

Matrix: A matrix is a system of mn numbered arranged in m rows and n columns it is called and $m \times n$ matrices

$$\text{e.g. A=} \begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1j} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2j} & \cdots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \cdots & a_{3j} & \cdots & a_{3n} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{i1} & a_{i2} & a_{i3} & \vdots & a_{ij} & \vdots & a_{in} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \cdots & a_{mj} & \cdots & a_{mn} \end{bmatrix}$$

Types of matrices

1) Matrix which contain only one rows is called row matrix

2) Matrix which contain only one column is called column matrix

e.g. A=
$$\begin{bmatrix} 5 \\ 23 \\ 15 \\ 8 \\ 10 \end{bmatrix}$$

3) Matrix in which number of rows and columns are same is called square matrix

e.g.
$$A = \begin{bmatrix} 4 & 2 & 6 & 8 \\ 8 & 5 & 5 & 9 \\ 4 & 2 & 7 & 8 \\ 5 & 3 & 9 & 8 \end{bmatrix}$$

4) Diagonal elements: In square matrix the elements lying along diagonal of a matrix are called diagonal elements

e.g.
$$A = \begin{bmatrix} 4 & 2 & 6 & 8 \\ 8 & 5 & 5 & 9 \\ 4 & 2 & 7 & 8 \\ 5 & 3 & 9 & 8 \end{bmatrix}$$
 Here **4**, **5**, **7**, **8** are the diagonal elements

5) Diagonal Matrix: a square matrix in which all the non-diagonal elements are equal to zero are called diagonal matrix.

e.g.
$$A = \begin{bmatrix} 4 & 0 & 0 & 0 \\ 0 & 5 & 0 & 0 \\ 0 & 0 & 7 & 0 \\ 0 & 0 & 0 & 8 \end{bmatrix}$$
 Here 4, 5, 7, 8 are the diagonal elements

6) Scalar matrix: a diagonal matrix whose all diagonal elements are equal is called scalar matrix. e.g.

$$A = \begin{bmatrix} 4 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 0 & 0 & 4 \end{bmatrix}$$

7) Unit matrix: a diagonal matrix whose all diagonal elements equal to one is called unit matrix.



e.g.
$$A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

8) Trace of a matrix: The sum of all the diagonal elements of a matrix is called trace of a matrix

If
$$A = \begin{bmatrix} 4 & 0 & 0 & 0 \\ 0 & 5 & 0 & 0 \\ 0 & 0 & 7 & 0 \\ 0 & 0 & 0 & 8 \end{bmatrix}$$
 then Trace of matrix $A = \sum_{i=1}^{n} a_{ii} = a_{11} + a_{22} + a_{33} + \dots + a_{nn}$

In given matrix Trace of A=4+5+7+8=24

- 9) Determinant of a square matrix A is denoted by |A|
- 10) Singular matrix: A square matrix A is said to be singular matrix if |A| = 0

e.g. ,
$$C = [0]$$
, $|C| = 0$, $A = \begin{bmatrix} 3 & 2 \\ 18 & 12 \end{bmatrix}$ then $|A| = 0$, $B = \begin{bmatrix} 1 & 3 & 5 \\ 8 & 4 & 3 \\ 2 & 6 & 10 \end{bmatrix}$ then $|B| = 0$

So matrices C, A, and B are singular matrices.

11) Non-singular matrix: A square matrix A is said to be non-singular matrix if $|A| \neq 0$

e.g.
$$A = \begin{bmatrix} 5 \end{bmatrix}, |A| = 5 \neq 0, B = \begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix}, |B| = -1 \neq 0 \ C = \begin{bmatrix} -1 & -2 & -2 \\ 2 & 1 & -2 \\ 2 & -2 & 1 \end{bmatrix}, |C| = 27 \neq 0$$

So matrices C, A, and B are singular matrices.

12) Upper triangular matrix: A matrix $A = [a_{ij}]$ is upper triangular matrix if $a_{ij} = 0$ for i > j

e.g. .
$$A = \begin{bmatrix} 4 & 2 & 6 & 8 \\ 0 & 5 & 5 & 9 \\ 0 & 0 & 7 & 8 \\ 0 & 0 & 0 & 8 \end{bmatrix}$$
 i.e. all the elements below the diagonal elements are zero.

13) Lower triangular matrix: A matrix $A = [a_{ij}]$ is lower triangular matrix if $a_{ij} = 0$ for i < j

. A=
$$\begin{bmatrix} 4 & 0 & 0 & 0 \\ 8 & 5 & 0 & 0 \\ 4 & 2 & 7 & 0 \\ 5 & 3 & 9 & 8 \end{bmatrix}$$
 i.e. all the elements above the diagonal elements are zero.

14) Transpose of a matrix: Matrix obtained by interchange of rows and column of a matrix A is called Transpose of a matrix and is denoted by A^T

If .
$$A = \begin{bmatrix} 4 & 2 & 6 & 8 \\ 8 & 5 & 5 & 9 \\ 4 & 2 & 7 & 8 \\ 5 & 3 & 9 & 8 \end{bmatrix}$$
 then $A^{T} = \begin{bmatrix} 4 & 8 & 4 & 5 \\ 2 & 5 & 2 & 3 \\ 6 & 5 & 7 & 9 \\ 8 & 9 & 8 & 8 \end{bmatrix}$



15) Conjugate of a matrix: The matrix obtained from a given matrix by replacing each element by it's complex conjugate is called the conjugate of the given matrix and is denoted by \bar{A}

Thus if
$$A = \begin{bmatrix} -2+3i & 3-2i & -6i \\ 4i & 1-2i & -5+2i \\ 3 & -4-6i & 8+2i \end{bmatrix}$$
 then $\bar{A} = \begin{bmatrix} -2-3i & 3+2i & 6i \\ -4i & 1+2i & -5-2i \\ 3 & -4+6i & 8-2i \end{bmatrix}$

16) Transposed conjugate of a matrix: The transpose of a complex conjugate of a given is called the transposed conjugate of a matrix A and is denoted by A^{θ}

i.e.
$$A^{\theta} = \bar{A}' = \bar{A}$$

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e.g. if if $A = \begin{bmatrix} -2+3i & 3-2i & -6i \\ 4i & 1-2i & -5+2i \\ 3 & -4-6i & 8+2i \end{bmatrix}$ then $\bar{A} = \begin{bmatrix} -2-3i & 3+2i & 6i \\ -4i & 1+2i & -5-2i \\ 3 & -4+6i & 8-2i \end{bmatrix}$
and $A^{\theta} = \bar{A}' = \begin{bmatrix} -2-3i & -4i & 3 \\ 3+2i & 1+2i & -4+6i \end{bmatrix}$

and
$$A^{\theta} = \bar{A'} = \begin{bmatrix} -2 - 3i & -4i & 3\\ 3 + 2i & 1 + 2i & -4 + 6i\\ 6i & -5 - 2i & 8 - 2i \end{bmatrix}$$

17) Symmetric matrix: A matrix $A = [a_{ij}]$ is said to be symmetric matrix if $a_{ij} = a_{ji} \ \forall \ i,j$

Or
$$A^T = A$$

$$A = \begin{bmatrix} 4 & -2 & 6 & 8 \\ -2 & 5 & -1 & -3 \\ 6 & -1 & 7 & 9 \\ 8 & -3 & 9 & 8 \end{bmatrix}, A = \begin{bmatrix} 1 & -2 & 3 \\ -2 & 5 & -7 \\ 3 & -7 & 8 \end{bmatrix}, A = \begin{bmatrix} 1 & 2 \\ 2 & 5 \end{bmatrix}$$

18) Skew-symmetric matrix: A matrix $A = [a_{ij}]$ is said to be skew-symmetric matrix if $a_{ij} = -a_{ji} \forall i, j$ Or $A^T = -A$

$$A = \begin{bmatrix} 0 & 2 & -6 & -8 \\ -2 & 0 & 1 & 3 \\ 6 & -1 & 0 & -9 \\ 8 & -3 & 9 & 0 \end{bmatrix} A = \begin{bmatrix} 0 & -2 & -3 \\ 2 & 0 & 7 \\ 3 & -7 & 0 \end{bmatrix}, A = \begin{bmatrix} 0 & -5 \\ 5 & 0 \end{bmatrix}$$

Note: In skew-symmetric matrix all the diagonal elements equal to zero

19) Hermitian matrix: Matrix $A = [a_{ij}]$ is said to be Hermitian matrix if $\overline{a_{ij}} = a_{ji} \ \forall \ i, j$

Or
$$A^{\theta} = A$$

$$A = \begin{bmatrix} 1 & 2-3i & 5+6i \\ 2-3i & 3 & 8-2i \\ 5-6i & 8+2i & 6 \end{bmatrix}, A = \begin{bmatrix} 2 & 3-5i \\ 3+5i & 7 \end{bmatrix}$$

Note: In Hermitian matrix all the diagonal elements are purely real.

20) Skew-Hermitian matrix: Matrix $A = [a_{ij}]$ is said to be Skew-Hermitian matrix if

$$\overline{a_{ij}} = -a_{ji} \ \forall \ i,j \ \mathsf{Or} \ A^{\theta} = -A$$

$$A = \begin{bmatrix} 0 & 2-3i & 5+6i \\ -2-3i & 3i & 8-2i \\ -5+6i & -8-2i & -6i \end{bmatrix}, A = \begin{bmatrix} 2i & 3-5i \\ -3-5i & 0 \end{bmatrix}$$



Note: In Skew-Hermitian matrix all the diagonal elements are either zero or purely imaginary

Note:

- 1) If a Matrix A is Hermition then iA is skew Hermitian Matrix
- 2) If a matrix A is Skew Hermitian then iA is Hermition Matrix

Theorem: Every matrix A can be expressed as sum of symmetric and skew-symmetric matrices. i.e. $A = \frac{1}{2}(A + A^T) + \frac{1}{2}(A - A^T)$

Where $\frac{1}{2}(A + A^T)$ is symmetric matrix, and $\frac{1}{2}(A - A^T)$ is Skew – symmetric matrix

e.g. Let
$$A = \begin{bmatrix} 6 & 10 & 16 \\ 20 & 26 & 30 \\ 40 & 50 & 60 \end{bmatrix}$$
 $\therefore A^T = \begin{bmatrix} 6 & 20 & 40 \\ 10 & 26 & 50 \\ 16 & 30 & 60 \end{bmatrix}$

Now
$$A + A^T = \begin{bmatrix} 12 & 30 & 56 \\ 30 & 52 & 80 \\ 56 & 80 & 120 \end{bmatrix}$$
, and $A - A^T = \begin{bmatrix} 0 & -10 & -24 \\ 10 & 0 & -20 \\ 24 & 20 & 0 \end{bmatrix}$

$$\frac{1}{2}(A - A^{T}) = \begin{bmatrix} 0 & -5 & -12 \\ 5 & 0 & -10 \\ 12 & 10 & 0 \end{bmatrix}$$
 is skew – symmetric

And
$$\begin{bmatrix} 6 & 10 & 16 \\ 20 & 26 & 30 \\ 40 & 50 & 60 \end{bmatrix} = \begin{bmatrix} 6 & 15 & 28 \\ 15 & 26 & 40 \\ 28 & 40 & 60 \end{bmatrix} + \begin{bmatrix} 0 & -5 & -12 \\ 5 & 0 & -10 \\ 12 & 10 & 0 \end{bmatrix}$$
 i.e. $A = \frac{1}{2}(A + A^T) + \frac{1}{2}(A - A^T)$

Example: Express the following matrices as sum of symmetric and skew-symmetric matrices

$$1)A = \begin{bmatrix} 5 & 7 \\ -3 & 4 \end{bmatrix}, 2)A = \begin{bmatrix} 2 & -4 & 9 \\ 14 & 7 & 13 \\ 3 & 5 & 11 \end{bmatrix}, 3)A = \begin{bmatrix} 0 & 5 & -3 \\ 1 & 1 & 1 \\ 4 & 5 & 9 \end{bmatrix}, 4)A = \begin{bmatrix} 1 & 0 & 5 & 3 \\ -2 & 1 & 6 & 1 \\ 3 & 2 & 7 & 1 \\ 4 & -4 & 2 & 0 \end{bmatrix}, 5)A = \begin{bmatrix} 1 & 5 & 7 \\ -1 & -2 & -4 \\ 8 & 2 & 13 \end{bmatrix}$$



Theorem: Every matrix A can be expressed as sum of Hermitian and skew-Hermitian matrices. i.e. $A = \frac{1}{2}(A + A^{\theta}) + \frac{1}{2}(A - A^{\theta})$

Where $\frac{1}{2}(A+A^{\theta})$ is Hermitian matrix, and $\frac{1}{2}(A-A^{\theta})$ is Skew - Hermitian matrix

e.g. Let
$$A = \begin{bmatrix} 2+4i & 4-6i & 6+8i \\ 8-10i & 10+12i & 12-14i \\ 14+16i & 16-18i & 18+20i \end{bmatrix}$$
 $\therefore \bar{A} = \begin{bmatrix} 2-4i & 4+6i & 6-8i \\ 8+10i & 10-12i & 12+14i \\ 14-16i & 16+18i & 18-20i \end{bmatrix}$

$$A^{\theta} = \bar{A}^{T} = \begin{bmatrix} 2 - 4i & 8 + 10i & 14 - 16i \\ 4 + 6i & 10 - 12i & 16 + 18i \\ 6 - 8i & 12 + 14i & 18 - 20i \end{bmatrix}$$

Now

$$A + A^{\theta} = \begin{bmatrix} 4 & 12 + 4i & 20 - 8i \\ 12 - 4i & 20 & 28 + 4i \\ 20 + 8i & 28 - 4i & 36 \end{bmatrix}, \text{ and } A - A^{\theta} = \begin{bmatrix} 8i & -4 - 16i & -8 + 24i \\ 4 - 16i & 24i & -4 - 32i \\ 8 + 24i & 4 - 32i & 40i \end{bmatrix}$$

$$\frac{1}{2}(A - A^{\theta}) = \begin{bmatrix} 4i & -2 - 8i & -4 + 12i \\ 2 - 8i & 12i & -2 - 16i \\ 4 + 12i & 2 - 16i & 20i \end{bmatrix} \text{ is skew } - \text{Hermitain matrix}$$

$$\operatorname{And}\begin{bmatrix}2+4i & 4-6i & 6+8i \\ 8-10i & 10+12i & 12-14i \\ 14+16i & 16-18i & 18+20i\end{bmatrix} = \begin{bmatrix}2 & 6+2i & 10-4i \\ 6-2i & 10 & 14+2i \\ 10+4i & 14-2i & 18\end{bmatrix} + \begin{bmatrix}4i & -2-8i & -4+12i \\ 2-8i & 12i & -2-16i \\ 4+12i & 2-16i & 20i\end{bmatrix}$$

i.e.
$$A = \frac{1}{2}(A + A^{\theta}) + \frac{1}{2}(A - A^{\theta})$$

Example: Express the following matrices as sum of symmetric and skew-symmetric matrices

$$1)A = \begin{bmatrix} 3i & -1+i & 3-2i \\ 1+i & -i & 1+2i \\ -3-2i & -1+2i & 0 \end{bmatrix}, 2)A = \begin{bmatrix} 2 & 2+i & 3 \\ -2+i & 0 & 4i \\ -i & 3-i & 1-i \end{bmatrix}, 3)A = \begin{bmatrix} 2 & 3-i & 2+i \\ i & 0 & 1-i \\ 1+2i & i & 3i \end{bmatrix}, 4)A = \begin{bmatrix} 1 & 1+i & 2+3i \\ 1-i & 2 & -i \\ 2-3i & i & 0 \end{bmatrix}, 5)A = \begin{bmatrix} 2i & 2+i & 1-i \\ -2+i & -i & 3i \\ -1-i & 3i & 0 \end{bmatrix}, 6)A = \begin{bmatrix} 2+3i & 0 & 4i \\ 5 & i & 8 \\ 1-i & -3+i & 6 \end{bmatrix}$$

7)
$$A = \begin{bmatrix} 3i & -1+i & 3-2i \\ 1+i & -i & 1+2i \\ -3+2i & -1+2i & 0 \end{bmatrix}$$
, 8) $A = \begin{bmatrix} 2 & 4+i & 4i \\ 3i & 6-i & 2 \\ 6 & 4-2i & 1-i \end{bmatrix}$, 9) $A = \begin{bmatrix} 2 & 4+i & 6i \\ 6 & 5-i & 4 \\ 0 & 1-i & 8i \end{bmatrix}$



Theorem: Every square matrix A can be expressed as P + iQ where P, and Q are Hermitian matrices

Note:
$$(i)^{\theta} = -i, (-i)^{\theta} = i$$

Proof:
$$A = \frac{1}{2}[A + A] = \frac{1}{2}[A + A^{\theta} + A - A^{\theta}] = \frac{1}{2}[(A + A^{\theta}) + i\frac{1}{i}(A - A^{\theta})] = \left[\frac{1}{2}(A + A^{\theta}) + i\frac{1}{2i}(A - A^{\theta})\right]$$

$$A = P + iQ$$
 where $P = \frac{1}{2}(A + A^{\theta})$, and $Q = \frac{1}{2i}(A - A^{\theta})$

Now
$$P^{\theta} = \left(\frac{1}{2}(A + A^{\theta})\right)^{\theta} = \frac{1}{2}(A^{\theta} + (A^{\theta})^{\theta}) = \frac{1}{2}(A^{\theta} + A) = P$$
 so P is hermition Matrix

$$Q = \left(\frac{1}{2i}(A - A^{\theta})\right)^{\theta} = \frac{1}{2i^{\theta}}(A^{\theta} - (A^{\theta})^{\theta}) = \frac{1}{2(-i)}(A^{\theta} - A) = \frac{-1}{2i}(A^{\theta} - A) = \frac{1}{2i}(A - A^{\theta}) = Q$$
So Q is hermitian matrix

So Q is hermitian matrix

Thus

$$A=P+iQ$$
 where $P=rac{1}{2}ig(A+A^{ heta}ig)$, and $Q=rac{1}{2i}ig(A-A^{ heta}ig)$ then P and Q are hermitian matrices

Example: Express the matrix $A = \begin{bmatrix} 2 & 3-i & 2+i \\ i & 0 & 1-i \\ 1+2i & 1 & 3i \end{bmatrix}$ as P+iQ, where P and Q are hermitian matrices

Solution: By given
$$A = \begin{bmatrix} 2 & 3-i & 2+i \\ i & 0 & 1-i \\ 1+2i & 1 & 3i \end{bmatrix}$$
, $So\ \bar{A} = \begin{bmatrix} 2 & 3+i & 2-i \\ -i & 0 & 1+i \\ 1-2i & 1 & -3i \end{bmatrix}$

$$A^{\theta} = (\bar{A})^{T} = \begin{bmatrix} 2 & -i & 1 - 2i \\ 3 + i & 0 & 1 \\ 2 - i & 1 + i & -3i \end{bmatrix}$$

Now
$$(A + A^{\theta}) = \begin{bmatrix} 4 & 3 - 2i & 3 - i \\ 3 + 2i & 0 & 2 - i \\ 3 + i & 2 + i & 0 \end{bmatrix}$$
, and $(A - A^{\theta}) = \begin{bmatrix} 0 & 3 & 1 + 3i \\ -3 & 0 & -i \\ -1 + 3i & -i & 6i \end{bmatrix}$

Let
$$P = \frac{1}{2}(A + A^{\theta}) = \frac{1}{2}\begin{bmatrix} 4 & 3 - 2i & 3 - i \\ 3 + 2i & 0 & 2 - i \\ 3 + i & 2 + i & 0 \end{bmatrix}$$
, $Q = \frac{1}{2i}(A - A^{\theta}) = \frac{1}{2i}\begin{bmatrix} 0 & 3 & 1 + 3i \\ -3 & 0 & -i \\ -1 + 3i & -i & 6i \end{bmatrix}$

Then P and Q are Hermition Matrices

Thus A = P + iQ

i.e.
$$\begin{bmatrix} 2 & 3-i & 2+i \\ i & 0 & 1-i \\ 1+2i & 1 & 3i \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 4 & 3-2i & 3-i \\ 3+2i & 0 & 2-i \\ 3+i & 2+i & 0 \end{bmatrix} + i \begin{pmatrix} \frac{1}{2i} \begin{bmatrix} 0 & 3 & 1+3i \\ -3 & 0 & -i \\ -1+3i & -i & 6i \end{bmatrix} \end{pmatrix}$$



Example: Express the matrix 1)
$$A = \begin{bmatrix} 2i & -3 & 1-i \\ 0 & 2+3i & 1+i \\ -3i & 3+2i & 2-5i \end{bmatrix}$$
, 2) $A = \begin{bmatrix} 1+2i & 2 & 3-i \\ 2+3i & 2i & 1-2i \\ 1+i & 0 & 3+2i \end{bmatrix}$

Theorem: Every Hermition matrix A can be written as A = B + B

iC, where B is real symmetric matrix and C is real skew — symmetric matrix

Solution: By given A is hermition matrix $A^{\theta} = A i.e.(\bar{A})^T = A, or \overline{(A^T)} = A \cdots (*)$

Now
$$A = \frac{1}{2}(A + A) = \frac{1}{2}(A + \bar{A} + A - \bar{A}) = \frac{1}{2}(A + \bar{A}) + i\frac{1}{2i}(A - \bar{A}) = P + iQ \cdots (1)$$

Where
$$P = \frac{1}{2}(A + \bar{A}), Q = \frac{1}{2i}(A - \bar{A})\cdots(2)$$

We know if z = x + iy, $\bar{z} = x - iy$, where x and y are real numbers ,then

$$z + \bar{z} = 2x, z - \bar{z} = i2y \Rightarrow \frac{1}{2}(z + \bar{z}) = x,$$
 and $\frac{1}{2i}(z - \bar{z}) = y \Rightarrow \frac{1}{2}(z + \bar{z}),$ and $\frac{1}{2i}(z - \bar{z})$ are real numbers

From equation (2) $P = \frac{1}{2}(A + \bar{A})$, $Q = \frac{1}{2i}(A - \bar{A})$ are real numbers i.e. P and Q are real numbers

Now From equation (2)
$$P^T = \left(\frac{1}{2}(A + \bar{A})\right)^T = \frac{1}{2}(A^T + \bar{A}^T) = \frac{1}{2}(A^T + A^\theta) = \frac{1}{2}(A^T + A) \{using (*)\}$$

$$P^T = \frac{1}{2}(A + A^T) = P$$
 {Using (2)} \Rightarrow P is symmetric

Now From equation (2)
$$Q^T = \left(\frac{1}{2i}(A - \bar{A})\right)^T = \frac{1}{2i}(A^T - \bar{A}^T) = \frac{1}{2i}(A^T - A^\theta) = \frac{1}{2i}(A^T - A) \{using (*)\}$$

$$Q^T = \frac{-1}{2i}(A - A^T) = -Q$$
 {Using (2)} \Rightarrow Q is skew-symmetric

Matrix A can be expressed as A = P + iQ where

$$P = \frac{1}{2}(A + \bar{A})$$
 is real and symmetric and $Q = \frac{1}{2i}(A - \bar{A})$ is real and skew – symmetric

Example: Express the matrix
$$A = \begin{bmatrix} 2 & 1+i & -i \\ 1-i & 0 & -3-i \\ i & -3+i & -1 \end{bmatrix}$$
 as $A = P+iQ$, where

P is real and symmetric and Q is real and skew - symmetric

Solution:
$$A = \begin{bmatrix} 2 & 1+i & -i \\ 1-i & 0 & -3-i \\ i & -3+i & -1 \end{bmatrix}$$
, $\bar{A} = \begin{bmatrix} 2 & 1-i & i \\ 1+i & 0 & -3+i \\ -i & -3-i & -1 \end{bmatrix}$

$$A + \bar{A} = \begin{bmatrix} 4 & 2 & 0 \\ 2 & 0 & -6 \\ 0 & -6 & -2 \end{bmatrix} \Rightarrow \frac{1}{2} (A + \bar{A}) = \begin{bmatrix} 2 & 1 & 0 \\ 1 & 0 & -3 \\ 0 & -3 & -1 \end{bmatrix}$$
 is symmetric

And
$$A - \bar{A} = \begin{bmatrix} 0 & 2i & -2i \\ -2i & 0 & -2i \\ 2i & 2i & 0 \end{bmatrix} \Rightarrow \frac{1}{2i} (A - \bar{A}) = \begin{bmatrix} 0 & 1 & -1 \\ -1 & 0 & -1 \\ 1 & 1 & 0 \end{bmatrix}$$
 is skew-symmetric



Thus A = P + iQ, Where $P = \frac{1}{2}(A + \bar{A}) = \begin{bmatrix} 2 & 1 & 0 \\ 1 & 0 & -3 \\ 0 & -3 & -1 \end{bmatrix}$ is real and symmetric matrix

And
$$Q = \frac{1}{2i}(A - \bar{A}) = \begin{bmatrix} 0 & 1 & -1 \\ -1 & 0 & -1 \\ 1 & 1 & 0 \end{bmatrix}$$
 is real and skew-symmetric matrix

Example: Express the matrix 1)
$$A = \begin{bmatrix} 1 & 2+i & -1+i \\ 2-i & 1 & 2i \\ -1-i & -2i & 0 \end{bmatrix}$$
, 2) $A = \begin{bmatrix} 2 & 2+i & -2i \\ 2-i & 3 & i \\ 2i & -i & 1 \end{bmatrix}$





Theorem: Every Skew-Hermitian matrix A can be expressed as A = P + iQ where P is real and skewsymmetric and Q is real and symmetric.

Solution: By given A is skew-hermitian matrix $A^{\theta} = -A$, or $(\bar{A})^T = -A$, or $(\bar{A}^T)^T = -A$

Now
$$A = \frac{1}{2}(A + A) = \frac{1}{2}(A + \bar{A} + A - \bar{A}) = \frac{1}{2}(A + \bar{A}) + i\frac{1}{2i}(A - \bar{A}) = P + iQ \cdots (1)$$

Where
$$P = \frac{1}{2}(A + \bar{A}), Q = \frac{1}{2i}(A - \bar{A})\cdots(2)$$

We know if z = x + iy, $\bar{z} = x - iy$, where x and y are real numbers ,then

$$z + \bar{z} = 2x$$
, $z - \bar{z} = i2y \Rightarrow \frac{1}{2}(z + \bar{z}) = x$, and $\frac{1}{2i}(z - \bar{z}) = y \Rightarrow \frac{1}{2}(z + \bar{z})$, and $\frac{1}{2i}(z - \bar{z})$ are real numbers

From equation (2) $P = \frac{1}{2}(A + \bar{A})$, $Q = \frac{1}{2i}(A - \bar{A})$ are real numbers i.e. P and Q are real numbers

Now From equation (2)
$$P^T = \left(\frac{1}{2}(A + \bar{A})\right)^T = \frac{1}{2}(A^T + \bar{A}^T) = \frac{1}{2}(A^T + A^\theta) = \frac{1}{2}(A^T - A) \{using (*)\}$$

$$P^T = \frac{-1}{2}(A - A^T) = -P$$
 {Using (2)} \Rightarrow P is skew-symmetric

Now From equation (2)
$$Q^T = \left(\frac{1}{2i}(A - \bar{A})\right)^T = \frac{1}{2i}(A^T - \bar{A}^T) = \frac{1}{2i}(A^T - A^\theta) = \frac{1}{2i}(A^T + A)$$
 {using (*)}

$$Q^T = \frac{1}{2i}(A + A^T) = Q$$
 {Using (2)} \Rightarrow Q is symmetric

Matrix A can be expressed as A = P + iQ where

 $P = \frac{1}{2}(A + \overline{A})$ is real and symmetric and $Q = \frac{1}{2i}(A - \overline{A})$ is real and skew – symmetric

1) Example: Express the matrix
$$A = \begin{bmatrix} 2i & 2+i & 1-i \\ -2+i & -i & 3i \\ -1-i & 3i & 0 \end{bmatrix}$$
 as $A = P+iQ$, where P is real and skew $-$ symmetric and Q is real and symmetric

Solution:
$$A = \begin{bmatrix} 2i & 2+i & 1-i \\ -2+i & -i & 3i \\ -1-i & 3i & 0 \end{bmatrix}, \bar{A} = \begin{bmatrix} -2i & 2-i & 1+i \\ -2-i & i & -3i \\ -1+i & -3i & 0 \end{bmatrix}$$

$$A + \bar{A} = \begin{bmatrix} 0 & 4 & 2 \\ -4 & 0 & 0 \\ -2 & 0 & 0 \end{bmatrix} \Rightarrow \frac{1}{2} (A + \bar{A}) = \begin{bmatrix} 0 & 2 & 1 \\ -2 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix}$$
 is skew-symmetric

And
$$A - \bar{A} = \begin{bmatrix} 4i & 2i & -2i \\ 2i & -2i & 6i \\ -2i & 6i & 0 \end{bmatrix} \Rightarrow \frac{1}{2i}(A - \bar{A}) = \begin{bmatrix} 2 & 1 & -1 \\ 1 & -1 & 3 \\ -1 & 3 & 0 \end{bmatrix}$$
 is symmetric



Thus
$$A = P + iQ$$
, Where $P = \frac{1}{2}(A + \overline{A}) = \begin{bmatrix} 0 & 2 & 1 \\ -2 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix}$ is real and skew – symmetric matrix

And
$$Q = \frac{1}{2i}(A - \bar{A}) = \begin{bmatrix} 2 & 1 & -1 \\ 1 & -1 & 3 \\ -1 & 3 & 0 \end{bmatrix}$$
 is real and symmetric *matrix*

Example: Express the matrix 1)
$$A = \begin{bmatrix} i & 1-i & 2+3i \\ -1-i & 2i & -3i \\ -2+3i & -3i & -i \end{bmatrix}$$
, 2) $A = \begin{bmatrix} 3i & -1+i & 3-2i \\ 1+i & -i & 1+2i \\ -3-2i & -1+2i & 0 \end{bmatrix}$