

tesseract_scene_graph
/include/tesseract_scene
_graph/srdf/disabled_collisions.h

```
graph BT; A["tesseract_scene_graph  
/src/srdf_model.cpp"] --> C["tesseract_scene_graph  
/include/tesseract_scene_graph/srdf/disabled_collisions.h"]; B["tesseract_scene_graph  
/test/tesseract_scene_graph_srdf_unit.cpp"] --> C;
```

This diagram illustrates the relationship between two source files and a header file. Two boxes at the bottom point via arrows to a single box at the top, indicating that both source files include the header file.

tesseract_scene_graph
/src/srdf_model.cpp

tesseract_scene_graph
/test/tesseract_scene
_graph_srdf_unit.cpp