

tesseract\_scene\_graph  
/include/tesseract\_scene  
\_graph/srdf/group\_rop\_kinematics.h

```
graph BT; A["tesseract_scene_graph  
/src/srdf_model.cpp"] --> C["tesseract_scene_graph  
/include/tesseract_scene_graph/srdf/group_rop_kinematics.h"]; B["tesseract_scene_graph  
/test/tesseract_scene_graph_srdf_unit.cpp"] --> C;
```

A diagram showing two source files at the bottom and a header file at the top. Two blue arrows point from the source files to the header file, indicating that both source files include the header file.

tesseract\_scene\_graph  
/src/srdf\_model.cpp

tesseract\_scene\_graph  
/test/tesseract\_scene  
\_graph\_srdf\_unit.cpp