

Adversarially Constrained Autoencoder Interpolation using Wasserstein Autoencoder

Machine Learning

Lorenzo Palloni

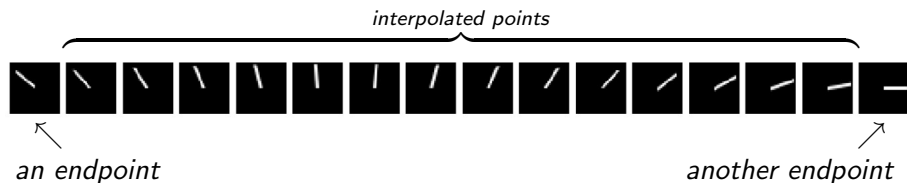
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Introduction

- **Unsupervised Learning** context.
- We aim to obtain "high-quality" **interpolations**.
- An interpolation example:

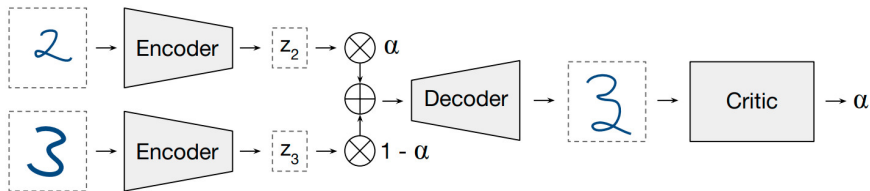


- An "high-quality" interpolation point have two characteristics:
 - is indistinguishable from real data;
 - represents a semantically smooth morphing between the endpoints.

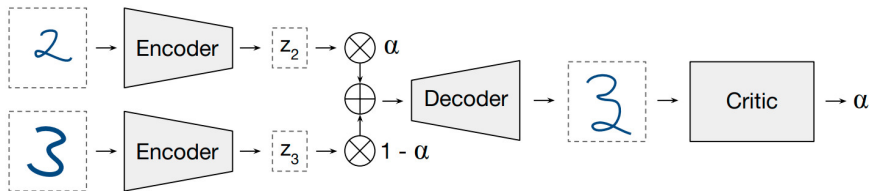
- Uncover underlying structure of dataset.
- Better representations \rightarrow better results in other tasks.
- Implemented¹ frameworks:
 - Adversarially Constrained Autoencoder Interpolation (ACAI) [1];
 - Wasserstein Autoencoder (WAE) [2];

¹All the models are implemented using pytorch [4]

- Graphical representation of ACAI structure:

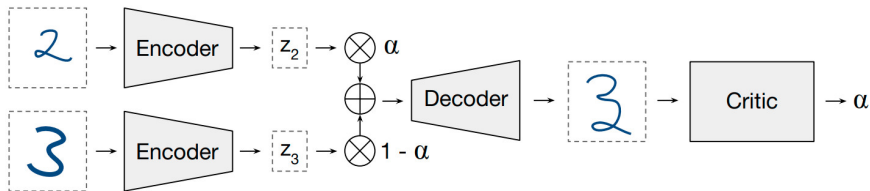


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- Loss functions:

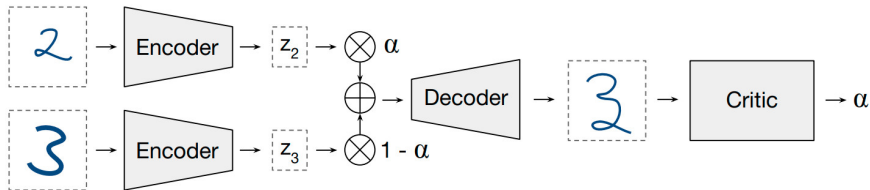
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$$\mathcal{L}_d := \|d_w(\hat{x}_\alpha) - \alpha\|^2 + \|d_w(\gamma x + (1 - \gamma)g_\phi(f_\theta(x)))\|^2$$

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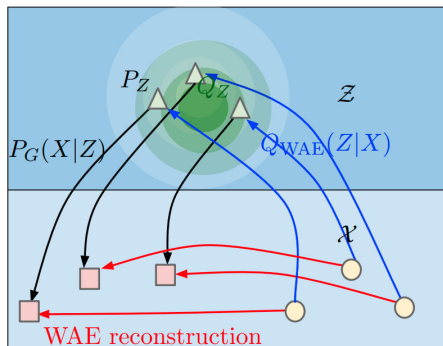


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$$\mathcal{L}_d := \|d_\omega(\hat{x}_\alpha) - \alpha\|^2 + \|d_\omega(\gamma x + (1 - \gamma)g_\phi(f_\theta(x)))\|^2$$

$$\mathcal{L}_{f,g} := \|x - g_\phi(f_\theta(x))\|^2 + \lambda \cdot \|d_\omega(\hat{x}_\alpha)\|^2$$

- Graphical representation of WAE structure:



- Loss function:

$$D_{WAE}(P_X, P_G) := \inf_{Q(Z|X) \in \mathcal{Q}} \mathbb{E}_{P_X} \mathbb{E}_{Q(Z|X)} [c(X, G(Z))] + \lambda \cdot \mathcal{D}_Z(Q_Z, P_Z)$$

Different penalties, different WAEs (1/2)

- Setting

$$\mathcal{D}_Z(Q_Z, P_Z) = MMD_k(Q_Z, P_Z)$$

→ **we obtain WAE-MMD.**

- where $MMD_k(\cdot, \cdot)$ is the Maximum Mean Discrepancy [10]:

$$MMD_k(Q_Z, P_Z) := \left\| \int_{\mathcal{Z}} k(z, \cdot) dQ_Z(z) - \int_{\mathcal{Z}} k(z, \cdot) dP_Z(z) \right\|_{\mathcal{H}_k}$$

- where k is a positive-definite kernel $k: \mathcal{Z} \times \mathcal{Z} \rightarrow \mathcal{R}$.

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- Kernel used in the WAE paper:
 - Radial Basis Function: $k(x, y) = \exp(-\gamma \|x - y\|^2)$
 - Inverse Multiquadratic: $k(x, y) = \frac{C}{C + \|x - y\|^2}$, $C \in \mathcal{R}$

Different penalties, different WAEs (2/2)

- Setting

$$\mathcal{D}_Z(Q_Z, P_Z) = \underbrace{\|\mu_{P_Z} - \mu_{Q_Z}\|^2 + \text{Tr} \left(\Sigma_{P_Z} + \Sigma_{Q_Z} - 2(\Sigma_{P_Z} \Sigma_{Q_Z})^{\frac{1}{2}} \right)}_{\text{2-Wasserstein distance between two multivariate normal distributions [6]}}$$

- and assuming the prior P_Z normal distributed,
→ **we obtain WWAE** (Wasserstein-Wasserstein Autoencoder) [3].

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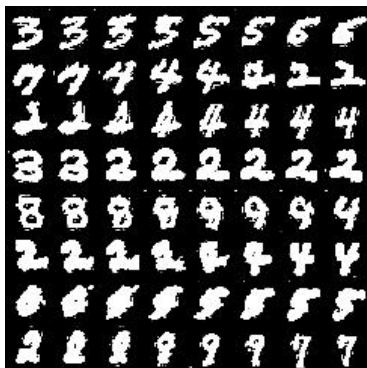
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- ③ ACAI + WWAE applied on MNIST → good results (next slide).
- ④ ACAI + WWAE applied on NESMDB → requires too time to collect results.

Results on MNIST

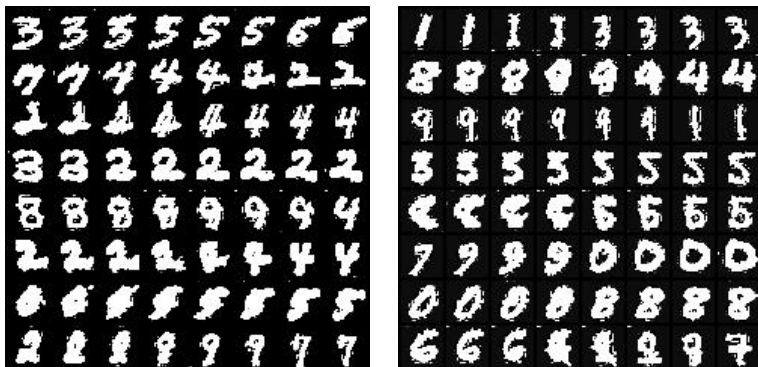
- Example interpolations on MNIST made with ACAI + WWAE:



- Each row is made by reconstructing (a sample) of the linear convex combination of the latent representation between the first and the last element of the row.

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- We achieve pretty good quality interpolations on image data using ACAI + WWAE.
- All models discussed so far require:
 - high computational resources for training;
 - have the lack of an objective way to assess the performance.
- Raw audio in waveform probably needs:
 - another type of representation (e.g. MIDI) [7] [8];
 - another autoencoder structure (e.g. Wavenet Autoencoder [9])

References I



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Appendix - Wasserstein distance

- Kantorovich's formulation of the *optimal transport* problem:

$$W_c(P_X, P_G) := \inf_{\Gamma \in \mathcal{P}(X \sim P_X, Y \sim P_G)} \mathbb{E}_{(X,Y) \sim \Gamma} [c(X, Y)]$$

- with some weak constrains it could be written as the following:

$$W_1(P_X, P_G) = \sup_{f \in \mathcal{F}_{L_1}} \mathbb{E}_{X \sim P_X} [f(X)] - \mathbb{E}_{Y \sim P_G} [f(Y)]$$

- Moreover defining P_G in two steps:

① $Z \sim P_Z$

② $G : \mathcal{Z} \rightarrow \mathcal{R}^d$

- we have:

$$\inf_{\Gamma \in \mathcal{P}(X \sim P_X, Y \sim P_G)} \mathbb{E}_{(X,Y) \sim \Gamma} [c(X, Y)] = \inf_{Q: Q_Z = P_Z} \mathbb{E}_{Q(X|Z)} [c(X, G(Z))]$$