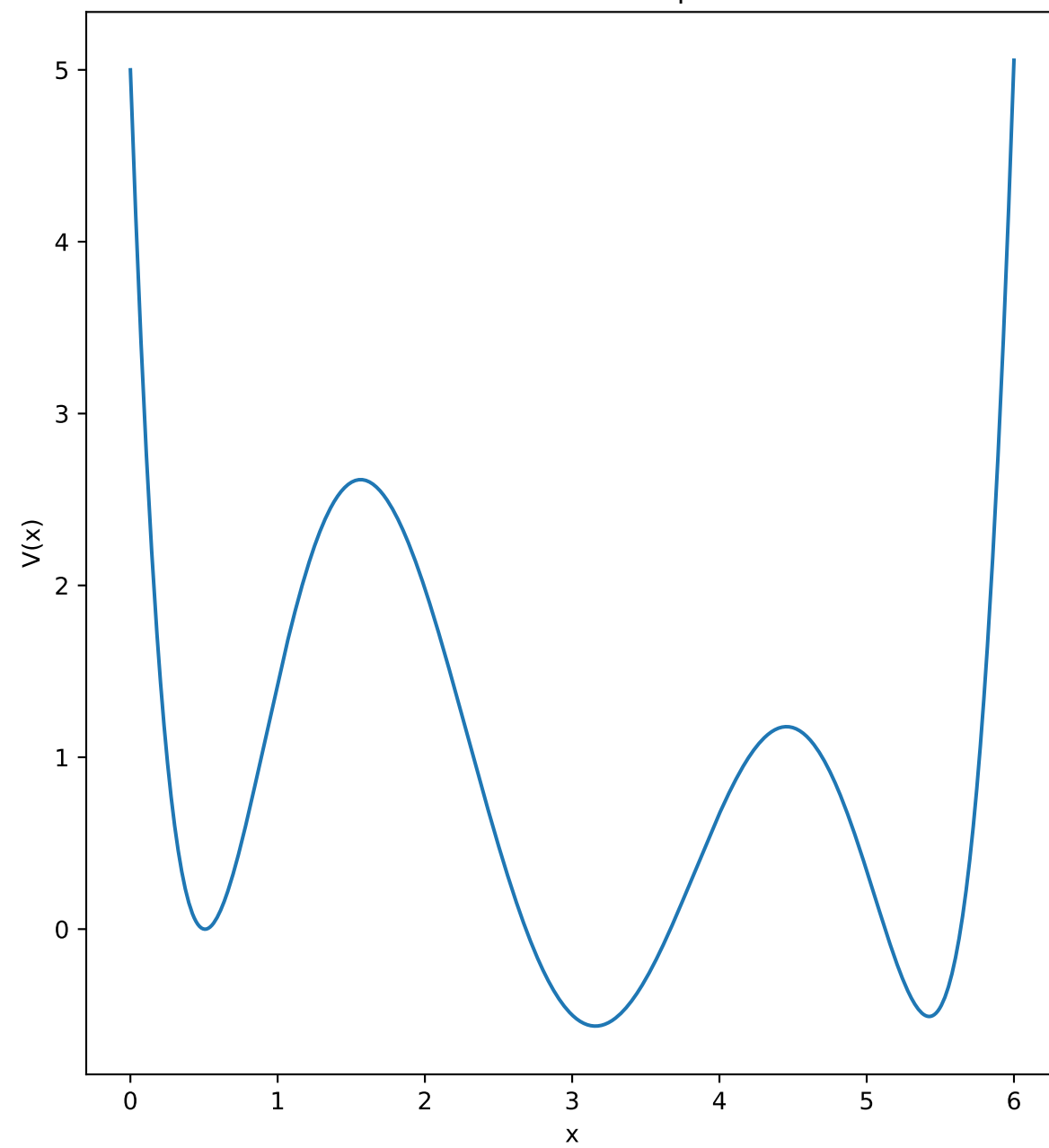


Potential landscape



Histogram of trajectory

