

tesseract_scene_graph
/include/tesseract_scene
_graph/srdf/group_rop_kinematics.h

```
graph BT; A["tesseract_scene_graph  
/src/srdf_model.cpp"] --> C["tesseract_scene_graph  
/include/tesseract_scene_graph/srdf/group_rop_kinematics.h"]; B["tesseract_scene_graph  
/test/tesseract_scene_graph_srdf_unit.cpp"] --> C;
```

A diagram illustrating file dependencies. At the top is a grey box containing the header file path: `tesseract_scene_graph /include/tesseract_scene_graph/srdf/group_rop_kinematics.h`. Below it are two white boxes. The left box contains `tesseract_scene_graph /src/srdf_model.cpp` and the right box contains `tesseract_scene_graph /test/tesseract_scene_graph_srdf_unit.cpp`. Blue arrows point from each of these two boxes up to the header file box, indicating that both source files include this header.

tesseract_scene_graph
/src/srdf_model.cpp

tesseract_scene_graph
/test/tesseract_scene
_graph_srdf_unit.cpp