ICRA 2021 Workshop on Representing and Manipulating Deformable Objects

Coffee break
We will resume at 16:00 GMT+00

ICRA 2021 RMDO Workshop – Coffee break

Up Next:

16:00 – 16:30	**Dinesh Manocha:** Learning based Methods for High-DOF Grasping
16:30 – 17:00	**Jeannette Bohg:** Bridging Topology and Geometry Using Reinforcement Learning
17:00 – 17:45	**Open discussion round with** • Dmitry Berenson • Wenzhen Yuan • Dinesh Manocha • Jeannette Bohg • Rika Antonova

Dinesh Manocha

Paul Chrisman Iribe Professor of Computer Science,

Professor of Electrical and Computer Engineering

Department of Computer Science University of Maryland, USA

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https://deformable-workshop.github.io/icra2021/

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Jeannette Bohg

Assistant Professor for Robotics

Stanford University, USA

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Discussion topics:

• Simulation and transfer to reality: can we leverage simulators for real-world applications?

• Method evaluation: how could we compare different approaches on deformable objects?

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