

Smacof at 50: Part xx

Utilities

Jan de Leeuw

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Note: This is a working manuscript which will be expanded/updated frequently. All suggestions for improvement are welcome. All Rmd, tex, html, pdf, R, and C files are in the public domain. Attribution will be appreciated, but is not required. The files can be found at <https://github.com/deleeuw> in the repositories smacofCode, smacofManual, and smacofExamples.

1 Simultaneous Iteration

The problem in this section is to maximize

$$\lambda(K) := \text{tr } K' A K \quad (1)$$

over all $n \times p$ orthonormal K . Suppose for the time being that A is positive semi-definite.

Define $k = \text{vec}(K)$ and

$$A_p := \underbrace{A \oplus \dots \oplus A}_{p \text{ times}} \quad (2)$$

Then $\lambda = k' A_p k$, which shows that λ is convex, and that consequently for all k and \tilde{k} we have the minorization

$$k' A_p k \geq \tilde{k}' A_p \tilde{k} + 2\tilde{k}' A_p (k - \tilde{k}) = 2k' A_p \tilde{k} - \tilde{k}' A_p \tilde{k} \quad (3)$$

It follows that we increase λ by increasing $\text{tr } K' A \tilde{K}$ over $K' K = I$.

$$K^{(\nu+1)} = \underset{K' K = I}{\text{argmax}} \text{tr } K' A K^{(\nu)} \quad (4)$$

Computing $K^{(\nu+1)}$ is an orthogonal Procrustes problem (Gower and Dijksterhuis (2004)). Thus from the singular value decomposition $A K^{(\nu)} = P \Phi Q'$ we find $K^{(\nu+1)} = P Q'$.

There are two remaining elaborations of this result. First, we want to get rid of the assumption that A is positive semi-definite. We do this by adding a constant to the diagonal of A . To compute a suitable constant μ , use the fact that a diagonally dominant symmetric matrix with a non-negative diagonal is positive semidefinite. Thus if

$$\mu \geq \max_i \sum_{j \neq i} |a_{ij}| - a_{ii} \quad (5)$$

for all i then the matrix $\bar{A} := A + \mu I$ is positive semi-definite. We now use Equation 4 with the adjusted \bar{A} and after convergence we subtract $p\mu$ from λ .

Second, instead of computing the singular value decomposition to update K in each iteration we can use the Q from the less expensive QR decomposition. The argument is the same as in Gifi (1990) (page 98-99, page 171). The QR update of K is a rotation of the Procrustes update of K , and it consequently gives the same value of λ from Equation 1.

2 Symmetric Matrix Approximation

The problem in this section is to minimize

$$\sigma(X) = \text{tr} (C - XX')^2 \quad (6)$$

over all $n \times p$ matrices X . Note there are no weights. The solution is well-known (Eckart and Young (1936), Keller (1962)). If $C = K\Lambda K'$ is the eigen-decomposition of C , with eigenvalues in non-increasing order on the diagonal of Λ , then define $\bar{\Lambda}$ with elements $\max(0, \lambda_s)$. Then use the p largest eigenvalues and corresponding vectors to compute $X = K_p \bar{\Lambda}_p$. Note that $\text{rank}(X)$ is less than p if C has fewer than p positive eigenvalues.

Our algorithm to minimize, or at least decrease, the loss function in Equation 6. Uses a combination of alternating least squares (De Leeuw (1994)) and majorization (De Leeuw (1994)) or MM (Lange (2016)). We first write X in the form $X = K\Lambda$, with $K'K = I$ and Λ diagonal. Then rewrite Equation 6 as

$$\sigma(K, \Lambda) = \text{tr} (C - K\Lambda^2 K')^2 = \text{tr} C^2 - 2\text{tr} K'CK\Lambda^2 + \text{tr} \Lambda^4. \quad (7)$$

Again, for the time being, assume C is positive semi-definite. The minimum over Λ for given K has $\lambda_s^2 = k'_s C k_s$. Thus

$$\min_{K'K=I} \min_{\Lambda} \sigma(K, \Lambda) = \text{tr} C^2 - \max_{K'K=I} \sum_{s=1}^p (k'_s C k_s)^2 \quad (8)$$

The term depending on K is convex and can consequently be minorized by the linear function

$$\sum_{s=1}^p (k'_s C k_s)^2 = \sum_{s=1}^p (\tilde{k}'_s C \tilde{k}_s)^2 + 2 \sum_{s=1}^p (\tilde{k}'_s C \tilde{k}_s) \tilde{k}'_s C (k_s - \tilde{k}_s).$$

In iteration $\nu + 1$ we must maximize $\text{tr} K'CK^{(\nu)}\Lambda^{(\nu)}$ over $K'K = I$, where $\Lambda^{(\nu)} = \text{diag}\{K^{(\nu)}\}'CK^{(\nu)}\}$. Again, this is an orthogonal Procrustus problem.

3 Various Simple

```
smacofEi <- function(i, n) {  
  return(ifelse(i == 1:n, 1, 0))  
}  
  
smacofAij <- function(i, j, n) {  
  ei <- ifelse(i == 1:n, 1, 0)  
  ej <- ifelse(j == 1:n, 1, 0)  
  return(outer(ei - ej, ei - ej))  
}  
  
smacofDoubleCenter <- function(a) {  
  r <- apply(a, 1, mean)  
  s <- mean(a)  
  return(a - outer(r, r, "+") + s)  
}  
  
smacofCenter <- function(x) {  
  return(apply(x, 2, function(x) x - mean(x)))  
}  
  
smacofTrace <- function(a) {  
  return(sum(diag(a)))  
}  
  
smacofMakeDoubleCenter <- function(w) {  
  v <- -w  
  diag(v) <- -rowSums(v)  
  return(v)  
}  
  
smacofDoubleCenterGeneralizedInverse <- function(v) {  
  n <- nrow(v)  
  return(solve(v + (1 / n)) - 1 / n)  
}
```

4 Data formats

```
smacofMakeData <-  
  function(delta,  
            weights = rep(1, length(delta)),  
            winclude = FALSE,  
            fname) {  
    m <- length(delta)  
    n <- as.integer((1 + sqrt(1 + 8 * m)) / 2)  
    h <- fullIndex(n)  
    g <- cbind(h$ii, h$jj, delta, weights)  
    for (k in 1:m) {  
      if ((g[k, 4] == 0) || is.na(g[k, 4]) || is.na(g[k, 3])) {  
        continue  
      } else {  
        if (winclude) {  
          cat(  
            formatC(g[k, 1], digits = 3, format = "d"),  
            formatC(g[k, 2], digits = 3, format = "d"),  
            formatC(g[k, 3], digits = 6, format = "f"),  
            formatC(g[k, 4], digits = 6, format = "f"),  
            "\n",  
            file = fname, append = TRUE  
          )  
        } else {  
          cat(  
            formatC(g[k, 1], digits = 3, format = "d"),  
            formatC(g[k, 2], digits = 3, format = "d"),  
            formatC(g[k, 3], digits = 6, format = "f"),  
            "\n",  
            file = fname, append = TRUE  
          )  
        }  
      }  
    }  
  }  
}  
  
fullIndex <- function(n) {
```

```

ii <- c()
jj <- c()
for (j in 1:(n - 1)) {
  for (i in (j + 1):n) {
    ii <- c(ii, i)
    jj <- c(jj, j)
  }
}
return(list(ii = ii, jj = jj))
}

```

5 I/O

```

smacofMatrixPrint <- function(x,
                              digits = 6,
                              width = 8,
                              format = "f",
                              flag = "+") {
  print(noquote(
    formatC(
      x,
      digits = digits,
      width = width,
      format = format,
      flag = flag
    )
  ))
}

```

6 Indices

sindex tindex mindex vindex

References

- De Leeuw, J. 1994. “Block Relaxation Algorithms in Statistics.” In *Information Systems and Data Analysis*, edited by H. H. Bock, W. Lenski, and M. M. Richter, 308–24. Berlin: Springer Verlag. <https://jansweb.netlify.app/publication/deleeuw-c-94-c/deleeuw-c-94-c.pdf>.
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