# Linear Equations Unit 3

Linear Algebra and its Applications, David C. Lay Linear Algebra and its Applications, Gilbert Strang Applied Numerical Analysis, Gerald and Wheatly

# Linear equation

A linear equation in the variables  $x_1, x_2, \dots, x_n$  is an equation that can be written in the form

$$a_1x_1 + a_2x_2 + a_3x_3 + \dots + a_nx_n = b$$

where b and the coefficients of  $x_1, x_2, \dots, x_n$  are real or complex numbers

Eg. 
$$7x_1 + 5x_2 - 12x_3 = 4.5$$

# System of linear equations

A system of linear equations (or a linear system) is a collection of one or more linear equations involving the same variables  $x_1, x_2, \dots, x_n$ 

• 
$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

• 
$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

• 
$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

# Homogeneous linear equations

A system of linear equations

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$
  

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$
  

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

is called homogeneous if  $b_1 = b_2 = \cdots = b_m = 0$  and non-homogeneous, otherwise.

Eg.

$$x_1 - x_2 + x_3 = 0$$
  
 $x_1 - 4x_3 = 0$ 

• A solution of the system is a list  $\{s_1, s_2, \dots, s_n\}$  of numbers that makes each equation a true statement when the values  $s_1, s_2, \dots, s_n$  are substituted for  $x_1, x_2, \dots, x_n$  respectively.

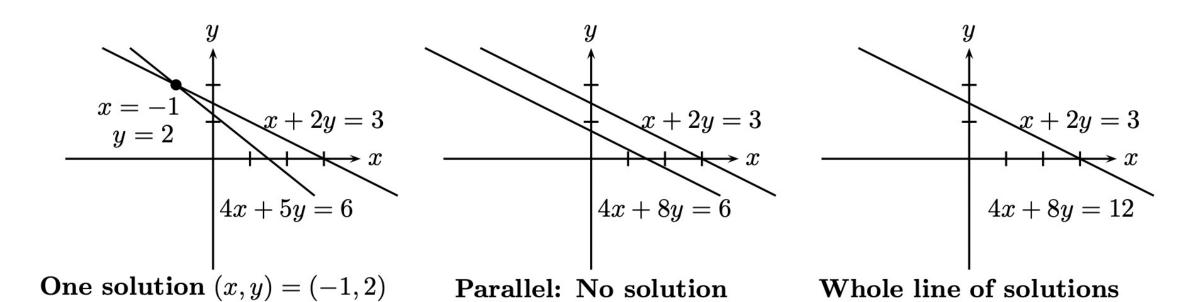
Eg.,

$$x_1 - x_2 + x_3 = 8$$
  
 $x_1 - 4x_3 = 7$ 

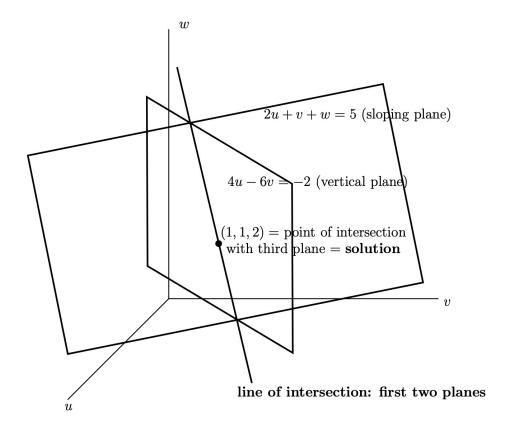
• {11, 4, 1} is a solution of the above equations because, when these values are substituted for  $x_1, x_2, \dots, x_n$ , respectively, the equations simplify to 8 = 8 and 7 = 7

- The set of all possible solutions is called the solution set of the linear system.
- Two linear systems are called equivalent if they have the same solution set.
   That is, each solution of the first system is a solution of the second system, and each solution of the second system is a solution of the first.
- A system of linear equations has
- 1. no solution
- 2. exactly one solution
- 3. infinitely many solutions.

- A system of linear equations is said to be consistent if it has either one solution or infinitely many solutions;
- a system is inconsistent if it has no solution.



**Figure 1.1:** The example has one solution. Singular cases have none or too many.



**Figure 1.3:** The row picture: three intersecting planes from three linear equations.

Let the system be given by

$$a_{11}x_1 + a_{12}x_2 = b_1$$
 - (1)  
 $a_{21}x_1 + a_{22}x_2 = b_2$  -(2)

To solve for  $x_1$ Multiply first equation by  $a_{22}$  and second by  $a_{12}$  we get

$$a_{22}a_{11}x_1 + a_{22}a_{12}x_2 = a_{22}b_1$$
  
$$a_{12}a_{21}x_1 + a_{12}a_{22}x_2 = a_{12}b_2$$

Therefore, we get  $(a_{22}a_{11} - a_{12}a_{21})x_1 = a_{22}b_1 - a_{12}b_2$   $x_1 = \frac{a_{22}b_1 - a_{12}b_2}{a_{22}a_{11} - a_{12}a_{21}}$ 

$$x_1 = \frac{D_{x1}}{D} = \frac{\begin{vmatrix} b_1 & a_{12} \\ b_2 & a_{22} \end{vmatrix}}{\begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix}}$$

 $D_{\chi 1}$ : Determinant of the numerator in the solution of  $\chi_1$  If we are solving for  $\chi_1$ , the column 1 is replaced with constants

To solve for  $x_2$ 

Multiply first equation by  $a_{21}$  and second by  $a_{11}$  we get

$$a_{21}a_{11}x_1 + a_{21}a_{12}x_2 = a_{21}b_1$$
  
$$a_{11}a_{21}x_1 + a_{11}a_{22}x_2 = a_{11}b_2$$

Therefore, we get 
$$(a_{21}a_{12}-a_{11}a_{22})x_2 = a_{21}b_1 - a_{11}b_2$$

$$x_2 = \frac{a_{21}b_1 - a_{11}b_2}{a_{21}a_{12} - a_{11}a_{22}}$$

$$x_2 = \frac{D_{x2}}{D} = \frac{\begin{vmatrix} a_{11} & b_1 \\ a_{21} & b_2 \end{vmatrix}}{\begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix}}$$

 $D_{x2}$ : determinant of the numerator in the solution of  $x_2$  If we are solving for  $x_2$ , the column 2 is replaced with constants

For the system of equations

$$a_{11}x_1 + a_{12}x_2 = b_1$$
  
$$a_{21}x_1 + a_{22}x_2 = b_2$$

If 
$$\begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} \neq 0$$

$$x_{1} = \frac{\begin{vmatrix} b_{1} & a_{12} \\ b_{2} & a_{22} \end{vmatrix}}{\begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix}} \text{ and } x_{2} = \frac{\begin{vmatrix} a_{11} & b_{1} \\ a_{21} & b_{2} \end{vmatrix}}{\begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix}}$$

eg.  

$$12x_1 + 3x_2 = 15$$

$$2x_1 - 3x_2 = 13$$

$$x_1 = \frac{\begin{vmatrix} 15 & 3 \\ 13 & -3 \end{vmatrix}}{\begin{vmatrix} 12 & 3 \\ 2 & -3 \end{vmatrix}} = \frac{-45 - 39}{-36 - 6} = \frac{-84}{-42} = 2$$

$$x_2 = \frac{\begin{vmatrix} 12 & 15 \\ 2 & 13 \end{vmatrix}}{\begin{vmatrix} 12 & 3 \\ 2 & -3 \end{vmatrix}} = \frac{156 - 30}{-36 - 6} = \frac{126}{-42} = -3$$

#### Solving for 3 equations

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 = b_1$$

$$a_{21}x_1 + a_{22}x_2 + a_{23}x_3 = b_2$$

$$a_{31}x_1 + a_{32}x_2 + a_{33}x_3 = b_3$$

$$D = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix}$$

$$= a_{11} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{12} \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + a_{13} \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix}$$

$$D x_1 = \begin{vmatrix} b_1 & a_{12} & a_{13} \\ b_2 & a_{22} & a_{23} \\ b_3 & a_{32} & a_{33} \end{vmatrix}$$

$$= b_1 \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{12} \begin{vmatrix} b_2 & a_{23} \\ b_3 & a_{33} \end{vmatrix} + a_{13} \begin{vmatrix} b_2 & a_{22} \\ b_3 & a_{32} \end{vmatrix}$$

D  $x_1$  is determinant of the numerator in the solution of  $x_1$ 

$$D x_2 = \begin{vmatrix} a_{11} & b_1 & a_{13} \\ a_{21} & b_2 & a_{23} \\ a_{31} & b_3 & a_{33} \end{vmatrix}$$

$$= a_{11} \begin{vmatrix} b_2 & a_{23} \\ b_3 & a_{33} \end{vmatrix} - b_1 \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + a_{13} \begin{vmatrix} a_{21} & b_2 \\ a_{31} & b_3 \end{vmatrix}$$

D  $x_2$  is determinant of the numerator in the solution of  $x_2$ 

$$D x_3 = \begin{vmatrix} a_{11} & a_{12} & b_1 \\ a_{21} & a_{22} & b_2 \\ a_{31} & a_{32} & b_3 \end{vmatrix}$$

$$= a_{11} \begin{vmatrix} a_{22} & b_2 \\ a_{32} & b_3 \end{vmatrix} - a_{12} \begin{vmatrix} a_{21} & b_2 \\ a_{31} & b_3 \end{vmatrix} + b_1 \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix}$$

D  $x_3$  is determinant of the numerator in the solution of  $x_3$ 

$$x_1 = \frac{D x_1}{D}$$
,  $x_2 = \frac{D x_2}{D}$ ,  $x_3 = \frac{D x_3}{D}$ 

Eg.  

$$x_1 + x_2 - x_3 = 6$$
  
 $3x_1 - 2x_2 + x_3 = -5$   
 $x_1 + 3x_2 - 2x_3 = 14$   

$$D = \begin{vmatrix} 1 & 1 & -1 \\ 3 & -2 & 1 \\ 1 & 3 & -2 \end{vmatrix}$$

$$= 1 \begin{vmatrix} -2 & 1 \\ 3 & -2 \end{vmatrix} - 1 \begin{vmatrix} 3 & 1 \\ 1 & -2 \end{vmatrix} - 1 \begin{vmatrix} 3 & -2 \\ 1 & 3 \end{vmatrix}$$

$$= 1(4-3) - (-6-1) - (9+2) = 1+7-11 = -3$$

$$Dx1 = \begin{vmatrix} 6 & 1 & -1 \\ -5 & -2 & 1 \\ 14 & 3 & -2 \end{vmatrix}$$

$$= 6 \begin{vmatrix} -2 & 1 \\ 3 & -2 \end{vmatrix} - 1 \begin{vmatrix} -5 & 1 \\ 14 & -2 \end{vmatrix} - 1 \begin{vmatrix} -5 & -2 \\ 14 & 3 \end{vmatrix}$$

$$= 6(4-3) - (10-14) - (-15+28)$$

$$= 6+4-13 = -3$$

$$Dx2 = \begin{vmatrix} 1 & 6 & -1 \\ 3 & -5 & 1 \\ 1 & 14 & -2 \end{vmatrix}$$

$$= 1 \begin{vmatrix} -5 & 1 \\ 14 & -2 \end{vmatrix} - 6 \begin{vmatrix} 3 & 1 \\ 1 & -2 \end{vmatrix} - 1 \begin{vmatrix} 3 & -5 \\ 1 & 14 \end{vmatrix}$$

$$= 1(10-14)-6(-6-1)-(42+5)$$

$$Dx3 = \begin{vmatrix} 1 & 1 & 6 \\ 3 & -2 & -5 \\ 1 & 3 & 14 \end{vmatrix}$$

$$=1\begin{vmatrix} -2 & -5 \\ 3 & 14 \end{vmatrix} - 1\begin{vmatrix} 3 & -5 \\ 1 & 14 \end{vmatrix} + 6\begin{vmatrix} 3 & -2 \\ 1 & 3 \end{vmatrix}$$

$$=1(-28+15) - (42+5) + 6(9+2)$$
  
=  $-13 - 47 + 66 = 6$ 

$$x_1 = \frac{D x_1}{D}, x_2 = \frac{D x_2}{D}, x_3 = \frac{D x_3}{D}$$

$$x_1 = \frac{-3}{-3}$$
,  $x_2 = \frac{-9}{-3}$ ,  $x_3 = \frac{6}{-3}$ 

$$x_1 = 1$$
,  $x_2 = 3$ ,  $x_3 = -2$ 

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Eg2.

2x_1 - 3x_2 + x_3 = 1

3x_1 + x_2 - x_3 = 2

x_1 - x_2 - x_3 = 1
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$$D = \begin{vmatrix} 2 & -3 & 1 \\ 3 & 1 & -1 \\ 1 & -1 & -1 \end{vmatrix}$$

$$= -14$$

$$Dx1 = \begin{vmatrix} 1 & -3 & 1 \\ 2 & 1 & -1 \\ 1 & -1 & -1 \end{vmatrix} = -8$$

$$Dx2 = \begin{vmatrix} 2 & 1 & 1 \\ 3 & 2 & -1 \\ 1 & 1 & -1 \end{vmatrix} = 1$$

$$Dx3 = \begin{vmatrix} 2 & -3 & 1 \\ 3 & 1 & 2 \\ 1 & -1 & 1 \end{vmatrix} = 5$$

$$x_1 = \frac{D x_1}{D}, x_2 = \frac{D x_2}{D}, x_3 = \frac{D x_3}{D}$$

$$x_1 = \frac{-8}{-14}$$
,  $x_2 = \frac{1}{-14}$ ,  $x_3 = \frac{5}{-14}$ 

$$x_1 = \frac{4}{7}, \qquad x_2 = -1/14, \qquad x_3 = -5/14$$

We now start with solving a systems of linear equations. The idea is to manipulate the rows of the augmented matrix in place of the linear equations themselves. Since, multiplying a matrix on the left corresponds to row operations, we left multiply by certain matrices to the augmented matrix so that the final matrix is in row echelon form. The process of obtaining the row echelon form of a matrix is called the Gauss Elimination method.

The general Gaussian elimination procedure is applied to the linear systems:

$$R_1: a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$
  
 $R_2: a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$   
 $R_n: a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n = b_n$ 

Form the augmented matrix from the system of equations

The unknowns are eliminated to obtain an upper-triangular matrix.

$$R_1: a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$R_2: a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$
To eliminate  $x_1$  from  $R_2$ , we multiply  $R_1$  by  $(-a_{21}/a_{11})$  and obtain  $-a_{21}x_1 - a_{12}\left(\frac{a_{21}}{a_{11}}\right)x_2 - \dots - a_{1n}\left(\frac{a_{21}}{a_{11}}\right)x_n = -b_1\left(\frac{a_{21}}{a_{11}}\right)$ 

Adding the above equation to R<sub>2</sub> we obtain

$$\left( a_{22} - a_{12} \frac{a_{21}}{a_{11}} \right) x_2 - \left( a_{23} - a_{13} \frac{a_{21}}{a_{11}} \right) x_3 \dots - \left( a_{2n} - a_{1n} \frac{a_{21}}{a_{11}} \right) x_n$$

$$= b_2 - b_1 \left( \frac{a_{21}}{a_{11}} \right)$$

R<sub>2</sub> can be rewritten as

$$R_2: a'_{22}x_2 + a'_{23}x_3 + \dots + a'_{2n}x_n = b'_2$$

Where 
$$a'_{22} = \left(a_{22} - a_{12} \frac{a_{21}}{a_{11}}\right)$$
 and so on.

In a similar fashion, we can eliminate  $x_1$  from the remaining equations and after eliminating  $x_1$  from the last row Rn, we obtain the system

$$R_1: a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = b_1$$

$$R_2: \qquad a'_{22}x_2 + a'_{23}x_3 + \dots + a'_{2n}x_n = b'_2$$

$$R_n: a'_{n2}x_2 + a'_{n3}x_3 + \dots + a'_{nn}x_n = b'_n$$

In the process of obtaining the above system, we have multiplied the first row by  $(-a_{21}/a_{11})$ , i.e. we have divided it by  $a_{11}$  which is therefore assumed to be nonzero. For this reason, the first row  $R_1$  in is called the pivot equation, and  $a_{11}$  is called the pivot or pivotal element. The method obviously fails if  $a_{11}$ = 0.

Similarly, we eliminate the variables will be obtain the upper-triangular matrix in the form:

$$R_1: a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = b_1$$

$$R_2: \qquad a'_{22}x_2 + a'_{23}x_3 + \dots + a'_{2n}x_n = b'_2$$

$$R_3:$$
  $a_{33}''x_3 + \cdots + a_{3n}''x_n = b_3''$ 

$$a_{nn}^{(n-1)}x_n = b_n^{(n-1)}$$

where  $a_{nn}^{(n-1)}$  indicates the element  $a_{nn}$  has changed (n-1) times.

From 
$$R_n: a_{nn}^{(n-1)} x_n = b_n^{(n-1)}$$

$$x_n = \frac{b_n^{(n-1)}}{a_{nn}^{(n-1)}}$$

This is then substituted in the  $R_{(n-1)}$  to obtain  $x_{n-1}$  and the process is repeated to compute the other unknowns. We have therefore first computed  $x_n$  then  $x_{n-1}$ , ... ...  $x_2$ ,  $x_1$  in that order. Due to this reason, the process is called back substitution.

$$x_2 + x_3 = 2$$
  
 $2x_1 + 3x_3 = 5$   
 $x_1 + x_2 + x_3 = 3$ .

The augmented matrix can be written as

$$\begin{bmatrix} 0 & 1 & 1 & 2 \\ 2 & 0 & 3 & 5 \\ 1 & 1 & 1 & 3 \end{bmatrix}$$

Interchange R<sub>2</sub> and R<sub>1</sub> to get

$$\begin{bmatrix} 2 & 0 & 3 & 5 \\ 0 & 1 & 1 & 2 \\ 1 & 1 & 1 & 3 \end{bmatrix}$$

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\begin{bmatrix} 2 & 0 & 3 & 5 \\ 0 & 1 & 1 & 2 \\ 1 & 1 & 1 & 3 \end{bmatrix}
 Replace R_3 by R_3 - \frac{1}{2}R_1 to get
 \begin{bmatrix} 2 & 0 & 3 & 5 \\ 0 & 1 & 1 & 2 \\ 1 - (\frac{1}{2})2 & 1 - (\frac{1}{2})0 & 1 - (\frac{1}{2})3 & 3 - (\frac{1}{2})5 \end{bmatrix}
= \begin{bmatrix} 2 & 0 & 3 & 5 \\ 0 & 1 & 1 & 2 \\ 0 & 1 & -\frac{1}{2} & \frac{1}{2} \end{bmatrix}
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Replace  $R_3$  by  $R_3 - R_2$  to get

$$\begin{bmatrix} 2 & 0 & 3 & 5 \\ 0 & 1 & 1 & 2 \\ 0 - 0 & 1 - 1 & -\binom{1}{2} - 1 & \binom{1}{2} - 2 \end{bmatrix}$$

$$= \begin{bmatrix} 2 & 0 & 3 & 5 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & -\frac{3}{2} & -\frac{3}{2} \end{bmatrix}$$

The matrix is in row echelon form. Using the last row we get  $x_3=1$  Second row of the matrix gives us  $x_2+x_3=2$  So,  $x_2=1$  First row gives us  $2x_1+3x_3=5$  So  $x_1=1$ 

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Eg2.

x_1 + 3x_2 + 5x_3 = 14

2x_1 - x_2 - 3x_3 = 3

4x_1 + 5x_2 - x_3 = 7
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The augmented matrix can be written as

$$\begin{bmatrix} 1 & 3 & 5 & | & 14 \\ 2 & -1 & -3 & | & 3 \\ 4 & 5 & -1 & | & 7 \end{bmatrix}$$

Replace  $R_2$  by  $R_2 - 2R_1$  and  $R_3$  by  $R_3 - 4R_1$  to get

$$\begin{bmatrix} 1 & 3 & 5 & 14 \\ 2-2 & -1-2(3) & -3-2(5) & 3-2(14) \\ 4-4 & 5-4(3) & -1-4(5) & 7-4(14) \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 3 & 5 & 14 \\ 0 & -7 & -13 & -25 \\ 0 & -7 & -21 & -49 \end{bmatrix}$$

Since all the elements in  $R_2$  and  $R_3$  are negative, we multiply throughout by -1

Replace  $R_2$  by  $(-1)R_2$  and  $R_3$  by  $(-1)R_3$  to get

$$\begin{bmatrix} 1 & 3 & 5 & 14 \\ 0 & -7 & -13 & -25 \\ 0 & -7 & -21 & -49 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 3 & 5 & | & 14 \\ 0 & 7 & 13 & | & 25 \\ 0 & 7 & 21 & | & 49 \end{bmatrix}$$

Replace R<sub>3</sub> by R<sub>3</sub> - R<sub>2</sub> to get

$$= \begin{bmatrix} 1 & 3 & 5 & | & 14 \\ 0 & 7 & 13 & | & 25 \\ 0 & 0 & 8 & | & 24 \end{bmatrix}$$

Now back substitution gives us

$$x_1 + 3x_2 + 5x_3 = 14$$
  
 $7x_2 + 13x_3 = 25$   
 $8x_3 = 24$ 

$$x_1 = 5$$
,  $x_2 = -2$ ,  $x_3 = 3$