

Unit 2 Review

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This Unit Contains:

1. Buckling Theory ✓
2. Torsion ✓
3. Beam Theory ✓
4. Rod Theory ✓
5. Elasticity Theory ✓
6. Strain ✓
7. Stress ✓

BUCKLING

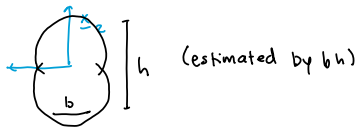
- arises when we think about equilibrium in the deformed condition (before, focused on the fact the equilibrium in undeformed held in deformed)
- compressive loads don't drive deformation; rather, they decrease the stiffness of the system
 $P = P_{cr} \rightarrow$ system has no stiffness (equilibrium for any lateral load)

there's a lot of stuff abt. this single-degree-of freedom example, but IDK how relevant this is.

COLUMNS



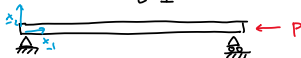
General symmetric cross-section



$L \gg b, h$ (long and slender)
 EI is constant

- only compressive loads along long direction
- shortening \bar{u}_1 and buckling \bar{u}_2

$$\bar{u}_2''(x_1) = \frac{M_3(x_1)}{EI}$$



EQUATIONS

Equilibrium

$$\frac{dN}{dx_1} = 0 \quad \frac{ds_2}{dx_1} = -p_2$$

\uparrow the compressive load \uparrow shear \uparrow distributed load

$$\frac{dM_3}{dx_1} + s_2 - \overset{\text{new}}{\boxed{N_1 \frac{d\bar{u}_2}{dx_1}}} = 0$$

Compatibility + Constitutive

$$M_3 = EI \frac{d^2 \bar{u}_2}{dx_1^2}$$

4th-Order Summary

$$EI \frac{d^4 \bar{u}_z}{dx_1^4} - N_1 \frac{d^2 \bar{u}_z}{dx_1^2} = P_2$$

↑ "moderately large" assumption

The Questions We Need to Ask

- what is the value of P_{cr} (at what load does buckling occur?)
- What shape does the buckled column assume?
- Will buckling always occur provided compressive load large enough?

SOLUTION METHOD (HOMOGENEOUS)

① $N_1 = -P$, assume $p_2(x_1) = 0$

$$EI \bar{u}_z''''(x_1) + P \bar{u}_z''(x_1) = 0$$

② Hey! This is a differential equation!

$$\lambda^4 + \frac{P}{EI} \lambda^2 = 0$$

③ $\bar{u}_z(x_1) = A \sin\left(\sqrt{\frac{P}{EI}} x_1\right) + B \cos\left(\sqrt{\frac{P}{EI}} x_1\right) + C + Dx_1$

BOUNDARY CONDITIONS

(Homogeneous, same as for beam-bending)

	$\bar{u}_z = 0$ $\bar{u}_z' = 0$
	$\bar{u}_z = 0$ $M_3 = 0$
	$\bar{u}_z' = 0$ $S_3 = 0$
	$M_3 = 0$ $S_3 = 0$

$$S_3 = -EI \bar{u}_z'''$$

$$M_3 = EI \bar{u}_z''$$

GENERAL SOL'N (WEIRD BOUNDARIES)

① Start with the general solution to the fourth-order ODE.

$$\bar{u}_z(x_1) = A \sin\left(\sqrt{\frac{P}{EI}} x_1\right) + B \cos\left(\sqrt{\frac{P}{EI}} x_1\right) + C + Dx_1$$

② Apply the boundary conditions (two at each end)

$$\begin{bmatrix} \sin \\ \cos \\ 1 \\ x_1 \end{bmatrix} \begin{bmatrix} A \\ B \\ C \\ D \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

③ To have a non-trivial solution, the determinant of M must be 0. Set $\det(M) = 0$ and solve for roots $P_{cr}(\lambda)$ of eq'n.

④ Homogeneous boundary conditions:

$$P_{cr} = \frac{c \pi^2 EI}{L^2} \quad c = \text{coefficient of edge fixity (?)}$$

INITIAL IMPERFECTIONS

① Initial deflection in column.



② Load not applied along the centerline of the column.



Solution Approach

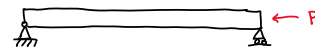
① $\frac{d^4 \bar{u}_z}{dx_1^4} + \frac{P}{EI} \frac{d^2 \bar{u}_z}{dx_1^2} = 0$

② General sol'n from before:

$$\bar{u}_z(x_1) = A \sin\left(\sqrt{\frac{P}{EI}} x_1\right) + B \cos\left(\sqrt{\frac{P}{EI}} x_1\right) + C + Dx_1$$

③ Boundary conditions for type 2 (to solve A, B, C, D)

EXAMPLE 1 (SIMPLY SUPPORTED)



$$u_z(0) = 0 \quad M(0) = 0$$

$$u_z(L) = 0 \quad M(L) = 0$$

$$u_z(0) = A \sin(0) + B \cos(0) + C + D(0) = 0$$

$$B + C = 0$$

$$u_z(L) = A \sin\left(\sqrt{\frac{P}{EI}} L\right) + B \cos\left(\sqrt{\frac{P}{EI}} L\right) + C + DL = 0$$

$$u_z''(x_1) = -A \left(\frac{P}{EI}\right) \sin\left(\sqrt{\frac{P}{EI}} x_1\right) - B \left(\frac{P}{EI}\right) \cos\left(\sqrt{\frac{P}{EI}} x_1\right)$$

$$M(x_1) = -AP \sin\left(\sqrt{\frac{P}{EI}} x_1\right) - BP \cos\left(\sqrt{\frac{P}{EI}} x_1\right)$$

$$M(0) = 0 = -BP$$

$$B = 0, C = 0$$

$$M(L) = -AP \sin\left(\sqrt{\frac{P}{EI}} L\right) = 0$$

$$A \sin\left(\sqrt{\frac{P}{EI}} L\right) = 0, \quad A \sin\left(\sqrt{\frac{P}{EI}} L\right) + DL = 0$$

$$D = 0$$

$$A \sin\left(\sqrt{\frac{P}{EI}} L\right) = 0$$

$A = 0$ (a stupid result) OR

$$\sin\left(\sqrt{\frac{P}{EI}} L\right) = 0$$

$$\sqrt{\frac{P}{EI}} L = n\pi \quad n \in \mathbb{Z}$$

Solve for P to see when buckling occurs.

$$\left(\sqrt{\frac{P}{EI}} L\right)^2 = (n\pi)^2$$

$$\frac{PL^2}{EI} = n^2 \pi^2$$

$$P = \frac{n^2 \pi^2 EI}{L^2}$$

plug buckling P into the deflection formula to see what it looks like.

$$\bar{u}_z(x_1) = A \sin\left(\sqrt{\frac{P}{EI}} x_1\right) = A \sin\left(\frac{n\pi x_1}{L}\right)$$

- the lowest buckling load is the one for which $n = 1$

$$\bar{u}_2(x_1) = A \sin\left(\sqrt{\frac{P}{EI}} x_1\right) + B \cos\left(\sqrt{\frac{P}{EI}} x_1\right) + C + Dx_1$$

③ Boundary conditions for type 2 (to solve A, B, C, D)

$$u_2(0) = 0 \quad u_2(L) = 0$$

$$M_3(0) = Pe \quad M_3(L) = 0$$

$$u_2(0) = 0 = 0A + B + C + 0D = 0$$

$$u_2''(0) = \frac{Pe}{EI} \rightarrow B = -e, C = e$$

$$u_2(L) = 0 \quad A \sin\left(\sqrt{\frac{P}{EI}} L\right) + DL = -e \left[1 - \cos\left(\sqrt{\frac{P}{EI}} L\right)\right]$$

$$u_2'(L) = \frac{Pe}{EI} \quad A \sin\left(\sqrt{\frac{P}{EI}} L\right) = -e \left[1 - \cos\left(\sqrt{\frac{P}{EI}} L\right)\right]$$

$$A = -e \frac{1 - \cos\left(\sqrt{\frac{P}{EI}} L\right)}{\sin\left(\sqrt{\frac{P}{EI}} L\right)}, D = 0$$

$$\textcircled{1} \bar{u}_2(x_1) = -e \left[\frac{1 - \cos\left(\sqrt{\frac{P}{EI}} L\right)}{\sin\left(\sqrt{\frac{P}{EI}} L\right)} \sin\left(\sqrt{\frac{P}{EI}} x_1\right) + \cos\left(\sqrt{\frac{P}{EI}} x_1\right) - 1 \right]$$

as long as $P \rightarrow \frac{n^2 \pi^2 EI}{L^2}$, then we're all good. $\sin\left(\sqrt{\frac{P}{EI}} L\right) =$

$$\sqrt{\frac{P}{EI}} L = n\pi$$

$$\frac{P}{EI} L^2 = n^2 \pi^2$$

$$P = \frac{n^2 \pi^2 EI}{L^2} \text{ (coincidentally, } P_{cr})$$

FAILURE OF COLUMNS

In the "perfect" case, a column will fail if it buckles

$\bar{u}_2 \rightarrow \infty$, so $M_3 \rightarrow \infty$, so $\sigma_{11} \rightarrow \infty$

Long and Slender

$$P_{cr} = \frac{c \pi^2 EI}{L^2}$$

$$\sigma_{11} = -P/A, \text{ so } \sigma_{cr} = \frac{c \pi^2 EI}{L^2 A}$$

where did the negative go?

Short Columns

reach "ultimate compressive stress" \rightarrow "failure by squishing"

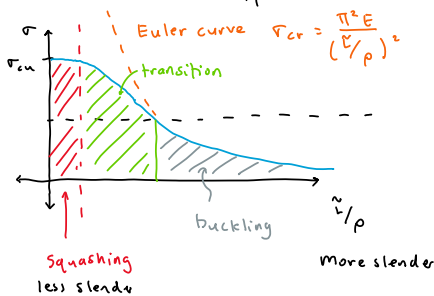
$$\sigma_{11} = -\frac{P}{A} = -\sigma_{cu}$$

Effective Length, $\tilde{L} = \sqrt{J_c}$

Radius of gyration, $\rho = \sqrt{I/A}$

$$\sigma_{cr} = \frac{c \pi^2 EI}{L^2 A} \Rightarrow \sigma_{cr} = \frac{c \pi^2 E}{(\tilde{L}/\rho)^2}$$

Slenderness Ratio: \tilde{L}/ρ



\tilde{L}/ρ big: fail by buckling

\tilde{L}/ρ small: squish

transition region: plastic deformation

$$\sigma_{cy} < |\sigma_{11}| < \sigma_{cu}$$

σ_{cy} = compressive yield stress

σ_{cu} = ultimate yield stress

TORSION (CIRCULAR SHAFTS)

- only external loads concentrated T or distributed torques t_3

Assumptions

① Displacement sections are perpendicular to the axis

- only external loads concentrated T or distributed torques t_3

Assumptions

- ① Planar cross-sections $x_3 = \text{constant}$
- ② Angle of twist ($\phi(x_3)$) function of x_3
- ③ No other deformation allowed.

$$u_1(x_1, x_2, x_3) = -\phi(x_3) x_2$$

$$u_2(x_1, x_2, x_3) = \phi(x_3) x_1$$

$$u_3(x_1, x_2, x_3) = 0$$

Strains

$$\epsilon_{11} = \frac{\partial u_1}{\partial x_1} = 0$$

$$\epsilon_{22} = \frac{\partial u_2}{\partial x_2} = 0$$

$$\epsilon_{33} = \frac{\partial u_3}{\partial x_3} = 0$$

$$\epsilon_{12} = \frac{1}{2} \left(\frac{\partial u_1}{\partial x_2} + \frac{\partial u_2}{\partial x_1} \right) = \frac{1}{2} (-\phi(x_3) + \phi(x_3)) = 0$$

$$\epsilon_{13} = \frac{1}{2} \left(\frac{\partial u_1}{\partial x_3} + \frac{\partial u_3}{\partial x_1} \right) = -\frac{1}{2} \left(\frac{d\phi(x_3)}{dx_3} x_2 + 0 \right) = \boxed{-\frac{1}{2} x_2 \frac{d\phi(x_3)}{dx_3}}$$

$$\epsilon_{23} = \frac{1}{2} \left(\frac{\partial u_2}{\partial x_3} + \frac{\partial u_3}{\partial x_2} \right) = \frac{1}{2} \left(\frac{d\phi(x_3)}{dx_3} x_1 + 0 \right) = \frac{1}{2} x_1 \frac{d\phi(x_3)}{dx_3}$$

Stresses

$$\epsilon_{11} = \epsilon_{22} = \epsilon_{33} = 0 \Rightarrow \sigma_{11} = \sigma_{22} = \sigma_{33} = 0$$

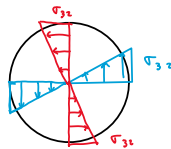
$$\tau_{12} = 2G \epsilon_{12} = 0$$

$$\tau_{13} = 2G \epsilon_{13} = -\frac{2}{2} G x_2 \frac{d\phi(x_3)}{dx_3}$$

only stresses shear stresses acting on plane
and pointing tangentially

$$\tau_{23} = 2G \epsilon_{23} = \frac{2}{2} G x_1 \frac{d\phi(x_3)}{dx_3}$$

linear radially



Because only stresses in $\tau_{31}, \tau_{32} \rightarrow$ only
contributes to shears in x_1, x_2 and moment in x_3

$$S_1(x_3) = \int_A \tau_{31}(x_1, x_2, x_3) dA$$

$$S_2(x_3) = \int_A \tau_{32}(x_1, x_2, x_3) dA$$

$$M_3(x_3) = \int_A (x_1 \tau_{23}(x_1, x_2, x_3) - x_2 \tau_{13}(x_1, x_2, x_3)) dA$$

$$T(x_3) = M_3(x_3) = GJ \phi'(x_3)$$

$$J = \int_A r^2 dA = \frac{\pi R^4}{2}$$

GJ = torsional stiffness (depends on material and geometry)

Equilibrium

$$T'(x_3) + t(x_3) = 0$$

Compatibility

$$T(x_3) = GJ \phi'(x_3)$$

$$(GJ (\phi'(x_3)))' + t(x_3) = 0$$

$$\tau_{13} = -\frac{T x_2}{J}$$

$$\tau_{23} = \frac{T x_1}{J}$$

statically determinate if we know a value of T somewhere in the
bar. Use the equilibrium equation and THEN sub into CC.

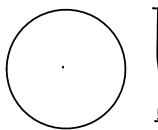
statically indeterminate \rightarrow use two kinematic boundary conditions.

τ_{30} shear stress: τ

$$\tau = \sqrt{\tau_{13}^2 + \tau_{23}^2}$$

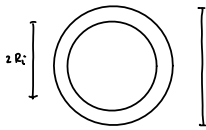
$$\tau = \frac{Tr}{J}$$

CALCULATING J

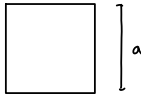


$$J = \frac{\pi R_0^4}{2}$$

$$\int_0^{2\pi} \int_0^R r^2 dr d\theta = \frac{1}{4} R^4 \cdot 2\pi = \frac{\pi R^4}{2}$$



$$J = \frac{\pi R_0^4}{2} - \frac{\pi R_i^4}{2}$$



$$J = .141 a^4$$

BEAM THEORY

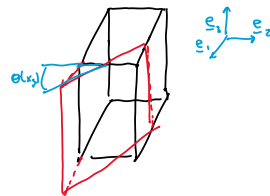
goal: compute internal resultant forces and moments, stresses and deformations of beam subjected to distributed load.

DERIVATION

Assumptions

- ① Cross-sections are rigid
- ② Cross-sections are planar
- ③ Only deformations in ϵ_z
 $u_1(x_1, x_2, x_3) = -x_2 \frac{d\bar{u}_z}{dx_1}$
 $u_2(x_1, x_2, x_3) = \bar{u}_z(x_1)$

what is a stress?



Strain Field

$$\epsilon_{11} = \frac{\partial u_1}{\partial x_1} = -x_2 \bar{u}_z''(x_1)$$

$$\epsilon_{22} = \frac{\partial u_2}{\partial x_2} = 0$$

$$2\epsilon_{12} = \frac{\partial u_1}{\partial x_2} + \frac{\partial u_2}{\partial x_1} = -\frac{d\bar{u}_z}{dx_1} + \frac{d\bar{u}_z}{dx_1} = 0$$

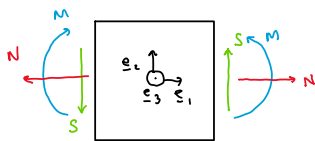
- $a|x_2|$ fibers stretch/contract proportionally to x_1, x_3 plane.
- no shear strains (b/c cross sections remain planar)
- no strains in plane (cross-sections rigid)

Constitutive Law for Cross-Section

$$\sigma_{22}, \sigma_{33} = 0$$

$$\sigma_{11}(x_1, x_2, x_3) = E \epsilon_{11}(x_1, x_2) = -E x_2 \bar{u}_z''(x_1)$$

Stress resultants: integral effects of internal stresses on cross-section



$$N(x_1) = \int_A \sigma_{11}(x_1, x_2, x_3) dA$$

$$M(x_1) = - \int_A x_2 \sigma_{11}(x_1, x_2) dA$$

$$S(x_1) = \int_A \sigma_{12}(x_1, x_2) dA$$

$$M(x_1) = - \int_A x_2 (-E x_2 \bar{u}_z''(x_1)) dA$$

$$= \left[\int_A E x_2^2 dA \right] \bar{u}_z''(x_1)$$

$$M_3(x_1) = H(x_1) \bar{u}_z''(x_1)$$

$$= E \int_A x_2^2 dA \bar{u}_z''(x_1)$$

$$M_3(x_1) = EI \bar{u}_z''(x_1)$$

important: $\sigma_{11}(x_1, x_2) = \frac{-M(x_1)}{I} x_2$

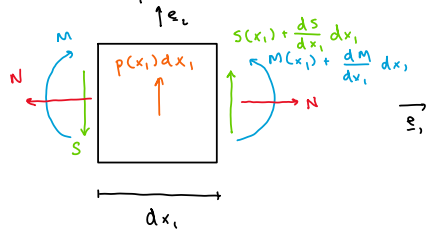
$$M_3(x_1) = EI \bar{u}_2''(x_1)$$

important: $\sigma_{11}(x_1, x_2) = \frac{-M(x_1)}{I} x_2$

Equilibrium

$$-S(x_1) + p_z(x_1) dx_1 + S(x_1) + S'(x_1) dx_1 = 0$$

$$S'(x_1) + p_z(x_1) = 0$$



$$-M(x_1) + S(x_1) dx_1 - p_z(x_1) dx_1 \frac{dx_1}{2} + M(x_1) + M'(x_1) dx_1 = 0$$

$$M'(x_1) + S(x_1) = 0$$

Equilibrium

$$S'(x_1) + p_z(x_1) = 0$$

$$M'(x_1) + S(x_1) = 0$$

$$M''(x_1) = p_z(x_1)$$

$$\frac{CL}{EI} \bar{u}_2''(x_1) = p(x_1)$$

BOUNDARY CONDITIONS

	\bar{u}_2, \bar{u}_2'
	\bar{u}_2, M
	\bar{u}_2', S
	M, S

SHEAR STRESSES IN BENT BEAMS

stress equilibrium

$$\frac{\partial \sigma_{11}}{\partial x_1} + \frac{\partial \sigma_{12}}{\partial x_2} = 0$$

$$\sigma_{11}(x_1, x_2) = \frac{-M(x_1)}{I} x_2$$

$$\frac{\partial \sigma_{12}}{\partial x_2} = \frac{M'(x_1)}{I} x_2$$

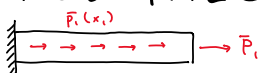
$$\sigma_{12} = \frac{-S(x_1)}{I} \frac{x_2^2}{2} + C$$

shear stress (σ_{12}) = 0 at top and bottom surfaces of the beam

$$C = \frac{S(x_1)}{I} \frac{\left(\frac{h}{2}\right)^2}{2}$$

$$\sigma_{12}(x_1, x_2) = \frac{-S(x_1)}{I} \left[\left(\frac{h}{2}\right)^2 - x_2^2 \right]$$

ROD THEORY



$$u_1(x_1, x_2, x_3) = \bar{u}_1(x_1)$$

$$\left. \begin{aligned} u_2(x_1, x_2, x_3) &= 0 \\ u_3(x_1, x_2, x_3) &= 0 \end{aligned} \right\} \begin{array}{l} \text{cross-sections deform} \\ \text{rigidly} \end{array}$$

Strain Field

$$\epsilon_{11}(x_1, x_2, x_3) = \bar{u}_1'(x_1), \text{ all other } 0$$

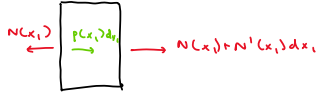
$$\sigma_{11}(x_1, x_2, x_3) = E \epsilon_{11}$$

$$\sigma_{11}(x_1, x_2, x_3) = E \bar{u}_1'(x_1) \longrightarrow \text{uniaxial stress}$$

Stress Resultant

$$\begin{aligned}
 N_1(x_1) &= \int_A \sigma_{11}(x_1, x_2, x_3) dA \\
 &= \int_A E u_1'(x_1) dA \\
 &= \int_A E dA \bar{u}_1'(x_1) \\
 S &= \int_A E(x_1, x_2, x_3) dA \\
 N(x_1) &= EA(x_1) \bar{u}_1'(x_1)
 \end{aligned}$$

Equilibrium



$$\begin{aligned}
 -N(x_1) + p_1(x_1)dx_1 + N(x_1) + N'(x_1)dx_1 &= 0 \\
 N'(x_1) + p_1 &= 0
 \end{aligned}$$

$$\frac{d(EA(x_1) \bar{u}_1'(x_1))}{dx_1} + p_1 = 0$$

2 boundary conditions

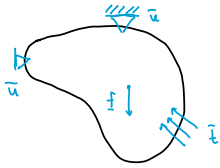
$$(\bar{u}_1 = 0, N_1 = 0 \text{ or } T_1)$$

Adding Thermal Changes

$$N(x_1) = EA(x_1) [\bar{u}_1'(x_1) - \alpha \Delta \theta(x_1)]$$

$$\text{and } N'(x_1) + p_1(x_1) = 0 \quad \text{+ BC}$$

ELASTICITY



$$\sigma_{ji,j} + f_i = 0 \quad \text{in } B$$

$$\epsilon_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \quad \text{in } B$$

$$\sigma_{ij} = C_{ijkl} \epsilon_{kl} \quad \text{in } B$$

$$\epsilon_{ij} = S_{ijkl} \sigma_{kl} \quad \text{in } B$$

For linear isotropic material:

$$\epsilon_{ij} = \frac{1}{E} \left[(1+\nu) \sigma_{ij} - \nu \sigma_{kk} \delta_{ij} \right]$$

$$\epsilon_{11} = \frac{1}{E} \left[\sigma_{11} - \nu (\sigma_{22} + \sigma_{33}) \right], \text{ similar for } \epsilon_{22}$$

$$\epsilon_{23} = \frac{1}{E} \left[(1+\nu) \sigma_{23} - \nu \sigma_{kk} \delta_{23} \right]$$

$$\epsilon_{23} = \frac{1+\nu}{E} \sigma_{23}$$

$$\epsilon_{11} = \frac{1}{E} \left[\sigma_{11} - \nu (\sigma_{22} + \sigma_{33}) \right]$$

$$\epsilon_{22} = \frac{1}{E} \left[\sigma_{22} - \nu (\sigma_{33} + \sigma_{11}) \right]$$

$$\epsilon_{33} = \frac{1}{E} \left[\sigma_{33} - \nu (\sigma_{11} + \sigma_{22}) \right]$$

$$2 \epsilon_{23} = \frac{1}{G} \sigma_{23}$$

$$2 \epsilon_{31} = \frac{1}{G} \sigma_{31}$$

$$2 \epsilon_{12} = \frac{1}{G} \sigma_{12}$$

$$n_i \sigma_{ij} = t_j = \bar{t}_j$$

$$u_i = \bar{u}_i$$

$$G = \frac{E}{2(1+\nu)}$$

STRESS TENSOR

MATHEMATICAL PRELIM

free indices \rightarrow not repeated in same additive term; goes through all values in range

$$a_{i2} \rightarrow a_{11}, a_{21}, a_{31}$$

$t_i = \sigma_{ij} n_j$ implies summation:

$$t_1 = \sigma_{11} n_1 + \sigma_{12} n_2 + \sigma_{13} n_3$$

$$t_2 = \sigma_{21} n_1 + \sigma_{22} n_2 + \sigma_{23} n_3$$

$$t_3 = \sigma_{31} n_1 + \sigma_{32} n_2 + \sigma_{33} n_3$$

Basis: any set of linearly independent

$t_i = \sigma_{ij} n_j$ implies summation:

$$\begin{aligned} t_1 &= \sigma_{11} n_1 + \sigma_{12} n_2 + \sigma_{13} n_3 \\ t_2 &= \sigma_{21} n_1 + \sigma_{22} n_2 + \sigma_{23} n_3 \\ t_3 &= \sigma_{31} n_1 + \sigma_{32} n_2 + \sigma_{33} n_3 \end{aligned}$$

Basis: any set of linearly independent

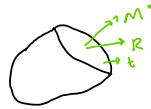
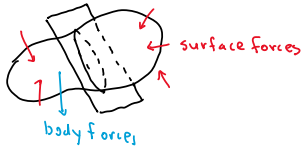
$$\delta_{ij} = \underline{e}_i \cdot \underline{e}_j = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{otherwise} \end{cases}$$

$$\epsilon_{ijk} = \begin{cases} 0 & \text{when anything repeated} \\ 1 & \text{clockwise} \\ -1 & \text{counterclockwise} \end{cases}$$



$$\underline{e}_i \times \underline{e}_j = \epsilon_{ijk} \underline{e}_k$$

$$\begin{aligned} \underline{e}_1 \times \underline{e}_2 &= \epsilon_{121} \underline{e}_1 + \epsilon_{122} \underline{e}_2 + \epsilon_{123} \underline{e}_3 \\ &= 0 + 0 + \underline{e}_3 \end{aligned}$$



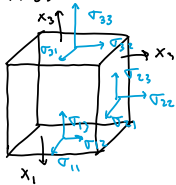
stress vector = force/unit area

$$\underline{t} = \lim_{\Delta S \rightarrow 0} \frac{\underline{F}}{\Delta S}$$

$$\text{resultant stress vector} \quad \int_S \underline{t} \, dS = \underline{R}$$

$$\text{resultant moment vector} \quad \int_S \underline{r} \times \underline{t} \, dS = \underline{M}^o$$

can decompose stress vectors (imagine they go through the same point, but have different normals)



$$\underline{t}^{(i)} = \sigma_{ij} \underline{e}_j$$

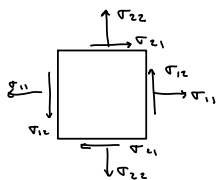
$$\underline{t}^{(n)} = \underline{n} (\underline{e}_1 \underline{t}^{(1)} + \underline{e}_2 \underline{t}^{(2)} + \underline{e}_3 \underline{t}^{(3)}) = \underline{n} \cdot (\underline{e}_1 \otimes \underline{t}^{(1)} + \underline{e}_2 \otimes \underline{t}^{(2)} + \underline{e}_3 \otimes \underline{t}^{(3)})$$

$$\underline{\sigma} = \underline{e}_i \sigma_{ij} \underline{e}_j = \sigma_{ij} \underline{e}_i \underline{e}_j$$

$$\sigma_{ij} = \begin{pmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{pmatrix} \rightarrow \text{components of stress tensor (acting on planes w/ normal } \underline{e}_i)$$

$$t_j^{(n)} = t_j(\underline{n}) = \sigma_{ij} n_i$$

TRANSFORMATIONS



$$\tilde{\sigma}_{ij} = \sigma_{kl} (\tilde{\underline{e}}_i \cdot \underline{e}_k) (\underline{e}_l \cdot \tilde{\underline{e}}_j)$$

$$\tilde{\sigma}_{11} = \frac{\sigma_{11} + \sigma_{22}}{2} + \frac{\sigma_{11} - \sigma_{22}}{2} \cos(2\alpha) + \sigma_{12} \sin(2\alpha)$$

$$\tilde{\sigma}_{22} = \frac{\sigma_{11} + \sigma_{22}}{2} - \frac{\sigma_{11} - \sigma_{22}}{2} \cos(2\alpha) - \sigma_{12} \sin(2\alpha)$$

$$\tilde{\sigma}_{12} = -\frac{\sigma_{11} - \sigma_{22}}{2} \sin(2\alpha) + \sigma_{12} \cos(2\alpha)$$

Maximum Normal Stress

- zero shear stress

$$\tan(2\alpha_p) = \frac{2\sigma_{12}}{\sigma_{11} - \sigma_{22}}$$

- principal stresses are eigenvalues of matrix of stress tensor components
- principal directions corresponding eigenvectors
- σ symmetric, eigenvalues real and eigenvectors orthogonal

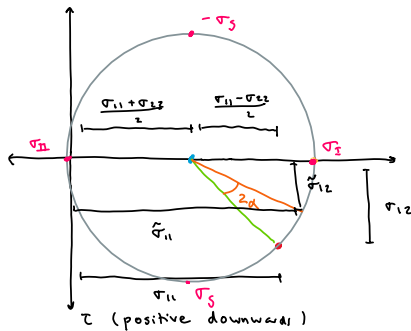
$$\sigma_{I,II} = \frac{\sigma_{11} + \sigma_{22}}{2} \pm \sqrt{\left(\frac{\sigma_{11} - \sigma_{22}}{2}\right)^2 + \sigma_{12}^2}$$

$$\tan(2\alpha_s) = -\frac{\sigma_{11} - \sigma_{22}}{2\sigma_{12}}$$

$$\sigma_s = \sqrt{\left(\frac{\sigma_{11} - \sigma_{22}}{2}\right)^2 + \sigma_{12}^2}$$

here, normal stresses are average stress: $\frac{\sigma_{11} + \sigma_{22}}{2}$

MOHR'S CIRCLE



- 1 Plot reference pt. $A = (\sigma_{11}, \sigma_{12})$
stress components on plane w/ normal \underline{e}_1 ($\alpha=0$)
- 2 Plot circle's center, C , at avg. stress $(\frac{\sigma_{11} + \sigma_{22}}{2}, 0)$
- 3 The distance between the two is the radius, R .
- 4 Sketch the circle centered at C w/ radius R .
- 5 $\sigma_I, \sigma_{II}, \sigma_s$, and $-\sigma_s$ are labelled appropriately.

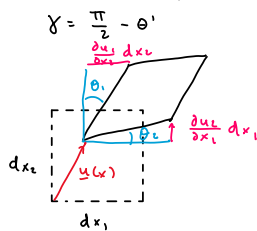
STRAIN

DEFINITIONS

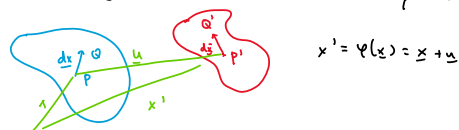
normal strain = elongation or contraction of a line segment per unit length

$$\epsilon = \lim_{\Delta S \rightarrow 0} \frac{\Delta S' - \Delta S}{\Delta S} \quad (\Delta S = \text{line segment undeformed})$$

shear strain = change in angle between two perpendicular line segments



can describe the deformation a body undergoes with deformation mapping.



Lots of math happens. It doesn't seem very important.

$$\epsilon_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} + \underbrace{\frac{\partial u_m}{\partial x_i} \frac{\partial u_m}{\partial x_j}}_{\text{ignore HOT}} \right)$$

$$\epsilon_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

- strain tensor symmetric

$$\epsilon_{11} = \frac{1}{2} \left(\frac{\partial u_1}{\partial x_1} + \frac{\partial u_1}{\partial x_1} \right)$$

2.. 2.. 2..

- strain tensor symmetric

$$\epsilon_{11} = \frac{1}{2} \left(\frac{\partial u_1}{\partial x_1} + \frac{\partial u_1}{\partial x_1} \right)$$

$$\epsilon_{11} = \frac{\partial u_1}{\partial x_1}, \quad \epsilon_{22} = \frac{\partial u_2}{\partial x_2}, \quad \epsilon_{33} = \frac{\partial u_3}{\partial x_3}$$

$$\epsilon_{12} = \frac{1}{2} \left(\frac{\partial u_1}{\partial x_2} + \frac{\partial u_2}{\partial x_1} \right) = \epsilon_{21}$$

$$\epsilon_{13} = \frac{1}{2} \left(\frac{\partial u_1}{\partial x_3} + \frac{\partial u_3}{\partial x_1} \right) = \epsilon_{31}$$

$$\epsilon_{23} = \frac{1}{2} \left(\frac{\partial u_2}{\partial x_3} + \frac{\partial u_3}{\partial x_2} \right) = \epsilon_{32}$$

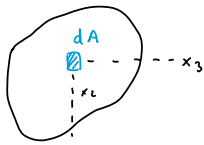
and the transformations

$$\tilde{\epsilon}_{ij} = \epsilon_{kl} (\tilde{e}_k \cdot e_i) (\tilde{e}_j \cdot e_k)$$

so every thing above works.

(and formulas given).

BEAM INERTIA



① First Moment of Area = Center of Area

$$Q_2 = \int_A x_3 dA, \quad Q_3 = \int_A x_2 dA$$

Geometric Center:

$$x_3^G = \frac{Q_2}{A} = \frac{\int_A x_3 dA}{A}, \quad x_2^G = \frac{Q_3}{A} = \frac{\int_A x_2 dA}{A}$$

② Second Moments of Area

$$I_{22} = \int_A x_3^2 dA, \quad I_{33} = \int_A x_2^2 dA$$

$$I = I_{33} = \int_A x_2^2 dA$$

x_2 = distance to center of area

$$I = I^G + A d^2$$

↑ neutral axis ↗ distance to neutral axis