CPE 301 - 1001 DESIGN ASSIGNMENT 2

The goal of the assignment is use GPIO, delays, and Interrupts:

- 1. Design a delay subroutine to generate a delay of 0.15 sec.
- 2. Connect a switch to PORTC.1 to poll for an event to turn on the led at PORTB.5 for 1.5 sec after the event.
- 3. Continue with task 2, connect a switch to INTO (PD2 pin) (active high turn on the pull up transistor) and using an interrupt mechanism turn on the led at PORTB.5 for 3 sec after the event.
- 4. Submit codes and demos for three tasks, one for (2), another for (3), and another for (2 & 3) working together. Verify the delays using simulation and logic analyzer.

Components Used/Connected

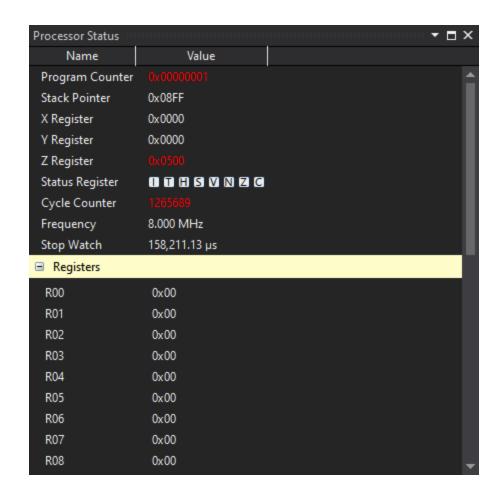
ATMega328P and Arduino Uno Pin Mapping

Arduino function			•	Arduino function
reset	(PCINT14/RESET) PC6	, \bigcup_{28}	☐ PC5 (ADC5/SCL/PCINT1:	3) analog input 5
digital pin 0 (RX)	(PCINT16/RXD) PD0	2 27	☐ PC4 (ADC4/SDA/PCINT1:	2) analog input 4
digital pin 1 (TX)	(PCINT17/TXD) PD1	3 26	☐ PC3 (ADC3/PCINT11)	analog input 3
digital pin 2	(PCINT18/INT0) PD2	4 25	☐ PC2 (ADC2/PCINT10)	analog input 2
digital pin 3 (PWM)	(PCINT19/OC2B/INT1) PD3	5 24	PC1 (ADC1/PCINT9)	analog input 1
digital pin 4	(PCINT20/XCK/T0) PD4	6 23	☐ PC0 (ADC0/PCINT8)	analog input 0
VCC	vccロ	7 22	□GND	GND
GND	GND	8 21	AREF	analog reference
crystal	(PCINT6/XTAL1/TOSC1) PB6	9 20	□ AVCC	VCC
crystal	(PCINT7/XTAL2/TOSC2) PB7	10 19	PB5 (SCK/PCINT5)	digital pin 13
digital pin 5 (PWM)	(PCINT21/OC0B/T1) PD5	11 18	☐ PB4 (MISO/PCINT4)	digital pin 12
digital pin 6 (PWM)	(PCINT22/OC0A/AIN0) PD6	12 17	☐ PB3 (MOSI/OC2A/PCINT:	3) digital pin 11(PWM)
digital pin 7	(PCINT23/AIN1) PD7	13 16	☐ PB2 (SS/OC1B/PCINT2)	digital pin 10 (PWM)
digital pin 8	(PCINT0/CLKO/ICP1) PB0	14 15	□ PB1 (OC1A/PCINT1)	digital pin 9 (PWM)

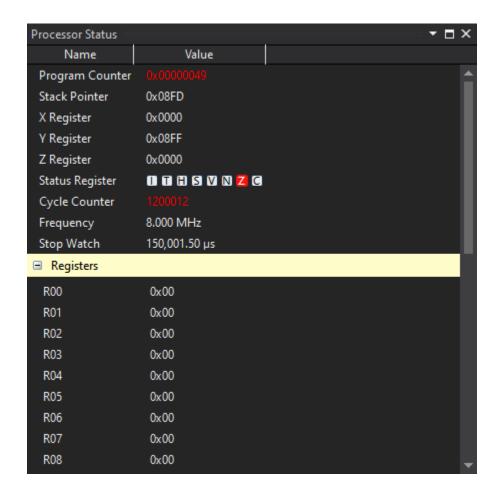
Digital Pins 11,12 & 13 are used by the ICSP header for MOSI, MISO, SCK connections (Atmega168 pins 17,18 & 19). Avoid low-impedance loads on these pins when using the ICSP header.

Task 1

```
1. ; AssemblerApp_DA2_1.asm
2.;
3.; Created: 3/9/2025 7:21:43 PM
4.; Author: enriq
5.;
6.
7. .include "M328Pdef.inc"
8. .equ Value = 0xFB2C ; Timing value for 0.15 sec delay
9.
10. Main:
       rcall Delay
                        ; Call the 0.15 second delay
11.
12.
        nop
13. Done:
14.
                          ; Loop forever
       rjmp Done
15.
                           ; ~0.15 second delay using Timer1
16. Delay:
       ldi R30, high(Value)
17.
18.
       sts TCNT1H, R30
19.
       ldi R30, low(Value)
20.
       sts TCNT1L, R30
                          ; Load TCNT1 with starting value
21.
       ldi R31, 0x00
23.
       sts TCCR1A, R31
                          ; Normal mode
24.
                          ; Prescaler 1024
25.
       ldi R31, 0x05
26.
       sts TCCR1B, R31
                          ; Start Timer1
27.
28. Wait:
       sbis TIFR1, TOV1
                          ; Wait for overflow flag
29.
30.
       rjmp Wait
31.
       sbi TIFR1, TOV1
32.
                           ; Clear overflow flag
33.
       ldi R30, 0x00
                          ; Stop Timer1
34.
       sts TCCR1B, R30
35.
36.
       ret
37.
```

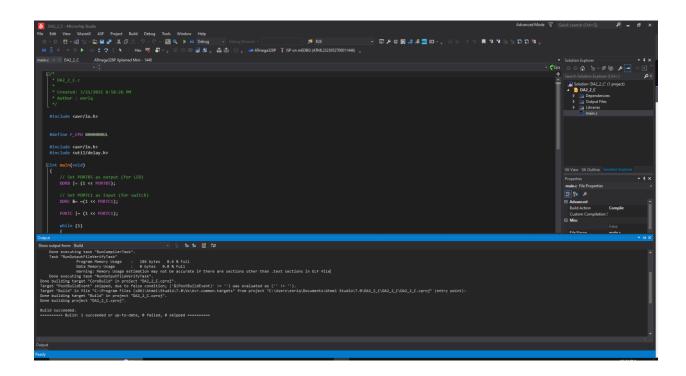


```
1. /*
 2. * GccApp_DA2_1.c
3. *
4. * Created: 3/9/2025 7:55:28 PM
5. * Author : enriq
 6. */
 7.
 8. #define F_CPU 8000000UL
 9.
10. #include <avr/io.h>
11. #include <util/delay.h>
13. int main(void)
14. {
15.
            _delay_ms(150);
16.
17.
18. }
            return 0;
19.
```



Task 2

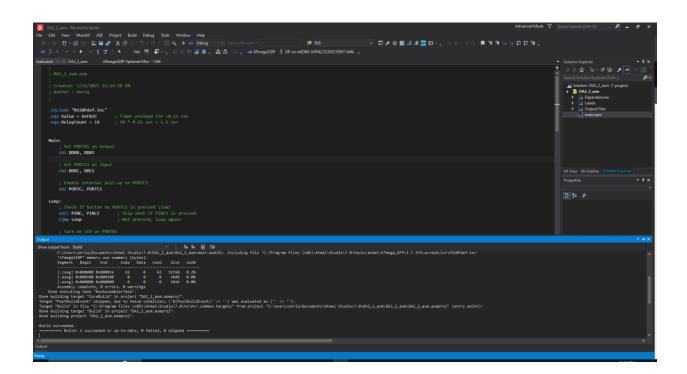
```
1. /*
 2. * DA2_2_C.c
 3. *
 4. * Created: 3/21/2025 8:58:26 PM
5. * Author : enriq
6. */
 7.
8. #include <avr/io.h>
9.
10.
11. #define F_CPU 8000000UL
13. #include <avr/io.h>
14. #include <util/delay.h>
15.
16. int main(void)
17. {
          // Set PORTB5 as output (for LED)
18.
19.
          DDRB |= (1 << PORTB5);</pre>
20.
          // Set PORTC1 as input (for switch)
21.
          DDRC &= ~(1 << PORTC1);
22.
23.
          PORTC |= (1 << PORTC1);
24.
25.
26.
          while (1)
27.
28.
                    // check if pressed (low)
                    if (!(PINC & (1 << PINC1)))</pre>
29.
30.
                    {
31.
                               // Turn LED on
32.
                               PORTB |= (1 << PORTB5);
33.
                               // Delay for 1.5 seconds
34.
35.
                               _delay_ms(1500);
36.
37.
                               // Turn LED off
                               PORTB \&= \sim (1 << PORTB5);
38.
                    }
39.
40.
          }
41.
42.
          return 0;
43. }
44.
```

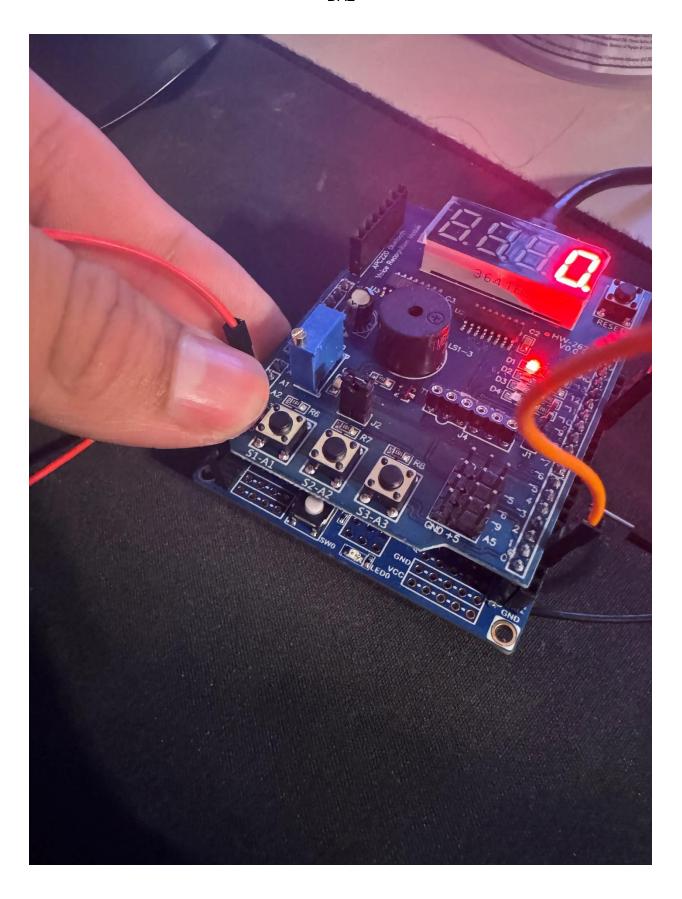


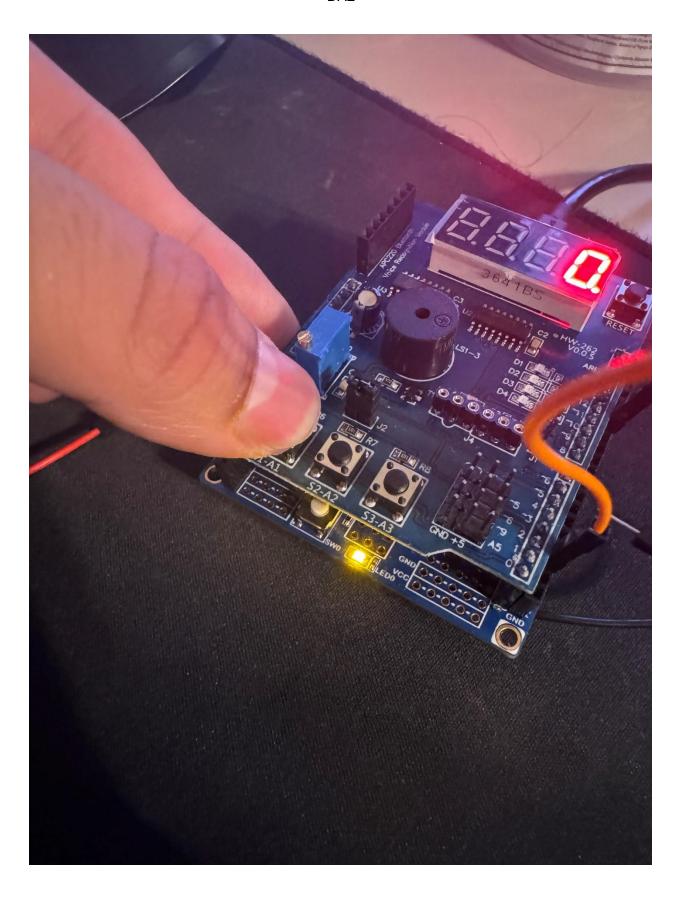
```
1.;
2. ; DA2_2_asm.asm
3.;
4.; Created: 3/21/2025 11:29:28 PM
5. ; Author : enriq
6.;
7.
8. .include "M328Pdef.inc"
                           ; Timer preload for ~0.15 sec
; 10 * 0.15 sec = 1.5 sec
9. .equ Value = 0xFB2C
10. .equ DelayCount = 10
12.
13. Main:
       ; Set PORTB5 as output
14.
        sbi DDRB, DDB5
17.
        ; Set PORTC1 as input
        cbi DDRC, DDC1
18.
19.
20.
        ; Enable internal pull-up on PORTC1
        sbi PORTC, PORTC1
21.
22.
23. Loop:
        ; Check if button on PORTC1 is pressed (low)
24.
25.
        sbic PINC, PINC1
                            ; Skip next if PINC1 is pressed
26.
        rjmp Loop
                               ; Not pressed, loop again
27.
        ; Turn on LED on PORTB5
28.
29.
        sbi PORTB, PORTB5
30.
31.
        ; Delay for 1.5 seconds using 10x 0.15 sec Delay
        ldi R20, DelayCount
32.
33. DelayLoop:
34.
        rcall Delay
35.
        dec R20
36.
        brne DelayLoop
37.
        ; Turn off LED on PORTB5
38.
        cbi PORTB, PORTB5
39.
40.
41.
                               ; Wait for next press
        rjmp Loop
42.
43.; 0.15 Second Delay
44.
45. Delay:
46.
        ldi R30, high(Value)
47.
        sts TCNT1H, R30
        ldi R30, low(Value)
48.
49.
        sts TCNT1L, R30
                                ; Load TCNT1 with starting value
50.
51.
        ldi R31, 0x00
52.
        sts TCCR1A, R31
                                ; Normal mode
53.
        ldi R31, 0x05
                                ; Prescaler 1024
54.
55.
        sts TCCR1B, R31
                                ; Start Timer1
56.
57. Wait:
        sbis TIFR1, TOV1
58.
                                ; Wait for overflow flag
59.
        rjmp Wait
60.
        sbi TIFR1, TOV1
61.
                                ; Clear overflow flag
62.
        ldi R30, 0x00
63.
        sts TCCR1B, R30
                                ; Stop Timer1
64.
```

65. ret

66.

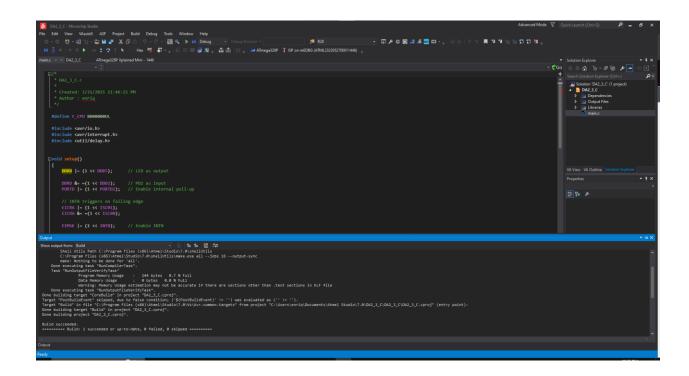






Task 3

```
1. /*
2. * DA2_3_C.c
3. *
4. * Created: 3/21/2025 11:46:25 PM
5. * Author : enriq
6. */
7.
8. #define F_CPU 8000000UL
9.
10. #include <avr/io.h>
11. #include <avr/interrupt.h>
12. #include <util/delay.h>
14.
15. void setup()
16. {
17.
         DDRB |= (1 << DDB5);
                                // LED as output
18.
                                // PD2 as input
19.
         DDRD &= ~(1 << DDD2);
         PORTD |= (1 << PORTD2); // Enable internal pull-up
20.
21.
         // INTO triggers on falling edge
22.
23.
         EICRA |= (1 << ISC01);
         EICRA &= ~(1 << ISC00);
24.
25.
         EIMSK = (1 << INT0);
26.
                                // Enable INT0
27.
28.
                                // Global interrupt enable
         sei();
29. }
31. int main(void)
32. {
33.
         setup();
34.
35.
         while (1)
36.
37.
         }
38.
39. }
41. ISR(INT0_vect)
42. {
43.
         PORTB |= (1 << PORTB5); // LED ON
         44.
45.
46. }
47.
```



```
2. ; DA2_3_asm.asm
 3.;
 4.; Created: 3/22/2025 6:27:19 PM
 5. ; Author : enriq
 6.;
 7.
 8. .include "M328Pdef.inc"
9. .equ Value = 0xFB2C ; Timer preload for \sim 0.15 sec 10. .equ DelayCount = 20 ; 20 \times 0.15 \text{ s} = 3 \text{ s} total
10. .equ DelayCount = 20
12. .cseg
13. .org 0x0000
14.
       rjmp Setup
16. .org 0x0002
                                 ; INTO vector
17. rjmp INTO_ISR
18.
19.
20. Setup:
        ldi r16, high(RAMEND)
21.
        out SPH, r16
22.
23.
        ldi r16, low(RAMEND)
24.
        out SPL, r16
25.
        sbi DDRB, DDB5
26.
                                  ; Set PB5 as output
27.
                                  ; PD2 input
        cbi DDRD, DDD2
28.
29.
        sbi PORTD, PORTD2
                                  ; Enable pull-up on PD2
30.
31.
        ; set INT0
32.
33.
        ldi r16, (1 << ISC01)
34.
        sts EICRA, r16
35.
        ; Enable INTO interrupt
36.
37.
        ldi r16, (1 << INT0)
        sts EIMSK, r16
38.
39.
40.
        sei ; Global interrupt enable
41.
42. Main:
43.
        rjmp Main
44.
45. INTO ISR:
46.
        sbi PORTB, PORTB5
                            ; Turn on LED at PB5
47.
        ldi r20, DelayCount
48.
49. DelayLoop:
       rcall Delay
50.
51.
        dec r20
52.
       brne DelayLoop
53.
       ; Turn off LED at PB5
54.
        cbi PORTB, PORTB5
55.
56.
57.
        reti
58.
60. Delay:
                             ; ~0.15 second delay using Timer1
        ldi R30, high(Value)
61.
        sts TCNT1H, R30
62.
63.
        ldi R30, low(Value)
        sts TCNT1L, R30
                         ; Load TCNT1 with starting value
64.
```

```
65.
66.
       ldi R31, 0x00
67.
       sts TCCR1A, R31
                          ; Normal mode
68.
69.
       ldi R31, 0x05
                          ; Prescaler 1024
70.
       sts TCCR1B, R31
                           ; Start Timer1
71.
72. Wait:
73.
       sbis TIFR1, TOV1
                          ; Wait for overflow flag
74.
       rjmp Wait
75.
       sbi TIFR1, TOV1
                           ; Clear overflow flag
76.
       ldi R30, 0x00
77.
78.
       sts TCCR1B, R30
                           ; Stop Timer1
79.
80.
       ret
81.
```

