

tesseract\_scene\_graph  
/include/tesseract\_scene  
\_graph/srdf/disabled\_collisions.h

```
graph BT; A["tesseract_scene_graph  
/src/srdf_model.cpp"] --> C["tesseract_scene_graph  
/include/tesseract_scene_graph/srdf/disabled_collisions.h"]; B["tesseract_scene_graph  
/test/tesseract_scene_graph_srdf_unit.cpp"] --> C;
```

This diagram illustrates the relationship between two source files and a header file. Two boxes at the bottom point via arrows to a single box at the top, indicating that both source files include the header file.

tesseract\_scene\_graph  
/src/srdf\_model.cpp

tesseract\_scene\_graph  
/test/tesseract\_scene  
\_graph\_srdf\_unit.cpp