

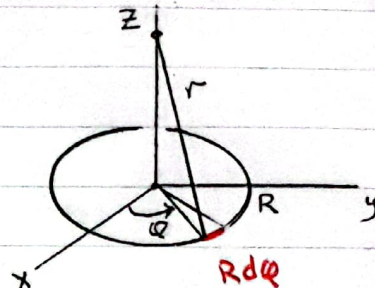
General Physics II

Solutions to the Final Exam

Spring 2023

$$1. \quad a) \quad V(z) = k \int \frac{dq}{r} = k \int_0^{2\pi} \frac{R \lambda d\varphi}{\sqrt{z^2 + R^2}} = \frac{k R \lambda}{\sqrt{z^2 + R^2}} \int_0^{2\pi} d\varphi$$

$$= \frac{k \lambda R 2\pi}{\sqrt{z^2 + R^2}} = \frac{k q}{\sqrt{z^2 + R^2}}$$



$$b) \quad \vec{E} = -\vec{\nabla} V = -\left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z}\right) V(z)$$

$$= -\hat{z} \frac{d}{dz} V(z) = -\hat{z} \frac{d}{dz} \frac{k q}{\sqrt{z^2 + R^2}} = + \frac{k q z}{(z^2 + R^2)^{3/2}} \hat{z}$$

$$\lambda = \frac{q}{2\pi R}$$

$$c) \quad \text{For } z \ll R: \quad V(z) = \frac{k q}{R \sqrt{1 + z^2/R^2}} \xrightarrow{z \ll R} \frac{k q}{R} \left(1 - \frac{z^2}{2R^2}\right) \xrightarrow{z=0} \frac{k q}{R}$$

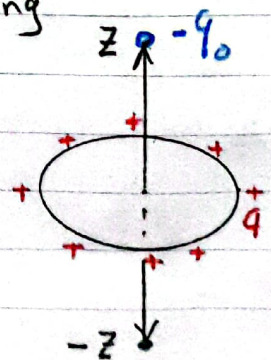
$$\vec{E}(z) = \frac{k q z \hat{z}}{R^3 (1 + z^2/R^2)^{3/2}} \xrightarrow{z \ll R} \frac{k q z}{R^3} \left(1 - \frac{3}{2} \frac{z^2}{R^2}\right) \xrightarrow{z=0} 0$$

$$\text{For } z \gg R: \quad V(z) = \frac{k q}{z \sqrt{1 + R^2/z^2}} \xrightarrow{z \gg R} \frac{k q}{z} \left(1 - \frac{R^2}{2z^2}\right) \xrightarrow{z \gg R} \frac{k q}{z}$$

$$\vec{E}(z) = \frac{k q z \hat{z}}{z^3 (1 + R^2/z^2)^{3/2}} \xrightarrow{z \gg R} \frac{k q \hat{z}}{z^2} \left(1 - \frac{3}{2} \frac{R^2}{z^2}\right) \xrightarrow{z \gg R} \frac{k q}{z^2} \hat{z}$$

$\vec{E}(0) = 0$ by symmetry. For $z \gg R$ the results are those of a point charge.

d) The negative test charge is attracted to the ring and executes periodic motion with amplitude z about zero.



For $z \ll R$ the potential energy is

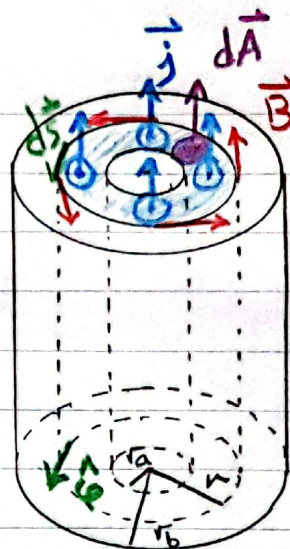
$$U(z) = -q_0 V(z) = -\frac{k q q_0}{R} + \frac{k q q_0}{2R^3} z^2$$

constant

quadratic \Rightarrow simple harmonic motion in z

$$\sim \frac{1}{2} K z^2 \Rightarrow \omega_0 = \sqrt{\frac{K}{m}} = \sqrt{\frac{k q q_0}{R^3 m}}$$

$$\begin{aligned}
 2. \quad \int \vec{B} \cdot d\vec{s} &= \mu_0 I_{in} = \mu_0 \int_{r_a}^r \vec{j} \cdot d\vec{A} \\
 \Rightarrow B \int ds &= \mu_0 \int_{r_a}^r \frac{j_0}{a} r' (r' dr' d\phi) \\
 \Rightarrow 2\pi r B &= \frac{\mu_0 j_0}{a} 2\pi \frac{1}{3} (r^3 - r_a^3) \\
 I &= \int_{r_a}^r \vec{j} \cdot d\vec{A} = \frac{j_0}{a} 2\pi \frac{1}{3} (r^3 - r_a^3) \\
 \vec{B}(r) &= \frac{\mu_0}{2\pi r} \left(I \frac{r^3 - r_a^3}{r_b^3 - r_a^3} \right) \hat{\phi}
 \end{aligned}$$



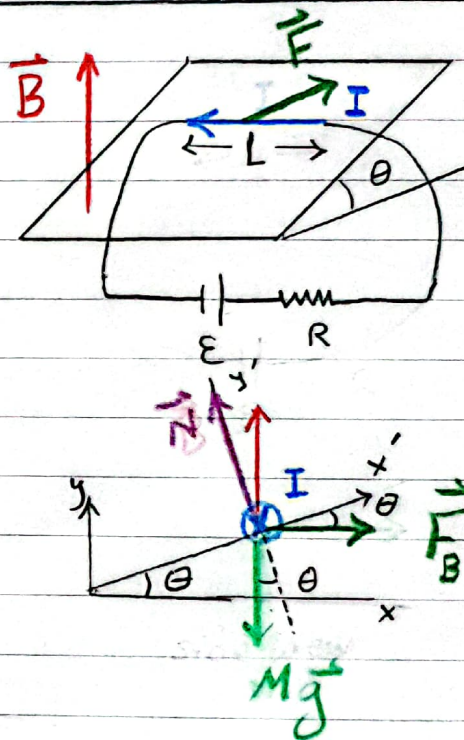
$$3. \quad \vec{F}_B = I \vec{L} \times \vec{B} = ILB \hat{x}$$

$$\text{Equilibrium} \Rightarrow \hat{x}: F_B \cos \theta = Mg \sin \theta$$

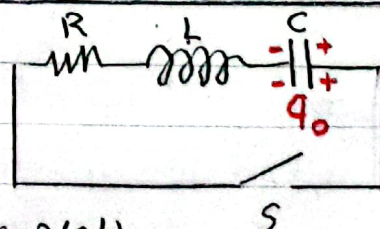
$$\hat{y}: N = Mg \cos \theta$$

$$\Rightarrow F_B = ILB = Mg \tan \theta$$

$$\Rightarrow I = \frac{Mg \tan \theta}{LB}$$



$$4. \quad L \frac{dI}{dt} + IR + \frac{q}{C} = 0$$



$$\Rightarrow L \frac{d^2 q}{dt^2} + R \frac{dq}{dt} + \frac{1}{C} q = 0 \quad \text{Try } q(t) = q_0 \exp(at)$$

$$\Rightarrow q_0 (La^2 + Ra + \frac{1}{C}) = 0 \Rightarrow a = \frac{1}{2L} (-R \pm \sqrt{R^2 - 4L/C}) = -\frac{R}{2L} \pm i \sqrt{\frac{1}{LC} - (\frac{R}{2L})^2}$$

$$q(t) = A e^{(-\frac{R}{2L} + i\omega')t} + B e^{(-\frac{R}{2L} - i\omega')t} \in \mathbb{R} \Rightarrow B = A^*$$

$$A = |A| e^{i\phi} \Rightarrow B = |A| e^{-i\phi}$$

$$\omega' = \sqrt{\frac{1}{LC} - (\frac{R}{2L})^2}$$

s.a.m

$$\Rightarrow q(t) = |A| \left\{ e^{[-\frac{R}{2L} + i\omega']t + i\phi} + e^{[-\frac{R}{2L} - i\omega']t - i\phi} \right\}$$

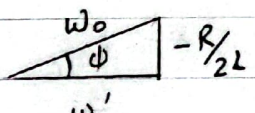
$$= 2|A| e^{-\frac{R}{2L}t} \cos(\omega't + \phi)$$

$$I(t) = \frac{dq}{dt} = 2|A| e^{-\frac{R}{2L}t} \left[-\omega' \sin(\omega't + \phi) - \frac{R}{2L} \cos(\omega't + \phi) \right]$$

Initial conditions

$$q(0) = q_0 = 2|A| \cos(\phi)$$

$$I(0) = 0 = 2|A| \left[-\omega' \sin(\phi) - \frac{R}{2L} \cos(\phi) \right] \Rightarrow \tan \phi = -\frac{R}{2L\omega'}$$

$$\sqrt{\omega'^2 + \left(\frac{R}{2L}\right)^2} = \sqrt{\omega_0^2 - \left(\frac{R}{2L}\right)^2 + \left(\frac{R}{2L}\right)^2} = \omega_0 \quad \cos \phi = \frac{\omega'}{\omega_0}$$


$$V_C = \frac{1}{C} q(t) = \frac{1}{C} q_0 \frac{\omega_0}{\omega'} e^{-\frac{R}{2L}t} \cos(\omega't + \phi)$$

$$V_R = RI(t) = -Rq_0 \frac{\omega_0^2}{\omega'} e^{-\frac{R}{2L}t} \left[\frac{\cos \phi}{\omega_0} \sin(\omega't + \phi) + \frac{\overbrace{R/2L}^{-\sin \phi}}{\omega_0} \cos(\omega't + \phi) \right]$$

$$= -Rq_0 \frac{\omega_0^2}{\omega'} e^{-\frac{R}{2L}t} \sin(\omega't + \phi - \phi)$$

$$V_L = L \frac{dI}{dt} = -Lq_0 \frac{\omega_0^3}{\omega'} e^{-\frac{R}{2L}t} \left[\frac{\cos \phi}{\omega_0} \cos \omega't - \frac{\overbrace{R}^{+\sin \phi}}{2L\omega_0} \sin \omega't \right]$$

$$= -Lq_0 \frac{\omega_0^3}{\omega'} e^{-\frac{R}{2L}t} \cos(\omega't - \phi)$$

You can check that

$$V_C(t) + V_R(t) + V_L(t) = 0$$

