Chapter 9: Linear Functions

Outline

Function Notation

Linear Functions and Superposition

Linear Function Representation

Vector-valued linear functions

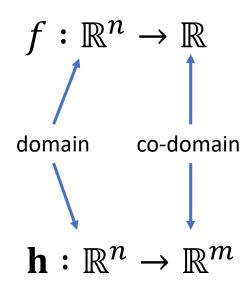
Projection Function

Orthogonal Projection Matrix

Function Notation

Scalar-valued functions

Vector-valued functions



Example:

$$f(\mathbf{x}) = \langle \mathbf{a}, \mathbf{x} \rangle$$

Linear Functions and Superposition

• Linear function or linear transformation or linear map $f: \mathbb{R}^n \to \mathbb{R}$

- Two key properties:
 - Additivity

$$f(\mathbf{u} + \mathbf{v}) = f(\mathbf{u}) + f(\mathbf{v})$$

Homogeneity

$$f(\alpha \mathbf{u}) = \alpha f(\mathbf{u})$$

• or, superposition

$$f(\alpha_1 \mathbf{v}_1 + \alpha_2 \mathbf{v}_2) = \alpha_1 f(\mathbf{v}_1) + \alpha_2 f(\mathbf{v}_2)$$

Example: Inner Product

• Consider
$$f(\mathbf{x}) = \langle \mathbf{a}, \mathbf{x} \rangle = a_1 x_1 + a_2 x_2 + \dots + a_n x_n$$

Then we have

$$f(\alpha \mathbf{x} + \beta \mathbf{y}) = \langle \mathbf{a}, \alpha \mathbf{x} + \beta \mathbf{y} \rangle$$
 definition of f

$$= \langle \mathbf{a}, \alpha \mathbf{x} \rangle + \langle \mathbf{a}, \beta \mathbf{y} \rangle$$
 distributivity with vector addition
$$= \alpha \langle \mathbf{a}, \mathbf{x} \rangle + \beta \langle \mathbf{a}, \mathbf{y} \rangle$$
 associativity over scalar multiplication
$$= \alpha f(\mathbf{x}) + \beta f(\mathbf{y})$$
 definition of f

Hence inner product (for given a) satisfies superposition and is *linear*

Result: any linear function = inner product

• Let us consider linear $f:\mathbb{R}^n \to \mathbb{R}$

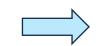


$$f(\mathbf{x} + \mathbf{y}) = f(\mathbf{x}) + f(\mathbf{y})$$
$$f(c\mathbf{x}) = cf(\mathbf{x})$$

- Recall standard unit vectors \mathbf{e}_1 , \mathbf{e}_2 , ..., \mathbf{e}_n
- Can express any $\mathbf{x} = x_1 \mathbf{e}_1 + x_2 \mathbf{e}_2 + \cdots + x_n \mathbf{e}_n$

Result: any linear function = inner product

• Let us consider linear $f: \mathbb{R}^n \to \mathbb{R}$



$$f(\mathbf{x} + \mathbf{y}) = f(\mathbf{x}) + f(\mathbf{y})$$
$$f(c\mathbf{x}) = cf(\mathbf{x})$$

•
$$\mathbf{x} = x_1 \mathbf{e}_1 + x_2 \mathbf{e}_2 + \dots + x_n \mathbf{e}_n$$

• Define
$$\mathbf{a} = \begin{bmatrix} f(\mathbf{e}_1) \\ f(\mathbf{e}_2) \\ \vdots \\ f(\mathbf{e}_n) \end{bmatrix}$$

$$f(\mathbf{x}) = f(x_1\mathbf{e}_1 + x_2\mathbf{e}_2 + \dots + x_n\mathbf{e}_n)$$

$$= x_1f(\mathbf{e}_1) + x_2f(\mathbf{e}_2) + \dots + x_nf(\mathbf{e}_n)$$

$$= \langle \mathbf{a}, \mathbf{x} \rangle$$

Alternative way to calculate *f*

Representation of f as inner product is unique

- Proof by contradiction
 - assume contrary, then show that it is not possible
- Suppose $f(\mathbf{x}) = \langle \mathbf{u}, \mathbf{x} \rangle = \langle \mathbf{v}, \mathbf{x} \rangle$
- Setting $\mathbf{x} = \mathbf{e}_i$

$$f(\mathbf{e}_i) = \langle \mathbf{u}, \mathbf{e}_i \rangle = u_i$$
 (from the first representation)
= $\langle \mathbf{v}, \mathbf{e}_i \rangle = v_i$ (from the second representation)

• So, $u_i = v_i$ for all i: hence representation of f is unique

Reisz Representation Theorem: For any linear function $f: \mathbb{R}^n \to \mathbb{R}$, there exists unique \mathbf{u} such that $f(\mathbf{v}) = \mathbf{u}^T \mathbf{v}$ for every $\mathbf{v} \in \mathbb{R}^n$

Vector-valued linear functions

 $n ext{ inputs} \qquad m ext{ outputs}$ $\mathbf{f} \colon \mathbb{R}^n \to \mathbb{R}^m$

• Satisfy superposition:

$$\mathbf{f}(\alpha_1\mathbf{v}_1 + \alpha_2\mathbf{v}_2) = \alpha_1\mathbf{f}(\mathbf{v}_1) + \alpha_2\mathbf{f}(\mathbf{v}_2)$$

Example: projection onto x-axis

$$\mathbf{p} \begin{pmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \end{pmatrix} = \begin{bmatrix} x \\ 0 \end{bmatrix}$$

$$\mathbf{p} \colon \mathbb{R}^2 \to \mathbb{R}^2$$

Vector-valued linear function = $\mathbf{A}\mathbf{x}$

 Vector-valued function is a stack of scalar-valued functions

$$\mathbf{f}(\mathbf{x}) = \begin{bmatrix} f_1(\mathbf{x}) \\ f_2(\mathbf{x}) \\ \vdots \\ f_n(\mathbf{x}) \end{bmatrix}$$

• If each element is linear, it must be inner product $f_i(\mathbf{x}) = \mathbf{a}_i^T \mathbf{x}$

$$\mathbf{f}(\mathbf{x}) = \begin{bmatrix} \mathbf{a}_1^T \mathbf{x} \\ \mathbf{a}_2^T \mathbf{x} \\ \vdots \\ \mathbf{a}_m^T \mathbf{x} \end{bmatrix} = \begin{bmatrix} \mathbf{a}_1^T \\ \mathbf{a}_2^T \\ \vdots \\ \mathbf{a}_m^T \end{bmatrix} \mathbf{x} = \mathbf{A}\mathbf{x}$$

Example: scaling function

Scale each coordinate by a positive scalar

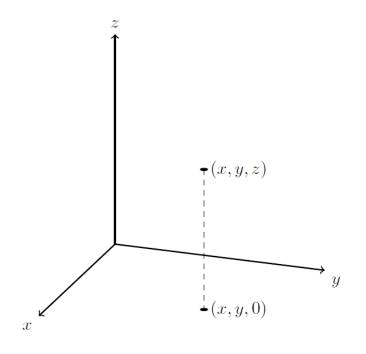
$$S(x) = Diag(s)x$$

$$[\mathbf{S}(\mathbf{x})]_i = s_i x_i$$
 $i \in \{1, 2, ..., n\}$

Example: Projection in 3D

Consider the *projection* function

$$\mathbf{p} \begin{pmatrix} \begin{bmatrix} x \\ y \\ Z \end{bmatrix} \end{pmatrix} = \begin{bmatrix} x \\ y \\ 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ Z \end{bmatrix}$$
Projection
Matrix P



Idempotent

$$\mathbf{P}^2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \mathbf{P}$$

Thank You

Next: Linear Systems