view_frames Result
Recorded at time: 1324503644.147
/odom_combined
Broadcaster: /robot_pose_ekf
Average rate: 20.359 Hz
Most recent transform: 1324503461.161 sec old
Buffer length: 4.961 sec
/base_footprint
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/base_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/base_bellow_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/base_laser_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/torso_lift_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/bl_caster_rotation_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/br_caster_rotation_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/fl_caster_rotation_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/fr_caster_rotation_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/torso_lift_motor_screw_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/head_pan_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/imu_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/l_torso_lift_side_plate_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/laser_tilt_mount_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/r_torso_lift_side_plate_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/l_shoulder_pan_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/r_shoulder_pan_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/bl_caster_l_wheel_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/bl_caster_r_wheel_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/br_caster_l_wheel_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/br_caster_r_wheel_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/fl_caster_l_wheel_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/fl_caster_r_wheel_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/fr_caster_l_wheel_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/fr_caster_r_wheel_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/head_tilt_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/laser_tilt_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/l_shoulder_lift_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/r_shoulder_lift_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/head_plate_frame
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/l_upper_arm_roll_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/r_upper_arm_roll_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/sensor_mount_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/projector_wg6802418_frame
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/l_upper_arm_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/r_upper_arm_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/double_stereo_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/high_def_frame
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/projector_wg6802418_child_frame
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/l_elbow_flex_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/r_elbow_flex_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/narrow_stereo_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/wide_stereo_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/high_def_optical_frame
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/l_forearm_roll_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/r_forearm_roll_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/narrow_stereo_gazebo_l_stereo_camera_frame
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/narrow_stereo_optical_frame
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/wide_stereo_gazebo_l_stereo_camera_frame
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/wide_stereo_optical_frame
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/l_forearm_cam_frame
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/l_forearm_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/r_forearm_cam_frame
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/r_forearm_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/narrow_stereo_gazebo_l_stereo_camera_optical_frame
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/narrow_stereo_gazebo_r_stereo_camera_frame
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/wide_stereo_gazebo_l_stereo_camera_optical_frame
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/wide_stereo_gazebo_r_stereo_camera_frame
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/l_forearm_cam_optical_frame
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/l_wrist_flex_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/r_forearm_cam_optical_frame
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/r_wrist_flex_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/narrow_stereo_gazebo_r_stereo_camera_optical_frame
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/wide_stereo_gazebo_r_stereo_camera_optical_frame
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/l_wrist_roll_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/r_wrist_roll_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/l_gripper_palm_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/r_gripper_palm_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/l_gripper_led_frame
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/l_gripper_motor_accelerometer_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/l_gripper_tool_frame
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/l_gripper_r_finger_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/l_gripper_l_finger_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/l_gripper_motor_slider_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/r_gripper_led_frame
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/r_gripper_motor_accelerometer_link
Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 1324503460.652 sec old
Buffer length: 4.960 sec
/r_gripper_tool_frame
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/r_gripper_r_finger_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/r_gripper_l_finger_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/r_gripper_motor_slider_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/l_gripper_r_finger_tip_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/l_gripper_l_finger_tip_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/l_gripper_motor_screw_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/r_gripper_r_finger_tip_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/r_gripper_l_finger_tip_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/r_gripper_motor_screw_link
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/l_gripper_l_finger_tip_frame
Broadcaster: /robot_state_publisher
Average rate: 31.036 Hz
Most recent transform: 1324503461.145 sec old
Buffer length: 4.962 sec
/r_gripper_l_finger_tip_frame