

3.13)

a) problem 1.11:  $|\alpha\rangle = \cos(\beta/2)|+\rangle + e^{i\alpha} \sin(\beta/2)|-\rangle$

$$\rightarrow \langle S_z \rangle = \frac{\hbar}{2} \langle \alpha | (|+\rangle\langle -| + |-\rangle\langle +|) | \alpha \rangle = \frac{\hbar}{2} \left( \cos \frac{\beta}{2} \sin \frac{\beta}{2} e^{-i\alpha} + \sin \frac{\beta}{2} \cos \frac{\beta}{2} e^{i\alpha} \right)$$

$$= \frac{\hbar}{2} \sin \beta \cos \alpha$$

$$\langle S_y \rangle = \frac{i\hbar}{2} \langle \alpha | (|-\rangle\langle +| - |+\rangle\langle -|) | \alpha \rangle$$

$$= -\frac{\hbar}{2} \left( \frac{e^{+i\alpha} - e^{-i\alpha}}{2} \right) \cos \beta \sin \frac{\beta}{2} = -\frac{\hbar}{2} \sin \alpha \sin \beta$$

$$\langle S_x \rangle = \frac{\hbar}{2} \langle \alpha | (|+\rangle\langle +| - |-\rangle\langle -|) | \alpha \rangle = \frac{\hbar}{2} \left[ \cos^2 \left( \frac{\beta}{2} \right) - \sin^2 \left( \frac{\beta}{2} \right) \right] = \frac{\hbar}{2} \cos \beta$$

می‌توانیم  $0 \leq \beta \leq \pi$  و  $0 \leq \alpha \leq 2\pi$  با بخش بزرگ  $\langle S_z \rangle$  مشخص می‌شود و با توجه به بازه  $\beta$  می‌توان  $\beta$  را به قدر دقیق مشخص کرد. از اندازه  $\langle S_x \rangle$  نیز مشخص می‌شود اما علامت  $\alpha$  را نمی‌توان با آن مشخص کرد که به این جا علامت  $\langle S_y \rangle$  را اضافه خواهد کرد.

b)

ما می‌خواهیم  $S_z$  باشد:  $\rho = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$  ماتریس چکان در پایه  $S_z$  است:

$$[S_x] = \frac{\hbar}{2} \text{Tr} \left[ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \right] = \frac{\hbar}{2} (b+c) \quad (1)$$

$$[S_y] = \frac{\hbar}{2} \text{Tr} \left[ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \right] = \frac{\hbar}{2} i(b-c) \quad (2)$$

$$[S_z] = \frac{\hbar}{2} \text{Tr} \left[ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \right] = \frac{\hbar}{2} (a-d) \quad (3)$$

هم چنین از آن جا که  $\text{Tr} \rho = 1$  داریم:  $a+d=1$  (4)

$$(3), (4) \rightarrow 2a = 1 + \frac{2}{\hbar} [S_z] \quad (5)$$

$$(1), (2) \rightarrow 2b = \frac{2}{\hbar} ([S_x] - i[S_y]) \quad (6)$$

$$(4), (5) \rightarrow d = \frac{1}{2} - \frac{[S_z]}{\hbar}$$

$$(6), (1) \rightarrow c = \frac{1}{\hbar} ([S_x] + i[S_y])$$

$$\rightarrow \rho = \begin{pmatrix} \frac{1}{2} + \frac{[S_z]}{\hbar} & \frac{[S_x] - i[S_y]}{\hbar} \\ \frac{[S_x] + i[S_y]}{\hbar} & \frac{1}{2} - \frac{[S_z]}{\hbar} \end{pmatrix}$$

3.14)

$$\rho = \sum w_i |\alpha_i\rangle\langle\alpha_i| ; \sum w_i = 1$$

We have 3 states with same  $w_i$ :  $\rho = \frac{1}{3} [|\alpha\rangle\langle\alpha| + |\beta\rangle\langle\beta| + |\gamma\rangle\langle\gamma|]$

$$|\alpha\rangle\langle\alpha| = \frac{1}{2} (|0\rangle + |1\rangle)(\langle 0| + \langle 1|) = \frac{1}{2} [ |0\rangle\langle 0| + |0\rangle\langle 1| + |1\rangle\langle 0| + |1\rangle\langle 1| ]$$

$$|\beta\rangle\langle\beta| = \frac{1}{2} (|1\rangle + |2\rangle)(\langle 1| + \langle 2|) = \frac{1}{2} [ |1\rangle\langle 1| + |1\rangle\langle 2| + |2\rangle\langle 1| + |2\rangle\langle 2| ]$$

$$\rightarrow \rho = \frac{1}{6} |0\rangle\langle 0| + \frac{1}{6} |0\rangle\langle 1| + \frac{1}{6} |1\rangle\langle 0| + \frac{1}{6} |1\rangle\langle 1| + \frac{1}{6} |1\rangle\langle 2| + \frac{1}{6} |2\rangle\langle 1| + \frac{1}{6} |2\rangle\langle 2|$$

$$\rho = \begin{pmatrix} \frac{1}{6} & \frac{1}{6} & 0 \\ \frac{1}{6} & \frac{1}{3} & \frac{1}{6} \\ 0 & \frac{1}{6} & \frac{1}{2} \end{pmatrix}$$

which is normal.

$$H = \hbar\omega (n + \frac{1}{2})$$

$$[H] = \text{Tr}(\rho H) = \text{Tr} \left[ \begin{pmatrix} \frac{1}{6} & \frac{1}{6} & 0 \\ \frac{1}{6} & \frac{1}{3} & \frac{1}{6} \\ 0 & \frac{1}{6} & \frac{1}{2} \end{pmatrix} \begin{pmatrix} \hbar\omega/2 & 0 & 0 \\ 0 & 3/2 \hbar\omega & 0 \\ 0 & 0 & 5/2 \hbar\omega \end{pmatrix} \right]$$

$$= \hbar\omega \left( \frac{1}{12} + \frac{1}{2} + \frac{5}{4} \right) = \hbar\omega \left( \frac{1+6+15}{12} \right) = \hbar\omega \frac{22}{12} = \hbar\omega \frac{11}{6}$$