

tesseract\_collision  
/include/tesseract\_collision  
/bullet/tesseract\_convex  
\_convex\_algorithm.h

```
graph BT; A["tesseract_collision  
/src/bullet/tesseract  
_collision_configuration.cpp"] --> C["tesseract_collision  
/include/tesseract_collision  
/bullet/tesseract_convex  
_convex_algorithm.h"]; B["tesseract_collision  
/src/bullet/tesseract  
_convex_convex_algorithm.cpp"] --> C;
```

The diagram illustrates a dependency structure where two source files, `_collision_configuration.cpp` and `_convex_convex_algorithm.cpp`, both include the header file `_convex_algorithm.h`. The header file is located in the `/include/tesseract_collision/bullet/` directory, while the source files are in the `/src/bullet/tesseract/` directory. The header file box is shaded gray, and blue arrows indicate the inclusion relationship from the source files to the header.

tesseract\_collision  
/src/bullet/tesseract  
\_collision\_configuration.cpp

tesseract\_collision  
/src/bullet/tesseract  
\_convex\_convex\_algorithm.cpp