

tesseract_scene_graph
/include/tesseract_scene
_graph/srdf/group_rop_kinematics.h

```
graph BT; A["tesseract_scene_graph  
/src/srdf_model.cpp"] --> C["tesseract_scene_graph  
/include/tesseract_scene_graph/srdf/group_rop_kinematics.h"]; B["tesseract_scene_graph  
/test/tesseract_scene_graph_srdf_unit.cpp"] --> C;
```

A diagram showing two source files at the bottom and a header file at the top. Two blue arrows point from the source files to the header file, indicating inclusion relationships.

tesseract_scene_graph
/src/srdf_model.cpp

tesseract_scene_graph
/test/tesseract_scene
_graph_srdf_unit.cpp