

Sr No	Title	Pg.no	Date	Sign
1	Implement basic operations with Scalars, Vectors, Matrices, and Tensors using NumPy.			
1 a	Perform matrix multiplication and vector operations			
1 b	Compute norms of vectors and matrices.			
2	Explore issues like overflow, underflow, and poor conditioning in numerical computation.			
2 a	Implement Gradient-Based Optimization algorithms (e.g., Gradient Descent) for simple optimization problems.			
2 b	Solve Constraint Optimization problems using optimization techniques.			
3	Implementing deep neural network for performing binary classification task. Solving XOR problem using deep feed forward network.			
4	Build and train a Multilayer Perceptron (MLP) for a classification task using TensorFlow or PyTorch.			
4 a	Apply regularization techniques such as dropout and weight decay to prevent overfitting			
4 b	Experiment with different optimization algorithms (e.g., SGD, Adam) for training the model.			
5	Implement convolutional layers and pooling layers from scratch using NumPy.			
5 a	Construct a simple CNN architecture and train it on a dataset for image classification.			
5 b	Explore various CNN architectures and their applications through hands-on exercises			
6	Implement basic RNN cells and sequence modeling using TensorFlow or PyTorch.			
6 a	Train an RNN model for language modeling and text generation tasks			
6 b	Understand the challenges of training RNNs and explore solutions like LSTM and GRU.			
7	Implement a sequence-to-sequence model for machine translation using RNNs or Transformer architecture.			
7 a	Train the model on a dataset and evaluate its performance using appropriate metrics.			
7 b	Explore attention mechanisms and their role in improving sequence-to-sequence models			
8	Implement basic reinforcement learning algorithms such as Q-learning and policy gradients.			
8 a	Apply these algorithms to solve simple Markov decision processes (MDPs).			
8 b	Experiment with different reward structures and explore their impact on learning.			

9	Implement a Variational Autoencoder (VAE) architecture for learning latent representations			
9 a	Train the VAE model on a dataset and visualize the learned latent space			
9 b	Explore techniques for generating new data samples using the trained VAE model.			
1 0	Implement a basic GAN architecture (e.g., DCGAN) using TensorFlow or PyTorch.			
1 0 a	Train the GAN model on a dataset for image generation or style transfer tasks.			
1 0 b	Experiment with different loss functions and architectures to improve GAN performance.			
1 1	Use pre-trained GAN models for image generation and synthesis tasks.			
1 1 b	use of GANs for text generation tasks such as dialogue generation or story generation			

Practical 1

Aim:-Implement basic operations with Scalars, Vectors, Matrices, and Tensors using NumPy.
 Perform matrix multiplication and vector operations
 Compute norms of vectors and matrices.

Practical 2

Aim:Explore issues like overflow, underflow, and poor conditioning in numerical computation.
 Implement Gradient-Based Optimization algorithms (e.g., Gradient Descent) for simple optimization problems.
 Solve Constraint Optimization problems using optimization techniques.

```
# Gradient Based Optimization

import tensorflow as tf

import matplotlib.pyplot as plt

def loss_function(x):
    return (x-3)**2

x = tf.Variable(initial_value = 5.0, trainable = True, dtype = tf.float32)

learning_rate = 0.1

steps = []

loss_values = []

for step in range(20):
    with tf.GradientTape() as tape:
        loss = loss_function(x)

    gradients = tape.gradient(loss, [x])

    x.assign_sub(learning_rate*gradients[0])

    steps.append(step)
    loss_values.append(loss.numpy())

    print(f'Step {step+1}: x = {x.numpy():.4f}, Loss = {loss.numpy():.4f}')

plt.plot(steps, loss_values, marker='o')
plt.title('Gradient-Based Optimization: :Loss Reduction')
plt.xlabel('Steps')
plt.ylabel('Loss')
plt.grid(True)
plt.show()
```

```
# Using Tensorflow Optimizers
```

```
x = tf.Variable(initial_value = 5.0, trainable = True, dtype = tf.float32)
```

```
optimizer = tf.keras.optimizers.Adam(learning_rate=0.1)
```

```
adam_steps = []
```

```
adam_loss_values = []
```

```
for step in range(20):
```

```
    with tf.GradientTape() as tape:
```

```
        loss = loss_function(x)
```

```
    gradients = tape.gradient(loss, [x])
```

```
    optimizer.apply_gradients(zip(gradients, [x]))
```

```
    adam_steps.append(step)
```

```
    adam_loss_values.append(loss.numpy())
```

```
    print(f'Step {step+1} (Adam): x = {x.numpy():.4f}, Loss = {loss.numpy():.4f}')
```

```
plt.plot(adam_steps, adam_loss_values, marker='o', color='red')
```

```
plt.title('Adam Optimization: Loss Reduction')
```

```
plt.xlabel('Steps')
```

```
plt.ylabel('Loss')
```

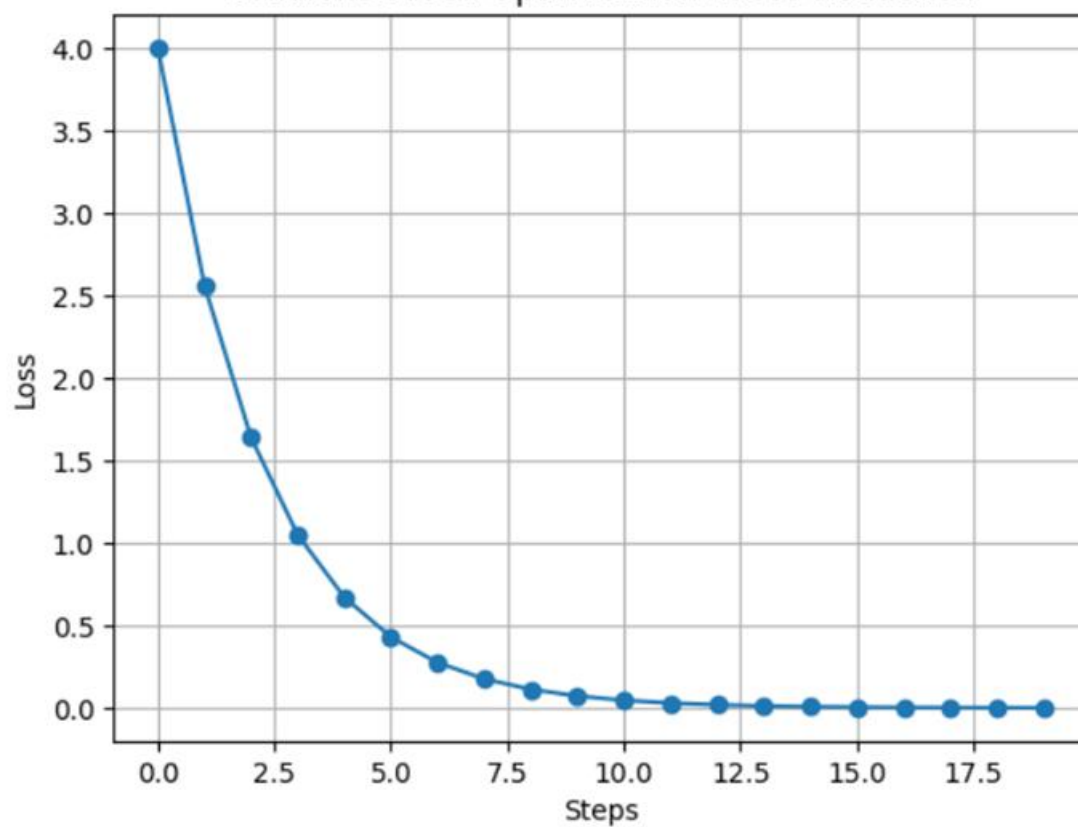
```
plt.grid(True)
```

```
plt.show()
```

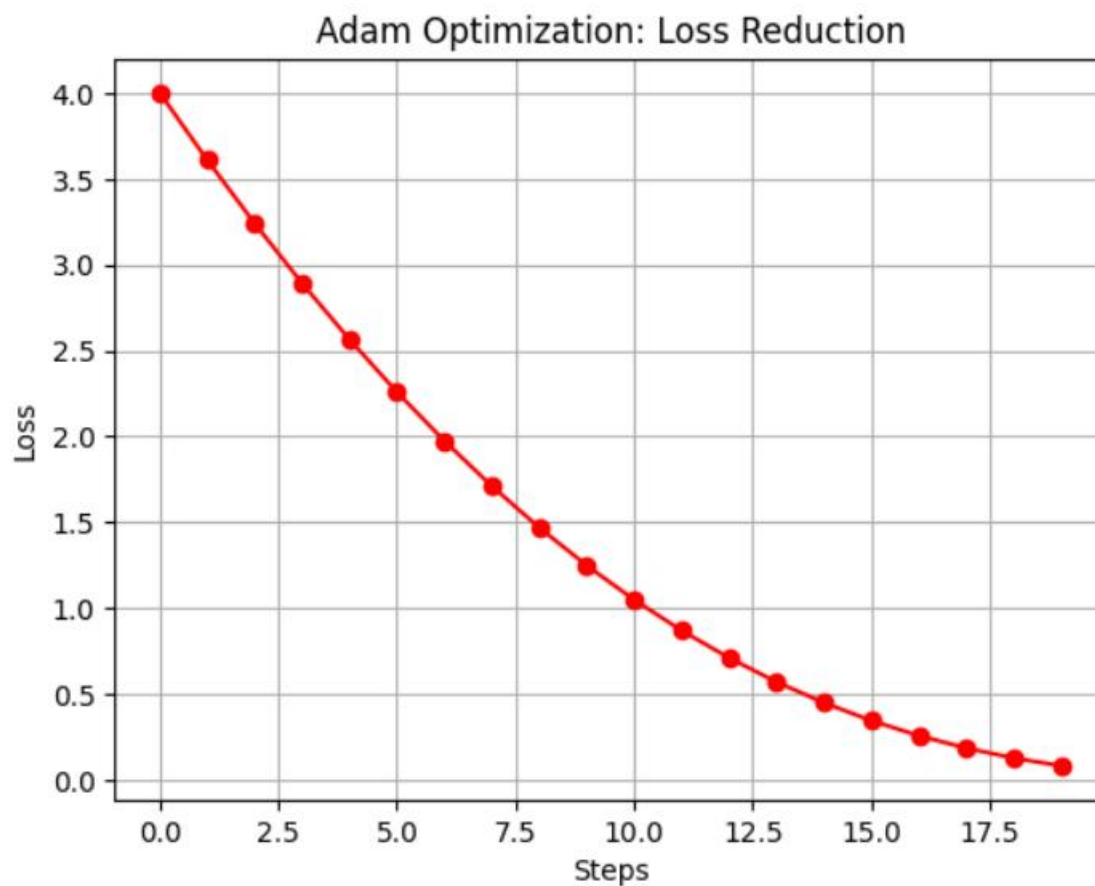
```
print("Gayatri Kulkarni -53004230002")
```

Step 1: $x = 4.6000$, Loss = 4.0000
Step 2: $x = 4.2800$, Loss = 2.5600
Step 3: $x = 4.0240$, Loss = 1.6384
Step 4: $x = 3.8192$, Loss = 1.0486
Step 5: $x = 3.6554$, Loss = 0.6711
Step 6: $x = 3.5243$, Loss = 0.4295
Step 7: $x = 3.4194$, Loss = 0.2749
Step 8: $x = 3.3355$, Loss = 0.1759
Step 9: $x = 3.2684$, Loss = 0.1126
Step 10: $x = 3.2147$, Loss = 0.0721
Step 11: $x = 3.1718$, Loss = 0.0461
Step 12: $x = 3.1374$, Loss = 0.0295
Step 13: $x = 3.1100$, Loss = 0.0189
Step 14: $x = 3.0880$, Loss = 0.0121
Step 15: $x = 3.0704$, Loss = 0.0077
Step 16: $x = 3.0563$, Loss = 0.0050
Step 17: $x = 3.0450$, Loss = 0.0032
Step 18: $x = 3.0360$, Loss = 0.0020
Step 19: $x = 3.0288$, Loss = 0.0013
Step 20: $x = 3.0231$, Loss = 0.0008

Gradient-Based Optimization: :Loss Reduction



Step 1 (Adam): $x = 4.9000$, Loss = 4.0000
Step 2 (Adam): $x = 4.8002$, Loss = 3.6100
Step 3 (Adam): $x = 4.7006$, Loss = 3.2406
Step 4 (Adam): $x = 4.6015$, Loss = 2.8921
Step 5 (Adam): $x = 4.5030$, Loss = 2.5648
Step 6 (Adam): $x = 4.4051$, Loss = 2.2589
Step 7 (Adam): $x = 4.3082$, Loss = 1.9744
Step 8 (Adam): $x = 4.2123$, Loss = 1.7114
Step 9 (Adam): $x = 4.1177$, Loss = 1.4698
Step 10 (Adam): $x = 4.0246$, Loss = 1.2493
Step 11 (Adam): $x = 3.9331$, Loss = 1.0498
Step 12 (Adam): $x = 3.8435$, Loss = 0.8707
Step 13 (Adam): $x = 3.7560$, Loss = 0.7115
Step 14 (Adam): $x = 3.6709$, Loss = 0.5716
Step 15 (Adam): $x = 3.5884$, Loss = 0.4501
Step 16 (Adam): $x = 3.5086$, Loss = 0.3462
Step 17 (Adam): $x = 3.4319$, Loss = 0.2587
Step 18 (Adam): $x = 3.3585$, Loss = 0.1866
Step 19 (Adam): $x = 3.2886$, Loss = 0.1285
Step 20 (Adam): $x = 3.2225$, Loss = 0.0833



Practical 3

Aim: Implementing deep neural network for performing binary classification task.
Solving XOR problem using deep feed forward network.

Aim: Build and train a Multilayer Perceptron (MLP) for a classification task using TensorFlow or PyTorch.

Aim: Apply regularization techniques such as dropout and weight decay to prevent overfitting

Experiment with different optimization algorithms (e.g., SGD, Adam) for training the model.

Practical 1

`1) Sigmoid:-

#Sigmoid Function

```
import matplotlib.pyplot as plt
```

```
import numpy as np
```

```
def sigmoid(x):
```

```
    s=1/(1+np.exp(-x))
```

```
    ds=s*(1-s)
```

```
    return s,ds
```

```
x=np.arange(-6,6,0.01)
```

```
sigmoid(x)
```

```
fig, ax = plt.subplots(figsize=(9, 5))
```

```
ax.spines['left'].set_position('center')
```

```
ax.spines['right'].set_color('none')
```

```
ax.spines['top'].set_color('none')
```

```
ax.xaxis.set_ticks_position('bottom')
```

```
ax.yaxis.set_ticks_position('left')
```

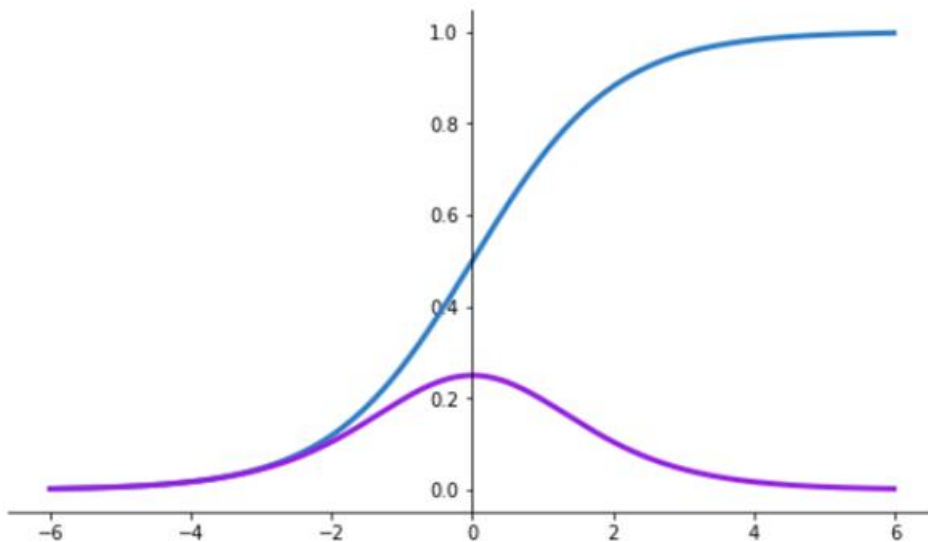
```
ax.plot(x,sigmoid(x)[0],color='#307EC7',linewidth=3, label="sigmoid")
```

```
ax.plot(x,sigmoid(x)[1],color='#9621e2',linewidth=3, label="derivative")
```

```
fig.show()
```

```
print("Gayatri Kulkarni - 53004230002")
```

```
C:\Users\admin\AppData\Local\Temp\ipykernel_13244\2117604978.py:18: UserWarning: Matplotlib is currently using module://matplotlib_inline.backend_inline, which is a non-GUI backend, so cannot show the figure.  
fig.show()
```



2)Tanh

#Tanh Function

```
import matplotlib.pyplot as plt
```

```
import numpy as np
```

```
def tanh(x):
```

```
    t=(np.exp(x)-np.exp(-x))/(np.exp(x)+np.exp(-x))
```

```
    dt=1-t**2
```

```
    return t,dt
```

```
z=np.arange(-4,4,0.01)
```

```
tanh(z)[0].size,tanh(z)[1].size
```

```
fig, ax = plt.subplots(figsize=(9, 5))
```

```
ax.spines['left'].set_position('center')
```

```
ax.spines['right'].set_color('none')
```

```
ax.spines['top'].set_color('none')
```

```
ax.xaxis.set_ticks_position('bottom')
```

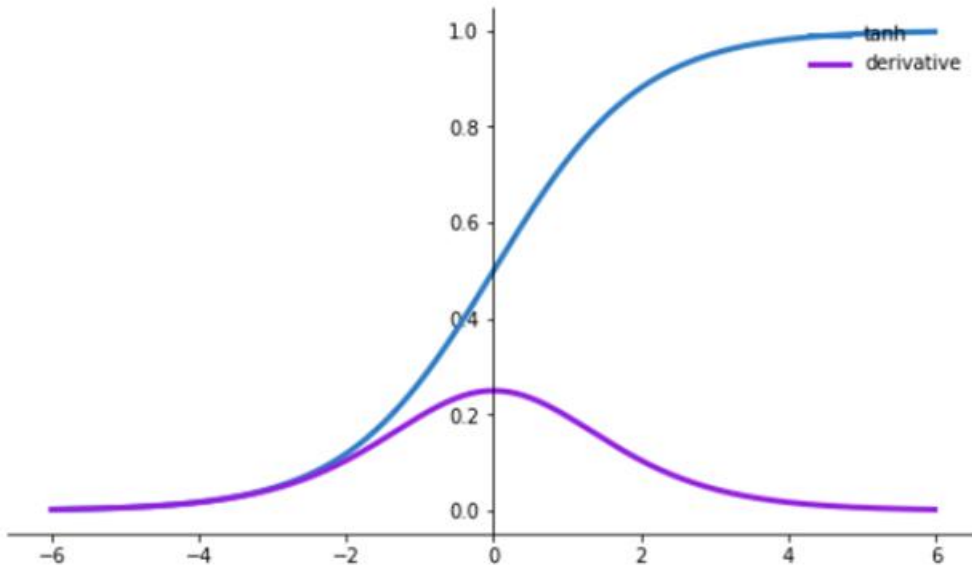
```
ax.yaxis.set_ticks_position('left')
```

```
ax.plot(x,sigmoid(x)[0],color='#307EC7',linewidth=3, label="tanh")
```

```
ax.plot(x,sigmoid(x)[1],color='#9621e2',linewidth=3, label="derivative")
```



```
ax.legend(loc="upper right", frameon=False)
plt.show()
print("Gayatri Kulkarni - 53004230002")
```



Gayatri Kulkarni - 53004230002

3)Relu

#Relu Function and its derivative

```
import matplotlib.pyplot as plt
```

```
import numpy as np
```

```
def relu(x):
```

```
    r = np.maximum(0, x)
```

```
    dr = np.where(x <= 0, 0, 1)
```

```
    return r,dr
```

```
x=np.arange(-6, 6, 0.1)#Range for the x-axis
```

```
relu_values, relu_derivatives = relu(x) #Compute ReLU AND its derivative
```

```
fig, ax = plt.subplots(figsize=(9, 5))
```

```
ax.spines['left'].set_position('center')
```

```
ax.spines['bottom'].set_position(('data', 0))#set the x-axis at y=0
```

```
ax.spines['right'].set_color('none')
```

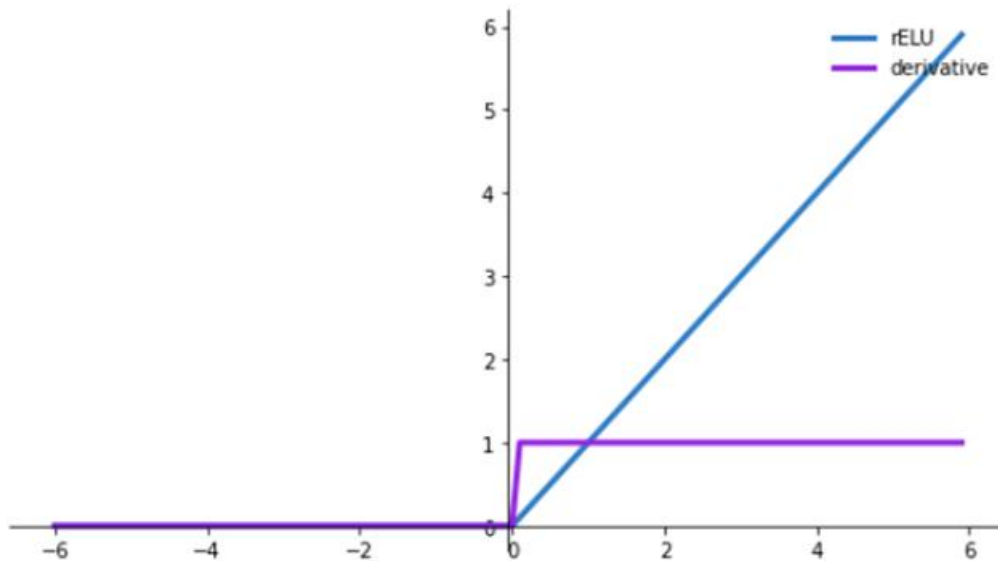
```
ax.spines['top'].set_color('none')
```

```
ax.xaxis.set_ticks_position('bottom')
```

```

ax.yaxis.set_ticks_position('left')
ax.plot(x,relu_values,color='#307EC7',linewidth=3, label="ReLU")
ax.plot(x,relu_derivatives,color='#9621e2',linewidth=3, label="derivative")
ax.legend(loc="upper right", frameon=False)
plt.show()
print("Gayatri Kulkarni - 53004230002")

```



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4) Leaky RELU

LEAKY Rectified Linear Unit(Leaky Relu)

```
import matplotlib.pyplot as plt
```

```
import numpy as np
```

```
def leaky_relu(x, alpha=0.01):
```

```
    r = np.maximum(alpha * x, x)
```

```
    dr = np.where(x < 0, alpha, 1)
```

```
    return r,dr
```

```
#Generate x values
```

```
x=np.arange(-6, 6, 0.1)#Range for the x-axis
```

```
leaky_relu_values, leaky_relu_derivatives = leaky_relu(x)
```

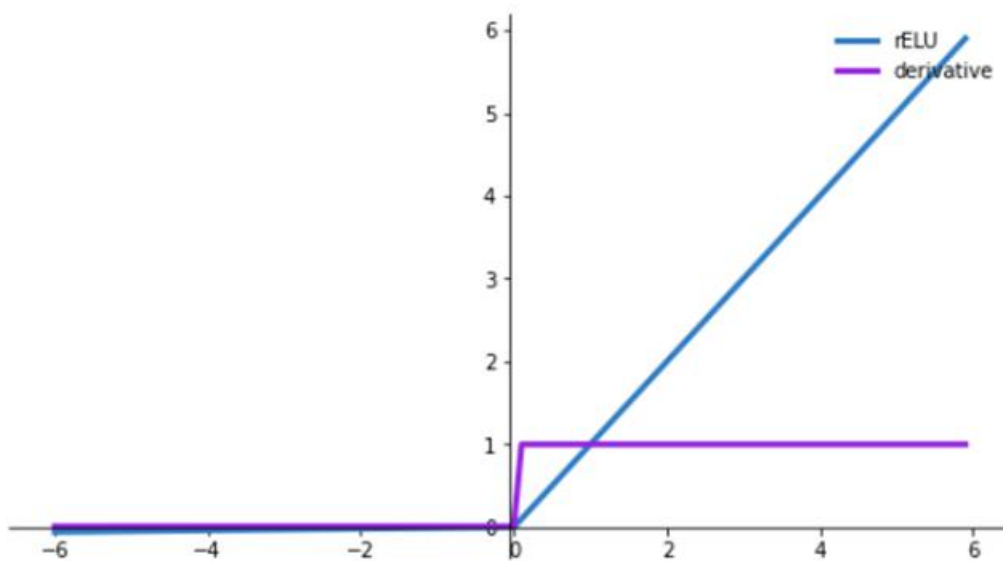
```
# Create the plot
```

```
fig, ax = plt.subplots(figsize=(9, 5))
```

```

ax.spines['left'].set_position('center')
ax.spines['bottom'].set_position(('data', 0))#set the x-axis at y=0
ax.spines['right'].set_color('none')
ax.spines['top'].set_color('none')
ax.xaxis.set_ticks_position('bottom')
ax.yaxis.set_ticks_position('left')
ax.plot(x, leaky_relu_values, color='#307EC7',linewidth=3, label="rELU")
ax.plot(x,leaky_relu_derivatives, color='#9621e2',linewidth=3, label="derivative")
ax.legend(loc="upper right", frameon=False)
#Show the plot
plt.show()
print("Gayatri Kulkarni - 53004230002")

```



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4)Prelu

Parametric Rectified Linear Unit (PRelu)

```
import matplotlib.pyplot as plt
```

```
import numpy as np
```

```
def prelu(x, alpha=0.25):
```

```
    r = np.maximum(alpha * x, x)
```

```
    dr = np.where(x < 0, alpha, 1)
```

```
    return r,dr
```

```
x=np.arange(-6, 6, 0.1)#Range for the x-axis
```

```
prelu_values, prelu_derivatives = prelu(x)
```

```
# Create the plot
```

```
fig, ax = plt.subplots(figsize=(9, 5))
```

```
ax.spines['left'].set_position('center')
```

```
ax.spines['bottom'].set_position(('data', 0))#set the x-axis at y=0
```

```
ax.spines['right'].set_color('none')
```

```
ax.spines['top'].set_color('none')
```

```
ax.xaxis.set_ticks_position('bottom')
```

```
ax.yaxis.set_ticks_position('left')
```

```
#Plotting the PRelu and its derivative
```

```
ax.plot(x, prelu_values, color='#307EC7',linewidth=3, label="PReLU")
```

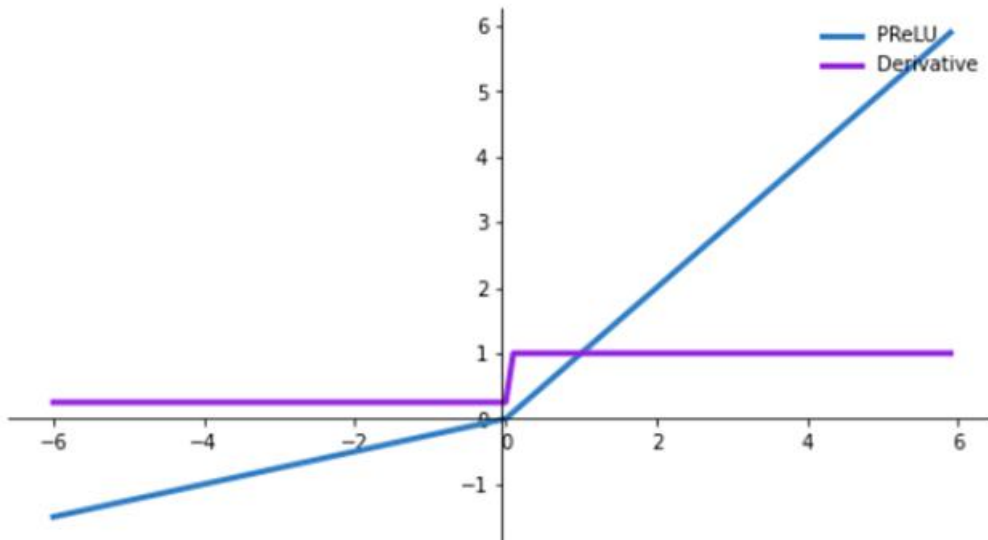
```
ax.plot(x,prelu_derivatives, color='#9621e2',linewidth=3, label="Derivative")
```

```
ax.legend(loc="upper right", frameon=False)
```

```
#Show the plot
```

```
plt.show()
```

```
print("Gayatri Kulkarni - 53004230002")
```



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5)ELU

```

# Exponential Linear Unit (ELU)

import matplotlib.pyplot as plt

import numpy as np

def elu(x, alpha=1.0):
    r = np.where(x >= 0, x, alpha * (np.exp(x) - 1))
    dr = np.where(x <= 0, 1, alpha * np.exp(x))
    return r,dr

x=np.arange(-6, 6, 0.1)#Range for the x-axis
elu_values, elu_derivatives = elu(x)

# Create the plot

fig, ax = plt.subplots(figsize=(9, 5))
ax.spines['left'].set_position('center')
ax.spines['bottom'].set_position(('data', 0))#set the x-axis at y=0
ax.spines['right'].set_color('none')
ax.spines['top'].set_color('none')
ax.xaxis.set_ticks_position('bottom')
ax.yaxis.set_ticks_position('left')

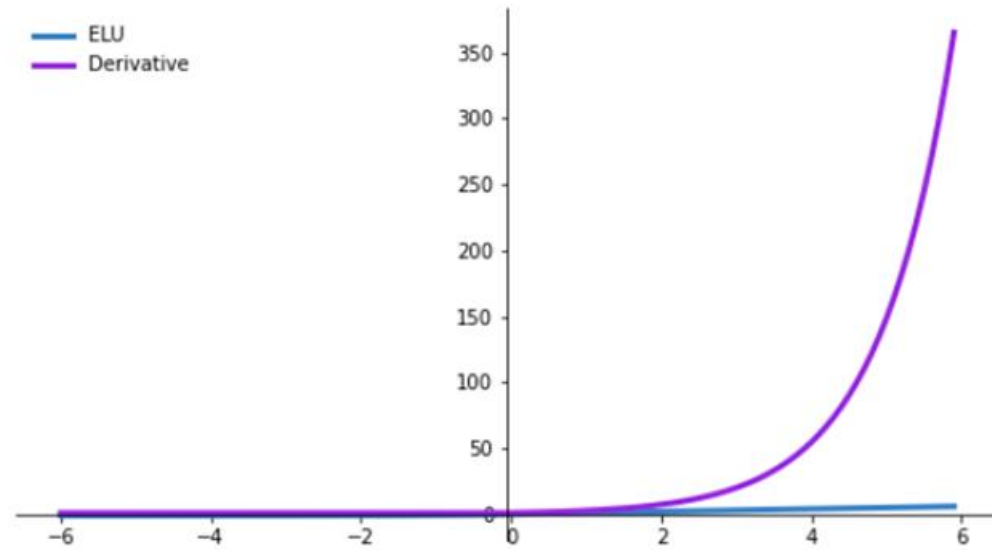
#Plotting the PRelu and its derivative
ax.plot(x, elu_values, color='#307EC7',linewidth=3, label="ELU")
ax.plot(x,prelu_derivatives, color='#9621e2',linewidth=3, label="Derivative")
ax.legend(loc="upper left", frameon=False)

#Show the plot

plt.show()

print("Gayatri Kulkarni - 53004230002")

```



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5) Softplus

```
import matplotlib.pyplot as plt
```

```
import numpy as np
```

```
def softplus(x):
```

```
    r = np.log(1 + np.exp(x))
```

```
    dr = 1/(1 + np.exp(x))
```

```
    return r,dr
```

```
x=np.arange(-6, 6, 0.1)#Range for the x-axis
```

```
softplus_values, softplus_derivatives = softplus(x)
```

```
fig, ax = plt.subplots(figsize=(9, 5))
```

```
ax.spines['left'].set_position('center')
```

```
ax.spines['bottom'].set_position(('data', 0))#set the x-axis at y=0
```

```
ax.spines['right'].set_color('none')
```

```
ax.spines['top'].set_color('none')
```

```
ax.xaxis.set_ticks_position('bottom')
```

```
ax.yaxis.set_ticks_position('left')
```

```
#Plotting the PRelu and its derivative
```

```

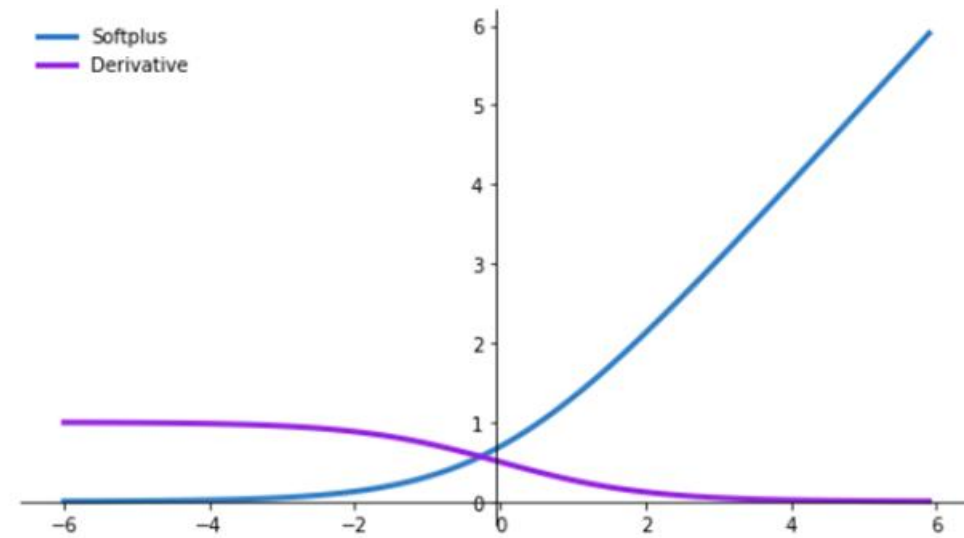
ax.plot(x, softplus_values, color='#307EC7',linewidth=3, label="Softplus")
ax.plot(x,softplus_derivatives, color='#9621e2',linewidth=3, label="Derivative")
ax.legend(loc="upper left", frameon=False)

#Show the plot

plt.show()

print("Gayatri Kulkarni - 53004230002")

```



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6)arctan

```

import matplotlib.pyplot as plt
import numpy as np

```

```

def arctan(x):
    r = np.arctan(x)
    dr = 1/(1 + x**2)
    return r,dr

```

```

x=np.arange(-6, 6, 0.1)#Range for the x-axis
arctan_values, arctan_derivatives = arctan(x)

```

```

fig, ax = plt.subplots(figsize=(9, 5))
ax.spines['left'].set_position('center')
ax.spines['bottom'].set_position(('data', 0))#set the x-axis at y=0

```

```

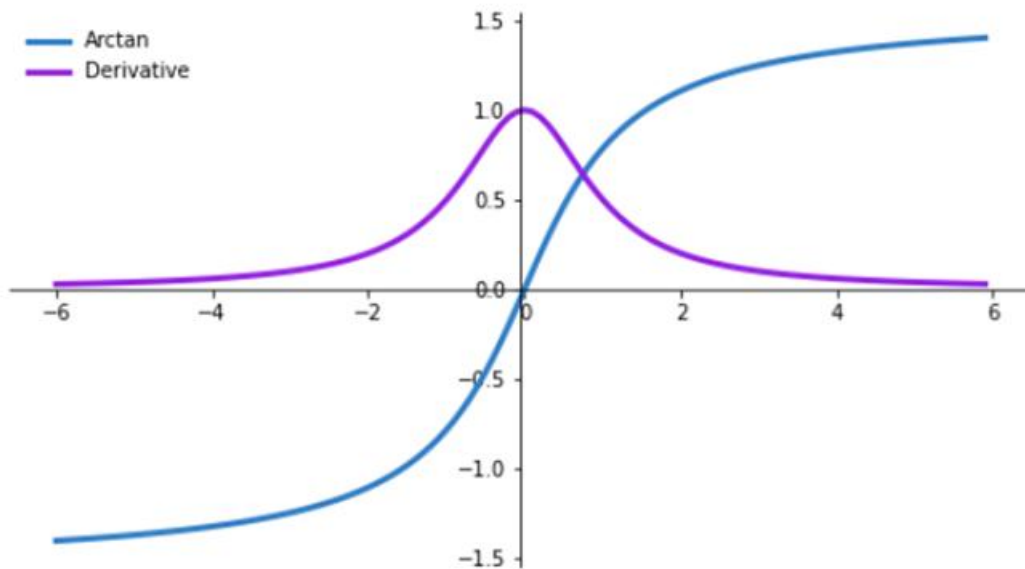
ax.spines['right'].set_color('none')
ax.spines['top'].set_color('none')
ax.xaxis.set_ticks_position('bottom')
ax.yaxis.set_ticks_position('left')

#Plotting the PRelu and its derivative
ax.plot(x, arctan_values, color='#307EC7',linewidth=3, label="Arctan")
ax.plot(x, arctan_derivatives, color='#9621e2',linewidth=3, label="Derivative")
ax.legend(loc="upper left", frameon=False)

#Show the plot
plt.show()

print("Gayatri Kulkarni - 53004230002")

```



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7) tanh

```

import matplotlib.pyplot as plt
import numpy as np

```

```

def tanh(x):
    r = np.tanh(x)
    dr = 1 - r**2
    return r, dr

```



```
x=np.arange(-6, 6, 0.1)#Range for the x-axis
```

```
tanh_values, tanh_derivatives = tanh(x)
```

```
fig, ax = plt.subplots(figsize=(9, 5))
```

```
ax.spines['left'].set_position('center')
```

```
ax.spines['bottom'].set_position(('data', 0))#set the x-axis at y=0
```

```
ax.spines['right'].set_color('none')
```

```
ax.spines['top'].set_color('none')
```

```
ax.xaxis.set_ticks_position('bottom')
```

```
ax.yaxis.set_ticks_position('left')
```

```
#Plotting the PRelu and its derivative
```

```
ax.plot(x, tanh_values, color='#307EC7',linewidth=3, label="Tanh")
```

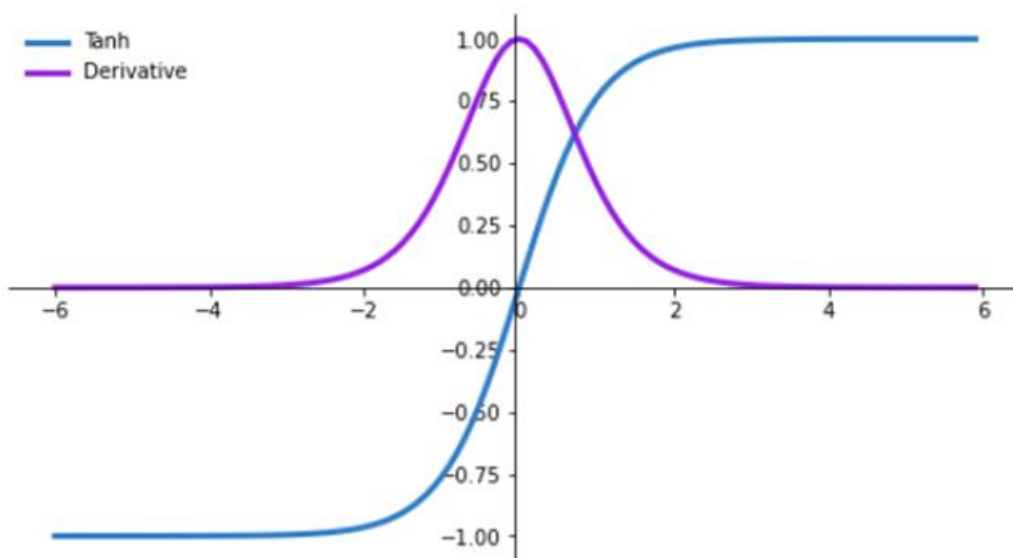
```
ax.plot(x, tanh_derivatives, color='#9621e2',linewidth=3, label="Derivative")
```

```
ax.legend(loc="upper left", frameon=False)
```

```
#Show the plot
```

```
plt.show()
```

```
print("Gayatri Kulkarni - 53004230002")
```



Gayatri Kulkarni - 53004230002

meet.google.com/dkf-kwae-fzs?pli=1

Rajesh Maurya (Presenting)

Jupyter Activation functions and derivatives Last Checkpoint: 6 months ago

```
[23]: import tensorflow as tf
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Dense
from tensorflow.keras.optimizers import Adam
from sklearn.datasets import make_moons
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import StandardScaler
import numpy as np
import matplotlib.pyplot as plt

# Data preparation
X, y = make_moons(n_samples=1000, noise=0.2, random_state=42)
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.3, random_state=42)
scaler = StandardScaler()
X_train = scaler.fit_transform(X_train)
X_test = scaler.transform(X_test)

# Model definition
model = Sequential([
    Dense(10, input_shape=(2,)),
    Dense(10, activation='elu'),
    Dense(1, activation='sigmoid')
])

model.compile(optimizer=Adam(learning_rate=0.01), loss='binary_crossentropy', metrics=['accuracy'])

history = model.fit(X_train, y_train, validation_data=(X_test, y_test), epochs=100, verbose=1)

def plot_decision_boundary(model, X, y):
```

17:00 | dkf-kwae-fzs

Meet - dkf-kwae-fzs

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Rajesh Maurya (Presenting)

Jupyter Activation functions and derivatives Last Checkpoint: 6 months ago

```
model.compile(optimizer=Adam(learning_rate=0.01), loss='binary_crossentropy', metrics=['accuracy'])

history = model.fit(X_train, y_train, validation_data=(X_test, y_test), epochs=100, verbose=1)

def plot_decision_boundary(model, X, y):
    x_min, x_max = X[:, 0].min() - 1, X[:, 0].max() + 1
    y_min, y_max = X[:, 1].min() - 1, X[:, 1].max() + 1
    xx, yy = np.meshgrid(np.linspace(x_min, x_max, 100), np.linspace(y_min, y_max, 100))
    Z = model.predict(np.c_[xx.ravel(), yy.ravel()])
    Z = Z.reshape(xx.shape)

    plt.contourf(xx, yy, Z, alpha=0.8)
    plt.scatter(X[:, 0], X[:, 1], c=y, s=20, edgecolor='k')
    plt.xlabel('Feature 1')
    plt.ylabel('Feature 2')
    plt.title('Decision Boundary and Test Data Points')

plt.figure(figsize=(10, 6))
plot_decision_boundary(model, np.vstack((X_train, X_test)), np.hstack((y_train, y_test)))
plt.show()

plt.plot(history.history['accuracy'], label='Training Accuracy')
plt.plot(history.history['val_accuracy'], label='Validation Accuracy')
plt.title('Model Training Performance')
plt.ylabel('Accuracy')
plt.xlabel('Epoch')
plt.legend()
plt.show()
```

17:01 | dkf-kwae-fzs

Practical 4

Aim: Build and train a Multilayer Perceptron (MLP) for a classification task using TensorFlow or PyTorch.

Apply regularization techniques such as dropout and weight decay to prevent overfitting

Experiment with different optimization algorithms (e.g., SGD, Adam) for training the model.

```
import tensorflow as tf

from tensorflow.keras import layers, models

import matplotlib.pyplot as plt

#-----part 3

print("====part3:Dataset Loading and preprocessing====")

#3.1 load datasets (eg. MNIST, CIFAR-10)

#load mnist datasets

(mnist_train, mnist_train_labels), (mnist_test, mnist_test_labels) = tf.keras.datasets.mnist.load_data()

#normalise

mnist_train = mnist_train/255.0

mnist_test = mnist_test/255.0


#expand dimensions (eg. MNIST images are grayscale)

mnist_train = mnist_train[..., tf.newaxis]

mnist_train = mnist_train[..., tf.newaxis]


print(f'MNIST Train Shape: {mnist_train.shape}, MNIST Test Shape: {mnist_test.shape}')


#3.2 Create a custom dataset using tf.data Datasets

batch_size = 32

train_dataset = tf.data.Dataset.from_tensor_slices((mnist_train, mnist_train_labels))

train_dataset = train_dataset.shuffle(buffer_size=10000).batch(batch_size)


test_dataset = tf.data.Dataset.from_tensor_slices((mnist_test, mnist_test_labels))

test_dataset = test_dataset.batch(batch_size)


#3.3 perform Data Augmentation using TensorFlow operations
```

```
def augment(image, label):
    image = tf.image.random_flip_left_right(image)
    image = tf.image.random_brightness(image, max_delta=0.1)
    return image, label

augment_train_dataset = train_dataset.map(augment)

====part3:Dataset Loading and preprocessing===
MNIST Train Shape: (60000, 28, 28, 1, 1), MNIST Test Shape: (10000, 28, 28)
```

```
#----- Part 4:Build and train simple model-----#
```

```
print("\n== Part 4:Build and Train a Simple Model==")
```

```
#4.1 Create a Neural Network to Classify MNIST using the Sequential API
```

```
model = models.Sequential([
    layers.Input(shape=(28, 28, 1)),
    layers.Conv2D(64, kernel_size=(3,3), activation='relu'),
    layers.MaxPooling2D(pool_size=(2,2)),
    layers.Conv2D(64, kernel_size=(3,3), activation='relu'),
    layers.MaxPooling2D(pool_size=(2,2)),
    layers.Flatten(),
    layers.Dense(128, activation='relu'),
    layers.Dense(10, activation='softmax') # 10 classes for MNIST digits
])
```

```
#Compile the model
```

```
model.compile(optimizer='adam',
              loss='sparse_categorical_crossentropy',
              metrics=['accuracy'])
```

```
# 4.2 Train the Model
```

```
history = model.fit(train_dataset, epochs=5, validation_data=test_dataset)
```

#4.3 Evaluate any Visualise Model Performance

```
plt.figure(figsize=(12, 4))  
plt.subplot(1,2,1)  
plt.plot(history.history['accuracy'], label='Train Accuracy')  
plt.plot(history.history['val_accuracy'], label='Validation Accuracy')  
plt.title('Model Accuracy')  
plt.xlabel('Epoch')  
plt.ylabel('Accuracy')  
plt.legend()
```

```
plt.subplot(1,2,2)  
plt.plot(history.history['loss'], label='Train Loss')  
plt.plot(history.history['val_loss'], label='Validation Loss')  
plt.title('Model Loss')  
plt.xlabel('Epoch')  
plt.ylabel('Loss')  
plt.legend()  
plt.show()  
print("Gayatri Kulkarni -5300423002")
```

== Part 4: Build and Train a Simple Model ==

Epoch 1/5

1875/1875 — 18s 9ms/step - accuracy: 0.9110 - loss: 0.2835 - val_accuracy: 0.9868 - val_loss: 0.0387

Epoch 2/5

1875/1875 — 17s 9ms/step - accuracy: 0.9856 - loss: 0.0456 - val_accuracy: 0.9869 - val_loss: 0.0402

Epoch 3/5

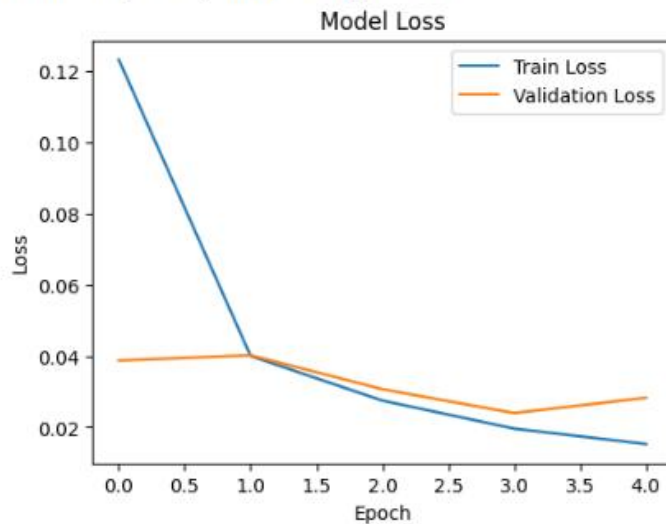
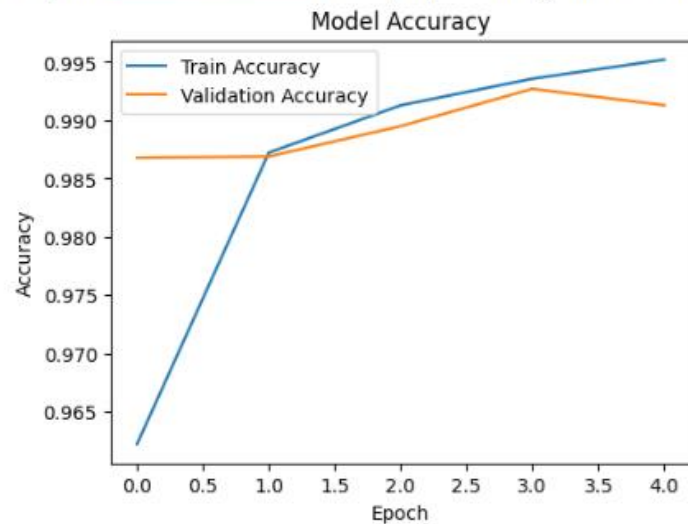
1875/1875 — 18s 10ms/step - accuracy: 0.9903 - loss: 0.0299 - val_accuracy: 0.9895 - val_loss: 0.0307

Epoch 4/5

1875/1875 — 18s 10ms/step - accuracy: 0.9934 - loss: 0.0208 - val_accuracy: 0.9927 - val_loss: 0.0240

Epoch 5/5

1875/1875 — 19s 10ms/step - accuracy: 0.9952 - loss: 0.0146 - val_accuracy: 0.9913 - val_loss: 0.0283



Gayatri Kulkarni -5300423002

Practical 5

Aim: Implement convolutional layers and pooling layers from scratch using NumPy
Construct a simple CNN architecture and train it on a dataset for image classification.

Explore various CNN architectures and their applications through hands-on exercises

Practical 6

Aim: Implement basic RNN cells and sequence modeling using TensorFlow or PyTorch
Train an RNN model for language modeling and text generation tasks
Understand the challenges of training RNNs and explore solutions like LSTM and GRU.

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from sklearn.preprocessing import MinMaxScaler
from sklearn.metrics import mean_squared_error
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Dense, SimpleRNN, LSTM
from sklearn.model_selection import train_test_split
import seaborn as sns

#load
url='https://raw.githubusercontent.com/jbrownlee/Datasets/master/airline-passengers.csv'
df=pd.read_csv(url,usecols=['Passengers'])
df.head()
```

Passengers	
0	112
1	118
2	132
3	129
4	121

#Data Preprocessing :Normalize the dataset for better performance of the neural network

```
scaler = MinMaxScaler(feature_range=(0, 1))
```

```
scaled_data = scaler.fit_transform(df)
```

#create

```
def create_dataset(data, time_step=1):
```

```
    X, Y = [], []
```

```
    for i in range(len(data)-time_step-1):
```

```
        a = data[i:(i+time_step), 0]
```

```
        X.append(a)
```

```
        Y.append(data[i + time_step, 0])
```

```
    return np.array(X), np.array(Y)
```

#prepare

```
time_step = 10
```

```
X, Y = create_dataset(scaled_data, time_step)
```

#SPLIT

```
X_train, X_test, Y_train, Y_test = train_test_split(X, Y, test_size=0.2, random_state=42)
```

#reshape

```
X_train = X_train.reshape(X_train.shape[0], X_train.shape[1], 1)
```

```
X_test = X_test.reshape(X_test.shape[0], X_test.shape[1], 1)
```


#Build and train thr RNN Model

```
model = Sequential()
```

```
model.add(SimpleRNN(50, return_sequences=True, input_shape=(time_step, 1)))
```

```
model.add(SimpleRNN(50, return_sequences=False))
```


```
model.add(Dense(25))
```


```
model.add(Dense(1))
```


```
model.compile(optimizer='adam', loss='mean_squared_error')
```


#Train the model


```
model.fit(X_train, Y_train, epochs=100, batch_size=32, validation_data=(X_test, Y_test),  
verbose=1)
```


Epoch 1/100
4/4  3s 110ms/step - loss: 0.1251 - val_loss: 0.0881


Epoch 2/100
4/4  0s 23ms/step - loss: 0.1027 - val_loss: 0.0120


Epoch 3/100
4/4  0s 21ms/step - loss: 0.0316 - val_loss: 0.0215


Epoch 4/100
4/4  0s 22ms/step - loss: 0.0236 - val_loss: 0.0248


Epoch 5/100
4/4  0s 22ms/step - loss: 0.0291 - val_loss: 0.0079


Epoch 6/100
4/4  0s 22ms/step - loss: 0.0118 - val_loss: 0.0129


Epoch 7/100
4/4  0s 22ms/step - loss: 0.0168 - val_loss: 0.0059


Epoch 8/100
4/4  0s 23ms/step - loss: 0.0096 - val_loss: 0.0079


Epoch 9/100
4/4  0s 20ms/step - loss: 0.0089 - val_loss: 0.0054


Epoch 10/100
4/4  0s 22ms/step - loss: 0.0083 - val_loss: 0.0062


Epoch 11/100
4/4  0s 22ms/step - loss: 0.0064 - val_loss: 0.0048


Epoch 12/100
4/4  0s 22ms/step - loss: 0.0068 - val_loss: 0.0047


Epoch 13/100
4/4  0s 22ms/step - loss: 0.0058 - val_loss: 0.0046


Epoch 14/100
4/4  0s 22ms/step - loss: 0.0058 - val_loss: 0.0040


Epoch 15/100
4/4  0s 21ms/step - loss: 0.0058 - val_loss: 0.0038


Epoch 16/100
4/4  0s 23ms/step - loss: 0.0046 - val_loss: 0.0036


Epoch 17/100
4/4  0s 21ms/step - loss: 0.0050 - val_loss: 0.0035


Epoch 18/100
4/4  0s 22ms/step - loss: 0.0043 - val_loss: 0.0035


Epoch 19/100
4/4  0s 22ms/step - loss: 0.0043 - val_loss: 0.0033


Epoch 20/100
4/4  0s 21ms/step - loss: 0.0040 - val_loss: 0.0031


Epoch 21/100
4/4  0s 22ms/step - loss: 0.0041 - val_loss: 0.0030


Epoch 22/100
4/4  0s 22ms/step - loss: 0.0039 - val_loss: 0.0029


Epoch 23/100
4/4  0s 22ms/step - loss: 0.0042 - val_loss: 0.0029


Epoch 24/100
4/4  0s 21ms/step - loss: 0.0038 - val_loss: 0.0029


Epoch 25/100
4/4  0s 22ms/step - loss: 0.0042 - val_loss: 0.0028


Epoch 26/100
4/4  0s 23ms/step - loss: 0.0037 - val_loss: 0.0028


Epoch 27/100
4/4  0s 21ms/step - loss: 0.0034 - val_loss: 0.0028


Epoch 28/100
4/4  0s 21ms/step - loss: 0.0034 - val_loss: 0.0027


Epoch 29/100
4/4  0s 23ms/step - loss: 0.0031 - val_loss: 0.0027


Epoch 30/100
4/4  0s 23ms/step - loss: 0.0036 - val_loss: 0.0027


Epoch 31/100
4/4  0s 22ms/step - loss: 0.0034 - val_loss: 0.0027


Epoch 32/100
4/4  0s 22ms/step - loss: 0.0037 - val_loss: 0.0026


Epoch 33/100
4/4  0s 23ms/step - loss: 0.0033 - val_loss: 0.0028


Epoch 34/100
4/4  0s 23ms/step - loss: 0.0028 - val_loss: 0.0031


Epoch 35/100
4/4  0s 23ms/step - loss: 0.0036 - val_loss: 0.0024


Epoch 36/100
4/4  0s 22ms/step - loss: 0.0033 - val_loss: 0.0023


Epoch 37/100
4/4  0s 23ms/step - loss: 0.0028 - val_loss: 0.0024


Epoch 38/100
4/4  0s 23ms/step - loss: 0.0029 - val_loss: 0.0023


Epoch 39/100
4/4  0s 22ms/step - loss: 0.0028 - val_loss: 0.0023


Epoch 40/100
4/4  0s 22ms/step - loss: 0.0030 - val_loss: 0.0023


Epoch 41/100
4/4  0s 23ms/step - loss: 0.0029 - val_loss: 0.0022


Epoch 42/100
4/4  0s 23ms/step - loss: 0.0030 - val_loss: 0.0023


Epoch 43/100
4/4  0s 22ms/step - loss: 0.0027 - val_loss: 0.0022


Epoch 44/100
4/4  0s 22ms/step - loss: 0.0026 - val_loss: 0.0022


Epoch 45/100
4/4  0s 23ms/step - loss: 0.0028 - val_loss: 0.0022



























Epoch 46/100
4/4  0s 23ms/step - loss: 0.0026 - val_loss: 0.0025

Epoch 47/100
4/4  0s 22ms/step - loss: 0.0029 - val_loss: 0.0024

Epoch 48/100
4/4  0s 22ms/step - loss: 0.0027 - val_loss: 0.0021

Epoch 49/100
4/4  0s 21ms/step - loss: 0.0028 - val_loss: 0.0022

Epoch 50/100
4/4  0s 23ms/step - loss: 0.0026 - val_loss: 0.0022

Epoch 50/100				
4/4		0s 23ms/step	- loss: 0.0026	- val_loss: 0.0022
Epoch 51/100				
4/4		0s 23ms/step	- loss: 0.0025	- val_loss: 0.0021
Epoch 52/100				
4/4		0s 25ms/step	- loss: 0.0025	- val_loss: 0.0021
Epoch 53/100				
4/4		0s 23ms/step	- loss: 0.0022	- val_loss: 0.0021
Epoch 54/100				
4/4		0s 23ms/step	- loss: 0.0024	- val_loss: 0.0024
Epoch 55/100				
4/4		0s 22ms/step	- loss: 0.0030	- val_loss: 0.0023
Epoch 56/100				
4/4		0s 23ms/step	- loss: 0.0029	- val_loss: 0.0023
Epoch 57/100				
4/4		0s 23ms/step	- loss: 0.0025	- val_loss: 0.0024
Epoch 58/100				
4/4		0s 23ms/step	- loss: 0.0031	- val_loss: 0.0021
Epoch 59/100				
4/4		0s 24ms/step	- loss: 0.0027	- val_loss: 0.0027
Epoch 60/100				
4/4		0s 23ms/step	- loss: 0.0036	- val_loss: 0.0021
Epoch 61/100				
4/4		0s 23ms/step	- loss: 0.0022	- val_loss: 0.0020
Epoch 62/100				
4/4		0s 23ms/step	- loss: 0.0022	- val_loss: 0.0020
Epoch 63/100				
4/4		0s 23ms/step	- loss: 0.0023	- val_loss: 0.0019
Epoch 64/100				
4/4		0s 23ms/step	- loss: 0.0022	- val_loss: 0.0021
Epoch 65/100				
4/4		0s 23ms/step	- loss: 0.0024	- val_loss: 0.0019
Epoch 66/100				
4/4		0s 23ms/step	- loss: 0.0023	- val_loss: 0.0021
Epoch 67/100				
4/4		0s 23ms/step	- loss: 0.0024	- val_loss: 0.0028
Epoch 68/100				
4/4		0s 22ms/step	- loss: 0.0035	- val_loss: 0.0026
Epoch 69/100				
4/4		0s 23ms/step	- loss: 0.0032	- val_loss: 0.0020
Epoch 70/100				
4/4		0s 23ms/step	- loss: 0.0022	- val_loss: 0.0021
Epoch 71/100				
4/4		0s 23ms/step	- loss: 0.0024	- val_loss: 0.0022
Epoch 72/100				
4/4		0s 23ms/step	- loss: 0.0026	- val_loss: 0.0017
Epoch 73/100				
4/4		0s 23ms/step	- loss: 0.0022	- val_loss: 0.0018
Epoch 74/100				
4/4		0s 22ms/step	- loss: 0.0021	- val_loss: 0.0018
Epoch 75/100				
4/4		0s 26ms/step	- loss: 0.0022	- val loss: 0.0023


```

4/4 ————— 0s 22ms/step - loss: 0.0021 - val_loss: 0.0016
Epoch 75/100
4/4 ————— 0s 26ms/step - loss: 0.0022 - val_loss: 0.0023
Epoch 76/100
4/4 ————— 0s 27ms/step - loss: 0.0029 - val_loss: 0.0025
Epoch 77/100
4/4 ————— 0s 23ms/step - loss: 0.0029 - val_loss: 0.0018
Epoch 78/100
4/4 ————— 0s 24ms/step - loss: 0.0021 - val_loss: 0.0017
Epoch 79/100
4/4 ————— 0s 23ms/step - loss: 0.0020 - val_loss: 0.0016
Epoch 80/100
4/4 ————— 0s 22ms/step - loss: 0.0021 - val_loss: 0.0017
Epoch 81/100
4/4 ————— 0s 23ms/step - loss: 0.0021 - val_loss: 0.0017
Epoch 82/100
4/4 ————— 0s 24ms/step - loss: 0.0019 - val_loss: 0.0027
Epoch 83/100
4/4 ————— 0s 26ms/step - loss: 0.0030 - val_loss: 0.0022
Epoch 84/100
4/4 ————— 0s 26ms/step - loss: 0.0029 - val_loss: 0.0023
Epoch 85/100
4/4 ————— 0s 25ms/step - loss: 0.0023 - val_loss: 0.0021
Epoch 86/100
4/4 ————— 0s 24ms/step - loss: 0.0027 - val_loss: 0.0022
Epoch 87/100
4/4 ————— 0s 25ms/step - loss: 0.0023 - val_loss: 0.0018
Epoch 88/100
4/4 ————— 0s 23ms/step - loss: 0.0022 - val_loss: 0.0018
Epoch 89/100
4/4 ————— 0s 23ms/step - loss: 0.0021 - val_loss: 0.0016
Epoch 90/100
4/4 ————— 0s 24ms/step - loss: 0.0019 - val_loss: 0.0015
Epoch 91/100
4/4 ————— 0s 23ms/step - loss: 0.0019 - val_loss: 0.0016
Epoch 92/100
4/4 ————— 0s 24ms/step - loss: 0.0021 - val_loss: 0.0017
Epoch 93/100
4/4 ————— 0s 25ms/step - loss: 0.0019 - val_loss: 0.0017
Epoch 94/100
4/4 ————— 0s 25ms/step - loss: 0.0020 - val_loss: 0.0018
Epoch 95/100
4/4 ————— 0s 22ms/step - loss: 0.0021 - val_loss: 0.0014
Epoch 96/100
4/4 ————— 0s 22ms/step - loss: 0.0019 - val_loss: 0.0023
Epoch 97/100
4/4 ————— 0s 29ms/step - loss: 0.0032 - val_loss: 0.0017
Epoch 98/100
4/4 ————— 0s 33ms/step - loss: 0.0024 - val_loss: 0.0017
Epoch 99/100
4/4 ————— 0s 43ms/step - loss: 0.0019 - val_loss: 0.0015
Epoch 100/100
4/4 ————— 0s 39ms/step - loss: 0.0016 - val_loss: 0.0016
: <keras.src.callbacks.history.History at 0x18b0197b9e0>

```

#Predict and Evaluation

```
train_predict = model.predict(X_train)
```

```
test_predict = model.predict(X_test)
```

#Inverse transform to get the actual values

```
train_predict = scaler.inverse_transform(train_predict)
```

```

test_predict = scaler.inverse_transform(test_predict)
#Y_train = scaler.inverse_transform([Y_train])
#Y_test = scaler.inverse_transform([Y_test])
Y_train = scaler.inverse_transform(Y_train.reshape(-1, 1))
Y_test = scaler.inverse_transform(Y_test.reshape(-1, 1))

# Calculate RMSE

train_rmse = np.sqrt(mean_squared_error(Y_train, train_predict[:,0]))
test_rmse = np.sqrt(mean_squared_error(Y_test, test_predict[:,0]))

print(f'Train RMSE: {train_rmse}')
print(f'Train RMSE: {test_rmse}')

```

```

4/4 ————— 0s 8ms/step
1/1 ————— 0s 41ms/step
Train RMSE: 21.52355107828995
Train RMSE: 20.813798677468384

```

#Compare with a Traditional Time Series Model (ARIMA)

```
from statsmodels.tsa.arima.model import ARIMA
```

Fit the ARIMA model

```
model_arima = ARIMA(df, order=(5,1,0))
```

```
model_arima_fit = model_arima.fit()
```

#Forecast

```
arima_pred = model_arima_fit.forecast(steps=len(X_test))
```

#Calculate RMSE for ARIMA

```
arima_rmse = np.sqrt(mean_squared_error(df[-len(arima_pred):], arima_pred))
```

```
print(f'ARIMA RMSE: {arima_rmse}')
```

```
ARIMA RMSE: 96.63626284391589
```

#Visualization : RNN Predications vs. Actual Vlues

```
plt.figure(figsize=(12,6))
```

```
#plot the actual data
```

```
plt.plot(df, label='Actual', color='blue')
```

```
#Plot the training predictions
```

```
plt.plot(range(time_step, time_step + len(train_predict)), train_predict, color='green', label='Train Predictions')
```

```
#Plot the testing predictions
```

```
plt.plot(range(len(df) - len(test_predict), len(df)), test_predict, color='green', label='Train Predictions')
```

```
#Plot the testing predictions
```

```
plt.plot(range(len(df) - len(test_predict), len(df)), test_predict, color='red', label='Test Predictions')
```

```
plt.legend()
```

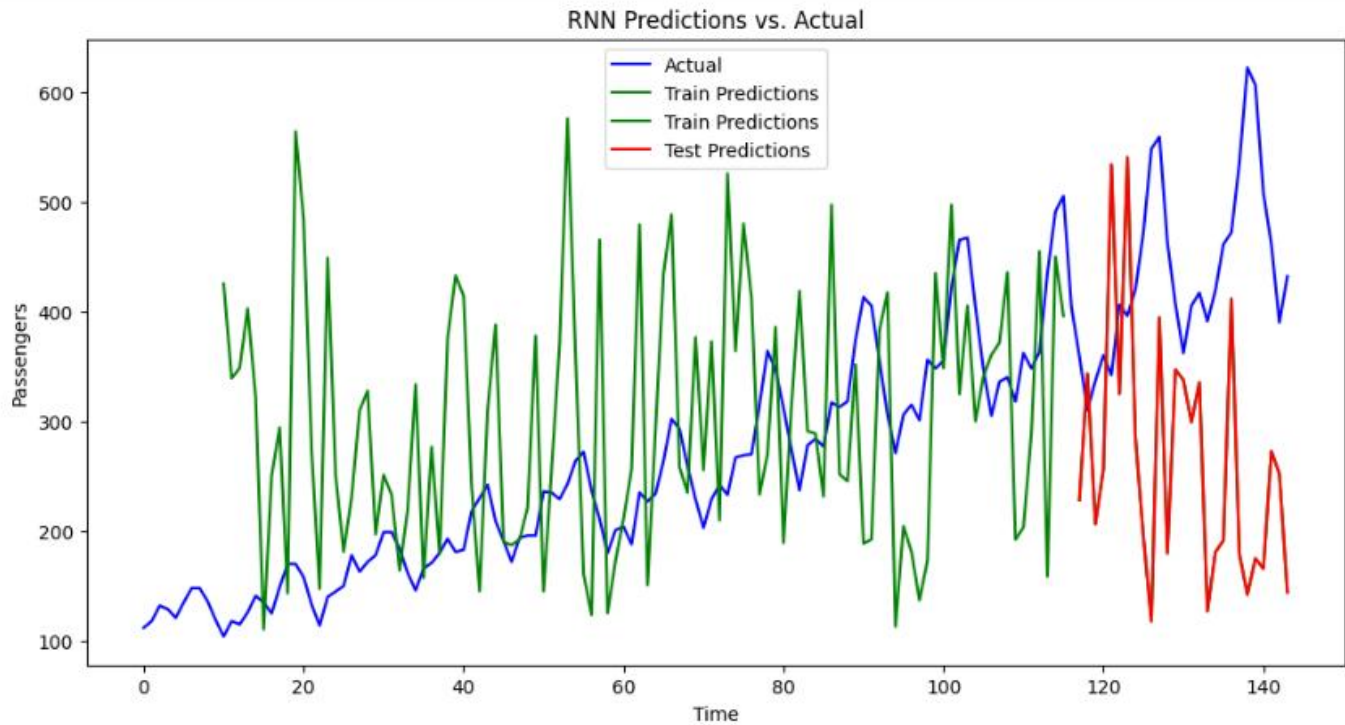
```
plt.title('RNN Predictions vs. Actual')
```

```
plt.xlabel('Time')
```

```
plt.ylabel('Passengers')
```

```
plt.show()
```

```
print("Gayatri Kulkarni - 53004230002")
```



Gayatri Kulkarni - 53004230002

Practical 7

Aim: Implement a sequence-to-sequence model for machine translation using RNNs or Transformer architecture.

Train the model on a dataset and evaluate its performance using appropriate metrics.

Explore attention mechanisms and their role in improving sequence-to-sequence models

```
import tensorflow as tf
```

```
import numpy as np
```

```
import matplotlib.pyplot as plt
```

```
import os
```

```
import zipfile
```

```
from tensorflow.keras.preprocessing.image import ImageDataGenerator
```

```
from tensorflow.keras.applications import VGG16
```

```
#Download
```

```
url = "https://storage.googleapis.com/mledu-datasets/cats\_and\_dogs\_filtered.zip"
```

```
#filename = os.path.join(os.getcwd(), "cats_and_dogs_filtered.zip")
```

```
cache_dir = os.getcwd()
```



```

filename = "cats_and_dogs_filtered.zip"
file_path = tf.keras.utils.get_file(fname=filename, origin=url, cache_dir=cache_dir, extract=False)
tf.keras.utils.get_file(filename, url)

#with zipfile.ZipFile("cats_and_dogs_filtered.zip", "r") as zip_ref:
    # zip_ref.extractall()

with zipfile.ZipFile(file_path, "r") as zip_ref:
    zip_ref.extractall()

#define
train_dir = os.path.join(os.getcwd(), "cats_and_dogs_filtered", "train")
validation_dir = os.path.join(os.getcwd(), "cats_and_dogs_filtered", "validation")


train_datagen = ImageDataGenerator(rescale=1./255,
                                   rotation_range=20,
                                   width_shift_range=0.2,
                                   height_shift_range=0.2,
                                   shear_range=0.2,
                                   zoom_range=0.2,
                                   horizontal_flip=True)

validation_datagen = ImageDataGenerator(rescale=1./255)


train_generator = train_datagen.flow_from_directory(train_dir,
                                                    target_size=(150,150),
                                                    batch_size=20,
                                                    class_mode="binary")

validation_generator = validation_datagen.flow_from_directory(validation_dir,
                                                            target_size=(150,150),
                                                            batch_size=20,
                                                            class_mode="binary")


#Load
conv_base = VGG16(weights="imagenet",
                  include_top=False,

```

```

        input_shape=(150, 150, 3))

#freeze
conv_base.trainable = False

#build
model = tf.keras.models.Sequential()
model.add(conv_base)
model.add(tf.keras.layers.Flatten())
model.add(tf.keras.layers.Dense(256, activation="relu"))
model.add(tf.keras.layers.Dropout(0.5))
model.add(tf.keras.layers.Dense(1, activation="sigmoid"))

#compile
model.compile(loss="binary_crossentropy",
              optimizer=tf.keras.optimizers.RMSprop(learning_rate=2e-5),
              metrics=["accuracy"])

#train
history = model.fit(train_generator,
                    steps_per_epoch=100,
                    epochs=30,
                    validation_data=validation_generator,
                    validation_steps=50)

#show
x, y_true = next(validation_generator)
y_pred = model.predict(x)
class_names = ['cat', 'dog']
for i in range(len(x)):
    plt.imshow(x[i])
    plt.title(f'Predicted class: {class_names[int(round(y_pred[i][0]))]}, True class: {class_names[int(y_true[i])]}')
    plt.show()

#plot
acc = history.history["accuracy"]
val_acc = history.history["val_accuracy"]

```

```
loss = history.history["loss"]  
val_loss = history.history["val_loss"]
```

```
epochs = range(1, len(acc) + 1)
```

```
plt.plot(epochs, acc, "bo", label="Training acc")  
plt.plot(epochs, val_acc, "b", label="Validation acc")  
plt.title("Training and validation accuracy")  
plt.legend()
```

```
plt.figure()  
plt.plot(epochs, loss, "bo", label="Training loss")  
plt.plot(epochs, val_loss, "b", label="Validation loss")  
plt.title("Training and validation loss")  
plt.legend()
```

```
plt.show()  
print("Gayatri kulkarni-53004230002")
```

Found 2000 images belonging to 2 classes.

Found 1000 images belonging to 2 classes.

Epoch 1/30

100/100 — 193s 2s/step - accuracy: 0.5729 - loss: 0.7041 - val_accuracy: 0.8090 - val_loss: 0.4944

Epoch 2/30

100/100 — 188s 2s/step - accuracy: 0.6999 - loss: 0.5629 - val_accuracy: 0.8300 - val_loss: 0.4217

Epoch 3/30

100/100 — 124s 1s/step - accuracy: 0.7726 - loss: 0.4817 - val_accuracy: 0.8280 - val_loss: 0.3885

Epoch 4/30

100/100 — 127s 1s/step - accuracy: 0.7806 - loss: 0.4596 - val_accuracy: 0.8470 - val_loss: 0.3512

Epoch 5/30

100/100 — 128s 1s/step - accuracy: 0.8122 - loss: 0.4338 - val_accuracy: 0.8610 - val_loss: 0.3313

Epoch 6/30

100/100 — 129s 1s/step - accuracy: 0.8047 - loss: 0.4178 - val_accuracy: 0.8620 - val_loss: 0.3181

Epoch 7/30

100/100 — 130s 1s/step - accuracy: 0.8153 - loss: 0.3823 - val_accuracy: 0.8690 - val_loss: 0.3064

Epoch 8/30

100/100 — 130s 1s/step - accuracy: 0.8443 - loss: 0.3569 - val_accuracy: 0.8720 - val_loss: 0.2975

Epoch 9/30

100/100 — 132s 1s/step - accuracy: 0.8293 - loss: 0.3777 - val_accuracy: 0.8690 - val_loss: 0.3025

Epoch 10/30

100/100 — 131s 1s/step - accuracy: 0.8446 - loss: 0.3544 - val_accuracy: 0.8730 - val_loss: 0.2888

Epoch 11/30

100/100 — 132s 1s/step - accuracy: 0.8265 - loss: 0.3804 - val_accuracy: 0.8720 - val_loss: 0.2928

Epoch 12/30

100/100 — 132s 1s/step - accuracy: 0.8303 - loss: 0.3672 - val_accuracy: 0.8760 - val_loss: 0.2907

Epoch 13/30

100/100 — 131s 1s/step - accuracy: 0.8420 - loss: 0.3543 - val_accuracy: 0.8760 - val_loss: 0.2853

Epoch 14/30

100/100 — 132s 1s/step - accuracy: 0.8539 - loss: 0.3267 - val_accuracy: 0.8740 - val_loss: 0.2750

Epoch 15/30

100/100 — 131s 1s/step - accuracy: 0.8602 - loss: 0.3221 - val_accuracy: 0.8800 - val_loss: 0.2725

Epoch 16/30

100/100 — 133s 1s/step - accuracy: 0.8543 - loss: 0.3292 - val_accuracy: 0.8820 - val_loss: 0.2711

Epoch 17/30

100/100 — 131s 1s/step - accuracy: 0.8470 - loss: 0.3374 - val_accuracy: 0.8820 - val_loss: 0.2677

Epoch 18/30

Epoch 17/30

100/100 — 131s 1s/step - accuracy: 0.8470 - loss: 0.3374 - val_accuracy: 0.8820 - val_loss: 0.2677

Epoch 18/30

100/100 — 131s 1s/step - accuracy: 0.8481 - loss: 0.3185 - val_accuracy: 0.8790 - val_loss: 0.2696

Epoch 19/30

100/100 — 132s 1s/step - accuracy: 0.8702 - loss: 0.2956 - val_accuracy: 0.8830 - val_loss: 0.2718

Epoch 20/30

100/100 — 131s 1s/step - accuracy: 0.8602 - loss: 0.3240 - val_accuracy: 0.8850 - val_loss: 0.2736

Epoch 21/30

100/100 — 132s 1s/step - accuracy: 0.8687 - loss: 0.3232 - val_accuracy: 0.8720 - val_loss: 0.2729

Epoch 22/30

100/100 — 131s 1s/step - accuracy: 0.8595 - loss: 0.3172 - val_accuracy: 0.8810 - val_loss: 0.2626

Epoch 23/30

100/100 — 132s 1s/step - accuracy: 0.8659 - loss: 0.3095 - val_accuracy: 0.8870 - val_loss: 0.2676

Epoch 24/30

100/100 — 132s 1s/step - accuracy: 0.8739 - loss: 0.3086 - val_accuracy: 0.8840 - val_loss: 0.2647

Epoch 25/30

100/100 — 131s 1s/step - accuracy: 0.8902 - loss: 0.2802 - val_accuracy: 0.8810 - val_loss: 0.2597

Epoch 26/30

100/100 — 132s 1s/step - accuracy: 0.8800 - loss: 0.2985 - val_accuracy: 0.8800 - val_loss: 0.2595

Epoch 27/30

100/100 — 131s 1s/step - accuracy: 0.8613 - loss: 0.3291 - val_accuracy: 0.8860 - val_loss: 0.2603

Epoch 28/30

100/100 — 133s 1s/step - accuracy: 0.8743 - loss: 0.2973 - val_accuracy: 0.8840 - val_loss: 0.2567

Epoch 29/30

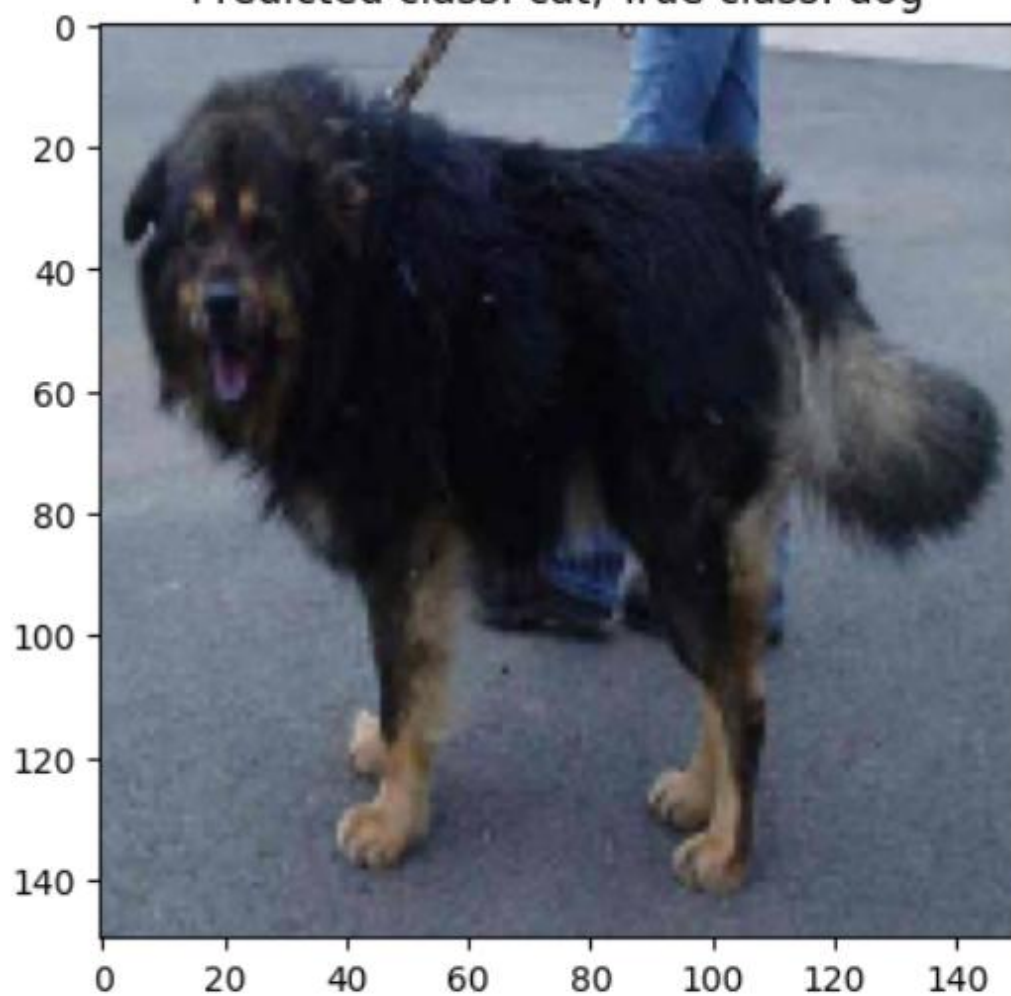
100/100 — 131s 1s/step - accuracy: 0.8615 - loss: 0.3243 - val_accuracy: 0.8830 - val_loss: 0.2552

Epoch 30/30

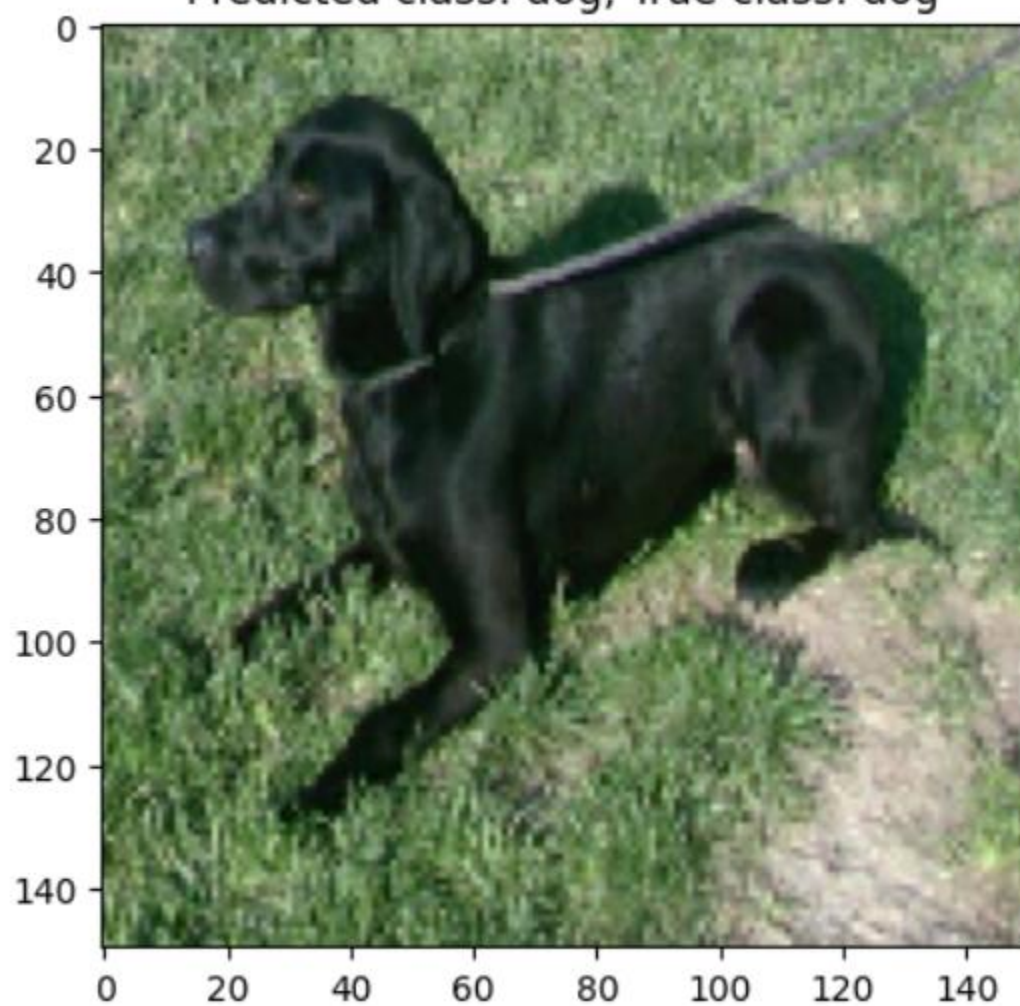
100/100 — 132s 1s/step - accuracy: 0.8827 - loss: 0.2882 - val_accuracy: 0.8830 - val_loss: 0.2548

1/1 — 1s 978ms/step

Predicted class: cat, True class: dog



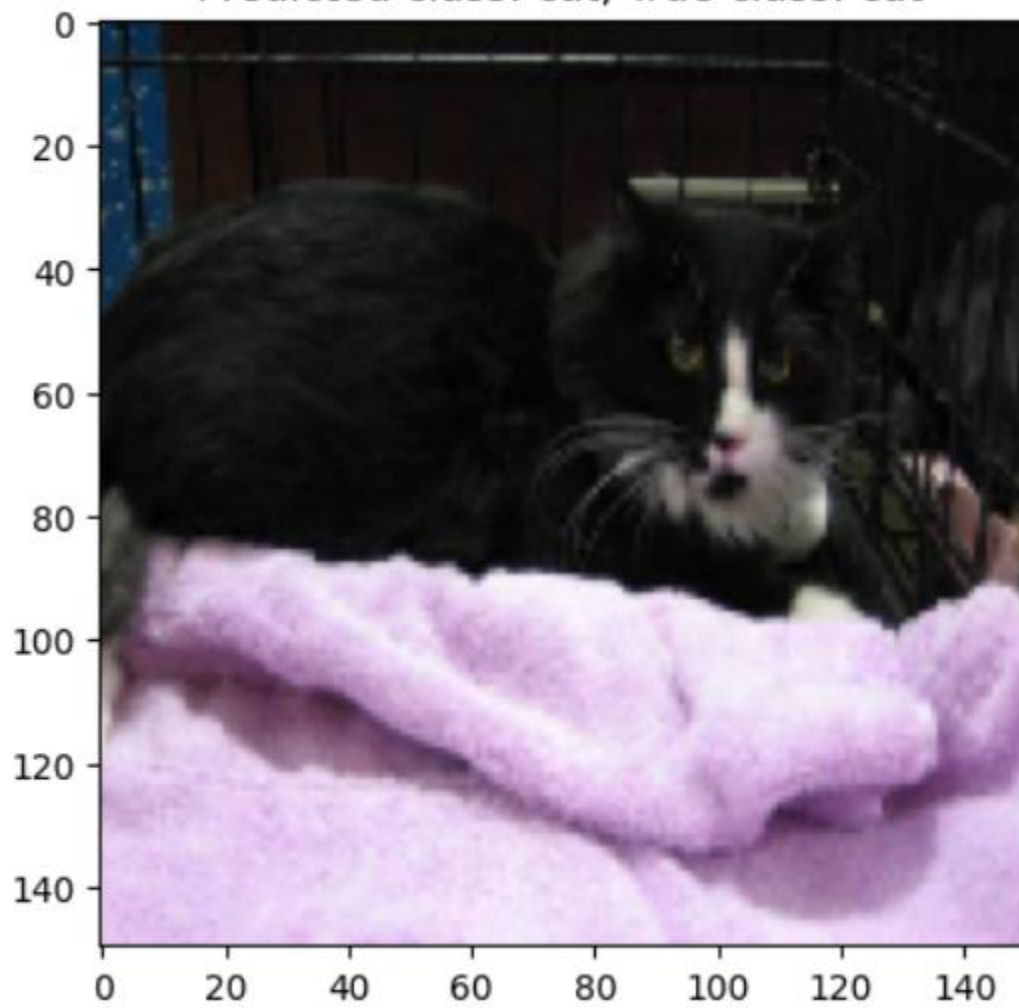
Predicted class: dog, True class: dog



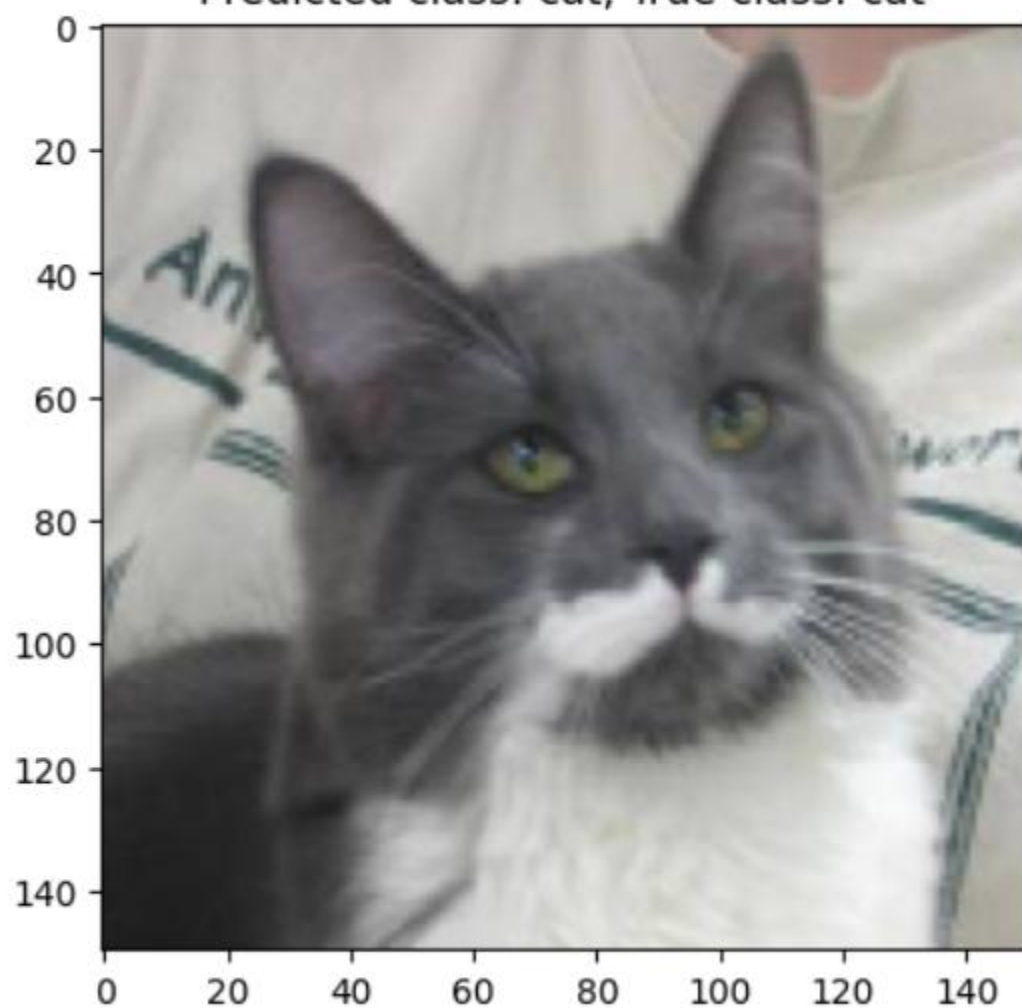
Predicted class: dog, True class: dog



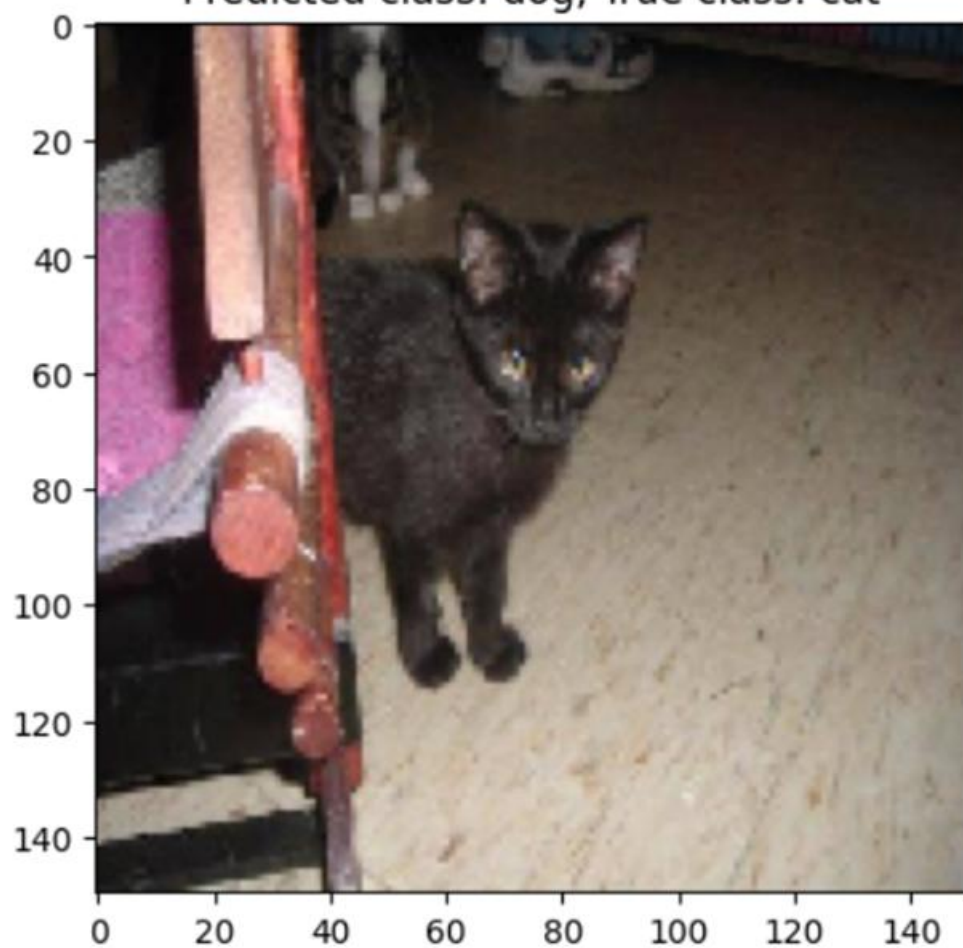
Predicted class: cat, True class: cat



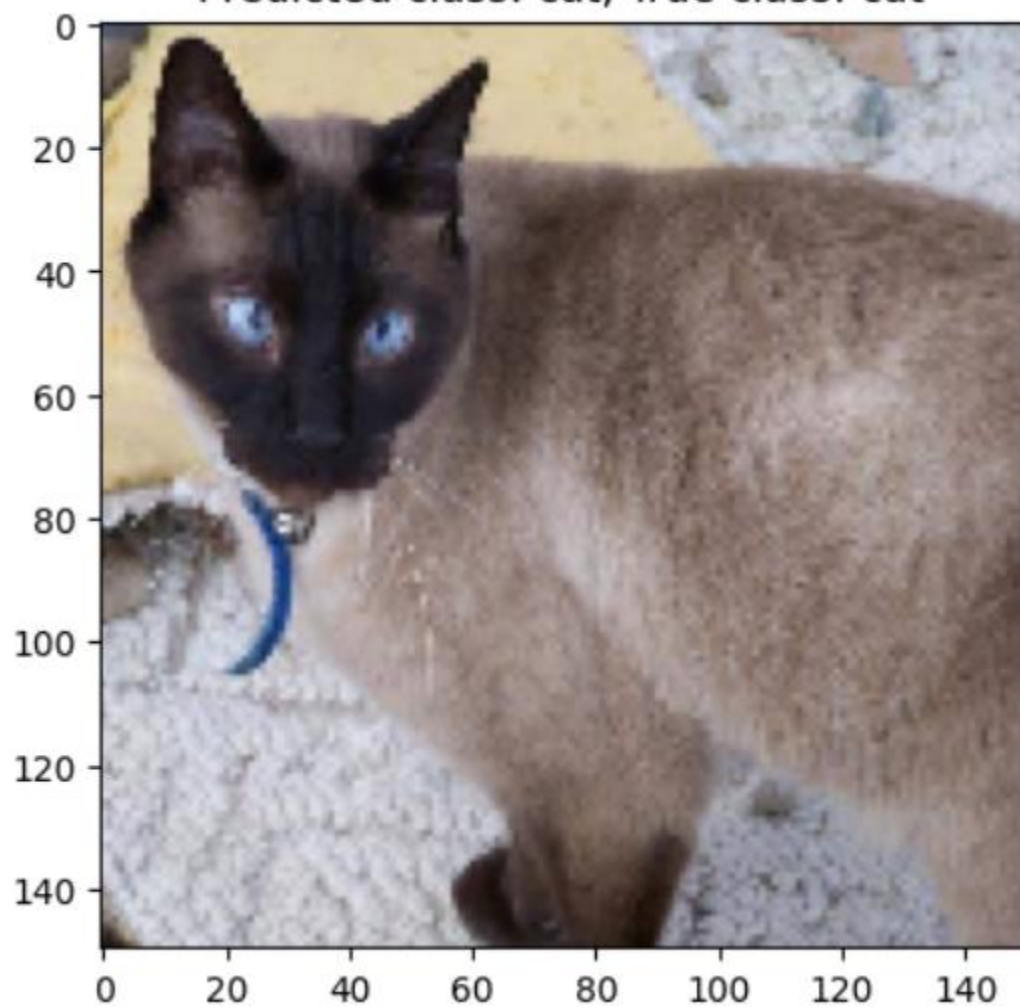
Predicted class: cat, True class: cat



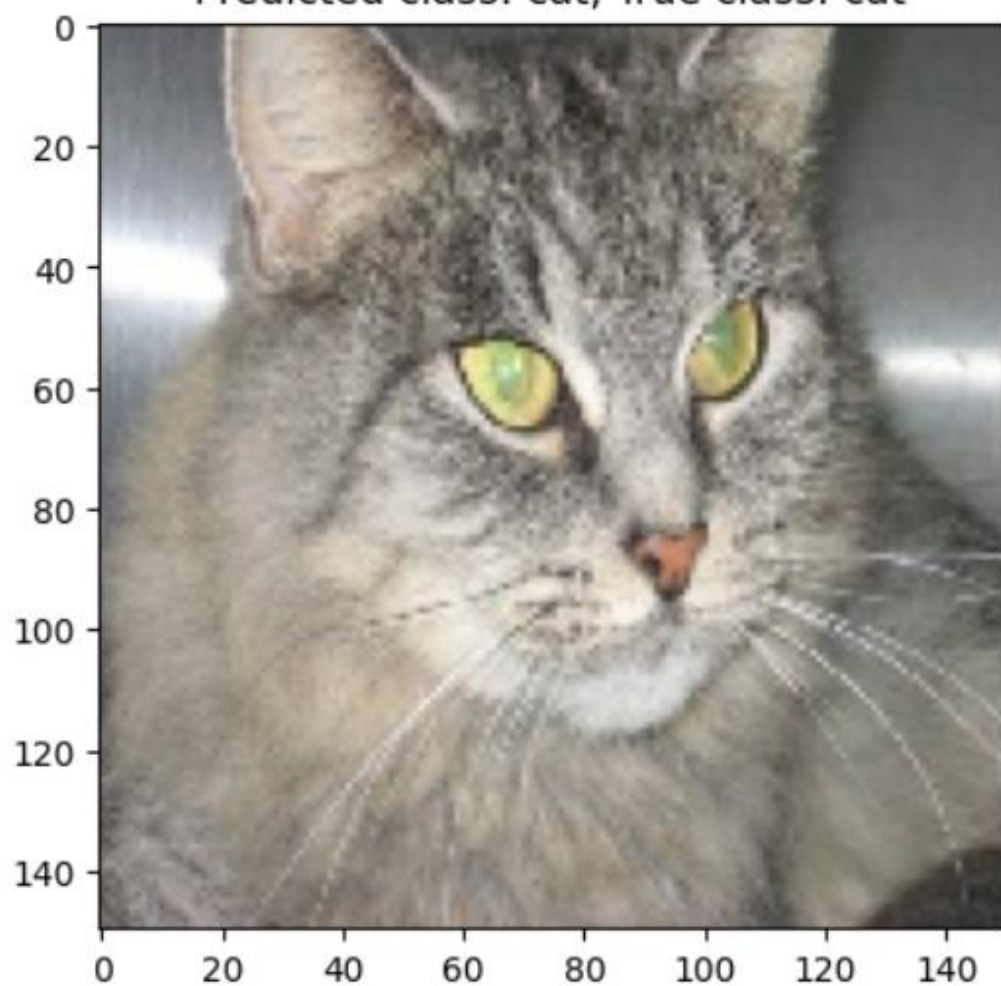
Predicted class: dog, True class: cat



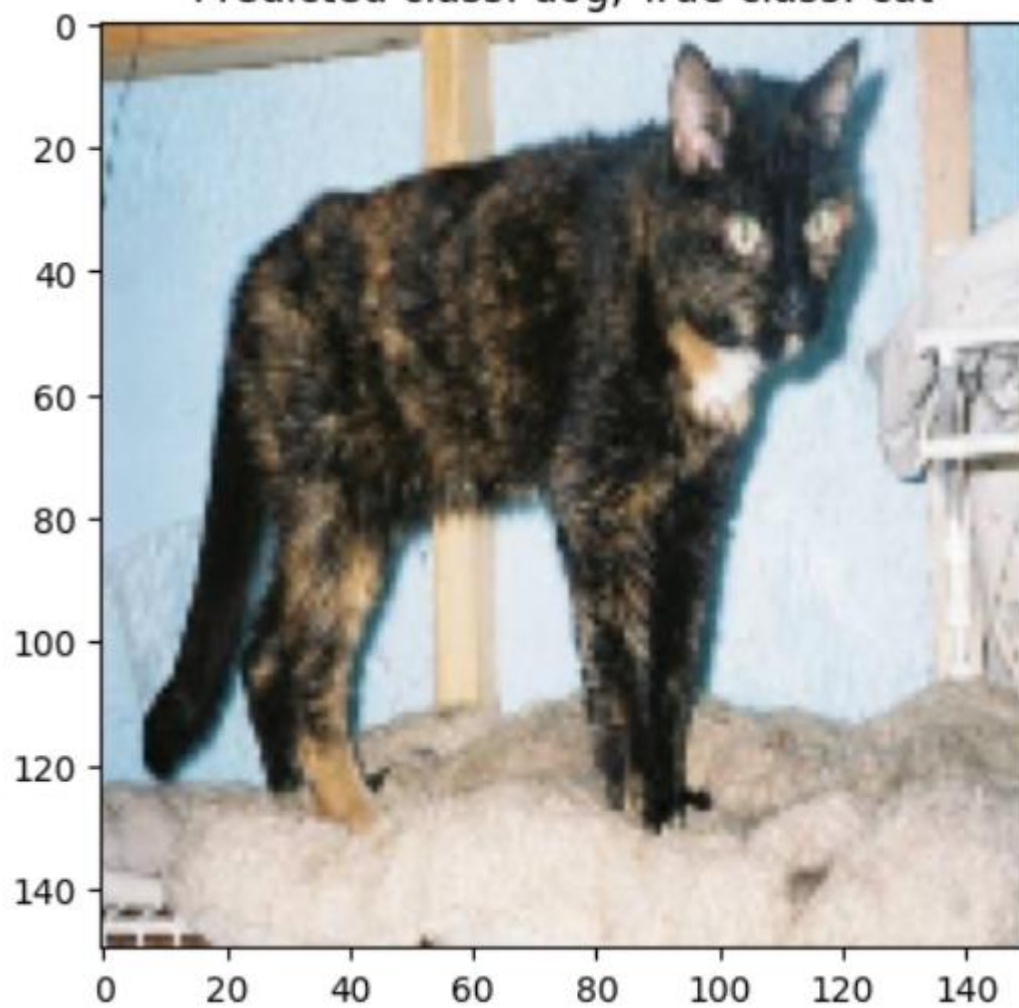
Predicted class: cat, True class: cat



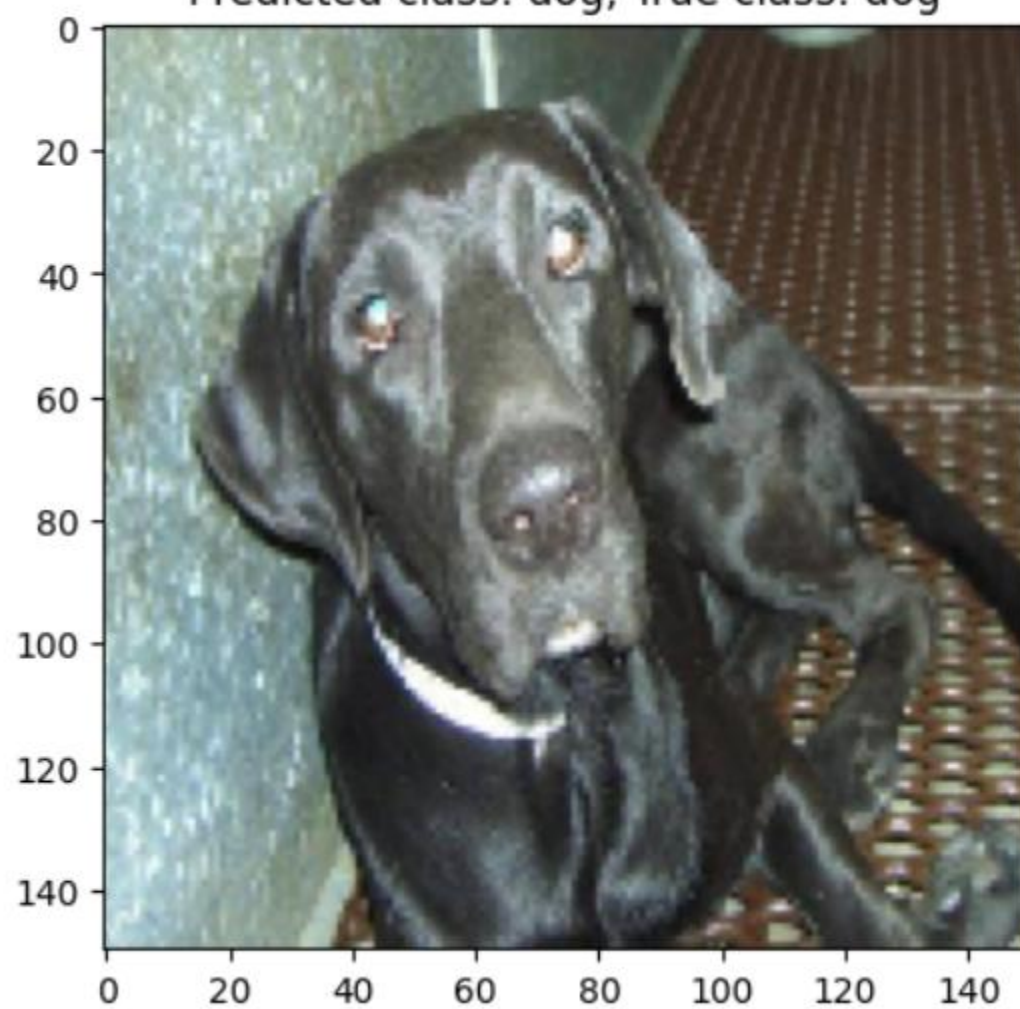
Predicted class: cat, True class: cat



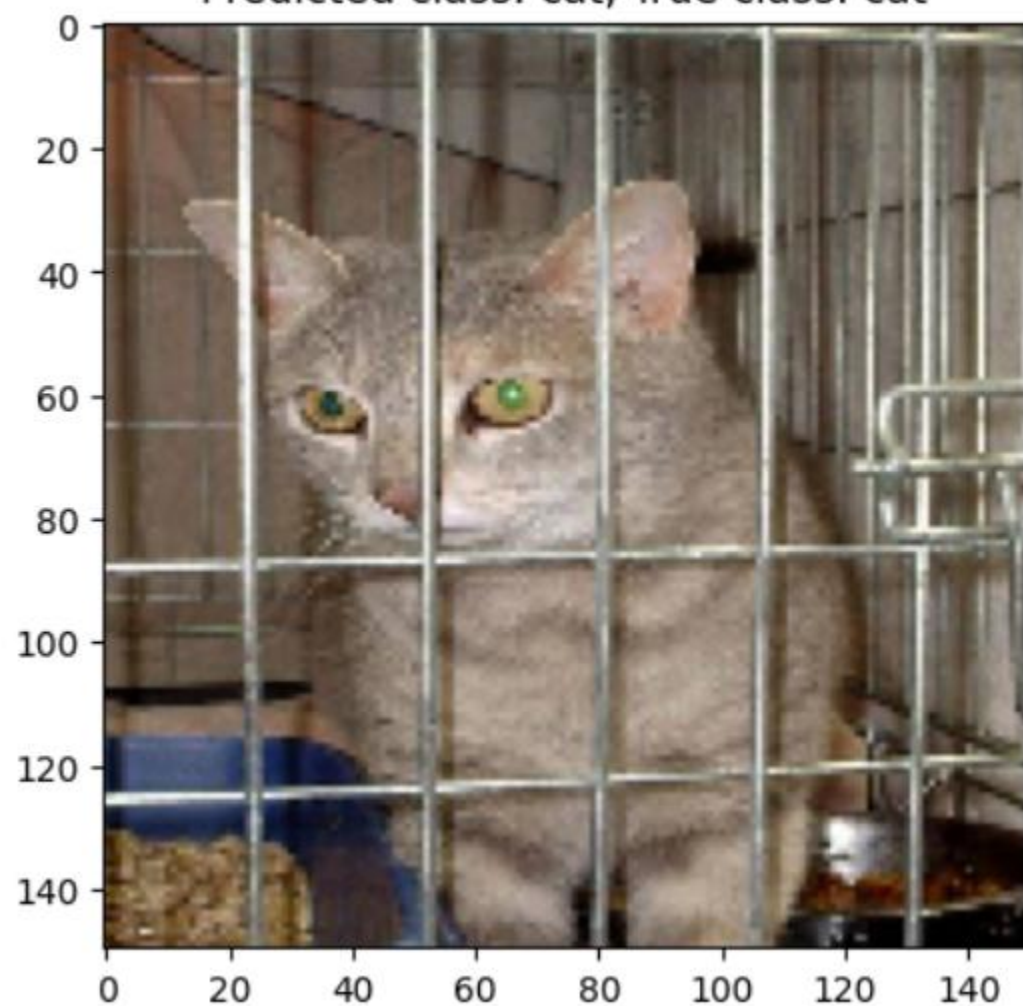
Predicted class: dog, True class: cat



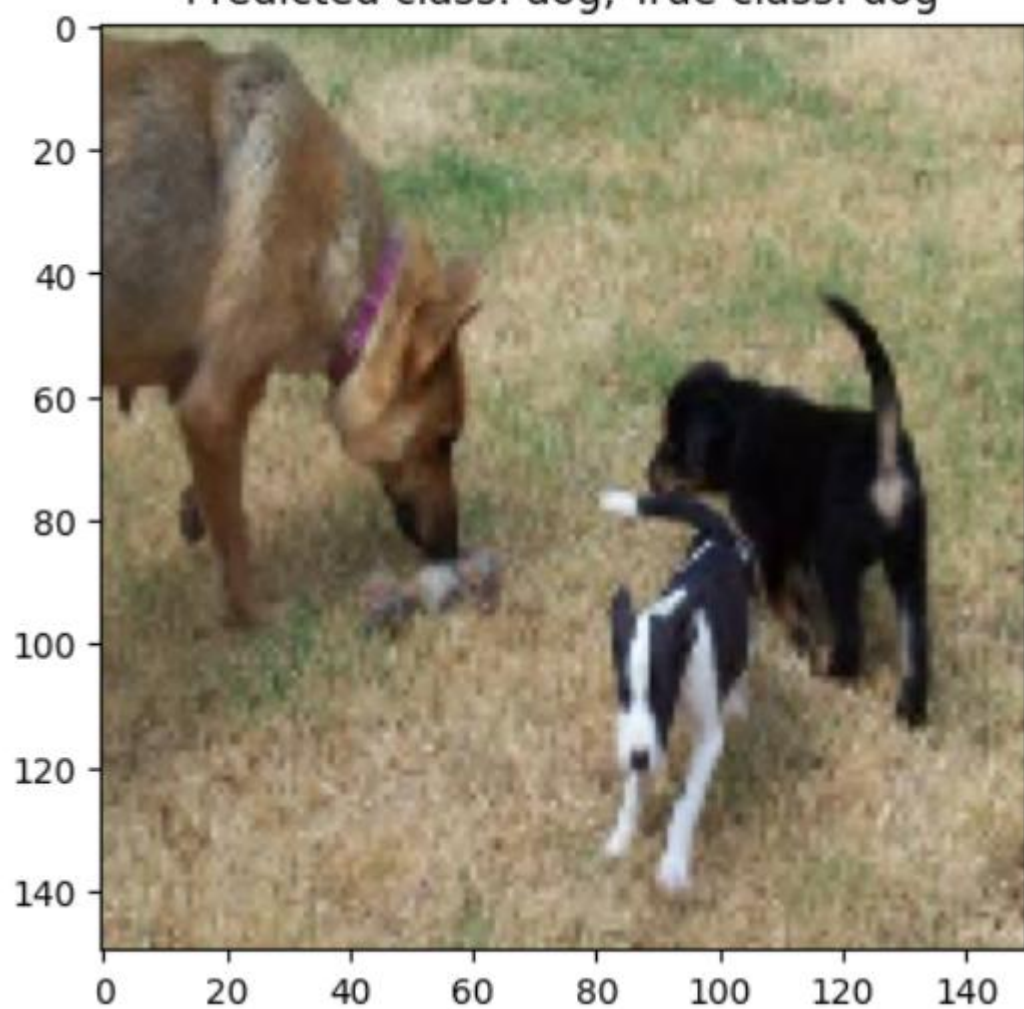
Predicted class: dog, True class: dog



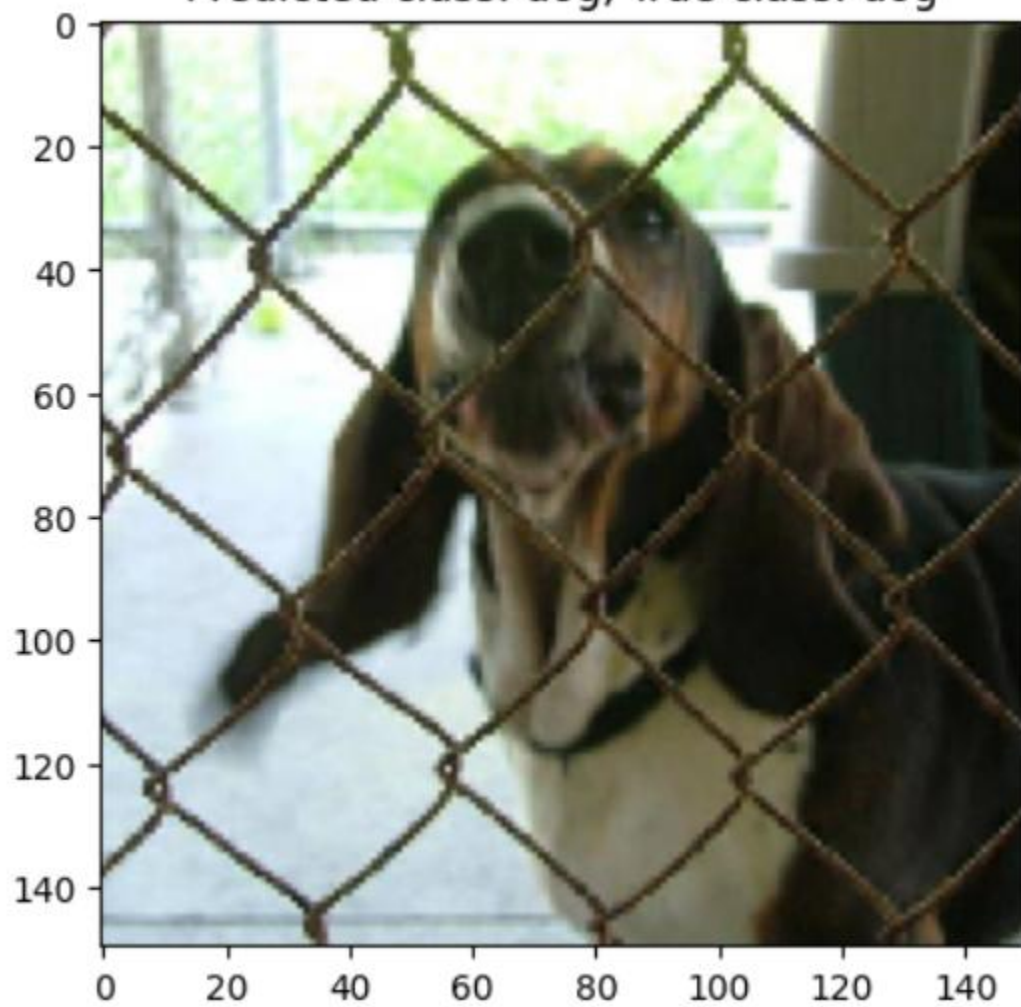
Predicted class: cat, True class: cat



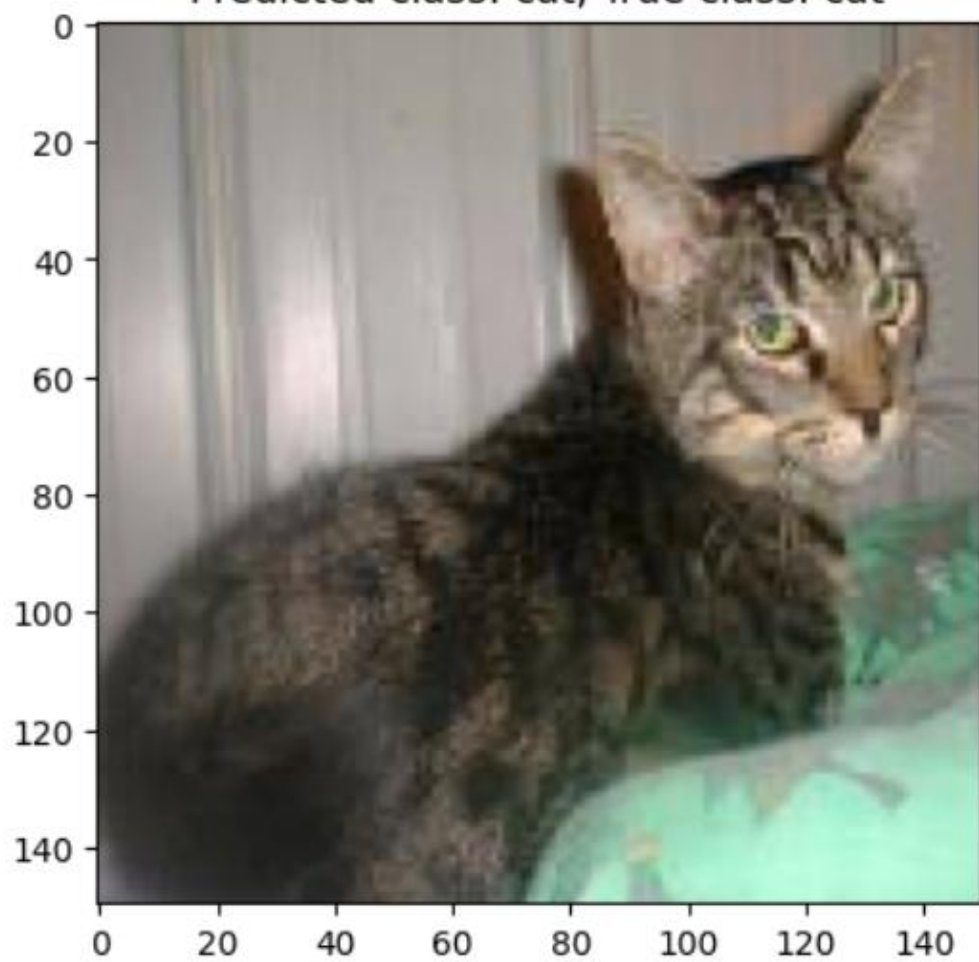
Predicted class: dog, True class: dog



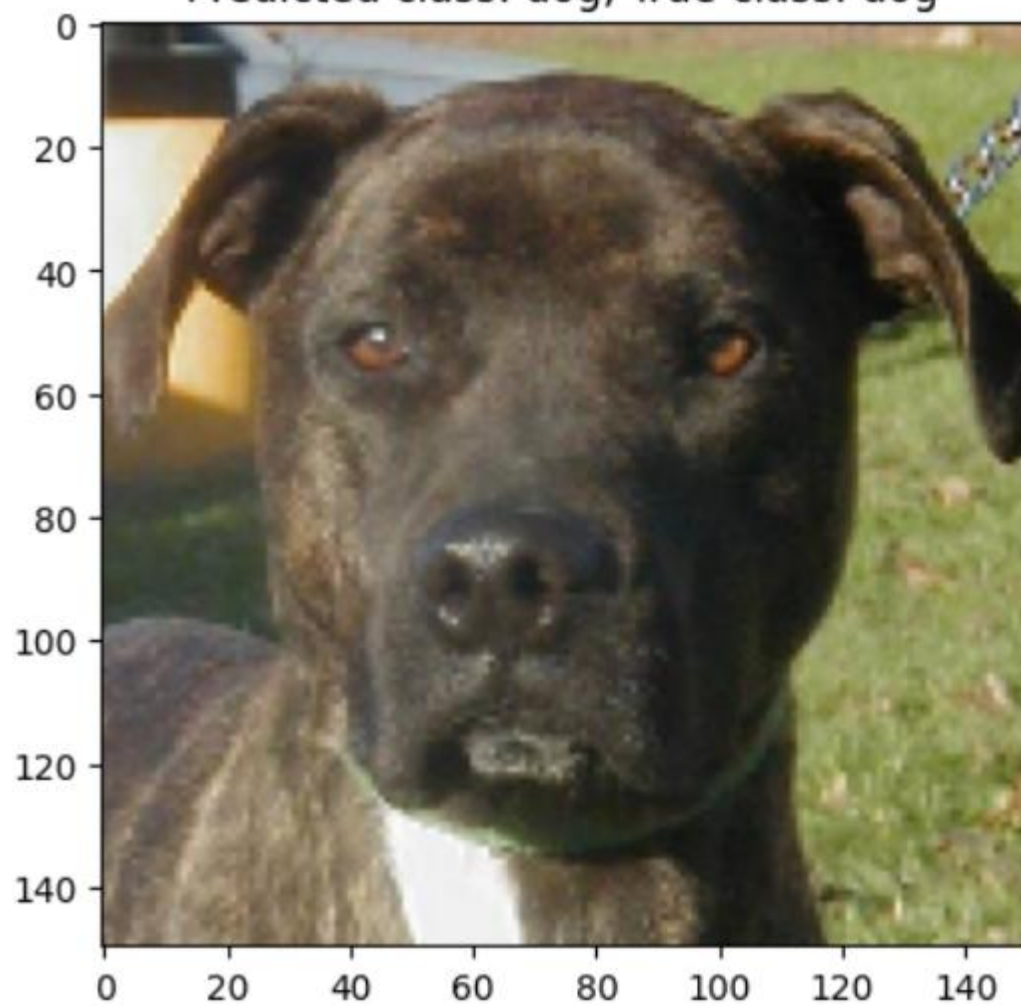
Predicted class: dog, True class: dog



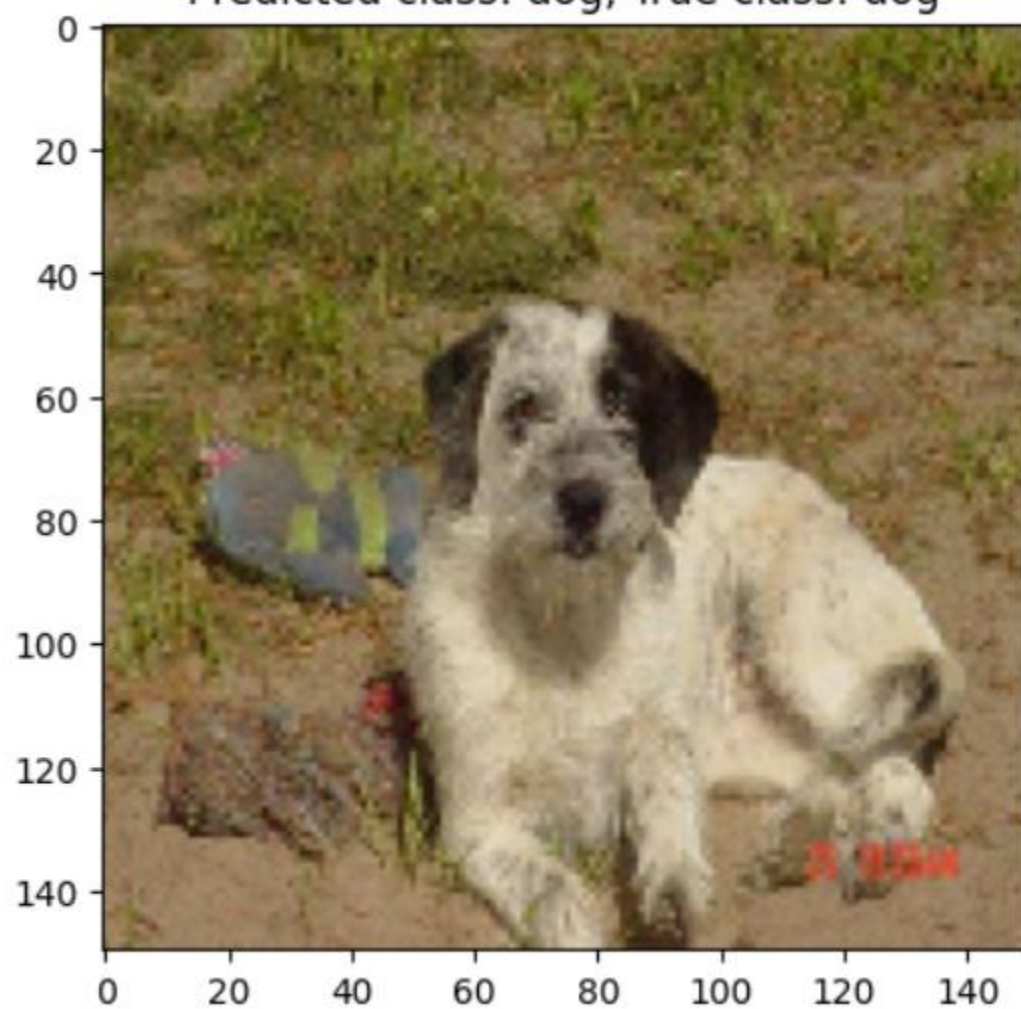
Predicted class: cat, True class: cat



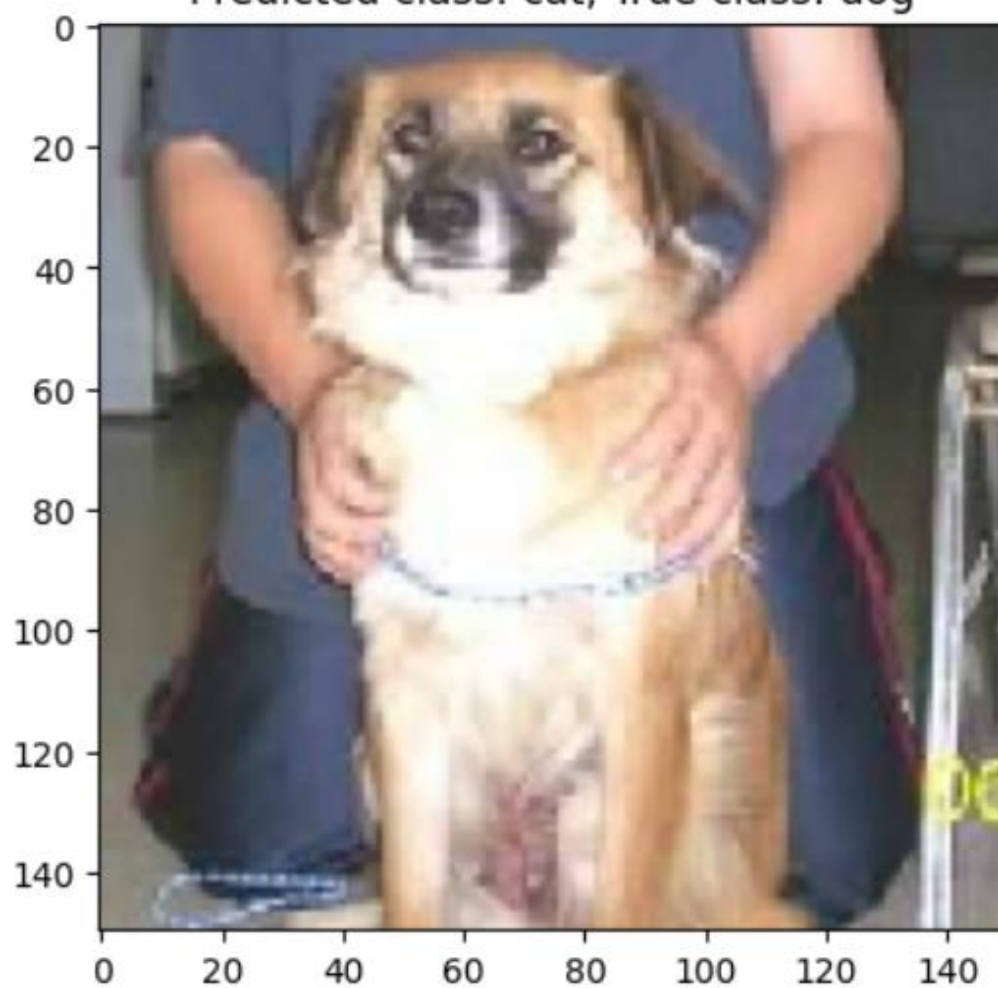
Predicted class: dog, True class: dog



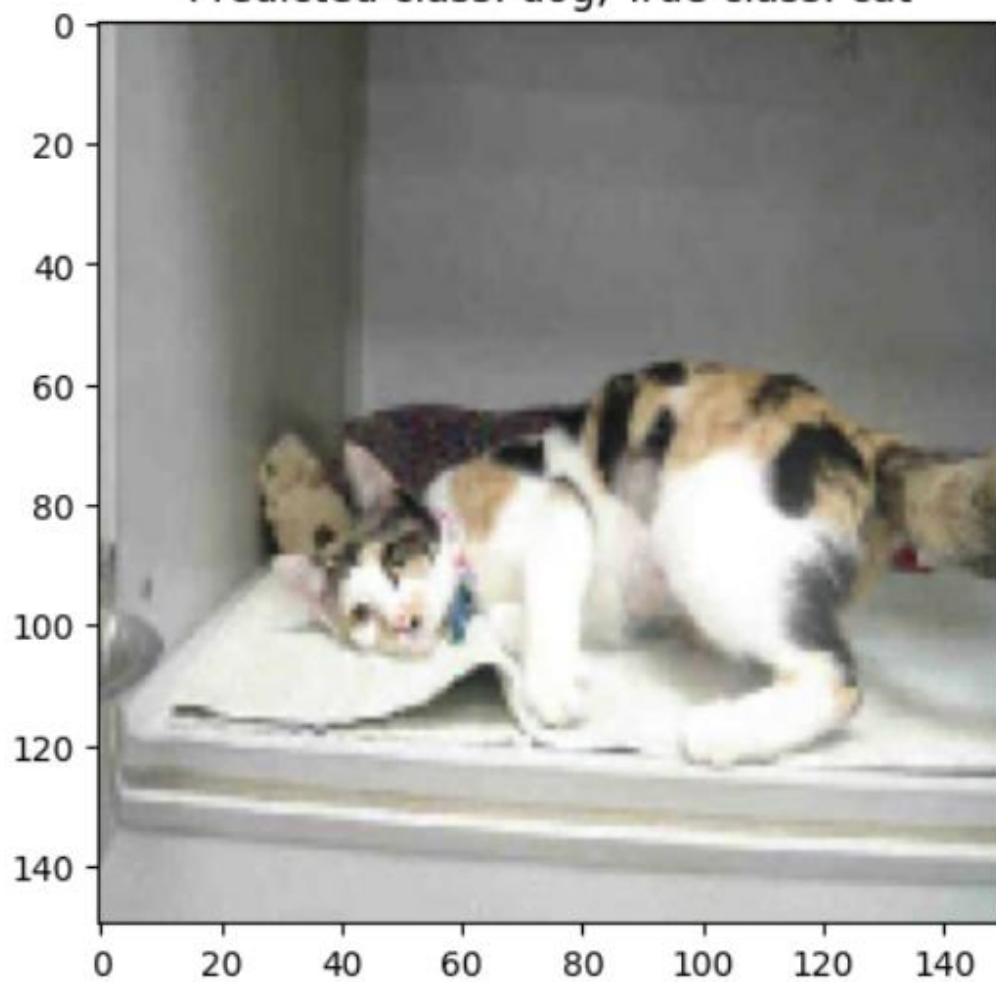
Predicted class: dog, True class: dog



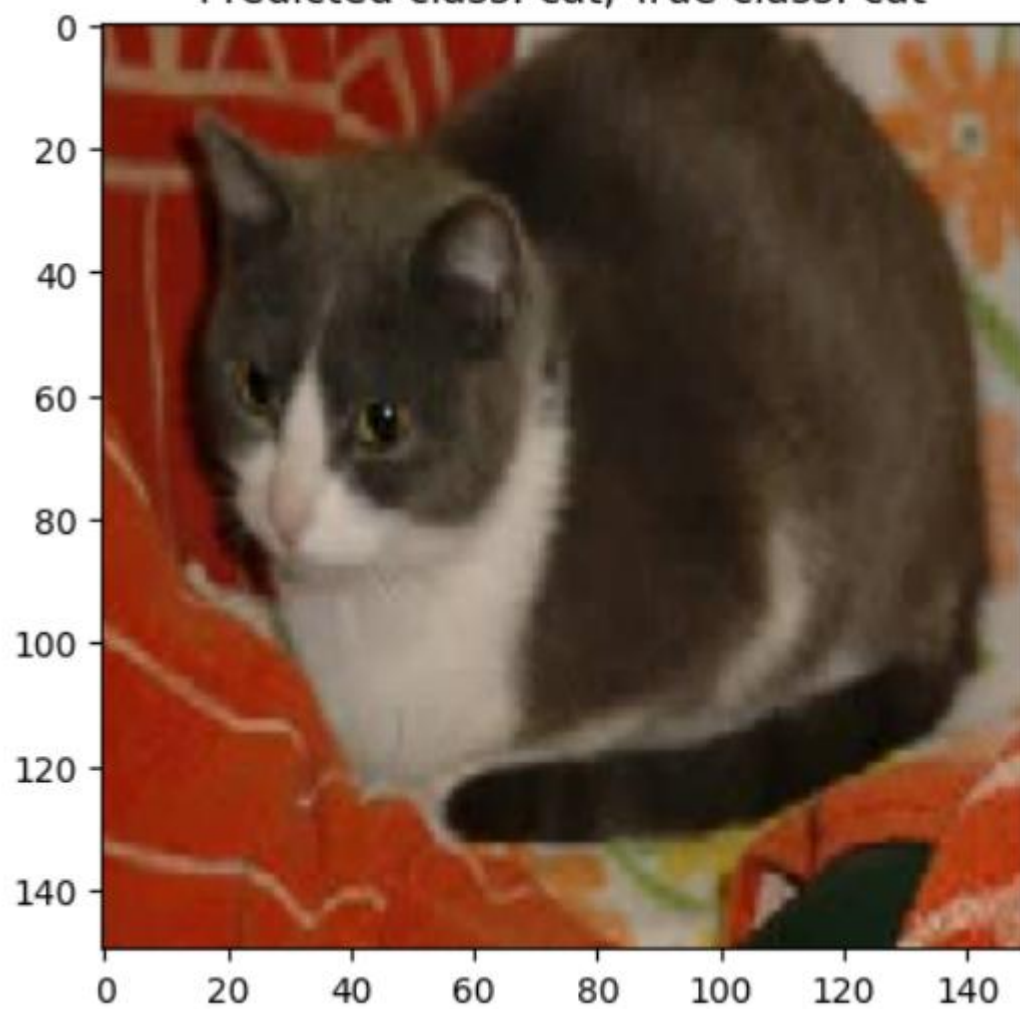
Predicted class: cat, True class: dog



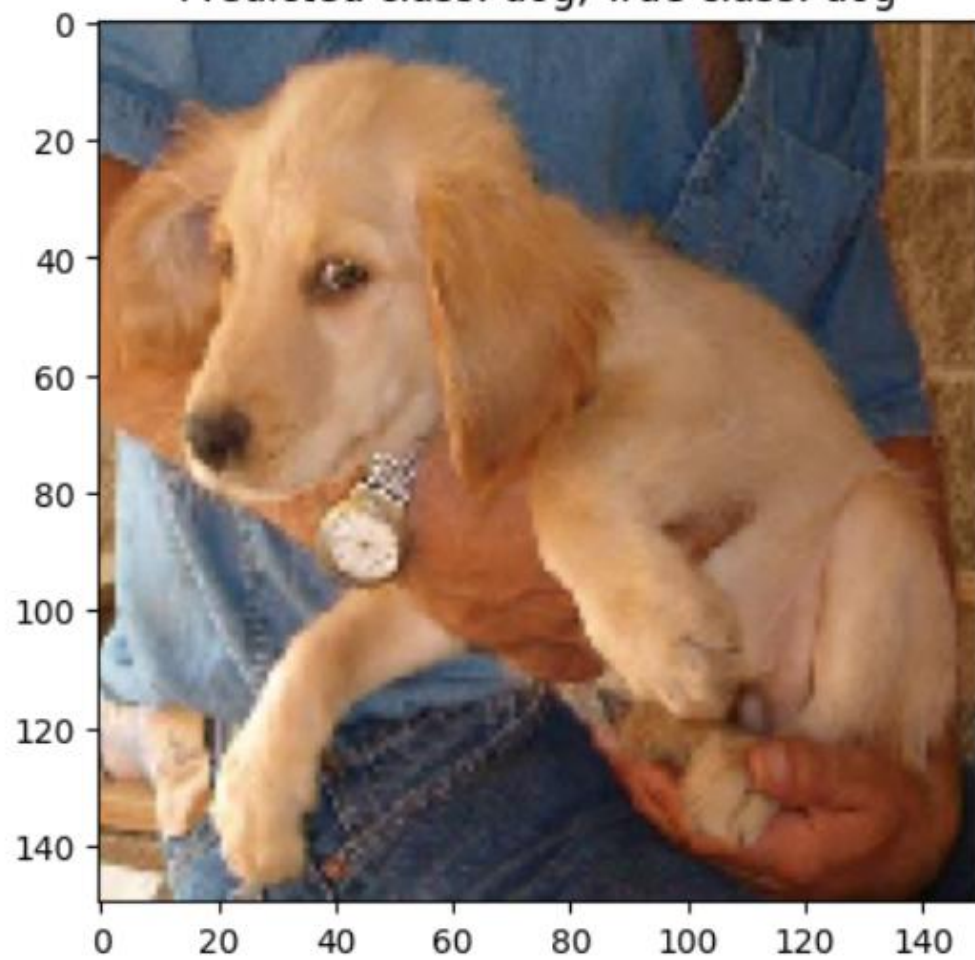
Predicted class: dog, True class: cat

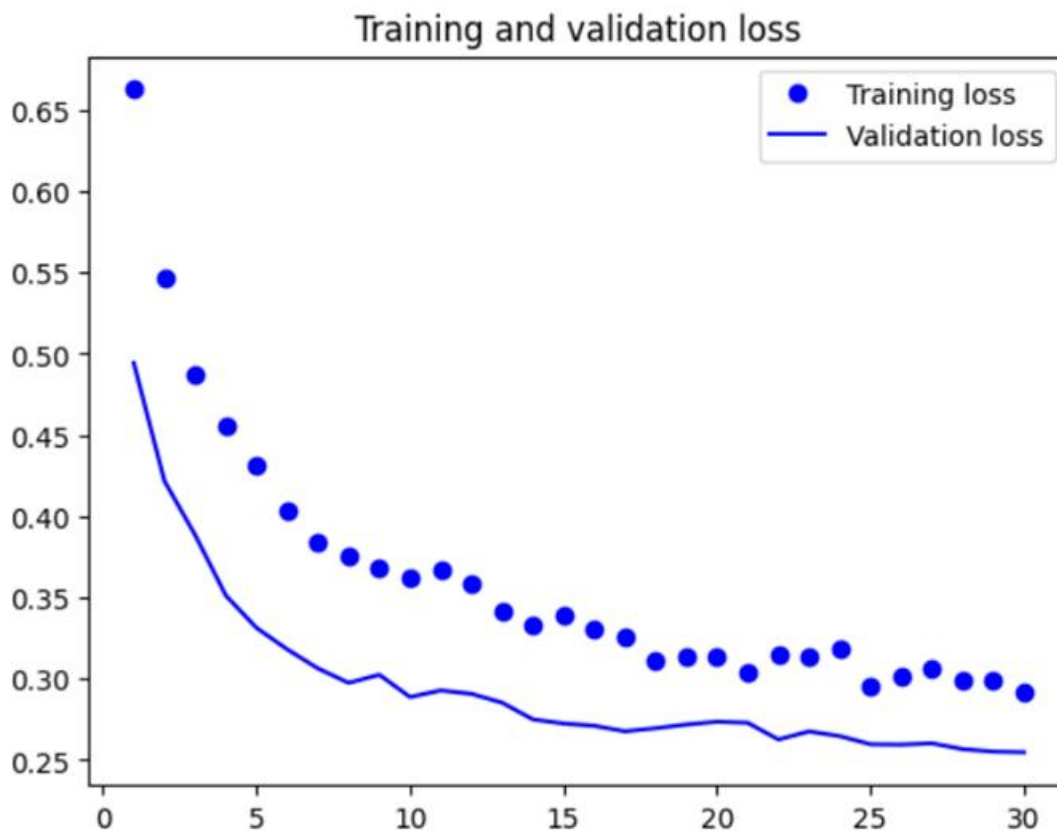
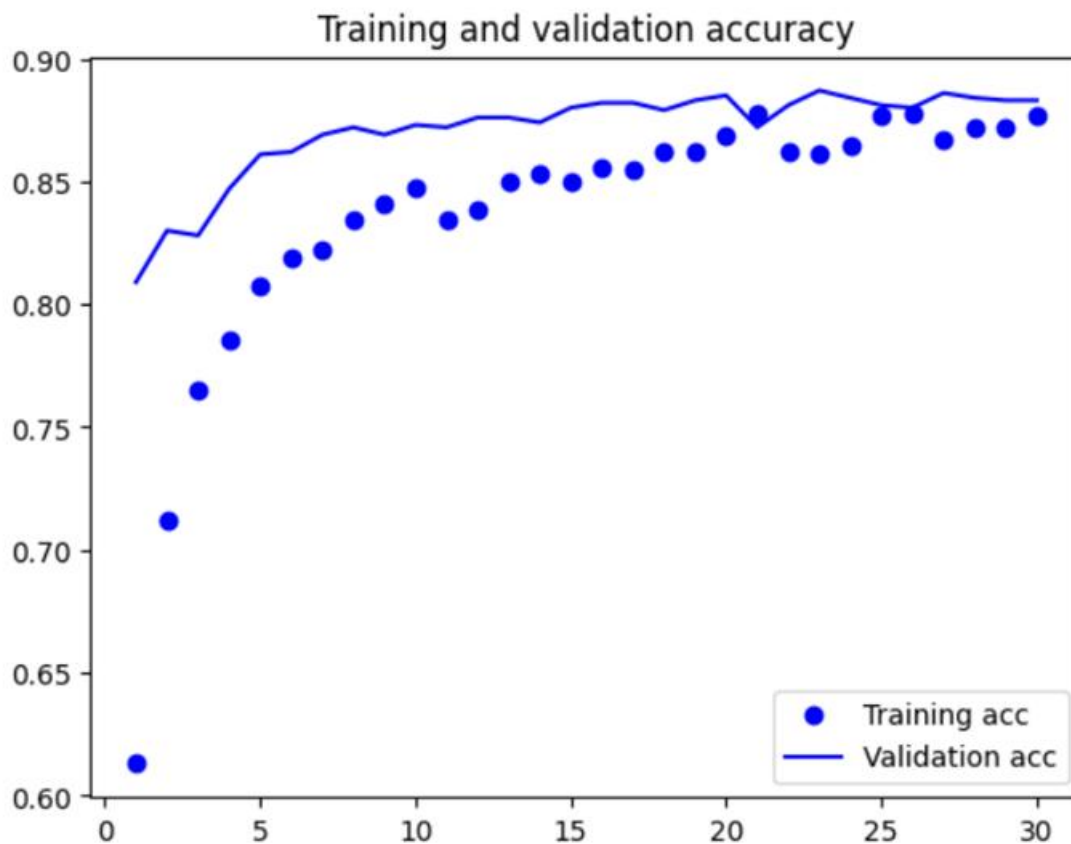


Predicted class: cat, True class: cat



Predicted class: dog, True class: dog





Practical 8

Aim: Implement basic reinforcement learning algorithms such as Q-learning and policy gradients.

Apply these algorithms to solve simple Markov decision processes (MDPs).

Experiment with different reward structures and explore their impact on learning.

Practical 9

Aim: Implement a Variational Autoencoder (VAE) architecture for learning latent representations

Train the VAE model on a dataset and visualize the learned latent space

Explore techniques for generating new data samples using the trained VAE model

```
import numpy as np
```

```
import matplotlib.pyplot as plt
```

```
import tensorflow as tf
```

```
from tensorflow.keras.layers import Input, Dense
```

```
from tensorflow.keras.models import Model
```

```
from tensorflow.keras.datasets import mnist
```

```
#load
```

```
(x_train, _), (x_test, _) = mnist.load_data()
```

```
#normalize
```

```
x_train = x_train.astype('float32') / 255.
```

```
x_test = x_test.astype('float32') / 255.
```

```
x_train = x_train.reshape((len(x_train), np.prod(x_train.shape[1:])))
```

```
x_test = x_test.reshape((len(x_test), np.prod(x_test.shape[1:])))
```

```
#size
```

```

encoding_dim = 32

#input
input_img = Input(shape=(784,))

#encoded
encoded = Dense(encoding_dim, activation='relu')(input_img)

#decoded
decoded = Dense(784, activation='sigmoid')(encoded)

#this model maps its reconstruction
autoencoder = Model(input_img, decoded)

#this model maps its encoded representation
encoder = Model(input_img, encoded)

#create
encoded_input = Input(shape=(encoding_dim,))

#retrive
decoder_layer = autoencoder.layers[-1]

#create
decoder = Model(encoded_input, decoder_layer(encoded_input))

autoencoder.compile(optimizer='adam', loss='binary_crossentropy')

autoencoder.fit(x_train, x_train,
                epochs=50,
                batch_size=256,
                shuffle=True,
                validation_data=(x_test, x_test))

#encode
encoded_imgs = encoder.predict(x_test)
decoded_imgs = decoder.predict(encoded_imgs)

```

```
#use
n=10
plt.figure(figsize=(20,4))
for i in range(n):
    ax = plt.subplot(2, n, i + 1)
    plt.imshow(x_test[i].reshape(28, 28))
    plt.gray()
    ax.get_xaxis().set_visible(False)
    ax.get_yaxis().set_visible(False)
plt.show()
print("Gayatri Kulkarni -53004230002")
```

```
Epoch 1/50
235/235 ————— 3s 11ms/step - loss: 0.3821 - val_loss: 0.1891
Epoch 2/50
235/235 ————— 2s 10ms/step - loss: 0.1800 - val_loss: 0.1538
Epoch 3/50
235/235 ————— 2s 7ms/step - loss: 0.1494 - val_loss: 0.1342
Epoch 4/50
235/235 ————— 2s 6ms/step - loss: 0.1318 - val_loss: 0.1218
Epoch 5/50
235/235 ————— 1s 6ms/step - loss: 0.1207 - val_loss: 0.1138
Epoch 6/50
235/235 ————— 1s 6ms/step - loss: 0.1135 - val_loss: 0.1084
Epoch 7/50
235/235 ————— 2s 7ms/step - loss: 0.1082 - val_loss: 0.1043
Epoch 8/50
235/235 ————— 2s 7ms/step - loss: 0.1047 - val_loss: 0.1009
Epoch 9/50
235/235 ————— 3s 10ms/step - loss: 0.1015 - val_loss: 0.0982
Epoch 10/50
235/235 ————— 2s 10ms/step - loss: 0.0989 - val_loss: 0.0963
Epoch 11/50
235/235 ————— 2s 9ms/step - loss: 0.0973 - val_loss: 0.0949
Epoch 12/50
235/235 ————— 2s 6ms/step - loss: 0.0957 - val_loss: 0.0941
Epoch 13/50
235/235 ————— 1s 6ms/step - loss: 0.0952 - val_loss: 0.0935
Epoch 14/50
235/235 ————— 2s 6ms/step - loss: 0.0948 - val_loss: 0.0932
Epoch 15/50
235/235 ————— 2s 6ms/step - loss: 0.0945 - val_loss: 0.0929
Epoch 16/50
235/235 ————— 2s 8ms/step - loss: 0.0943 - val_loss: 0.0927
Epoch 17/50
235/235 ————— 3s 11ms/step - loss: 0.0941 - val_loss: 0.0925
Epoch 18/50
235/235 ————— 3s 11ms/step - loss: 0.0938 - val_loss: 0.0924
Epoch 19/50
235/235 ————— 3s 11ms/step - loss: 0.0938 - val_loss: 0.0923
Epoch 20/50
235/235 ————— 1s 6ms/step - loss: 0.0937 - val_loss: 0.0922
Epoch 21/50
235/235 ————— 2s 7ms/step - loss: 0.0937 - val_loss: 0.0922
Epoch 22/50
235/235 ————— 2s 6ms/step - loss: 0.0935 - val_loss: 0.0921
Epoch 23/50
235/235 ————— 2s 7ms/step - loss: 0.0932 - val_loss: 0.0920
Epoch 24/50
235/235 ————— 2s 7ms/step - loss: 0.0935 - val_loss: 0.0920
Epoch 25/50
235/235 ————— 3s 12ms/step - loss: 0.0931 - val_loss: 0.0920
```

Epoch 26/50			
235/235	<div><div></div></div>	2s 9ms/step	loss: 0.0932 - val_loss: 0.0919
Epoch 27/50			
235/235	<div><div></div></div>	3s 11ms/step	loss: 0.0932 - val_loss: 0.0919
Epoch 28/50			
235/235	<div><div></div></div>	1s 6ms/step	loss: 0.0929 - val_loss: 0.0920
Epoch 29/50			
235/235	<div><div></div></div>	2s 7ms/step	loss: 0.0930 - val_loss: 0.0918
Epoch 30/50			
235/235	<div><div></div></div>	2s 7ms/step	loss: 0.0931 - val_loss: 0.0918
Epoch 31/50			
235/235	<div><div></div></div>	2s 7ms/step	loss: 0.0929 - val_loss: 0.0918
Epoch 32/50			
235/235	<div><div></div></div>	2s 7ms/step	loss: 0.0930 - val_loss: 0.0918
Epoch 33/50			
235/235	<div><div></div></div>	3s 11ms/step	loss: 0.0928 - val_loss: 0.0918
Epoch 34/50			
235/235	<div><div></div></div>	3s 12ms/step	loss: 0.0929 - val_loss: 0.0918
Epoch 35/50			
235/235	<div><div></div></div>	2s 8ms/step	loss: 0.0929 - val_loss: 0.0918
Epoch 36/50			
235/235	<div><div></div></div>	1s 6ms/step	loss: 0.0928 - val_loss: 0.0918
Epoch 37/50			
235/235	<div><div></div></div>	1s 6ms/step	loss: 0.0926 - val_loss: 0.0917
Epoch 38/50			
235/235	<div><div></div></div>	2s 7ms/step	loss: 0.0931 - val_loss: 0.0917
Epoch 39/50			
235/235	<div><div></div></div>	1s 6ms/step	loss: 0.0929 - val_loss: 0.0916
Epoch 40/50			
235/235	<div><div></div></div>	2s 7ms/step	loss: 0.0926 - val_loss: 0.0917
Epoch 41/50			
235/235	<div><div></div></div>	2s 9ms/step	loss: 0.0928 - val_loss: 0.0917
Epoch 42/50			
235/235	<div><div></div></div>	2s 9ms/step	loss: 0.0928 - val_loss: 0.0916
Epoch 43/50			
235/235	<div><div></div></div>	2s 10ms/step	loss: 0.0927 - val_loss: 0.0917
Epoch 44/50			
235/235	<div><div></div></div>	2s 9ms/step	loss: 0.0927 - val_loss: 0.0916
Epoch 45/50			
235/235	<div><div></div></div>	2s 6ms/step	loss: 0.0927 - val_loss: 0.0917
Epoch 46/50			
235/235	<div><div></div></div>	1s 6ms/step	loss: 0.0929 - val_loss: 0.0916
Epoch 47/50			
235/235	<div><div></div></div>	1s 6ms/step	loss: 0.0927 - val_loss: 0.0916
Epoch 48/50			
235/235	<div><div></div></div>	1s 6ms/step	loss: 0.0927 - val_loss: 0.0915
Epoch 49/50			
235/235	<div><div></div></div>	2s 6ms/step	loss: 0.0924 - val_loss: 0.0916
Epoch 50/50			
235/235	<div><div></div></div>	2s 7ms/step	loss: 0.0928 - val_loss: 0.0916
313/313	<div><div></div></div>	0s 1ms/step	
313/313	<div><div></div></div>	0s 1ms/step	

```
235/235 ————— 2s 6ms/step - loss: 0.0924 - val_loss: 0.0916
Epoch 50/50
235/235 ————— 2s 7ms/step - loss: 0.0928 - val_loss: 0.0916
313/313 ————— 0s 1ms/step
313/313 ————— 0s 1ms/step
```



Gayatri Kulkarni -53004230002

Practical 10

Aim: Implement a basic GAN architecture (e.g., DCGAN) using TensorFlow or PyTorch.

Train the GAN model on a dataset for image generation or style transfer tasks.

Experiment with different loss functions and architectures to improve GAN performance.

Practical 11

Aim: Use pre-trained GAN models for image generation and synthesis tasks.

use of GANs for text generation tasks such as dialogue generation or story generation

Tensorflow operations