

tesseract\_kinematics  
/include/tesseract\_kinematics  
/kdl/kdl\_inv\_kin\_chain\_lma  
\_factory.h

```
graph BT; A["tesseract_environment  
/src/core/manipulator  
_manager.cpp"] --> C["tesseract_kinematics  
/include/tesseract_kinematics  
/kdl/kdl_inv_kin_chain_lma  
_factory.h"]; B["tesseract_kinematics  
/test/kdl_kinematics  
_unit.cpp"] --> C;
```

A diagram showing two source files at the bottom and a header file at the top. Two blue arrows point from the source files to the header file, indicating inclusion relationships.

tesseract\_environment  
/src/core/manipulator  
\_manager.cpp

tesseract\_kinematics  
/test/kdl\_kinematics  
\_unit.cpp