

## **ADASI Test**

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### **Requirements**

The requirements to run the code are:

Gstreamer 1.0

OpenCV 3.4.2

cairo

CMake 3.5.1

C++ 17

VLC >3.0.6

### **Setup**

In order to set up, compile and run the code you have to follow the next steps:

- Install Gstreamer 1.0
- Install OpenCV 3.4.2
- Install CMake 3.5.1
- Install VLC >3.0.6
- Clone the repository:
  - Clone the repository using the next link:  
[https://github.com/deivy311/ADASI\\_Test](https://github.com/deivy311/ADASI_Test)
- If you don't have the repository, you can download the zip file, attached to the email named ADASI\_Test.zip and unzip it.
- Compile the code.

Go to the folder where you clone the repository and run the next commands:

```
mkdir build
```

```
cd build
```

```
cmake ../
```

```
make
```

You should see something like the next image.

### **Running the code**

Go to the folder where you compile the code and run the executable file, for this a better explanation is in this section.

There are a total of 5 executables files, from de point\_0 to point\_5, each one of them has a different functionality. The parameters from Point 0 to Point 2\_3 are the same, the only difference is the functionality of each one. And the parameters from Point 4 to Point 5 are the same.

For **point\_0, point\_1 and point\_2\_3** the parameters are:

**Source type:** Defines if we want to stream the camera or a file, by default is **autovideosrc** there are only two posible options:

**videotestsrc or autovideosrc**

**Examples:**

The input example for both are:

**Camera case:**

`./point_1 -s videotestsrc`

**File case:**

`./point_0 -s autovideosrc`

**Host:** Defines the host to stream by default is "127.0.0.1"

**Examples:**

**Localhost case:**

`sudo ./point_0 -h 127.0.0.1`

**Port:** Defines the port to stream by default is "5002"

**Examples:**

**By default case:**

`sudo ./point_0 -p 5002`

For **point\_4, point\_5 and point\_2\_3** the parameters are same as before but there a couple more:

**RTSP port:** Defines the RTSP port to stream by default is "5001"

**Examples:**

By default case:

`sudo ./point_4 -p_rtsp 5001`

**RTSP video file path:** Defines the RTSP video file path to stream by default is `"../Files/video_test_2.mp4"`, these videos are in the Files folder and also in the build/bin folder.

**Examples:**

**By default case:**

```
sudo ./point_5 -f ../Files/video_test_2.mp4
```

## Results

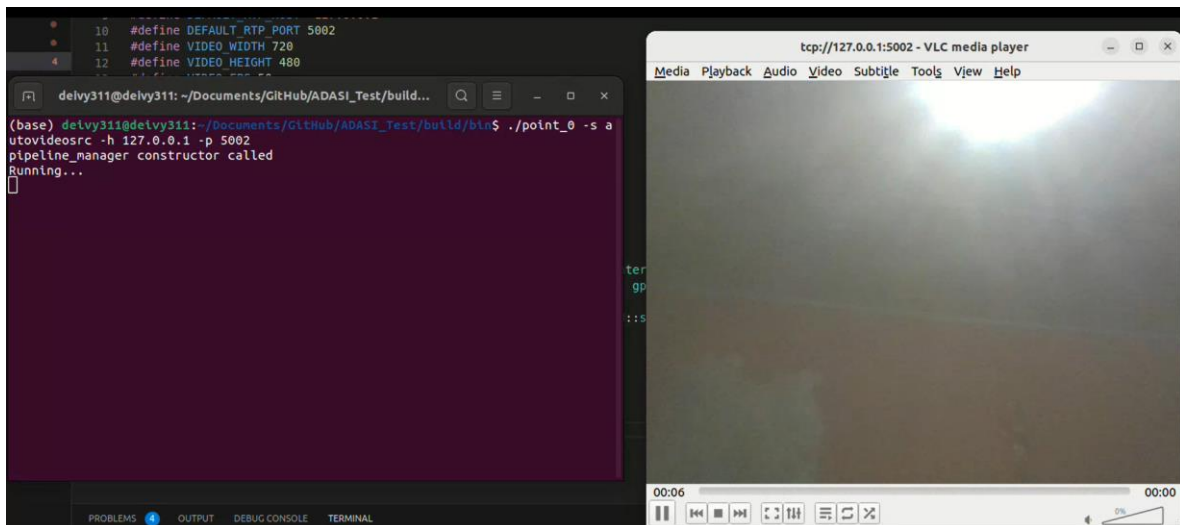
The executables **point\_0** and **point\_1**, can show the results for the literal 1, it is a simple RTP pipeline where can stream a video file or a camera.

**Case 1.1:** RTP with no overlay

Given the next command input:

```
./point_0 -s autovideosrc -h 127.0.0.1 -p 5002
```

We can see the next results:



In order to see the results by yourself you have to open VLC and go to Media -> Open Network Stream and put the next address:

```
tcp://127.0.0.1:5002
```

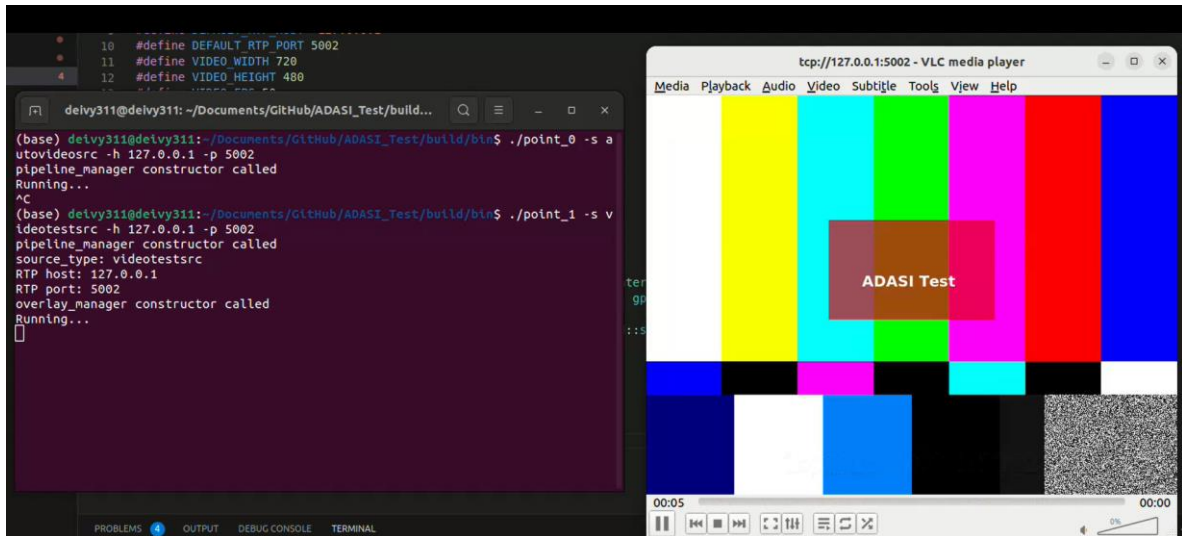
The video related to this is in the Folder Results, named `point_1_no_overlay.webm` which means it only streams video without any overlay.

**Case 1.2:** RTP with overlay, demo file

Given the next command input:

```
./point_1 -s videotestsrc -h 127.0.0.1 -p 5002
```

We can see the next results:



In order to see the results by yourself you have to open VLC and go to Media -> Open Network Stream and put the next address:

`tcp://127.0.0.1:5002`

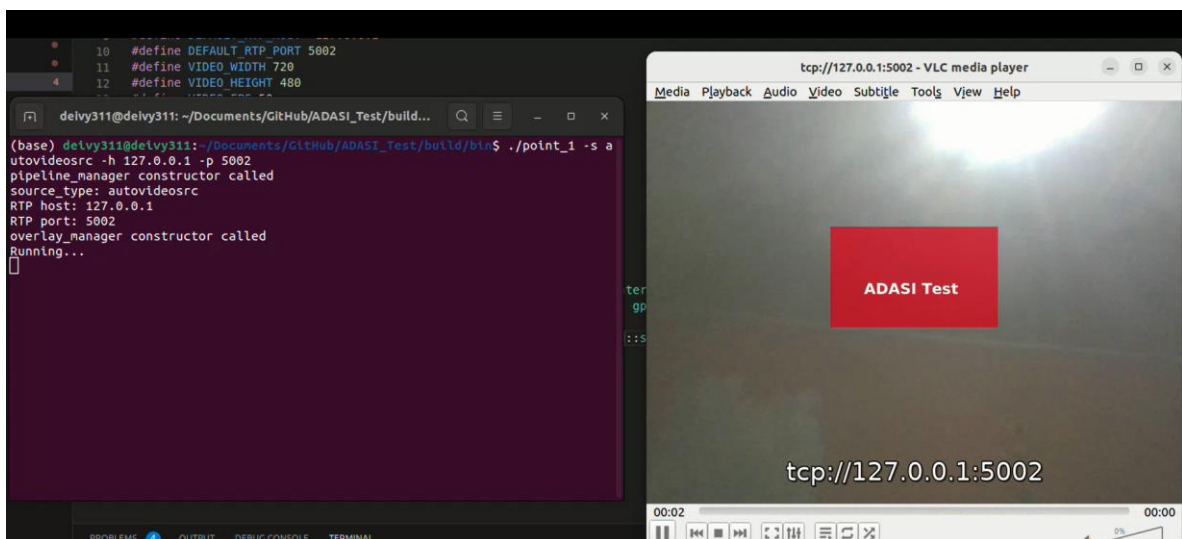
The video related to this is in the Folder Results, named `point_1_overlay_file.webm` which means it only streams video with overlay, in this case a red box.

### Case 1.3: RTP with overlay, camera

Given the next command input:

`./point_1 -s autovideosrc -h 127.0.0.1 -p 5002`

We can see the next results:



In order to see the results by yourself you have to open VLC and go to Media -> Open Network Stream and put the next address:

tcp://127.0.0.1:5002

The video related to this is in the Folder Results, named point\_1\_overlay\_camera.webm which means it only streams a camera video with overlay, in this case a red box.

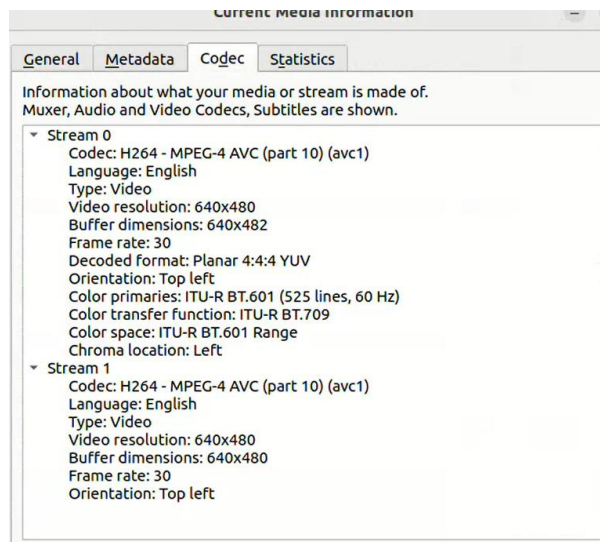
The executable **point\_2\_3**, can show the results for the literal 2 and 3, it is a RTP pipeline where can stream a video file or a camera and also can stream a video file or a camera with dynamic overlay and output the video in H264.

**Case 2.1:** RTP with dynamic overlay in H264 format video output, demo file

Given the next command input:

```
./point_2_3 -s videotestsrc -h 127.0.0.1 -p 5002
```

We can see the next results:



In order to see the results by yourself you have to open VLC and go to Media -> Open Network Stream and put the next address:

tcp://127.0.0.1:5002

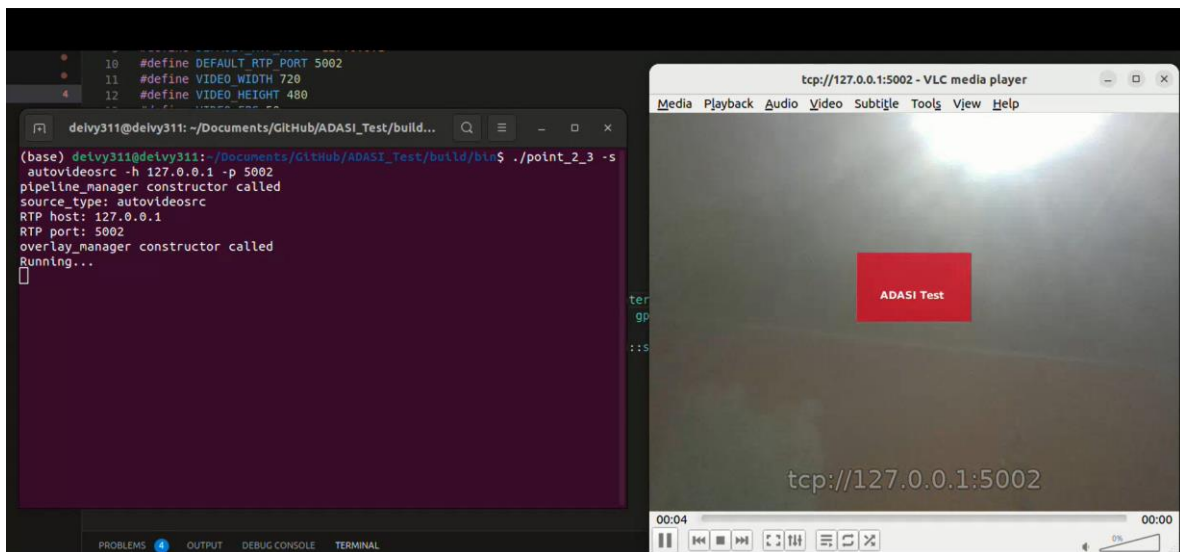
The video related to this is in the Folder Results, named point\_2\_3\_dynamic\_overlay\_file.webm which means it only streams a video file with dynamic overlay and output the video in H264 format.

**Case 2.2:** RTP with dynamic overlay in H264 format video output, camera.

Given the next command input:

```
./point_2_3 -s autovideosrc -h 127.0.0.1 -p 5002
```

We can see the next results:



In order to see the results by yourself you have to open VLC and go to Media -> Open Network Stream and put the next address:

```
tcp://127.0.0.1:5002
```

The video related to this is in the Folder Results, named `point_2_3_dynamic_overlay_camera.mp4` which means it only streams a camera video with dynamic overlay and output the camera video in H264 format.

The Executable **point\_4**, can show the results for the literal 4, it is a RTSP pipeline over RTP where can stream a video file or a camera with dinamica overlay and output the video in H264.

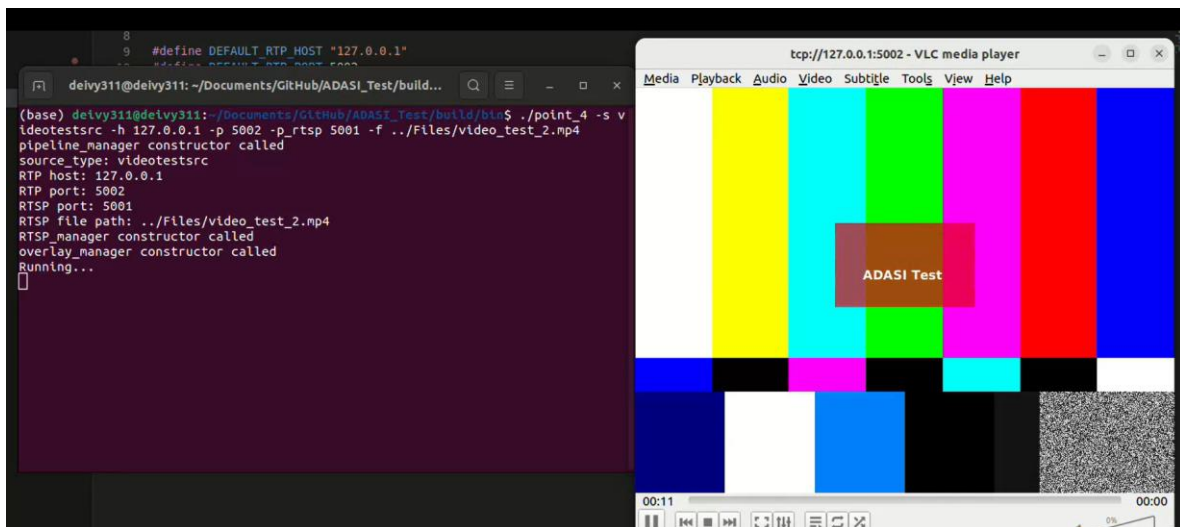
**Case 4.1:** RTSP with dinamic overlay in H264 format video output, demo file

Given the next command input:

```
./point_4 -s videotestsrc -h 127.0.0.1 -p 5002 -p_rtsp 5001 -f ../Files/video_test_2.mp4
```

We can see the next results:

**RTP server**

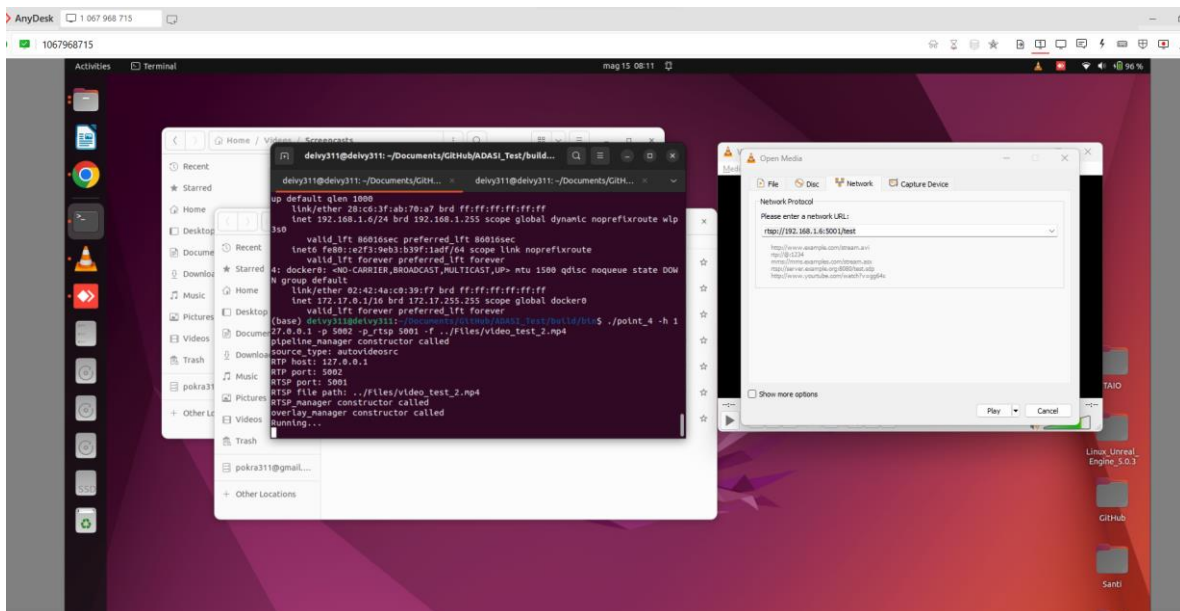


The video related to this is in the Folder Results, named point\_4\_RTP\_dynamic\_overlay\_file.webm which means it streams a video file with dynamic overlay and output the video in H264 format.

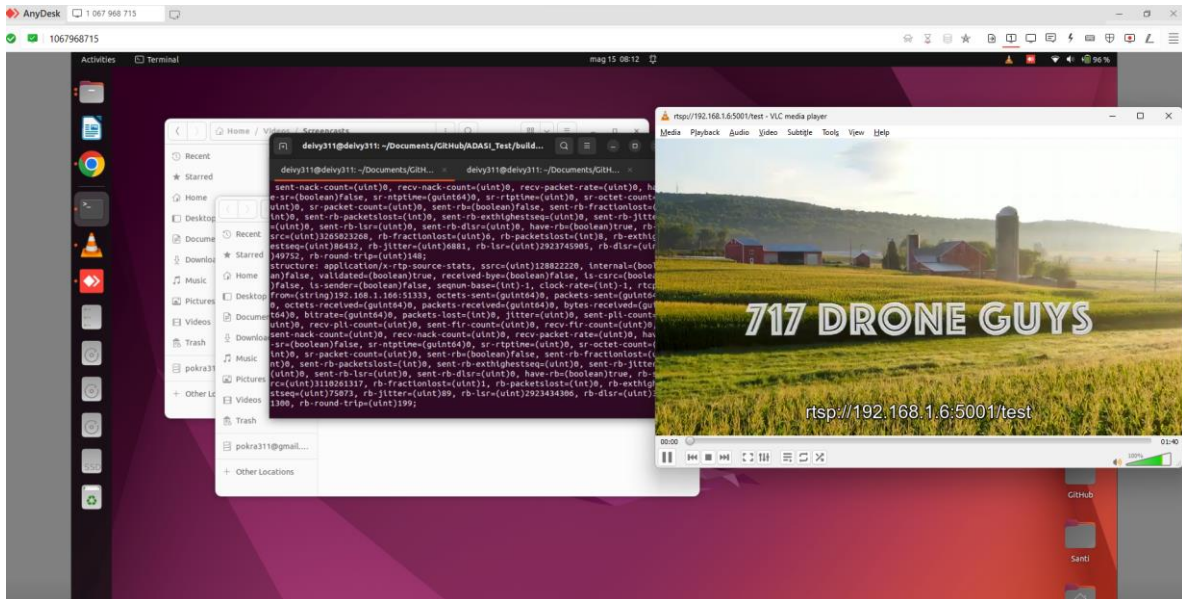
The VLC command to see the results is:

tcp://127.0.0.1:5002

## RTSP server







The video related to this is in the Folder Results, named `point_4_RTSP_dynamic_overlay_file.mp4` which means it streams a video file with dynamic overlay and output the video in H264 format.

The VLC command to see the results is:

`rtsp://192.168.1.6:5001/test` # this is the ip of the same computer but viewed from

The Executable **point\_5**, can show the results for the literal 5, it is a RTSP pipeline over RTP where can stream a video file or a camera with dynamic overlay and output the video in H264. As an additional feature the video streamed is stored.



### Case 5.1: Storing file.

Given the next command input:

```
./point_5 -s autovideosrc
```

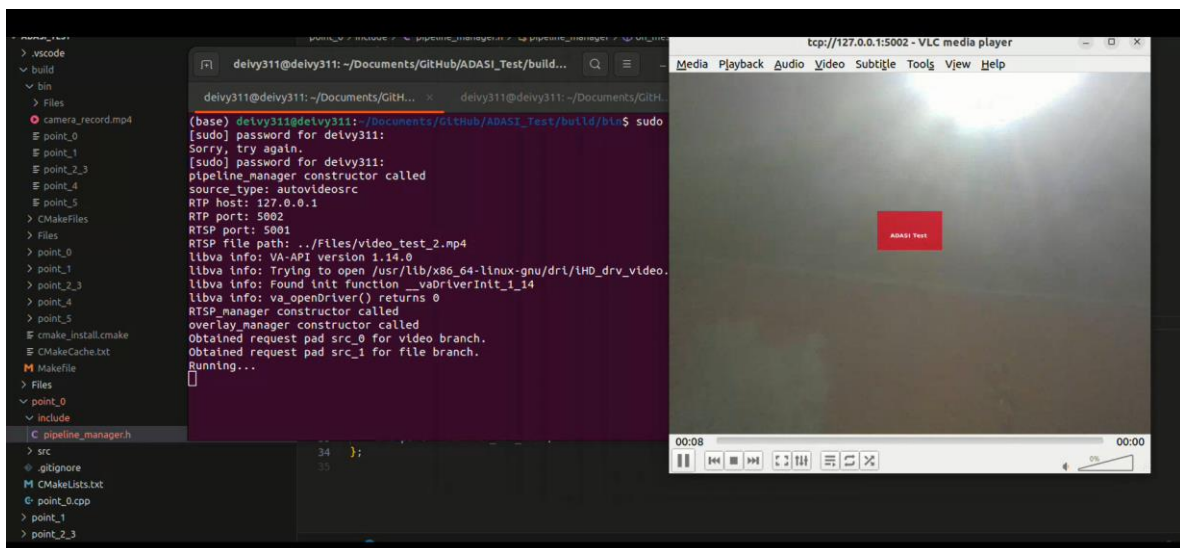
The video related to this is in the Folder Results, named `point_4_RTP_dynamic_overlay_camera.mp4` which means it streams a camera video with dynamic overlay and output the video in H264 format.

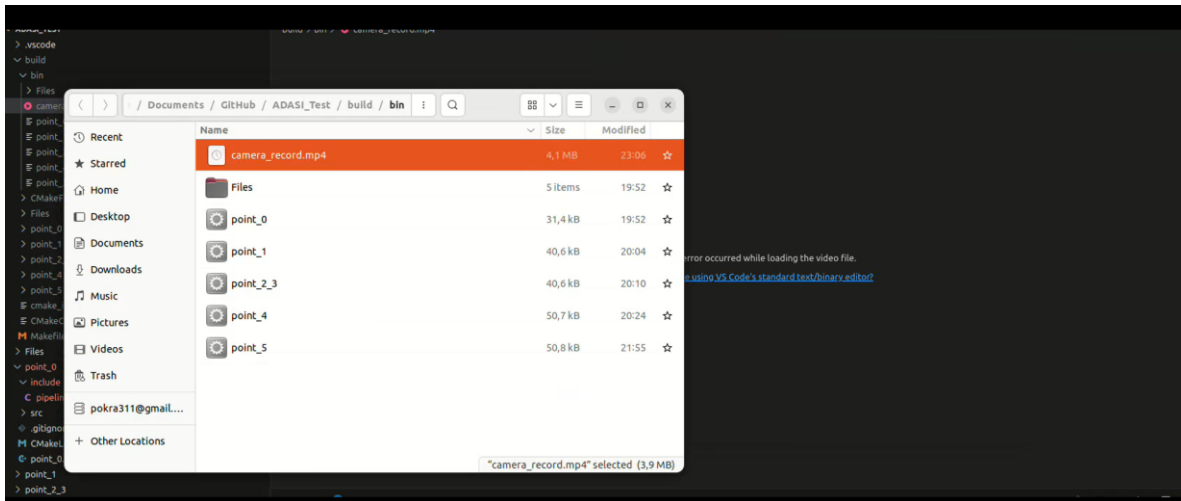
The VLC command to see the results is:

```
tcp://127.0.0.1:5002
```

```
rtsp://127.0.0.1:5001/test another
```

The video related to this is in the Folder Results, named `point_5_RTSP_RTP_dynamic_overlay_camera.mp4` which means it streams a camera video with dynamic overlay and output the video in H264 format.





Metrics:

In the next image we can see the metrics computed for the point\_4 and point\_5

