

Variations on a Theme by Eckart and Young

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TBD

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Note: This is a working manuscript which will be expanded/updated frequently. All suggestions for improvement are welcome. All Rmd, tex, html, pdf, R, and C files are in the public domain. Attribution will be appreciated, but is not required. The files can be found at <https://github.com/deleeuw/glspca>

1 Introduction

X is a “tall” matrix of rank r with n rows and m columns, $r \leq m \leq n$. We want to approximate A in the least-squarese sense by the product of two matrices A and B , where A is $n \times p$ and B is $m \times p$. Thus we want to find A and B in such a way that the sum-of-squares

$$\sigma(A, B) = \text{SSQ}(X - AB')$$

is minimized.

$$X \rightrightarrows [\begin{matrix} \\ \sigma(A) = \text{SSQ}(C - AA') \end{matrix}$$

2 Weighting

2.1 Elementwise Weighting

2.2 Kronecker Weighting

2.3 General Weighting

3 Intercept

4 GLS Loss

$$\sigma(A, B, D) = \text{tr } U(X - D - AB')V(X - D - AB')'$$

- X is $n \times m$ with $m \leq n$, completely known,
- U is positive definite of order n , completely known,
- V is positive definite of order m , completely known,
- A is $n \times p$ with $p \leq m$, to be estimated,
- B is $m \times p$ with $p \leq m$, to be estimated,
- D is $n \times m$, constrained to be in $\mathcal{D} \subseteq \mathbb{R}^{n \times m}$.

Example for \mathcal{D} : $\mu + \alpha_i + \beta_j$ but can be nonlinear.

Note: Correspondence analysis is a special case with \mathcal{D} equal to zero, but more generally D can be used in correspondence analysis to impute missing data. If there is no D then A and B can be found from a single SVD, no matter what U and V are.

Note: In ordinary multinomial analysis U is the identity. But in analyzing multivariate time series data (time points are rows of X) we need U . For spacetime data we need a third weighting matrix in a triple Kronecker product.

Minimize loss over A , B , and $D \in \mathcal{D}$. Let

$$H(D) := U^{\frac{1}{2}}(X - D)V^{\frac{1}{2}}$$

then

$$\sigma_{\star}(D) = \min_{A, B} \sigma(A, B, D) = \sum_{s=p+1}^m \lambda_s^2(H(D)).$$

with λ_s the $m - p$ smallest singular values.

Note: if there are constraints on A and/or B (as in canonical correspondence analysis) projection becomes more complicated. But we can always set $p = 0$ (there are no A and B) and put all unknowns into D .

Note: If there is no D then A and B can be found with a single SVD.

Note: Both U and V are supposed to be completely known. If they must be estimated we may run into Anderson-Rubin.

5 Symmetric case

$$\sigma(A, D) = \text{tr } W(C - D - AA')W(C - D - AA')'$$

$$H(D) := W^{\frac{1}{2}}(C - D)W^{\frac{1}{2}}$$

$$\sigma_{\star}(D) = \min_A \sigma(A, D) = \sum_{s=p+1}^m \lambda_s^2(H(D)).$$

with λ_s the $m - p$ smallest eigenvalues.

Example for D : diagonal matrix of uniquenesses

6 Algorithm

Use majorization for the initial estimate – reduce to a sequence of ULS problems. Then use `optim()` or Newton to minimize σ_* over $D \in \mathcal{D}$, using the eigen/singular value derivatives of deleeuw(2025). Majorization is usually still feasible if there are linear constraints on A/B (Takane).

7 Majorization

We first transform using $x := \text{vec}(X)$ and $y := \text{vec}(Y)$.

$$\sigma(Y) = \text{tr } U(X - Y)V(X - Y)' = (x - y)'(V \otimes U)(x - y).$$

Now suppose \tilde{y} is the previous solution. Then

$$\sigma(y) = ((x - \tilde{y}) - (y - \tilde{y}))'(V \otimes U)((x - \tilde{y}) - (y - \tilde{y}))$$

Thus

$$\sigma(y) = \sigma(\tilde{y}) - 2(y - \tilde{y})'(V \otimes U)(x - \tilde{y}) + (y - \tilde{y})'(V \otimes U)(y - \tilde{y}),$$

and, with λ_{\max} the largest eigenvalue of $U \otimes V$,

$$\sigma(y) \leq \sigma(\tilde{y}) - 2(y - \tilde{y})'(V \otimes U)(x - \tilde{y}) + \lambda_{\max}(y - \tilde{y})'(y - \tilde{y}),$$

with equality if $y = \tilde{y}$. Define

$$g := \tilde{y} + \lambda_{\max}^{-1}(V \otimes U)(x - \tilde{y}).$$

. Then

$$\sigma(y) \leq \sigma(\tilde{y}) + \lambda_{\max}(y - g)'(y - g) - \lambda_{\max}g'g$$

Now

$$(V \otimes U)(x - \tilde{y}) = \text{vec}(U(X - \tilde{Y})V)$$

so that the majorization step can also be written as the minimization of $\text{SSQ}(Y - G)$ with

$$G = \tilde{Y} + \lambda_{\max}^{-1} U(X - \tilde{Y})V$$

Remember that

$$\lambda_{\max}(V \otimes U) = \lambda_{\max}(V)\lambda_{\max}(U)$$

8 Code

To check the majorization result we analyze a simple example. The R function is `glsAdd()`, which can fit one of three types of “models”.

1. $\mu + \alpha_i + \beta_j$
2. $\sum_{s=1}^p a_{is} b_{js}$
3. $\mu + \alpha_i + \beta_j + \sum_{s=1}^p a_{is} b_{js}$

We first generate some random matrices for X , U , and V .

```
set.seed(12345)
x <- matrix(rnorm(40), 10, 4)
u <- crossprod(matrix(rnorm(100), 10, 10)) / 10
v <- crossprod(matrix(rnorm(16), 4, 4)) / 4
```

The R code is

```
library("RSpectra")

ulsPCA <- function(x, p) {
  s <- svd(x, nu = p, nv = p)
  a <- s$u
  b <- s$v %*% diag(s$d[1:p])
  return(list(a = a, b = b, ab = tcrossprod(a, b)))
}

ulsAdd <- function(x) {
  m <- mean(x)
  r <- apply(x, 1, mean) - m
  s <- apply(x, 2, mean) - m
  return(list(
    m = m,
    r = r,
    s = s,
    rs = outer(r, s, "+") + m
  ))
}

ulsBoth <- function(x, p) {
```

```

h1 <- ulsAdd(x)
h2 <- ulsPCA(x - h1$rs, p)
return(list(
  m = h1$m,
  r = h1$r,
  s = h1$s,
  a = h2$a,
  b = h2$b,
  y = h1$rs + h2$ab
))
}

glsLoss <- function(x, y, u, v) {
  d <- x - y
  return(sum(v * crossprod(d, (u %*% d))))
}

glsAdd <- function(x,
  u,
  v,
  type = 3,
  p = 2,
  itmax = 10000,
  eps = 1e-6,
  verbose = FALSE) {
  yold <- switch(type,
    ulsAdd(x)$rs,
    ulsPCA(x, p)$ab,
    ulsBoth(x, p)$y
  )
  sold <- glsLoss(x, yold, u, v)
  lbdm <- eigs_sym(u, 1)$values * eigs_sym(v, 1)$values
  itel <- 1
  repeat {
    d <- x - yold
    g <- yold + u %*% d %*% v / lbdm
    ynew <- switch(type,
      ulsAdd(g)$rs,
      ulsPCA(g, p)$ab,
      ulsBoth(g, p)$y
    )
  }
}

```



```

)
snew <- glsLoss(x, ynew, u, v)
if (verbose) {
  cat(
    "itel ",
    formatC(itel, format = "d"),
    "sold ",
    formatC(sold, digits = 10, format = "f"),
    "snew ",
    formatC(snew, digits = 10, format = "f"),
    "\n"
  )
}
if ((itel == itmax) || ((sold - snew) < eps)) {
  break
}
itel <- itel + 1
sold <- snew
yold <- ynew
}
return(list(y = ynew, loss = snew, itel = itel))
}

```

Apply our code.

```

h1 <- glsAdd(x, u, v, type = 1)
h2 <- glsAdd(x, u, v, type = 2)
h3 <- glsAdd(x, u, v, type = 3)

```

- For type 1 we have convergence in 291 iterations to loss 31.1720174.
- For type 2 we have convergence in 1275 iterations to loss 0.7924819.
- For type 3 we have convergence in 2427 iterations to loss 0.1039566.

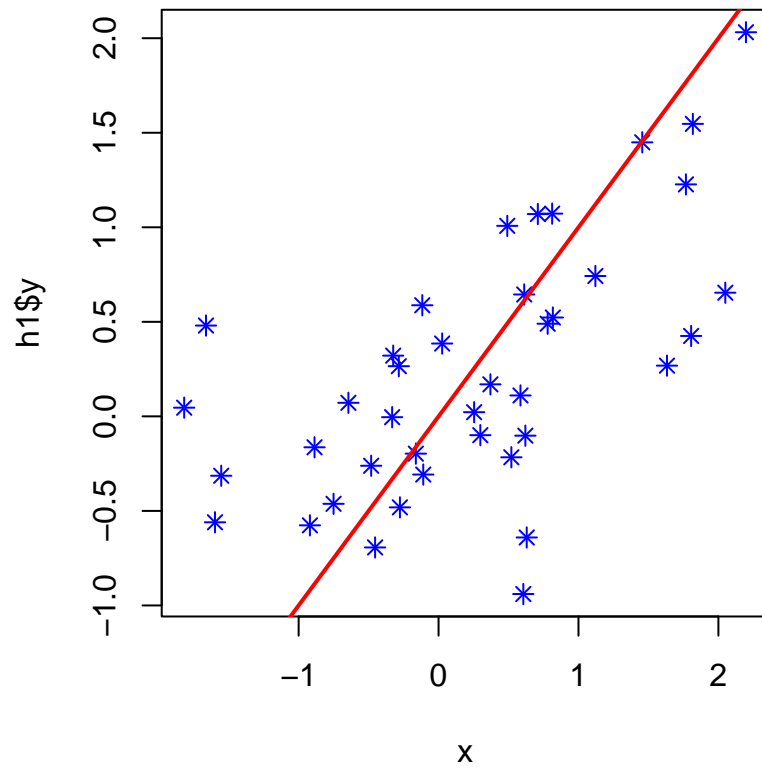


Figure 1: Type 1

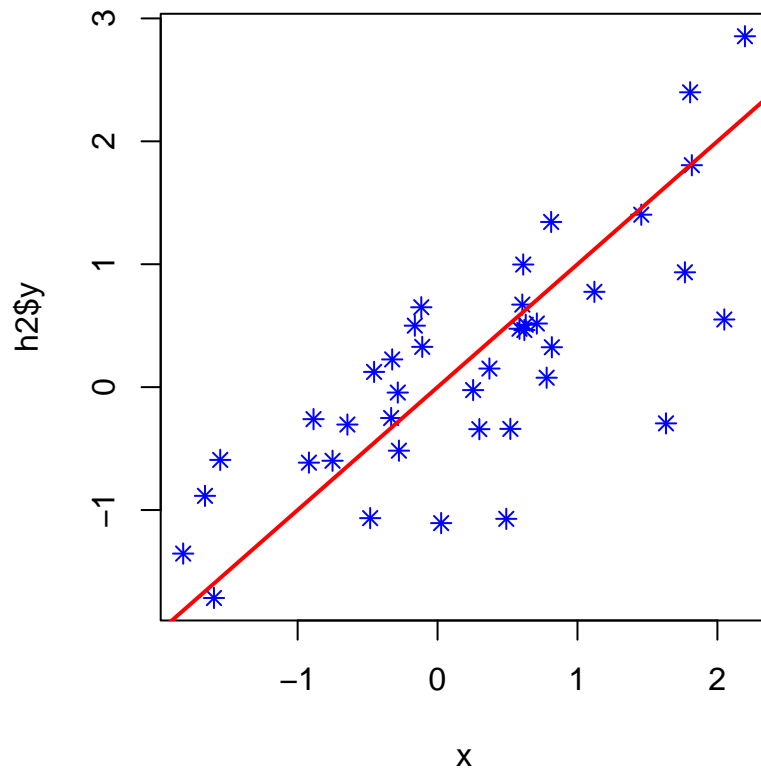


Figure 2: Type 2

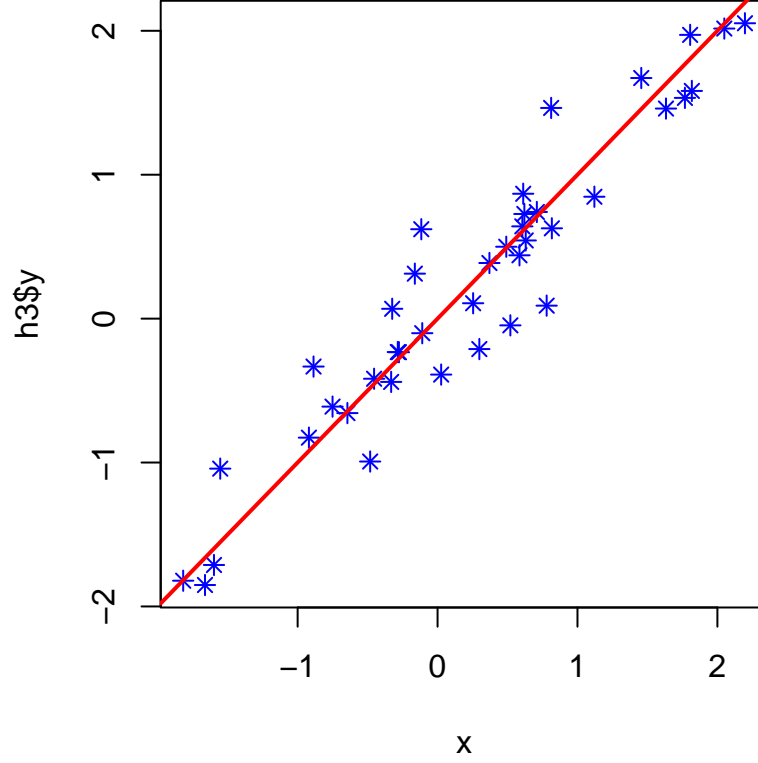


Figure 3: Type 3

9 Generalization

A far-reaching generalization of type 3 defines $D = EMF' + AB'$, with E and Q known matrices. In the unweighted case (and thus in the update step of the majorization algorithm) this amounts to an SVD of the residuals $P_E X P_F$, where P_E and P_F are projectors on the null spaces of E and F .

10 Correspondence Analysis

$$\sigma(A, B) = \text{tr } E^{-1}(F - AB')D^{-1}(F - AB)'$$

CCA

$$\sigma(A, B) = \text{tr } (Z'EZ)^{-1}(Z'F - AB')D^{-1}(Z'F - AB)'$$

Canonical Analysis

$$\sigma(A, B) = \text{tr} (X'X)^{-1}(X'Y - AB')(Y'Y)^{-1}(X'Y - AB)'$$

11 Redundancy Analysis

$$\sigma(A, B) = \text{tr} (X'X)^{-1}(X'Y - AB')(X'Y - AB)'$$

12 Aside

$$\sigma(A, B) = \text{SSQ}(X - GAB'H')$$

with G and H known.

$$\sigma(A, B) = \text{tr} X'X - 2\text{tr} X'GAB'H' + \text{tr} HBA'G'GAB'H' = \text{tr} X'X - 2\text{tr} H'X'GAB' + \text{tr} (H'H)BA'(G'G)AB'$$

Let $\tilde{B} = (H'H)^{\frac{1}{2}}B$ and $\tilde{A} = (G'G)^{\frac{1}{2}}A$.

Then

$$\text{tr} H'X'GAB' = \text{tr} (H'H)^{-\frac{1}{2}}H'X'G(G'G)^{-\frac{1}{2}}\tilde{A}\tilde{B}'$$

$$\text{tr} (H'H)BA'(G'G)AB' = \text{tr} (H'H)(H'H)^{-\frac{1}{2}}\tilde{B}\tilde{A}'(G'G)^{-\frac{1}{2}}(G'G)(G'G)^{-\frac{1}{2}}\tilde{A}\tilde{B}'(H'H)^{-\frac{1}{2}} = \text{SSQ}(\tilde{A}\tilde{B}')$$

Thus

$$\min_{A,B} \sigma(A, B) = \min_{A,B} \text{tr} (H'H)^{-1}(H'XG - AB')(G'G)^{-1}(H'XG - AB)'$$

which can be solved by an SVD of $(H'H)^{-\frac{1}{2}}H'X'G(G'G)^{-\frac{1}{2}}$

13 Aside 2

This generalizes type 3.

$$\sigma(A, B, S) = \text{tr} U(X - GSH' - AB')V(X - GSH' - AB)'$$

Again it can be solved with a single SVD.

13.1 Aside 3

Suppose U and V are singular. Let

$$U = \begin{bmatrix} K & K_{\perp} \end{bmatrix} \begin{bmatrix} \Phi^2 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} K' \\ K'_{\perp} \end{bmatrix}$$

$$V = \begin{bmatrix} L & L_{\perp} \end{bmatrix} \begin{bmatrix} \Psi^2 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} L' \\ L'_{\perp} \end{bmatrix}$$

Let $A = KP + K_{\perp}Q$ and $B = LR + L_{\perp}S$.

$$\text{SSQ}(U^{\frac{1}{2}}(X - AB')V^{\frac{1}{2}}) = \text{SSQ}(\Phi K'XL\Psi - \Phi PR'\Psi)$$

which is minimized by the SVD of $\Phi K'XL\Psi$.

14 Elementwise weights

Use $\text{vec}()$

$$\sigma(Y) = \sum_{i=1}^n \sum_{j=1}^m w_{ij}(x_{ij} - y_{ij})^2$$

Now any $V \geq W$ (elementwise) can be used to majorize.

$$\sigma(Y) \leq \sigma(\tilde{Y}) - 2 \sum_{i=1}^n \sum_{j=1}^m w_{ij}(y_{ij} - \tilde{y}_{ij})(x_{ij} - \tilde{y}_{ij}) + \sum_{i=1}^n \sum_{j=1}^m v_{ij}(y_{ij} - \tilde{y}_{ij})^2$$

which leads to the majorization step of minimizing

$$\sum_{i=1}^n \sum_{j=1}^m v_{ij}(z_{ij} - y_{ij})^2$$

with

$$z_{ij} = \tilde{y}_{ij} + \frac{w_{ij}}{v_{ij}}(x_{ij} - \tilde{y}_{ij})$$

In Groenen, Giaquinto, and Kiers (2003) $v_{ij} = \max_{j=1}^m w_{ij}$. In (??)?? $v_{ij} = \theta_i \xi_j$, where θ and ξ are chosen such that $\log \theta_i + \log \xi_j \geq \log w_{ij}$ and $\sum_{i=1}^n \sum_{j=1}^m (\log \theta_i + \log \xi_j)$ is minimized (a linear programming problem)

Groenen, P. J. F., P. Giaquinto, and H. A. L. Kiers. 2003. "Weighted Majorization Algorithms for Weighted Least Squares Decomposition Models." Econometric Institute Report EI 2003-09. Econometric Institute, Erasmus University Rotterdam. <https://repub.eur.nl/pub/1700>.