

tesseract_collision
/include/tesseract_collision
/bullet/tesseract_convex
_convex_algorithm.h

```
graph BT; A["tesseract_collision  
/src/bullet/tesseract  
_collision_configuration.cpp"] --> C["tesseract_collision  
/include/tesseract_collision  
/bullet/tesseract_convex  
_convex_algorithm.h"]; B["tesseract_collision  
/src/bullet/tesseract  
_convex_convex_algorithm.cpp"] --> C;
```

The diagram illustrates a file dependency structure. At the top is a header file box (shaded gray) containing the path 'tesseract_collision /include/tesseract_collision /bullet/tesseract_convex _convex_algorithm.h'. Below it are two source file boxes (white). The left box contains 'tesseract_collision /src/bullet/tesseract _collision_configuration.cpp' and the right box contains 'tesseract_collision /src/bullet/tesseract _convex_convex_algorithm.cpp'. Blue arrows point from each source file box up to the header file box, indicating that both source files include this header.

tesseract_collision
/src/bullet/tesseract
_collision_configuration.cpp

tesseract_collision
/src/bullet/tesseract
_convex_convex_algorithm.cpp