CPSC 457 Fall 2021 – Assignment 2

Due date is posted on D2L.

Individual assignment. Group work is NOT allowed.

Weight: 19% of the final grade.

Imagine you are writing a program that needs to call a function written by someone else. Unfortunately, this function occasionally misbehaves; sometimes this function crashes, sometimes it runs for far too long, and occasionally it never returns. How can you call such unsafe code in your program?

A possible answer to this question is that you can safely call unsafe code in your own program by a clever use of the fork() system call. In this assignment you will be given an unsafe code, and you will be asked to write code that invokes such unsafe code in a safe manner.

Overall description

For this assignment you need to write a function safecall with the signature:

```
int safecall(int n);
```

The purpose of safecall() function is to call another function, unsafe(), and return the result of that call. If the unsafe function was well behaved, you could write safecall like this:

```
int safecall(int i) {
  return unsafe(i);
}
```

However, the unsafe() function can misbehave, and you need to address this in your implementation of safecall. The misbehavior of unsafe() is that it sometimes runs for too long, sometimes it runs forever, and other times it even crashes. You need to write safecall() in such a way that it calls unsafe() similar to the above code, but also detects if unsafe misbehaves. If you detect no misbehavior, you simply return the result unsafe(), but if you detect misbehavior, you return special values (-1 or -2) as follows:

- If unsafe(i) runs for longer than 1 second, you stop the execution of unsafe(), and return -1
- if unsafe(i) crashes, you return -2
- If unsafe(i) returns a result in under 1 second, you return the result.

In order to deal with unsafe()'s misbehavior, you need to create a child process (using fork system call) and run unsafe() in the child process. The parent will then monitor the child process for misbehavior. You will also need a mechanism for transferring the results obtained by calling unsafe() in the child process back to the parent process. Please see the hints at the end of this documents for suggestions on how to accomplish this.

Starter code

Download the starter code from GitLab, and compile it:

```
$ git clone https://gitlab.com/cpsc457f21/safecall.git
```

```
$ cd safecall
$ make
```

The starter code includes an incomplete implementation of safecall() in the file safecall.cpp. The starter code also includes several example test inputs (see description below on their format). To run the code on test1.txt file, you can:

```
$ ./safecall < test1.txt
Finished in 0s
Correct results, good job.</pre>
```

Please note that some of the test files will cause the incomplete safecall function to misbehave (crash, run forever, or run for too long). Once you fix the safecall implementation, all test files should work fine.

Also, please note that the test files provided in the starter code are only samples. It is your job to design your own test files and test your implementation thoroughly before submitting.

Driver program

The included driver program (main.cpp) configures the unsafe function based on data from standard input. The driver then calls your safecall() function repeatedly. The driver then displays the outputs from your safecall() and compares them to the expected outputs. By default, the driver will only show outputs that are incorrect:

```
$ ./safecall < test4.txt</pre>
Only displaying outputs with errors
_____
      Expected
                 Observed
Index | Output
                Output
                1
   1 | -1
                           ! wrong
   3 | -1
                l 3
                           ! wrong
   5 -1
                5
                           ! wrong
   7 | -1
                1 7
                           ! wrong
   8 | -1
                 8
                           ! wrong
  10
      -1
                 10
                           ! wrong
  11
      -1
                11
                           ! wrong
  12 | -1
                 12
                           ! wrong
  13 l
      -1
                 13
                           ! wrong
  14 | -1
                14
                           ! wrong
Finished in 50.004s
Wrong results :(
```

To see more debugging information, and to see all outputs (including the correct ones), you can pass all as a command line argument to the executable:

```
$ ./safecall all < test4.txt</pre>
```

If you do not want to see the outputs at all, and only want to see whether your safecall() function worked correctly, pass none keyword to the executable:

```
$ ./safecall none < test4.txt
Finished in 50.004s
Wrong results :(</pre>
```

Input format

The input format is described here to help you design your own test files.

The input to the driver is a text file containing a set of integers, separated by white spaces (spaces, tabs or new lines). The driver loads these integers into an array input[] and then uses that array to configure the unsafe() function as follows:

<pre>input[i] >= 1</pre>	unsafe(i) immediately returns input[i]
input[i] == 0	unsafe(i)sleeps for 0.5s, then returns i
input[i] == -1	unsafe(i)sleeps for 5s, then returns i
input[i] == -2	unsafe(i)never returns
input[i] <= -3	unsafe(i)crashes

The driver then calls safecall(i) for every i in range [0, input.size()-1].

For example, if the input contains 7 numbers: 55 0 3 -1 -2 10 -50, then the driver will call safecall(i) on every i in range [0, 6], and usafe() will behave as follows:

i	<pre>input[i]</pre>	unsafe(i) behavior	Expected behavior of safecall()
0	55	Returns 55	returns 55 immediately
1	0	Returns 1 after 0.5s delay	returns 1 after 0.5s
2	3	Returns 3 immediately	returns 3 immediately
3	-1	Returns 3 after 5s delay	returns -1 after 1s
4	-2	Never returns	returns -1 after 1s
5	10	Returns 10 immediately	returns 10 immediately
6	-50	Crashes	returns -2 immediately

Submission

Submit a single file to D2L for this assignment:

safecall.cpp	Containing your implementation of sefacall()
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Write your entire implementation of safecall() in the file safecall.cpp. Please, only modify the safecall.cpp file, and **do not modify** any other source files. The safecall.cpp that you submit must compile and run with the rest of the code in the GitLab repository. During marking, we may use a slightly different driver to test your code, so it is important that you follow the above instructions.

Appendix - Hints

Sharing results between child/parent and dealing with crashes

In the child process you can call unsafe(), and if it returns, you can write its result to a temporary file. If unsafe() does not return, i.e. it crashes, your child will automatically exit, and the temporary file will not be created. The parent can detect whether the child finished or crashed by detecting whether a file was created or not.

You can use fopen, fclose, fread, fwrite and unlink system calls for the above. I recommend you use the /tmp directory for your temporary file, as it will be faster to read/write files there than in your home directory.

Note: If you know how to use mmap and munmap to setup shared memory, you can use those instead of temporary files to make your code run slightly more efficiently. This is **not required**.

Detecting if child runs for too long

I suggest using a busy loop with sleep in the parent process to detect when child runs for longer than 1s. Inside the busy loop you should periodically check whether the child is finished. To this end you should use the waitpid() system call, in non-blocking mode. I suggest you use it like this:

```
auto res = waitpid (pid, NULL, WNOHANG);
```

where pid is the child process ID (returned by fork). The WNOHANG option forces waitpid to return immediately. If the child finished, waitpid will return a positive integer, otherwise it will return a number smaller than 1.

To sleep for small amount of time in your loop, I suggest you use:

```
std::this thread::sleep for(std::chrono::microseconds(nap time));
```

where nap_time is the number of microseconds you would like to sleep. You can experiment with different values for this delay, but I found that 1ms worked well for me. Do not set the delay too long though, as it would slow down your code when unsafe() returns quickly.

In order to exit the busy loop in case unsafe runs longer than 1s, you will need to measure elapsed time since creating the child. To this end, I suggest you save the current time before calling fork:

```
auto start_time = std::chrono::steady_clock::now();
auto pid = fork();
```

Then, inside the busy loop, you can find out how much time has elapsed using code like this:

```
auto curr_time = std::chrono::steady_clock::now();
double elapsed = std::chrono::duration_cast<std::chrono::microseconds>
    (curr_time - start_time).count() / 1000000.0;
if( elapsed > 1.0) { /* unsafe() is taking too long */ }
```

To kill the child process if it runs longer than 1s, use:

```
kill( pid, SIGKILL);
```

Alternative way for detecting if child runs for too long

An alternative way of detecting whether the child runs for too long is to use a 2nd child process, instead of a busy wait loop. The 2nd child will simply sleep for 1 second and then exit. In the parent process you can then detect which child finished first by calling pid=wait(NULL), which will return the pid of the child that finished first. If the first child finishes first, that means it finished under 1s. If the second child finishes first, that means the first child is still running. Please remember to send SIGKILL to the child that did not yet finish, and then call another wait() for it to terminate.

This method can be simpler to program than the one in the previous hint, but it can also be quite a bit harder to debug. Therefore I recommend you use hint 1.

Appendix – correct solution

I made my sample solution available as an executable on linuxlab:

```
~pfederl/public/cpsc457f21/safecall
```

Here is how you can run it, for example, on test7.txt:

```
~pfederl/public/cpsc457f21/safecall all < test7.txt
```

General information about all assignments

- 1. All assignments are due on the date listed on D2L. Late submissions will not be marked.
- 2. Extensions may be granted only by the course instructor.
- 3. After you submit your work to D2L, verify your submission by re-downloading it.
- 4. You can submit many times before the due date. D2L will simply overwrite previous submissions with newer ones. It is better to submit incomplete work for a chance of getting partial marks, than not to submit anything. Please bear in mind that you cannot re-submit a single file if you have already submitted other files. Your new submission would delete the previous files you submitted. So please keep a copy of all files you intend to submit and resubmit all of them every time.
- 5. Assignments will be marked by your TAs. If you have questions about assignment marking, contact your TA first. If you still have questions after you have talked to your TA, then you can contact your instructor.
- 6. All programs you submit must run on linuxlab.cpsc.ucalgary.ca. If your TA is unable to run your code on the Linux machines, you will receive 0 marks for the relevant question.
- 7. Unless specified otherwise, you must submit code that can finish on any valid input under 10s on linuxlab.cpsc.ucalgary.ca, when compiled with -02 optimization. Any code that runs longer than this may receive a deduction, and code that runs for too long (about 30s) will receive 0 marks.
- 8. **Assignments must reflect individual work**. Here are some examples of what you are not allowed to do for individual assignments: you are not allowed to copy code or written answers (in part, or in whole) from anyone else; you are not allowed to collaborate with anyone; you are not allowed to share your solutions (code or pseudocode) with anyone; you are not allowed to sell or purchase a solution; you are not allowed to make your code available publicly. This list is not exclusive. For further information on plagiarism, cheating and other academic misconduct, check the information at this link: http://www.ucalgary.ca/pubs/calendar/current/k-5.html.

