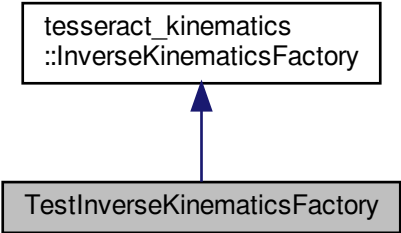


tesseract_kinematics
::InverseKinematicsFactory



```
graph BT; A[TestInverseKinematicsFactory] --> B[tesseract_kinematics::InverseKinematicsFactory];
```

TestInverseKinematicsFactory