CodeBook

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CodeBook for tidy.txt

This codebook accompanies "tidy.txt" which is produced from the original dataset taken from http://archive.ics.uci.edu/ml/datasets/Human+Activity+Recognition+Using+Smartphones.

The following enumerate the datasets included.

ID

- Subject each subject has a unique integer ID
- Activity the following are the codes for each activity

```
##
     V1
## 1
                    WALKING
## 2
      2
          WALKING_UPSTAIRS
## 3
      3 WALKING_DOWNSTAIRS
## 4
      4
                    SITTING
## 5 5
                  STANDING
## 6 6
                    LAYING
```

FEATURES

The following description was taken from the features_info.txt from the original dataset

The features selected for this database come from the accelerometer and gyroscope 3-axial raw signals tAcc-XYZ and tGyro-XYZ. These time domain signals (prefix 't' to denote time) were captured at a constant rate of 50 Hz. Then they were filtered using a median filter and a 3rd order low pass Butterworth filter with a corner frequency of 20 Hz to remove noise. Similarly, the acceleration signal was then separated into body and gravity acceleration signals (tBodyAcc-XYZ and tGravityAcc-XYZ) using another low pass Butterworth filter with a corner frequency of 0.3 Hz.

Subsequently, the body linear acceleration and angular velocity were derived in time to obtain Jerk signals (tBodyAccJerk-XYZ and tBodyGyroJerk-XYZ). Also the magnitude of these three-dimensional signals were calculated using the Euclidean norm (tBodyAccMag, tGravityAccMag, tBodyAccJerkMag, tBodyGyroJerkMag).

Finally a Fast Fourier Transform (FFT) was applied to some of these signals producing fBodyAcc-XYZ, fBodyAccJerk-XYZ, fBodyAccJerkMag, fBodyGyroJerkMag, fBodyGyroJerkMag. (Note the 'f' to indicate frequency domain signals).

These signals were used to estimate variables of the feature vector for each pattern:

'-XYZ' is used to denote 3-axial signals in the X, Y and Z directions.

For the purpose of this exercise, only the mean and standard deviation statistics were used.

The final list of features used are enumerated below.

```
## [1] "tBodyAcc-mean()-X"
## [2] "tBodyAcc-mean()-Y"
## [3] "tBodyAcc-mean()-Z"
```

```
##
    [4] "tBodyAcc-std()-X"
##
       "tBodyAcc-std()-Y"
    [5]
##
    [6] "tBodyAcc-std()-Z"
    [7] "tGravityAcc-mean()-X"
##
##
    [8]
       "tGravityAcc-mean()-Y"
        "tGravityAcc-mean()-Z"
##
    [9]
       "tGravityAcc-std()-X"
##
   Γ10]
        "tGravityAcc-std()-Y"
##
   [11]
##
   Γ12]
        "tGravityAcc-std()-Z"
        "tBodyAccJerk-mean()-X"
   [13]
   [14]
        "tBodyAccJerk-mean()-Y"
   [15]
        "tBodyAccJerk-mean()-Z"
##
        "tBodyAccJerk-std()-X"
##
   [16]
        "tBodyAccJerk-std()-Y"
##
   [17]
   [18]
        "tBodyAccJerk-std()-Z"
##
##
   [19]
        "tBodyGyro-mean()-X"
   [20]
        "tBodyGyro-mean()-Y"
##
        "tBodyGyro-mean()-Z"
   [21]
   [22]
       "tBodyGyro-std()-X"
   [23]
        "tBodyGyro-std()-Y"
##
   [24]
        "tBodyGyro-std()-Z"
   [25]
        "tBodyGyroJerk-mean()-X"
        "tBodyGyroJerk-mean()-Y"
   [26]
##
   [27]
        "tBodyGyroJerk-mean()-Z"
##
   [28]
        "tBodyGyroJerk-std()-X"
##
   [29]
        "tBodyGyroJerk-std()-Y"
   [30]
        "tBodyGyroJerk-std()-Z"
##
        "tBodyAccMag-mean()"
##
   [31]
##
        "tBodyAccMag-std()"
   [32]
        "tGravityAccMag-mean()"
   [33]
##
   [34]
        "tGravityAccMag-std()"
##
   [35]
        "tBodyAccJerkMag-mean()"
        "tBodyAccJerkMag-std()"
   [36]
   [37]
        "tBodyGyroMag-mean()"
##
        "tBodyGyroMag-std()"
   [38]
   [39]
        "tBodyGyroJerkMag-mean()"
##
   Γ401
        "tBodyGyroJerkMag-std()"
```

"fBodyAcc-mean()-X"

"fBodyAcc-mean()-Y"

"fBodyAcc-mean()-Z"

"fBodyAcc-std()-X"

"fBodyAcc-std()-Y"

"fBodyAcc-std()-Z"

"fBodyAcc-meanFreq()-X"

"fBodyAcc-meanFreq()-Y"

"fBodyAcc-meanFreq()-Z"

"fBodyAccJerk-mean()-X"

"fBodyAccJerk-mean()-Y"

"fBodyAccJerk-mean()-Z"
"fBodyAccJerk-std()-X"

"fBodyAccJerk-std()-Y"

"fBodyAccJerk-std()-Z"

[56] "fBodyAccJerk-meanFreq()-X"
[57] "fBodyAccJerk-meanFreq()-Y"

[41]

[42]

[43]

[44] [45]

Г461

[47]

[48]

[49]

[50] [51]

[52]

[53] [54]

[55]

##

##

##

##

##

##

##

##

##

##

##

```
## [58] "fBodyAccJerk-meanFreq()-Z"
   [59] "fBodyGyro-mean()-X"
  [60] "fBodyGyro-mean()-Y"
  [61] "fBodyGyro-mean()-Z"
   [62] "fBodyGyro-std()-X"
##
   [63]
       "fBodyGyro-std()-Y"
##
   Γ641
       "fBodyGyro-std()-Z"
   [65] "fBodyGyro-meanFreq()-X"
##
##
   [66]
       "fBodyGyro-meanFreq()-Y"
       "fBodyGyro-meanFreq()-Z"
   [67]
##
   [68] "fBodyAccMag-mean()"
   [69] "fBodyAccMag-std()"
##
       "fBodyAccMag-meanFreq()"
##
   [70]
   [71] "fBodyBodyAccJerkMag-mean()"
##
   [72] "fBodyBodyAccJerkMag-std()"
##
   [73] "fBodyBodyAccJerkMag-meanFreq()"
##
   [74]
       "fBodyBodyGyroMag-mean()"
   [75] "fBodyBodyGyroMag-std()"
   [76] "fBodyBodyGyroMag-meanFreq()"
   [77] "fBodyBodyGyroJerkMag-mean()"
##
  [78] "fBodyBodyGyroJerkMag-std()"
  [79] "fBodyBodyGyroJerkMag-meanFreq()"
  [80] "angle(tBodyAccMean,gravity)"
##
   [81]
        "angle(tBodyAccJerkMean),gravityMean)"
##
        "angle(tBodyGyroMean,gravityMean)"
   [82]
##
   [83]
       "angle(tBodyGyroJerkMean,gravityMean)"
   [84] "angle(X,gravityMean)"
##
   [85] "angle(Y,gravityMean)"
  [86] "angle(Z,gravityMean)"
```