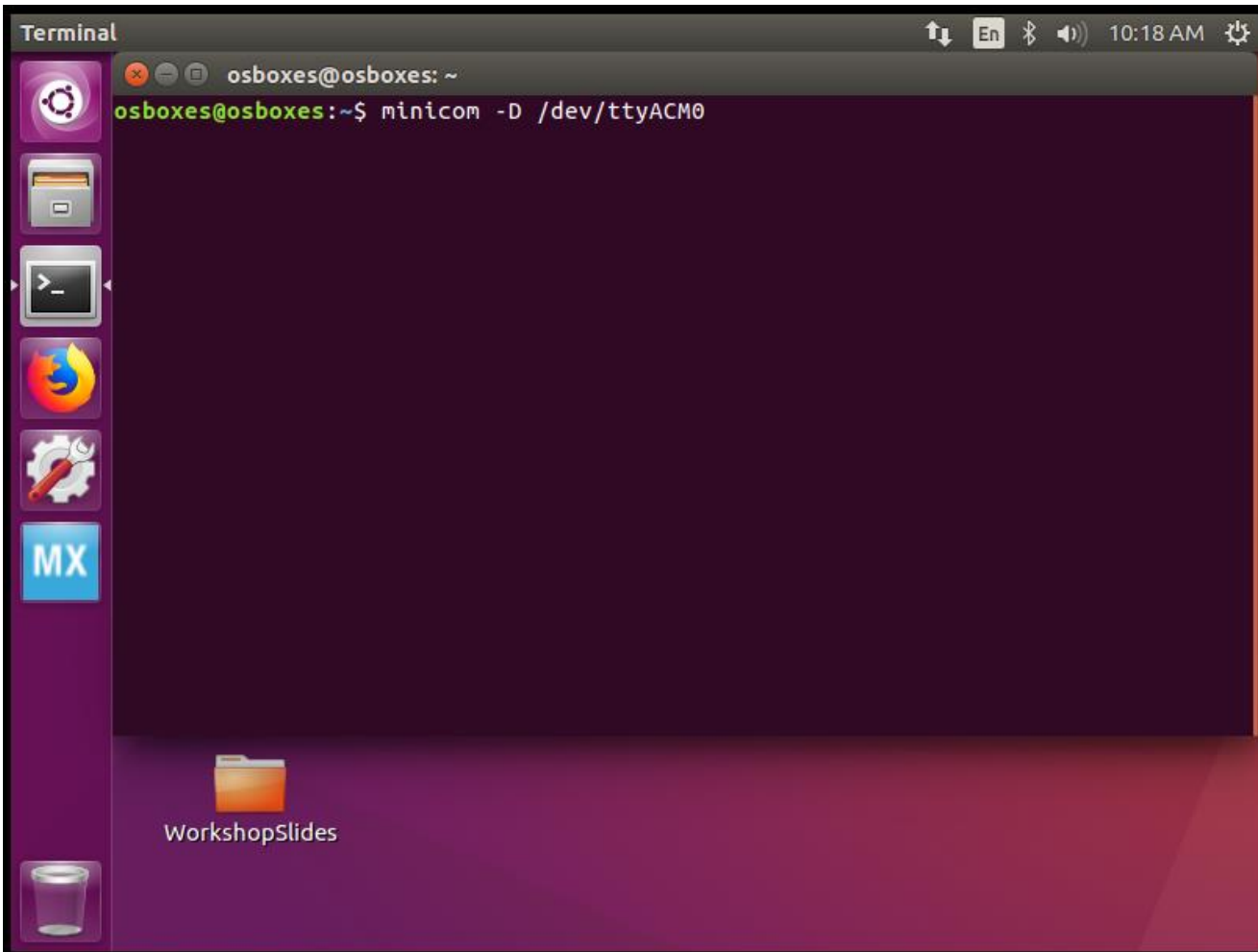
14

## Start minicom

- Start a minicom terminal in order to establish a serial connection between Linux host and the target

Enter on Host

```
minicom -D /dev/ttyACM0
```







# Lab *Developer Package*

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## Reboot the board

- Press the black reset button to reboot the board and observe the kernel boot log in the minicom terminal







# Lab *Developer Package*

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## Observe the kernel boot log

- Observe the kernel boot log

```
osboxes@osboxes: ~  
Verifying Checksum ... OK  
## Flattened Device Tree blob at c4000000  
Booting using the fdt blob at 0xc4000000  
XIP Kernel Image ... OK  
Using Device Tree in place at c4000000, end c4013f85  
  
Starting kernel ...  
[ 0.000000] Booting Linux on physical CPU 0x0  
[ 0.000000] Linux version 4.19.9 (oe-user@oe-host) (gcc version 8.2.0 (GCC))  
[ 0.000000] CPU: ARMv7 Processor [410fc075] revision 5 (ARMv7), cr=10c5387d  
[ 0.000000] CPU: div instructions available: patching division code  
[ 0.000000] CPU: PIPT / VIPT nonaliasing data cache, VIPT aliasing instruction  
[ 0.000000] OF: fdt: Machine model: STMicroelectronics STM32MP157C-DK2 Discod  
[ 0.000000] Memory policy: Data cache writealloc  
[ 0.000000] Reserved memory: created DMA memory pool at 0x10000000, size 0 MB  
[ 0.000000] OF: reserved mem: initialized node mcuram2@0x10000000, compatible  
[ 0.000000] Reserved memory: created DMA memory pool at 0x10040000, size 0 MB  
[ 0.000000] OF: reserved mem: initialized node vdev0vring0@10040000, compatible  
[ 0.000000] Reserved memory: created DMA memory pool at 0x10042000, size 0 MB  
[ 0.000000] OF: reserved mem: initialized node vdev0vring1@10042000, compatible  
[ 0.000000] Reserved memory: created DMA memory pool at 0x10044000, size 0 MB  
[ 0.000000] OF: reserved mem: initialized node vdev0buffer@10044000, compatible  
[ 0.000000] Reserved memory: created DMA memory pool at 0x30000000, size 0 MB  
[ 0.000000] OF: reserved mem: initialized node mcuram@0x30000000, compatible  
[ 0.000000] Reserved memory: created DMA memory pool at 0x38000000, size 0 MB  
[ 0.000000] OF: reserved mem: initialized node retram@0x38000000, compatible  
[ 0.000000] cma: Reserved 128 MiB at 0xd4000000  
[ 0.000000] psci: probing for conduit method from DT.  
[ 0.000000] psci: PSCIv1.1 detected in firmware.  
[ 0.000000] psci: Using standard PSCI v0.2 function IDs  
[ 0.000000] psci: MIGRATE_INFO_TYPE not supported  
  
CTRL-A Z for help | 115200 8N1 | NOR | Minicom 2.7 | VT102 | Offline | ttyACM0
```



# Lab *Developer Package*

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## Developer Package Prerequisite

- The Developer Package and SDK are already installed

```
osboxes@osboxes: /local/STM32MP15-Ecosystem-v1.0.0
osboxes@osboxes: /local/STM32MP15-Ecosystem-v1.0.0$ tree -L 2
.
├── Developer-Package
│   ├── en.SDK-x86_64-stm32mp1-openstlinux-4.19-thud-mp1-19-02-20.tar.xz
│   ├── en.SOURCES-kernel-stm32mp1-openstlinux-4.19-thud-mp1-19-02-20.tar.xz
│   ├── en.SOURCES-optee-stm32mp1-openstlinux-4.19-thud-mp1-19-02-20.tar.xz
│   ├── en.SOURCES-tf-a-stm32mp1-openstlinux-4.19-thud-mp1-19-02-20.tar.xz
│   ├── en.SOURCES-u-boot-stm32mp1-openstlinux-4.19-thud-mp1-19-02-20.tar.xz
│   └── SDK
│       └── stm32mp1-openstlinux-4.19-thud-mp1-19-02-20
├── Distribution-Package
│   └── openstlinux-4.19-thud-mp1-19-02-20
├── Starter-Package
│   ├── en.FLASH-stm32mp1-openstlinux-4.19-thud-mp1-19-02-20.tar.xz
│   └── stm32mp1-openstlinux-4.19-thud-mp1-19-02-20
└── 7 directories, 6 files
osboxes@osboxes: /local/STM32MP15-Ecosystem-v1.0.0$
```

SDK

Kernel, TF-A, Uboot  
source code



## Build environment setup

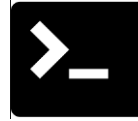
- 1) Open a new terminal window





## Build environment setup

- 1) Open a new terminal window
- 2) Setup build environment

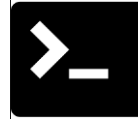


```
source $SDK_ROOT/SDK/environment-setup-cortexa7t2hf-neon-vfpv4-openstlinux_weston-linux-gnueabi
```



## Build environment setup

- 1) Open a new terminal window
- 2) Setup build environment



```
source $SDK_ROOT/SDK/environment-setup-cortexa7t2hf-neon-vfpv4-openstlinux_weston-linux-gnueabi
```

- 3) Check the environment

```
$CC --version
```

- Expected return value:

```
arm-openstlinux_weston-linux-gnueabi-gcc (GCC) 8.2.0
```



# Lab *Developer Package*

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## Copy lab material

- 1) Copy lab material from the desktop directory to the SDK

```
cp -a $HOME/Desktop/InputLabMaterial/Lab-DeveloperPackage $SDK_ROOT/
```



# Lab *Developer Package*

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## Copy lab material

- 1) Copy lab material from the desktop directory to the SDK

```
cp -a $HOME/Desktop/InputLabMaterial/Lab-DeveloperPackage $SDK_ROOT/
```

- 2) Move to the hello world example directory in the SDK

```
cd $SDK_ROOT/Lab-DeveloperPackage/gtk_hello_world_example/
```





# Lab *Developer Package*

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## Copy lab material

- 1) Copy lab material from the desktop directory to the SDK

```
cp -a $HOME/Desktop/InputLabMaterial/Lab-DeveloperPackage $SDK_ROOT/
```

- 2) Move to the hello world example directory in the SDK

```
cd $SDK_ROOT/Lab-DeveloperPackage/gtk_hello_world_example/
```

- 3) Open the source file using the gedit text editor

```
gedit gtk_hello_world.c &
```



## Review source code of the application

```
#include <gtk/gtk.h>

static void
print_hello (GtkWidget *widget,
             gpointer    data)
{
    g_print ("Hello World\n");
}

static void
activate (GtkApplication *app,
          gpointer         user_data)
{
    GtkWidget *window;
    GtkWidget *button;
    GtkWidget *button_box;

    window = gtk_application_window_new (app);
    gtk_window_set_title (GTK_WINDOW (window), "Window");
    gtk_window_set_default_size (GTK_WINDOW (window), 200, 200);

    button_box = gtk_button_box_new (GTK_ORIENTATION_HORIZONTAL);
    gtk_container_add (GTK_CONTAINER (window), button_box);

    button = gtk_button_new_with_label ("Hello World");
    g_signal_connect (button, "clicked", G_CALLBACK (print_hello), NULL);
    g_signal_connect_swapped (button, "clicked", G_CALLBACK (gtk_widget_destroy),
                             window);
    gtk_container_add (GTK_CONTAINER (button_box), button);
}
```

Nothing to change here!



## Review source code of the application

```
window = gtk_application_window_new (app);
gtk_window_set_title (GTK_WINDOW (window), "Window");
gtk_window_set_default_size (GTK_WINDOW (window), 200, 200);

button_box = gtk_button_box_new (GTK_ORIENTATION_HORIZONTAL);
gtk_container_add (GTK_CONTAINER (window), button_box);

button = gtk_button_new_with_label ("Hello World");
g_signal_connect (button, "clicked", G_CALLBACK (print_hello), NULL);
g_signal_connect_swapped (button, "clicked", G_CALLBACK (gtk_widget_destroy),
window);
gtk_container_add (GTK_CONTAINER (button_box), button);

gtk_widget_show_all (window);
}

int
main (int   argc,
      char **argv)
{
    GtkApplication *app;
    int status;

    app = gtk_application_new ("org.gtk.example", G_APPLICATION_FLAGS_NONE);
    g_signal_connect (app, "activate", G_CALLBACK (activate), NULL);
    status = g_application_run (G_APPLICATION (app), argc, argv);
    g_object_unref (app);

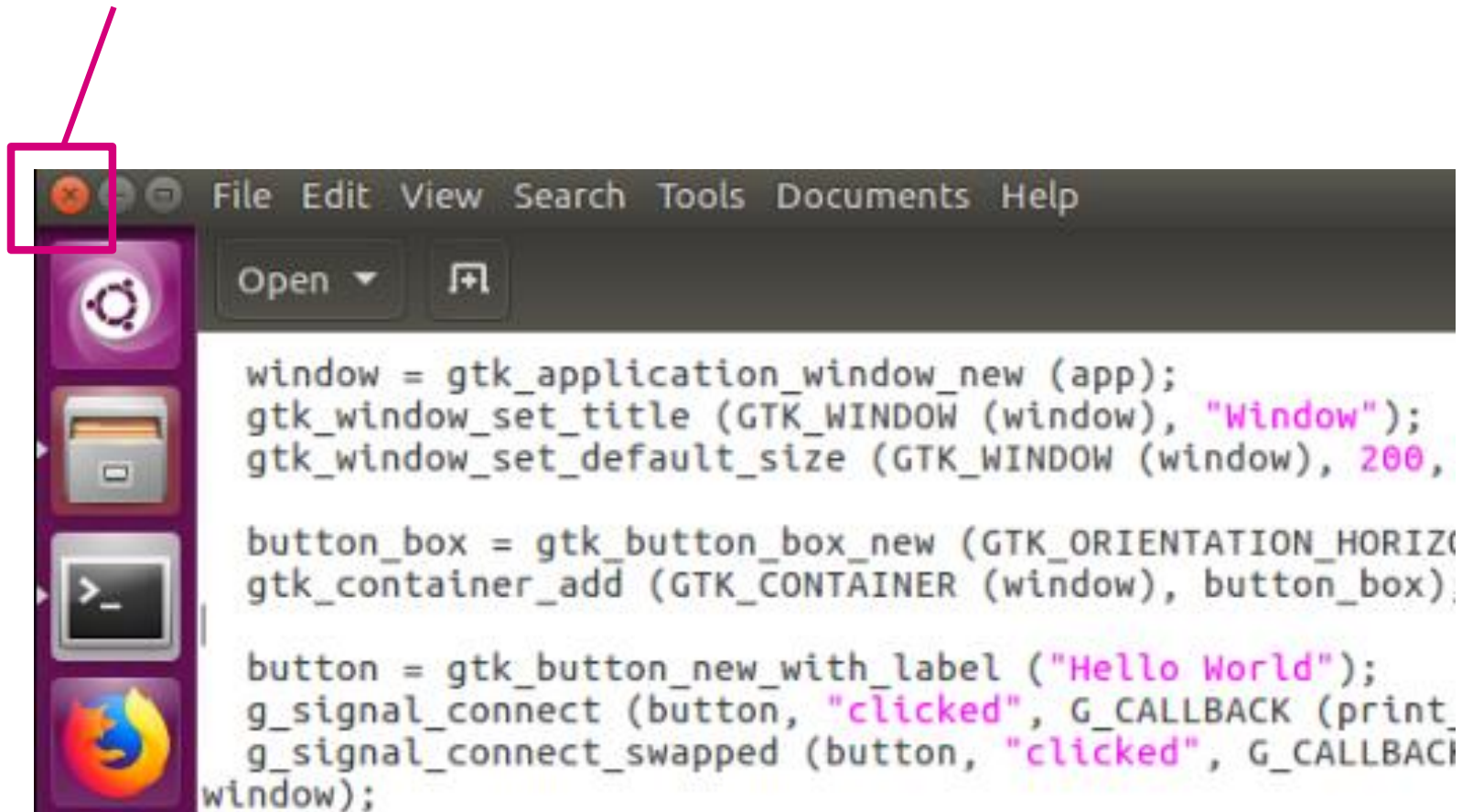
    return status;
}
```

Nothing to change here!



## Build simple hello world application

- Close the gedit text editor





## Compile the hello world example

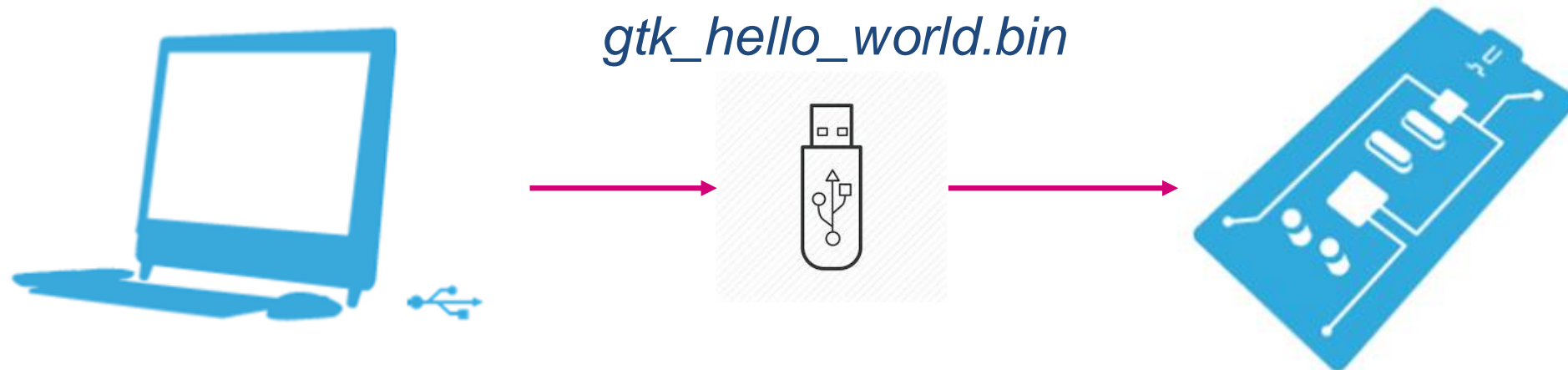
- Issue make command to compile the example

```
make
```



## Transferring the binary to the target

- Now, that we have a binary of the hello world example, the next step will be transferring the binary to the target and executing it there afterwards
- A USB stick will be used to transfer the binary





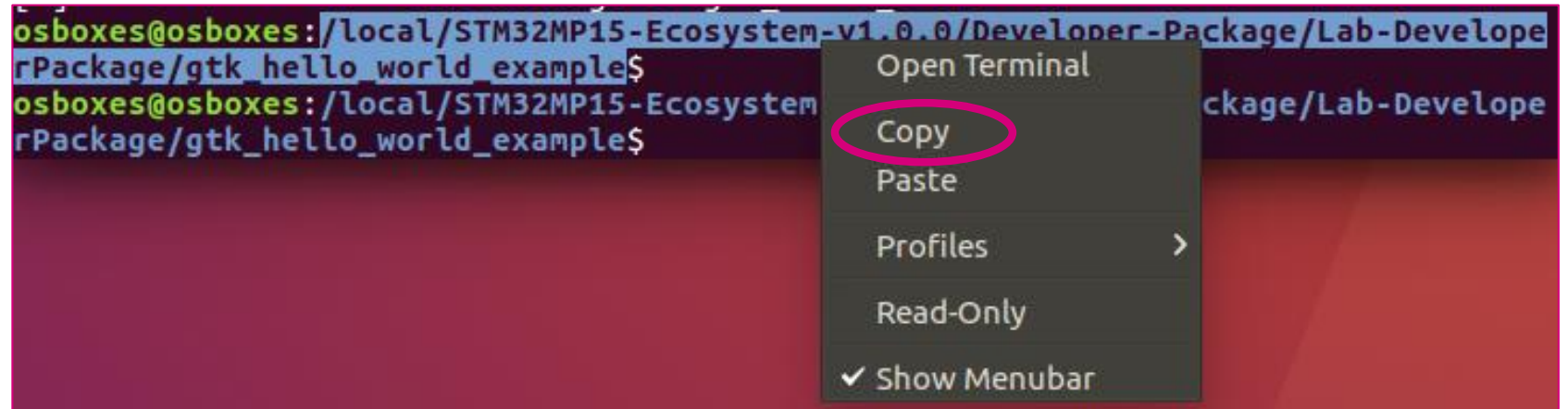
# Lab *Developer Package*

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## Compile the hello world example

1) Highlight the current path in the terminal and right click on it

2) Select copy



```
osboxes@osboxes: /local/STM32MP15-Ecosystem-v1.0.0/Developer-Package/Lab-DeveloperPackage/gtk_hello_world_example$  
osboxes@osboxes: /local/STM32MP15-Ecosystem-v1.0.0/Developer-Package/Lab-DeveloperPackage/gtk_hello_world_example$
```


The screenshot shows a terminal window with a right-click context menu open. The 'Copy' option is highlighted with a red circle. The terminal text shows the current directory path: `/local/STM32MP15-Ecosystem-v1.0.0/Developer-Package/Lab-DeveloperPackage/gtk_hello_world_example$`.



3) Open Files

4) Press CTRL+ L

5) Paste the path

 /local/STM32MP15-Ecosystem-v1.0.0/Developer-Package/Lab-DeveloperPackage/gtk\_hello\_world\_example





# Lab *Developer Package*

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## Compile the hello world example

1) Copy *gtk\_hello\_world* binary to the USB stick (Drag & Drop)



2) Unmount the USB stick afterwards



# Lab *Developer Package*

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## Plug in the USB stick

- 1) Plug the USB stick into one of the 4 USB host ports on the discovery board
- 2) Observe the log in the minicom terminal indicating that the USB stick has been recognized



```
root@stm32mp1:/# [ 64.100038] usb 2-1.4: new high-speed USB device number 3 using ehci-platform
[ 64.257216] usb-storage 2-1.4:1.0: USB Mass Storage device detected
[ 64.263116] scsi host0: usb-storage 2-1.4:1.0
[ 65.271348] scsi 0:0:0:0: Direct-Access SanDisk Cruzer 1.26 PQ: 0 ANSI: 5
[ 65.288637] sd 0:0:0:0: [sda] 7821312 512-byte logical blocks: (4.00 GB/3.73 GiB)
[ 65.294885] sd 0:0:0:0: Attached scsi generic sg0 type 0
[ 65.306175] sd 0:0:0:0: [sda] Write Protect is off
[ 65.311439] sd 0:0:0:0: [sda] Write cache: disabled, read cache: enabled, doesn't support DPO or
[ 65.345645] sda: sda1
[ 65.360110] sd 0:0:0:0: [sda] Attached SCSI removable disk
root@stm32mp1:/#
```



## Mount the USB stick on the Linux host

### 1) Mount the USB stick file system on the Linux host

```
root@stm32mp1: /#
```

```
mount /dev/sda1 /mnt
```

Note:

You can specify the file system type and enable verbose messaging with...

```
mount -t vfat /dev/sda1 /mnt -v
```



## Copy the binary file to the local directory

- 1) Mount the USB stick file system on the Linux host

```
root@stm32mp1: /#
```

```
mount /dev/sda1 /mnt
```

- 2) Copy the binary to the *usr/local* directory

```
root@stm32mp1: /#
```

```
cp /mnt/gtk_hello_world /usr/local
```



## Sync

- 1) Mount the USB stick file system on the Linux host

```
root@stm32mp1: /#
```

```
mount /dev/sda1 /mnt
```

- 2) Copy the binary to the *usr/local* directory

```
root@stm32mp1: /#
```

```
cp /mnt/gtk_hello_world /usr/local
```

- 3) Sync

```
root@stm32mp1: /#
```

```
sync
```



## Test the binary on the target

- 1) Move to the directory containing the binary

```
root@stm32mp1: /#
```

```
cd /usr/local
```



## Test the binary on the target

- 1) Move to the directory containing the binary

```
root@stm32mp1: /#
```

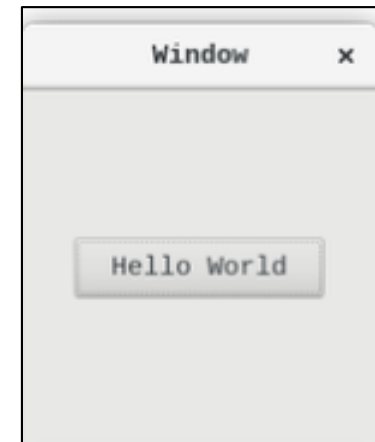
```
cd /usr/local
```

- 2) Add execution permission and run the binary

```
root@stm32mp1: /#
```

```
chmod +x gtk_hello_world  
./gtk_hello_world
```

- 3) A window will be displayed on the target





Thank you

