

Bayesian inference for a population growth model of the chytrid fungus

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1 Preliminaries

This vignette illustrates the steps needed to perform inference for a DDE model of population growth in a fungal pathogen. A detailed description of the rationale behind the Bayesian inference approach for differential equations can be found in the preprint describing the **deBInfer** package (Boersch-Supan & Johnson 2016).

This example assumes that **deBInfer** is installed and loaded. If this is not the case it needs to be installed from github, which requires the devtools package (Wickham & Chang 2016).

```
install.packages("devtools")
```

```
#Load the devtools package.  
library(devtools)
```

Then deBInfer can be installed from github.

```
install_github("pboesu/debinfer")
```

```
library(deBInfer)
```

2 The chytrid population growth model

Our example demonstrates parameter inference for a DDE model of population growth in the environmentally sensitive fungal pathogen *Batrachochytrium dendrobatidis* (Bd), which causes the amphibian disease chytridiomycosis (Rosenblum *et al.* 2010; Voyles *et al.* 2012). This model has been used to further our understanding of pathogen responses to changing environmental conditions. Further details about the model development, and the experimental procedures yielding the data used for parameter inference can be found in (Voyles *et al.* 2012).

The model follows the dynamics of the concentration of an initial cohort of zoospores, C , the concentration of zoospore-producing sporangia, S , and the concentration of zoospores in the next generation Z . The initial cohort of zoospores, C , starts at a known concentration, and zoospores in this initial cohort settle and become sporangia at rate s_r , or die at rate μ_Z . f_s is the fraction of sporangia that survive to the zoospore-producing stage. We assume that it takes a minimum of T_{min} days before the sporangia produce zoospores, after which they produce zoospores at rate η . Zoospore-producing sporangia die at rate d_s . The concentration of zoospores, Z , is the only state variable measured in the experiments, and it is assumed that these zoospores settle (s_r) or die (μ_Z) at the same rates as the initial cohort of zoospores.

2.1 DDE model

The equations that describe the population dynamics are as follows:

$$\frac{dC}{dt} = -(s_r + \mu_Z)C(t) \quad (1)$$

$$\frac{dS}{dt} = s_r f_s C(t - T_{min}) - d_s S(t) \quad (2)$$

$$\frac{dZ}{dt} = \eta S(t) - (s_r + \mu_Z)Z(t) \quad (3)$$

We can implement this system of differential equations for the `deSolve::dede` solver as follows. More details on how to specify differential equations for this solver can be found in the package documentation and vignettes (Soetaert *et al.* 2010).

```
#dede version
CSZ.dede<-function(t,y,p){

  sr    <- p["sr"]
  fs    <- p["fs"]
  ds    <- p["ds"]
  eta   <- p["eta"]
  Tmin  <- p["Tmin"]
  muz   <- p["muz"]

  Rs <- Ms <- 0
  lag1 <- lag2 <- 0

  if (t>Tmin) {
    lag1 <- lagvalue(t - Tmin)
    Rs <- sr * fs * lag1[1]
  }

  phiZ <- eta * y[2]
  dy1 <- -(muz + sr) * y[1]
  dy2 <- Rs - Ms - ds * y[2]
  dy3 <- phiZ - (muz + sr) * y[3]

  if(y[1]<0) dy1<-0
  if (y[2] < 0) {
    dy2 <- Rs - Ms
    dy3 <- -(muz + sr) * y[3]
  }
  if (y[3] < 0) {
    dy3 <- dy3 + (muz + sr) * y[3]
  }

  list(c(dy1,dy2,dy3))
}
```

2.2 Observation model

Even though the data used in this example come from an experimental study, the system is only partially observed. We know the initial conditions for all states, but we only have observations for the second generation of Zoospores Z . Because the observations are counts (i.e. discrete numbers), we assume that observations of

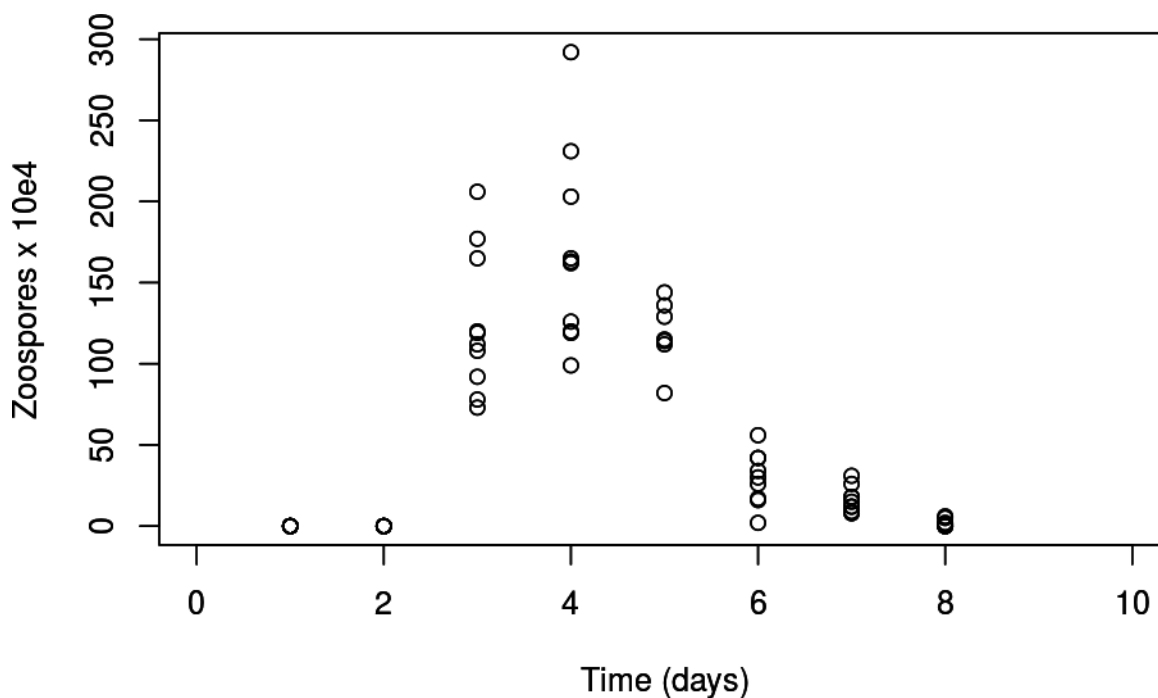
the system at a set of discrete times t' are independent Poisson random variables with a mean given by the solution of the DDE, at times t' .

The observations are provided with `deBInfer`. They can be loaded with the `data()` command.

```
#load chytrid data
data(chytrid)
#have a look at the variables
head(chytrid)
```

```
##   time count
## 1    1     0
## 2    1     0
## 3    1     0
## 4    1     0
## 5    1     0
## 6    1     0
```

```
#plot the data
plot(chytrid, xlab = "Time (days)", ylab = "Zoospores x 10e4", xlim = c(0,10))
```



The log-likelihood of the data given the parameters, underlying model, and initial conditions is then a sum over the n observations at each time point in t'

$$\ell(\mathbf{Z}|\theta) = \sum_t^n Z_t \log \lambda - n\lambda \quad (4)$$

This can be translated into an observation model function for `deBInfer`. The observation model function must have three named arguments `data`, `sim.data`, and `samp`, as these are used by the MCMC procedure to pass in the data (as a `data.frame`, i.e. indexed using the `$` operator and the column names of the input data), the current state of the Markov chain (as a named vector), and the associated DE model solution (as a

matrix-like object of class `deSolve`, i.e. indexed using the `[]` operator and the declared names of the state variables). We can access these inputs to define the data likelihood. In this case we have repeat measurements for each time point, so we iterate over the unique timepoints in `data$time`, and then calculate the sum log-likelihood over all matching `data$count` observations using the current value of the state variable `Z` from the DE model solution at this point in the Markov chain.

```
# observation model
chytrid_obs_model <- function(data, sim.data, samp) {

  ec <- 0.01
  llik.Z <- 0
  for(i in unique(data$time)){
    try(lik.Z <- lik.Z + sum(dpois(data$count[data$time == i],
                                  lambda = (sim.data[, "Z"][sim.data[, "time"] == i] + ec),
                                  log = TRUE)))
  }
  lik <- lik.Z
  return(lik)
}
```

Following Johnson et al. (2013) we employ a small correction `ec` that is needed because the DE solution can equal zero, whereas the parameter `lambda` of the Poisson likelihood must be strictly positive.

2.3 Parameter declaration

We continue by defining the parameters for inference

```
sr <- debinfer_par(name = "sr", var.type = "de", fixed = FALSE,
                  value = 2, prior = "gamma", hypers = list(shape = 5, rate = 1),
                  prop.var = c(3,4), samp.type = "rw-unif")

fs <- debinfer_par(name = "fs", var.type = "de", fixed = FALSE,
                  value = 0.5, prior = "beta", hypers = list(shape1 = 1, shape2 = 1),
                  prop.var = 0.01, samp.type = "ind")

ds <- debinfer_par(name = "ds", var.type = "de", fixed = FALSE,
                  value = 2, prior = "gamma", hypers = list(shape = 1, rate = 1),
                  prop.var = 0.1, samp.type = "rw")

muz <- debinfer_par(name = "muz", var.type = "de", fixed = FALSE,
                  value = 1, prior = "gamma", hypers = list(shape = 5, rate = 1),
                  prop.var = c(4,5), samp.type = "rw-unif")

eta <- debinfer_par(name = "eta", var.type = "de", fixed = FALSE,
                  value = 10, prior = "gamma", hypers = list(shape = 1, rate = 0.25),
                  prop.var = 5, samp.type = "rw")

Tmin <- debinfer_par(name = "Tmin", var.type = "de", fixed = FALSE,
                  value = 3, prior = "unif", hypers = list(min = 2, max = 6),
                  prop.var = 0.05, samp.type = "rw")

# ----inits-----
```

```
C <- debinfer_par(name = "C", var.type = "init", fixed = TRUE, value = 120)
S <- debinfer_par(name = "S", var.type = "init", fixed = TRUE, value = 0)
Z <- debinfer_par(name = "Z", var.type = "init", fixed = TRUE, value = 0)
```

2.4 MCMC Inference

The declared parameters are then collated using the `setup_debinfer` function. Note that **the initial values must be entered in the same order, as they are specified in the DE model function**, as the solver matches these values by position, rather than by name. More details can be found in `?deSolve::dede`. The remaining parameters can be entered in any order.

```
# -----setup-----
mcmc.pars <- setup_debinfer(sr, fs, ds, muz, eta, Tmin, C, S, Z)
```

`de_mcmc` is the workhorse of the package and runs the MCMC estimation. The progress of the MCMC procedure can be monitored using the `cnt`, `plot` and `verbose` options: Every `cnt` iterations the function will print out information about the current state, and, if `plot=TRUE`, traceplots of the chains will be plotted. Setting `verbose=TRUE` will print additional information. Note that frequent plotting will substantially slow down the MCMC sampler, and should be used only on short runs when tuning the sampler.

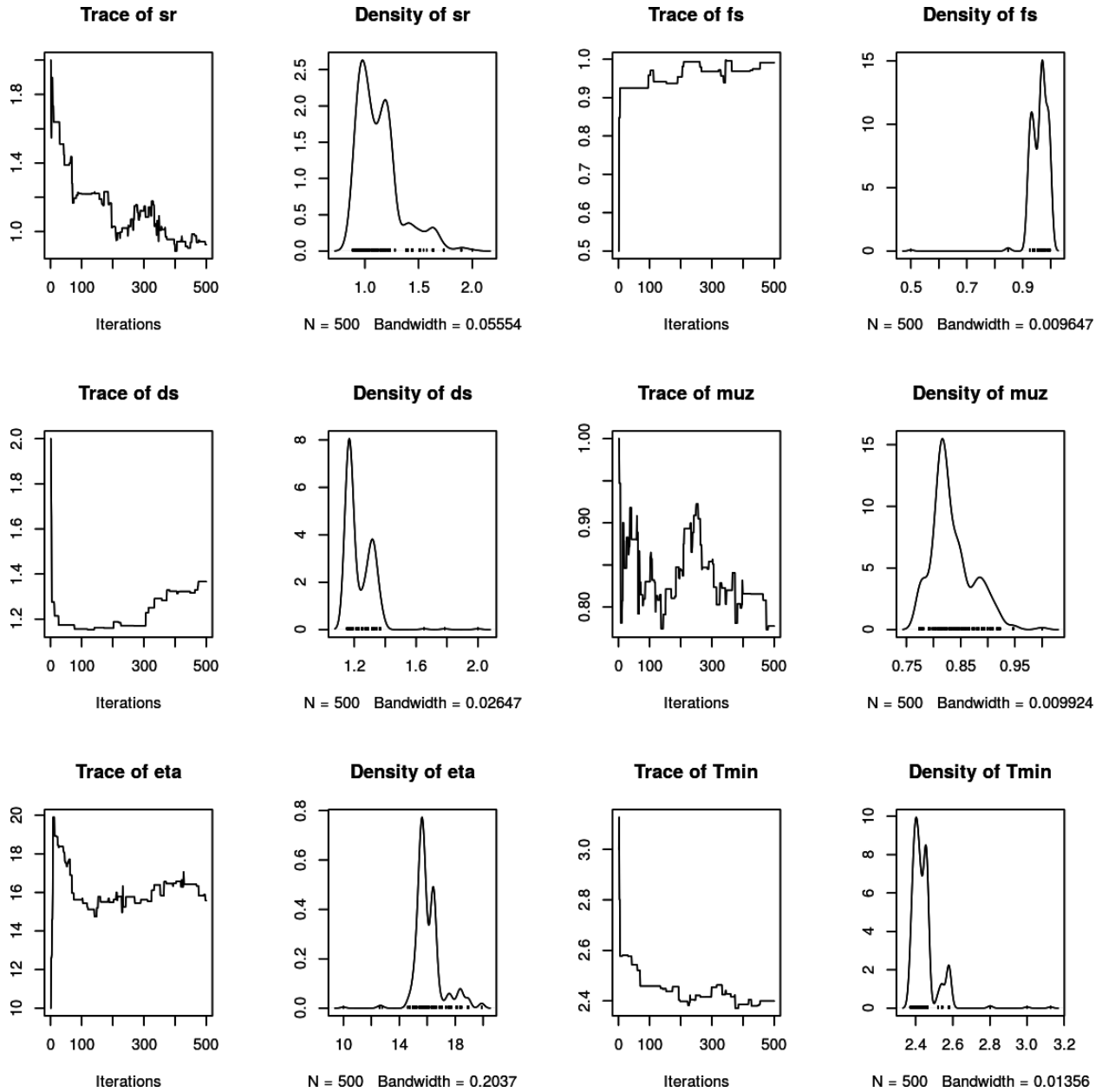
```
# do inference with deBInfer
# MCMC iterations
iter <- 500
# inference call
dede_rev <- de_mcmc(N = iter, data = chytrid, de.model = CSZ.dede,
  obs.model = chytrid_obs_model, all.params = mcmc.pars,
  Tmax = max(chytrid$time), data.times = c(0,chytrid$time), cnt = 50,
  plot = FALSE, sizestep = 0.1, solver = "dede", verbose.mcmc = FALSE)
```

Note that the number of iterations was set to 500 to keep the build time of the vignette within acceptable limits. For the inference results reported in Boersch-Supan and Johnson (2016) the MCMC procedure was run for 100000 iterations, which took about 4 hours on a 2014 Apple Mac mini with a 2.6 GHz Intel i5 processor.

2.5 MCMC diagnostics

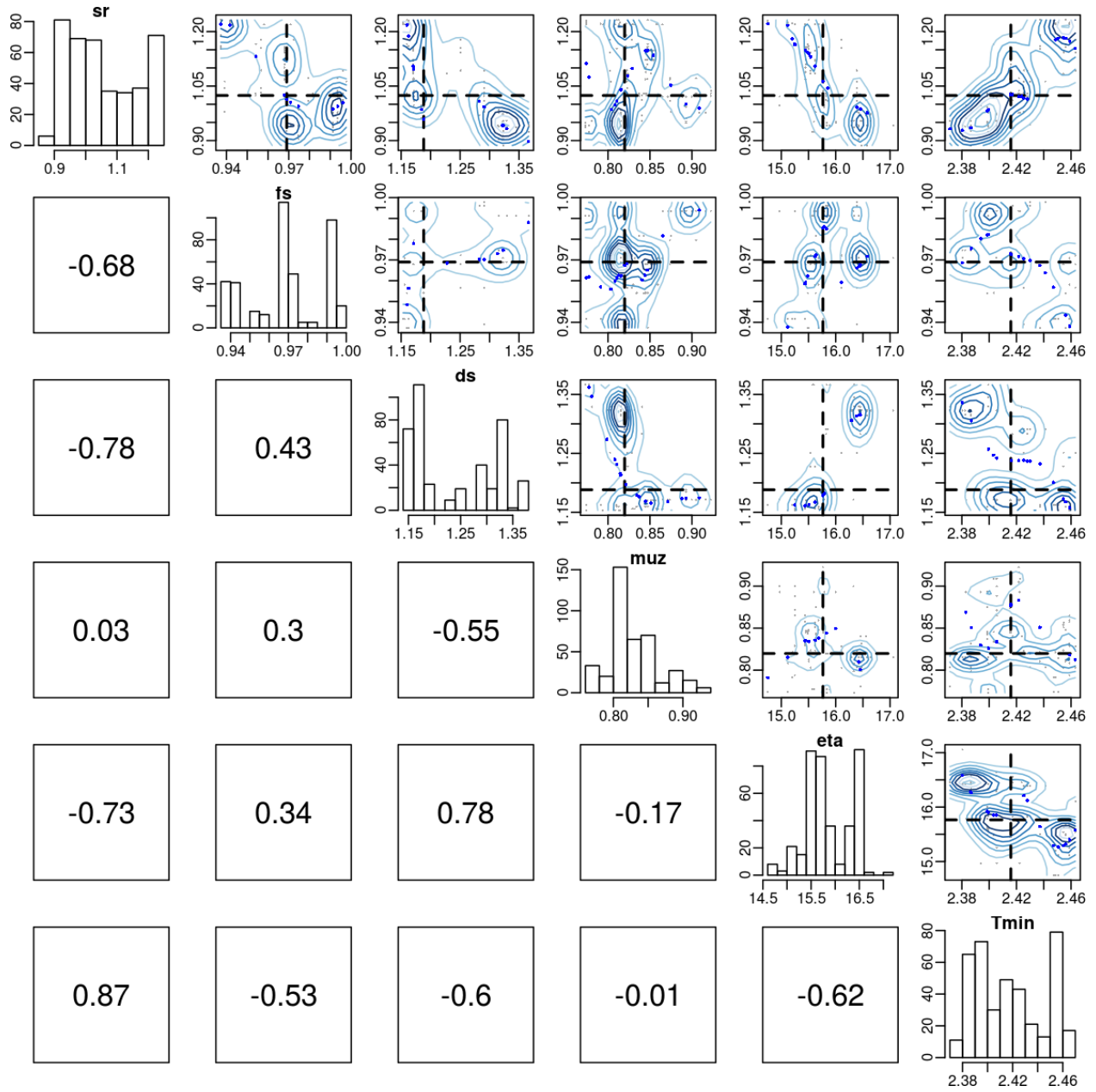
We plot and summarize the MCMC chains

```
par(mfrow = c(3,4))
plot(dede_rev, ask = FALSE, auto.layout = FALSE)
```

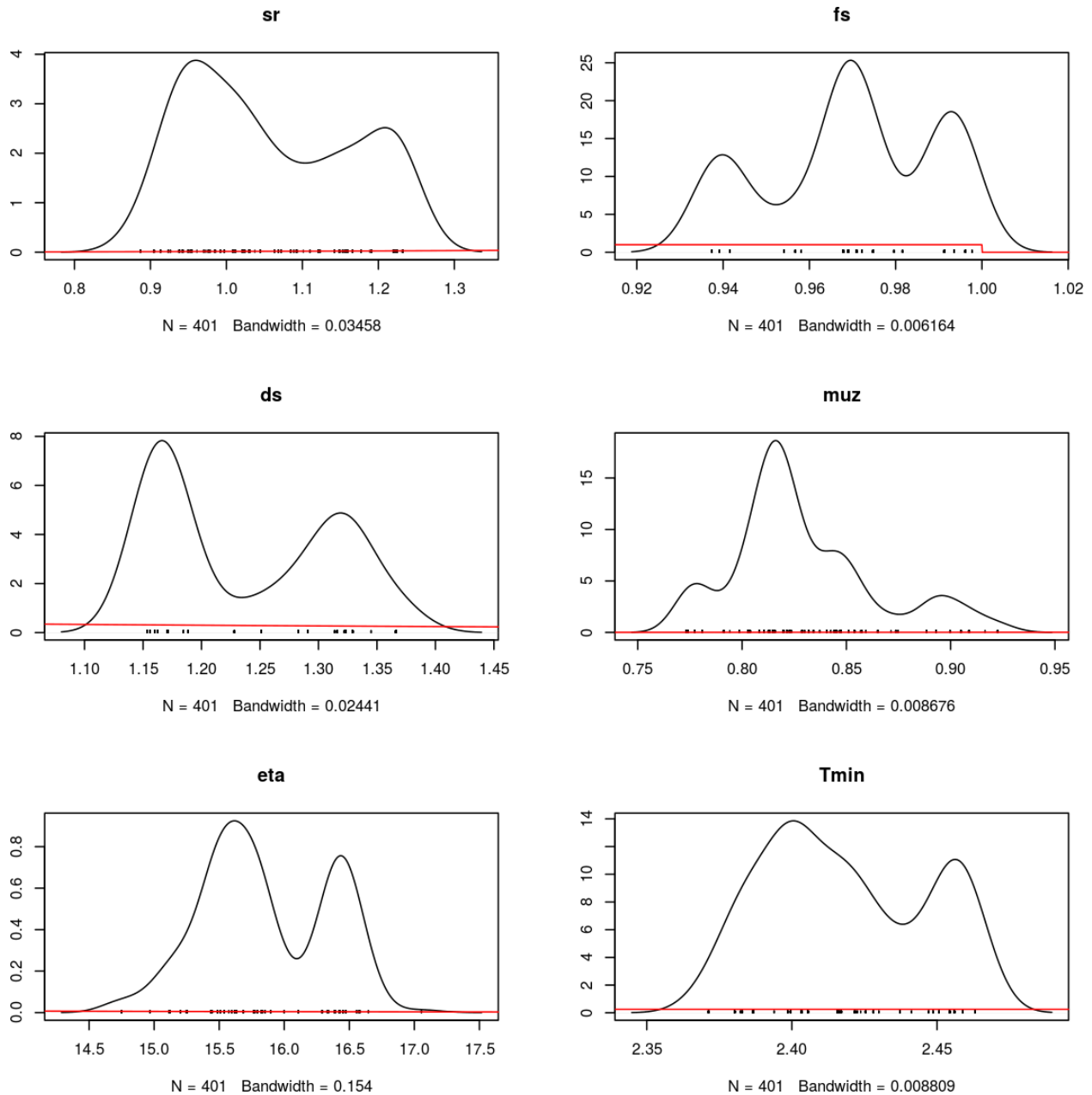


From the traceplot we can see that with only 500 iterations the chains have neither mixed well, nor reached stationarity. For demonstration purposes we remove a burnin period of 100 samples and have a look at parameter correlations, and the overlap between the posterior and prior densities.

```
burnin <- 100
pairs(dede_rev, burnin = burnin, scatter = TRUE, trend = TRUE)
```



```
post_prior_densplot(dede_rev, burnin = burnin)
```



More control over the `post_prior_densplot` can be achieved by plotting the parameters individually, using the `param` option. This way the x and y limits of the plots can be adjusted to show a larger portion of the prior support, and fancy labels can be added.

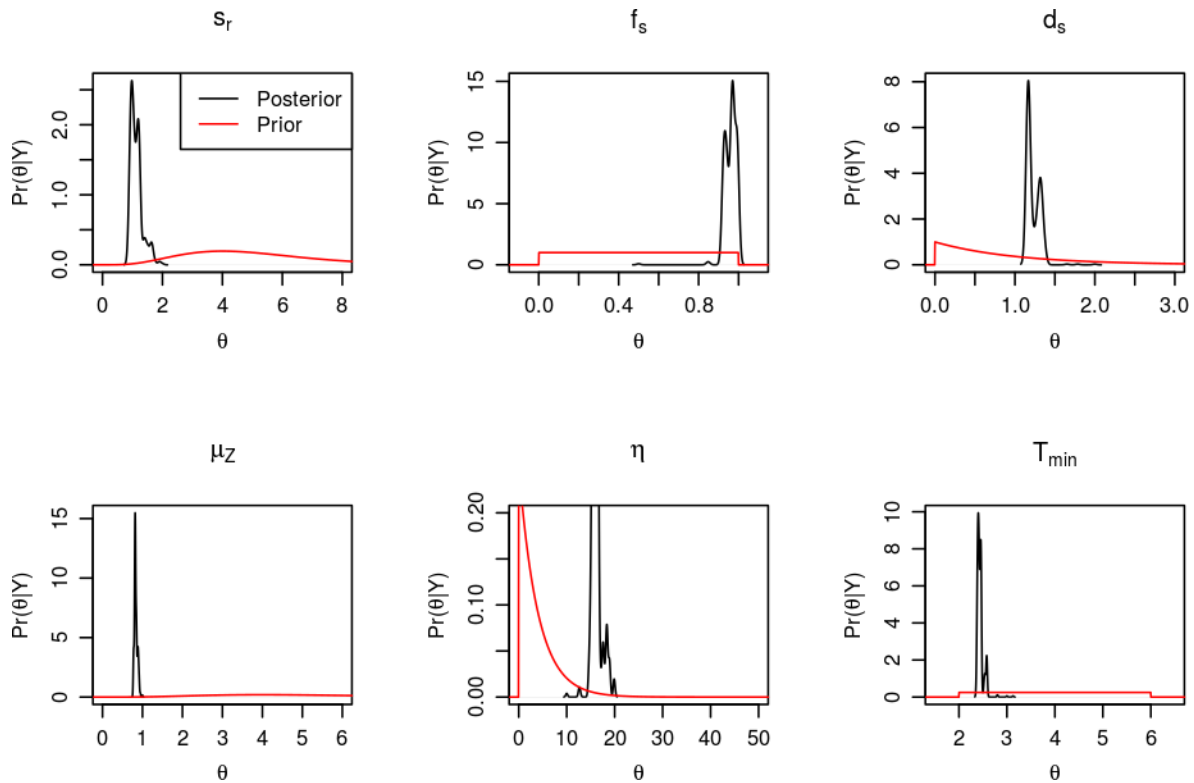
```
par(mfrow = c(2,3), mgp = c(2.2, 0.8, 0))
#define a fancy y axis label
ylabel = expression(paste(Pr,"(", theta,"|", "Y", ")"))
#plot the individual parameters
post_prior_densplot(dede_rev, param = "sr", xlab = expression(theta),
  ylab = ylabel, show.obs = FALSE, xlim = c(0,8),
  main = expression(paste("s",phantom()[{paste("r")}]}))
legend("topright", legend = c("Posterior","Prior"), lty = 1, col = c("black", "red"))
post_prior_densplot(dede_rev, param = "fs", xlab = expression(theta),
  ylab = ylabel, show.obs = FALSE, xlim = c(-0.1,1.1),
```



```

    main = expression(paste("f",phantom()[{paste("s")}]))
post_prior_densplot(dede_rev, param = "ds",xlab = expression(theta),
  ylab = ylabel, show.obs = FALSE, xlim = c(0,3),
  main = expression(paste("d",phantom()[{paste("s")}]))
post_prior_densplot(dede_rev, param = "muz",xlab = expression(theta),
  ylab = ylabel, show.obs = FALSE, xlim = c(0,6),
  main = expression(paste(mu,phantom()[{paste("Z")}]))
post_prior_densplot(dede_rev, param = "eta",xlab = expression(theta),
  ylab = ylabel, show.obs = FALSE, xlim = c(0,50), ylim = c(0,0.2),
  main = expression(eta))
post_prior_densplot(dede_rev, param = "Tmin",xlab = expression(theta),
  ylab = ylabel, show.obs = FALSE, xlim = c(1.5,6.5),
  main = expression(paste("T",phantom()[{paste("min")}]))

```



2.6 Simulating posterior trajectories

We simulate 100 DE model trajectories from the posterior and calculate the 95% highest posterior density interval for the deterministic part of the model.

```

post_traj <- post_sim(dede_rev, n = 100, times = seq(0,10,by = 0.1), burnin = burnin,
  output = "all", prob = 0.95)

```

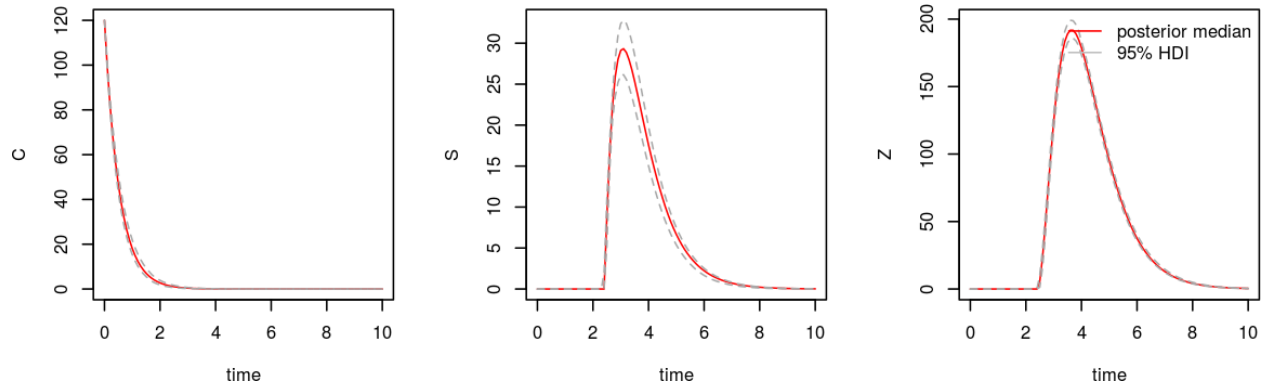
We can visualise the median posterior trajectory and the highest posterior density interval using

```

#median and HDI
par(mfrow = c(1,3))
plot(post_traj, plot.type = "medianHDI", auto.layout = FALSE)

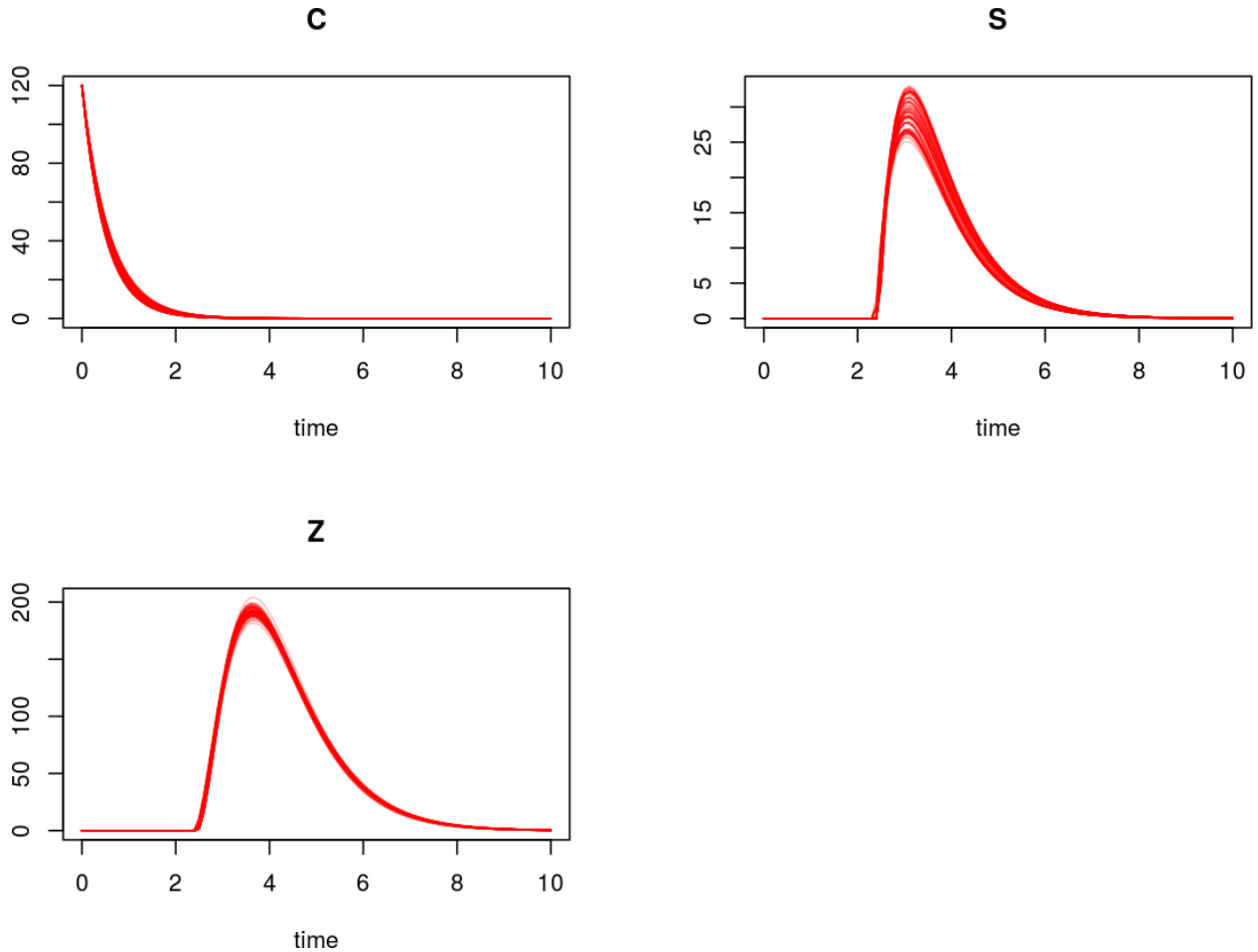
```

```
legend("topright", legend = c("posterior median", "95% HDI"), lty = 1,
      col = c("red", "grey"), bty = "n")
```



Alternatively we can plot an ensemble of posterior trajectories using

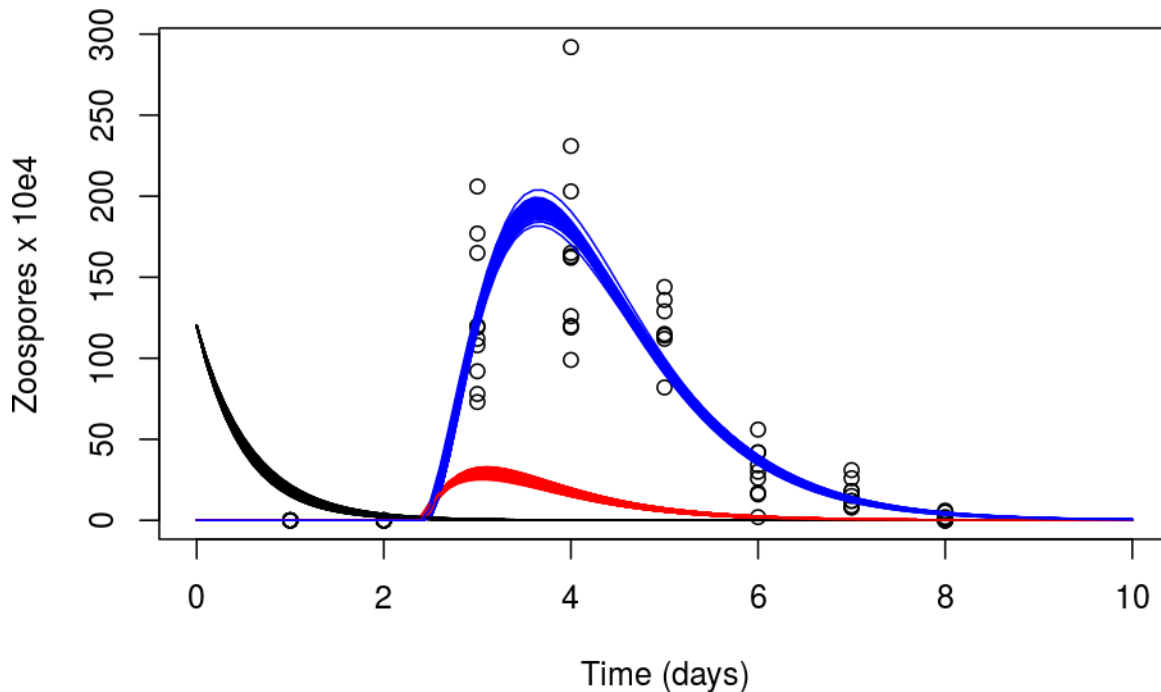
```
plot(post_traj, plot.type = "ensemble", col = "#FF000040")
```



Lastly, it is straightforward to create customized plots by accessing the simulated trajectories inside the `post_traj` object (as the class `post_sim_list` is simply a nested list). For example we can recreate Figure 5 in Boersch-Supan & Johnson (2016), which shows the trajectories of all three state variables in a single plot, with the following code:

```
plot(chytrid, xlab = "Time (days)", ylab = "Zoospores x 10e4", xlim = c(0,10))

for(i in seq_along(post_traj$sims)) {
  DATA1 <- as.data.frame(post_traj$sims[i])
  lines(DATA1[,2] ~ DATA1[,1])
  lines(DATA1[,3] ~ DATA1[,1],col = "red")
  lines(DATA1[,4] ~ DATA1[,1],col = "blue")
}
```



References

- Boersch-Supan, P. & Johnson, L. (2016). deBinfer: Bayesian inference for dynamical models of biological systems. *arXiv*, **1605.00021**.
- Johnson, L.R., Pecquerie, L. & Nisbet, R.M. (2013). Bayesian inference for bioenergetic models. *Ecology*, **94**, 882–894.
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- Soetaert, K., Petzoldt, T. & Setzer, R.W. (2010). Solving differential equations in R: Package deSolve. *Journal of Statistical Software*, **33**, 1–25.
- Voyles, J., Johnson, L.R., Briggs, C.J., Cashins, S.D., Alford, R.A., Berger, L., Skerratt, L.F., Speare, R. & Rosenblum, E.B. (2012). Temperature alters reproductive life history patterns in *batrachochytrium dendrobatidis*, a lethal pathogen associated with the global loss of amphibians. *Ecology and Evolution*, **2**, 2241–2249.
- Wickham, H. & Chang, W. (2016). *Devtools: Tools to make developing r packages easier*.