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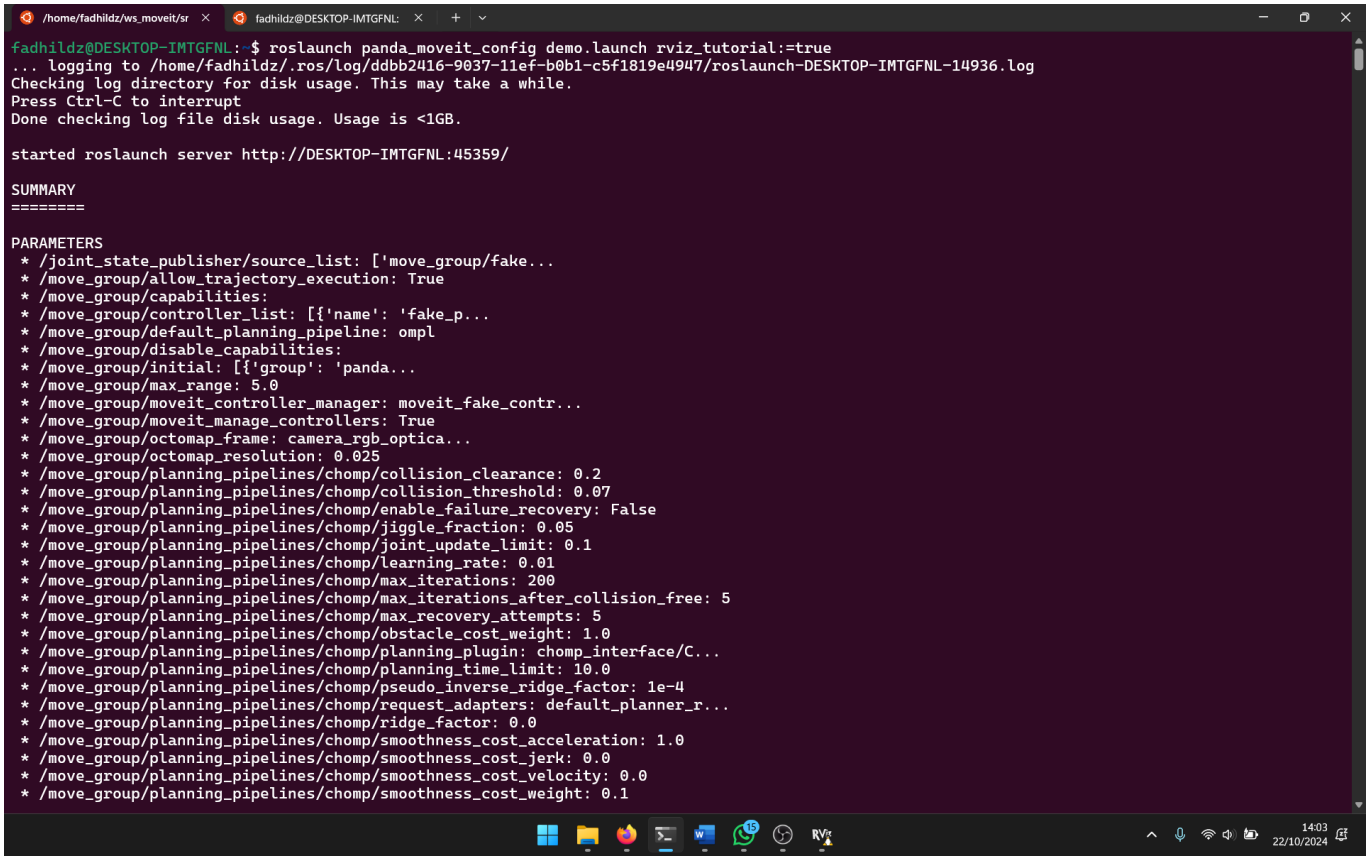
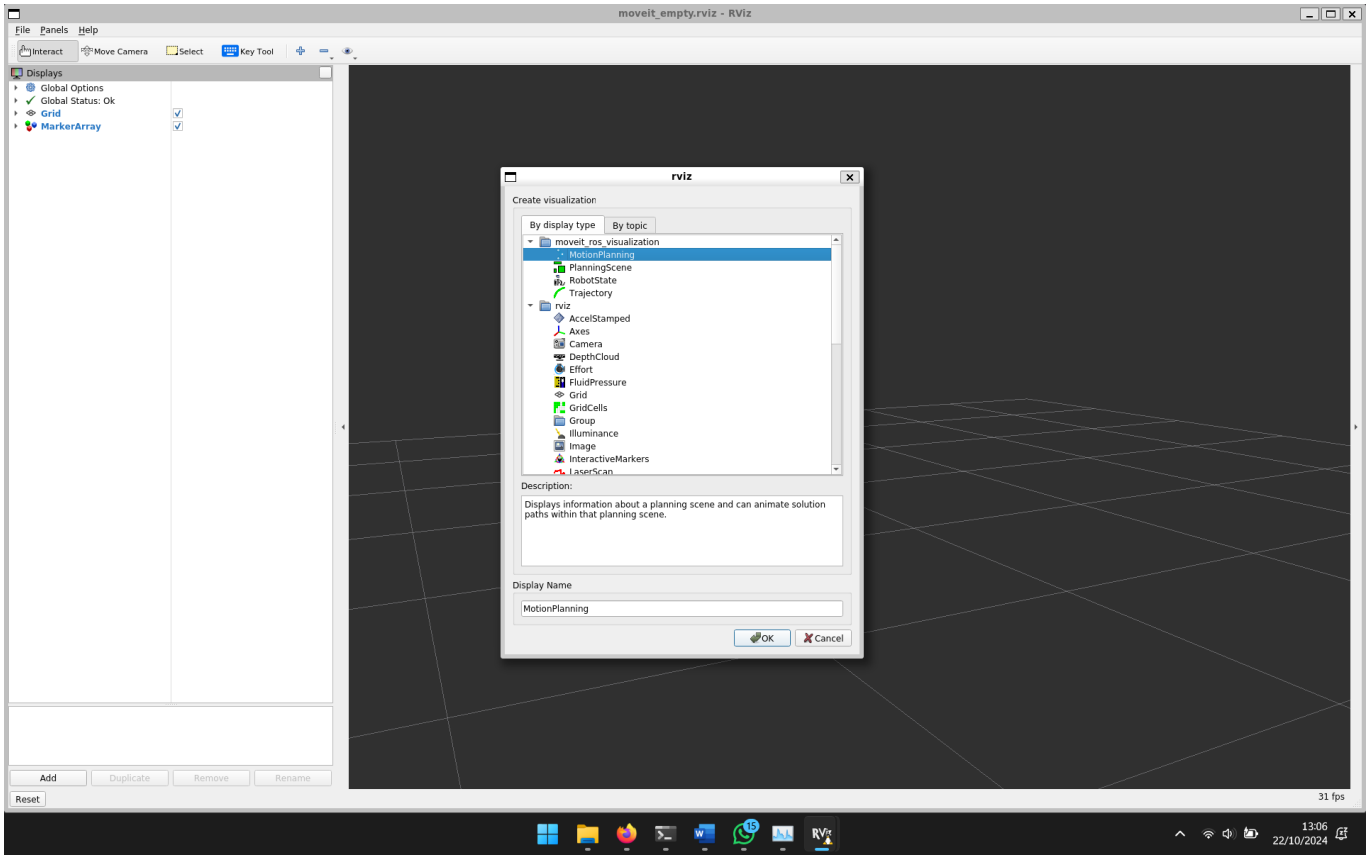
MoveIt Quickstart in RViz – MoveIt 1 Noetic

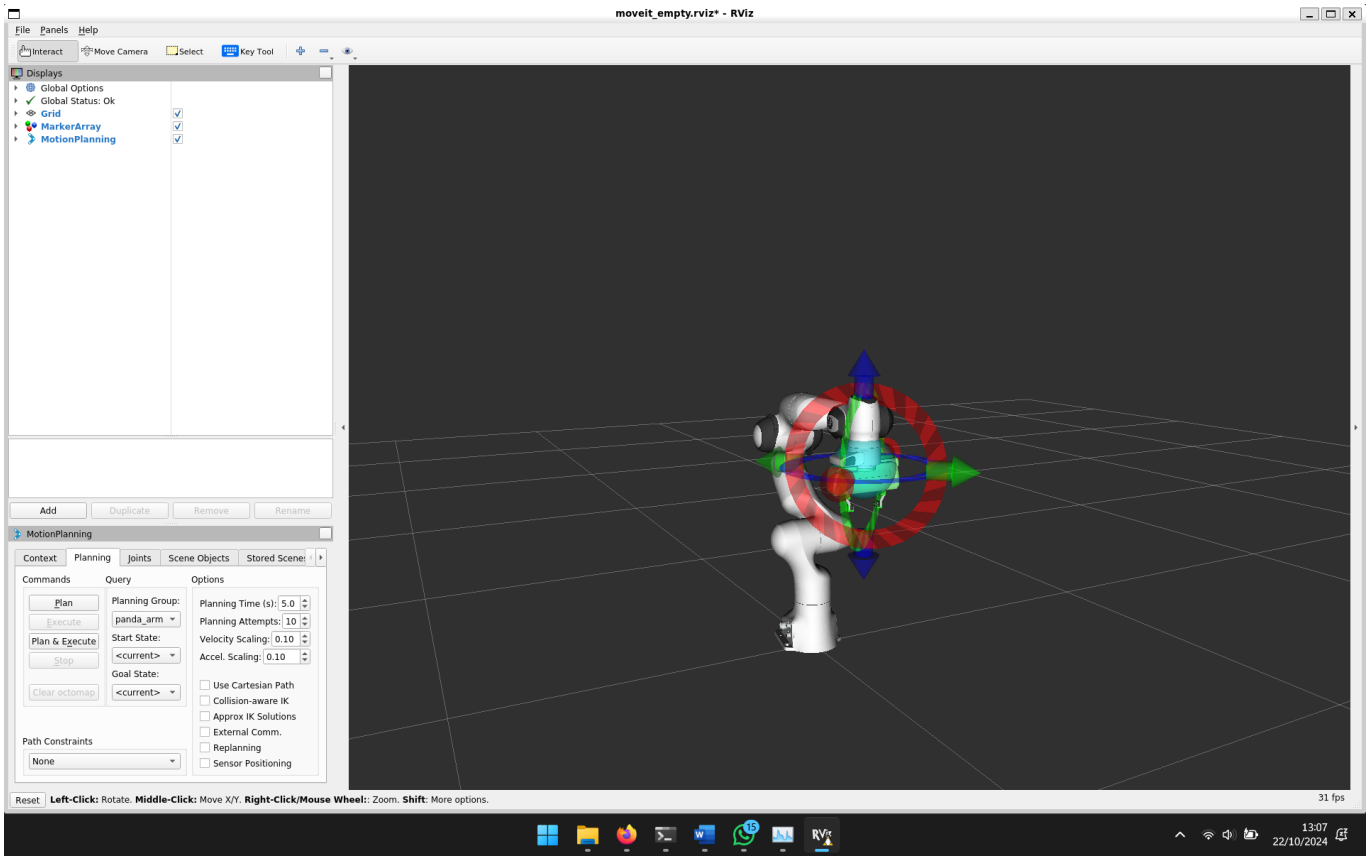
1. **roslaunch panda_moveit_config demo.launch rviz_tutorial:=true** untuk membuka Rviz.



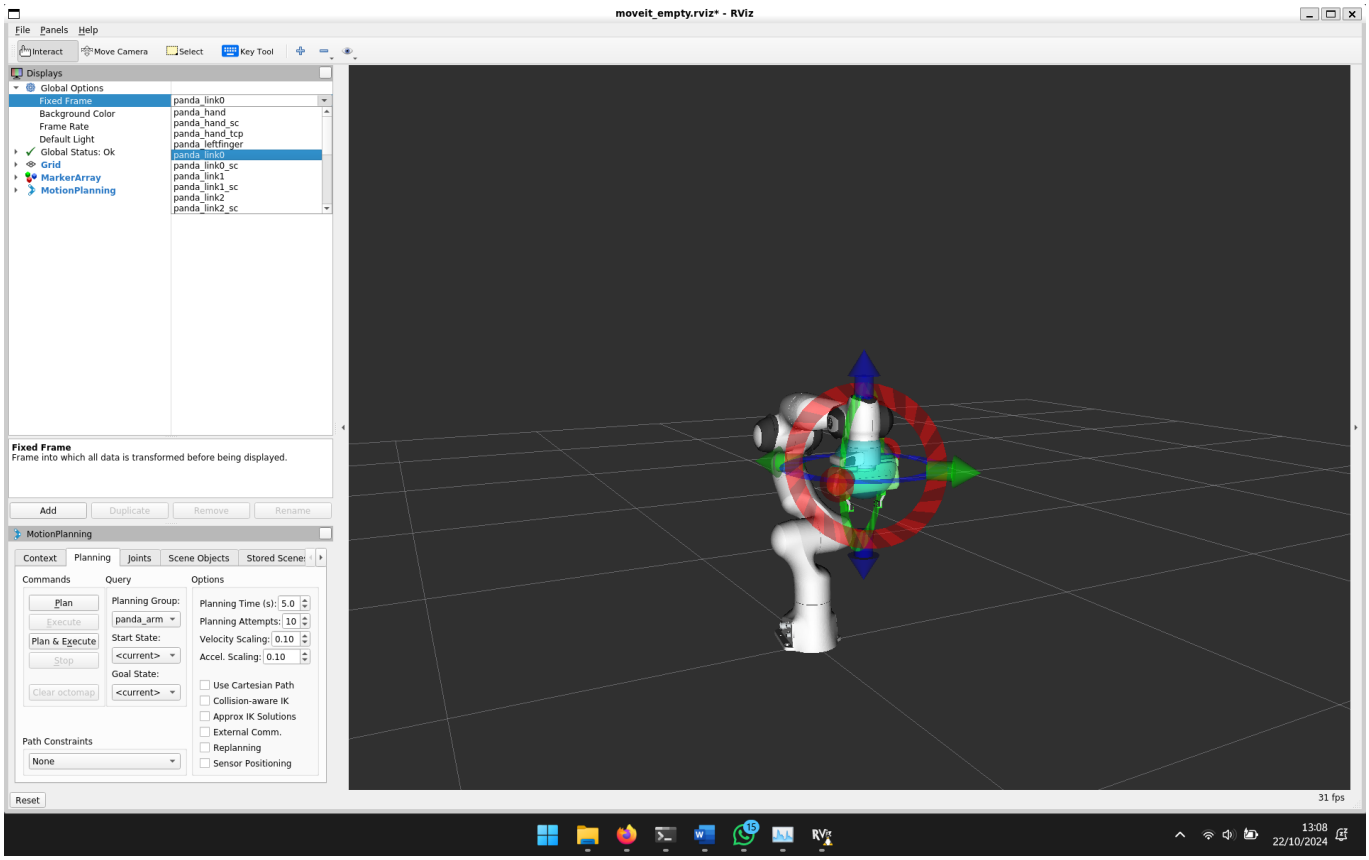
2. RViz akan terbuka, selanjutnya tambahkan MotionPlanning.



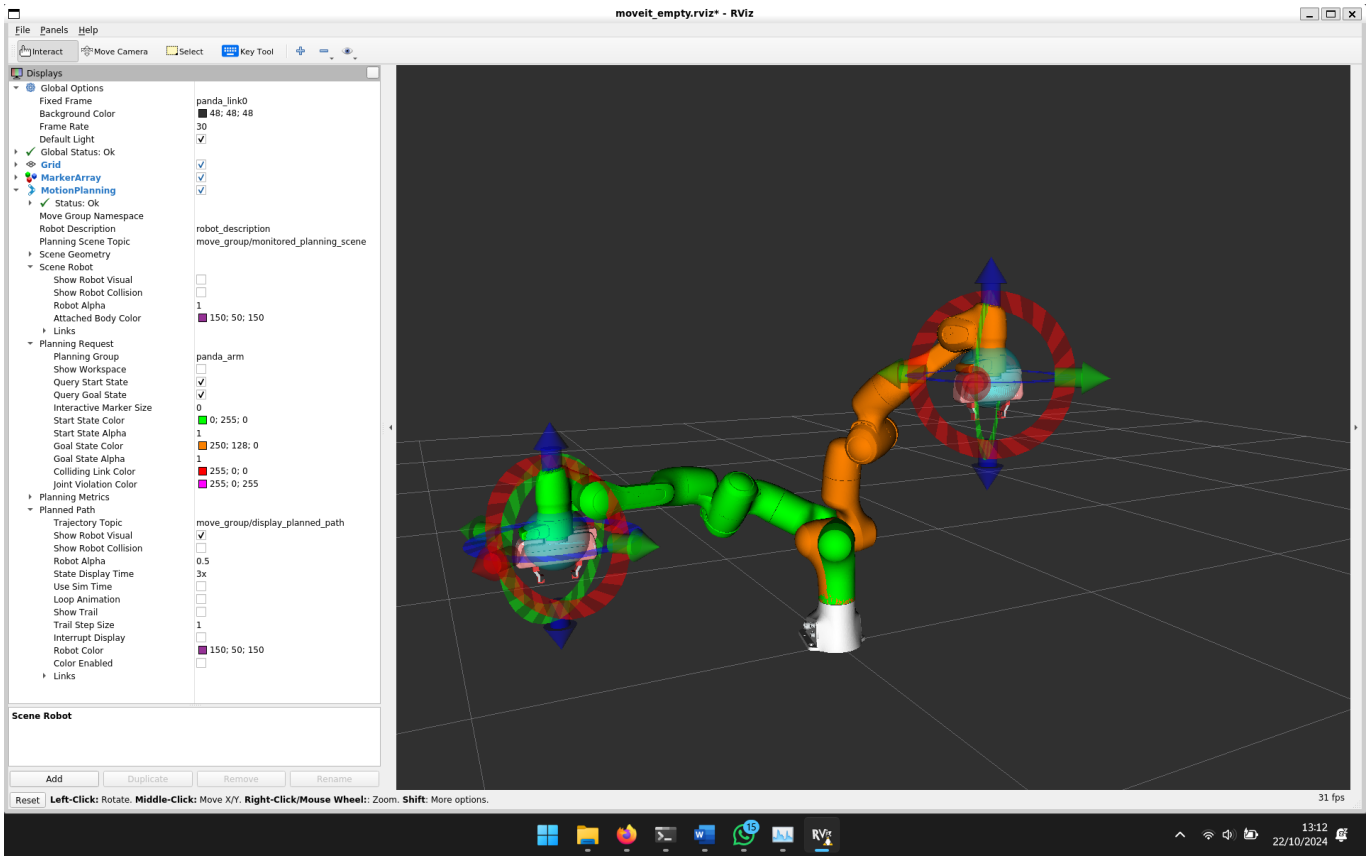
3. Robot panda_arm akan muncul di layar.



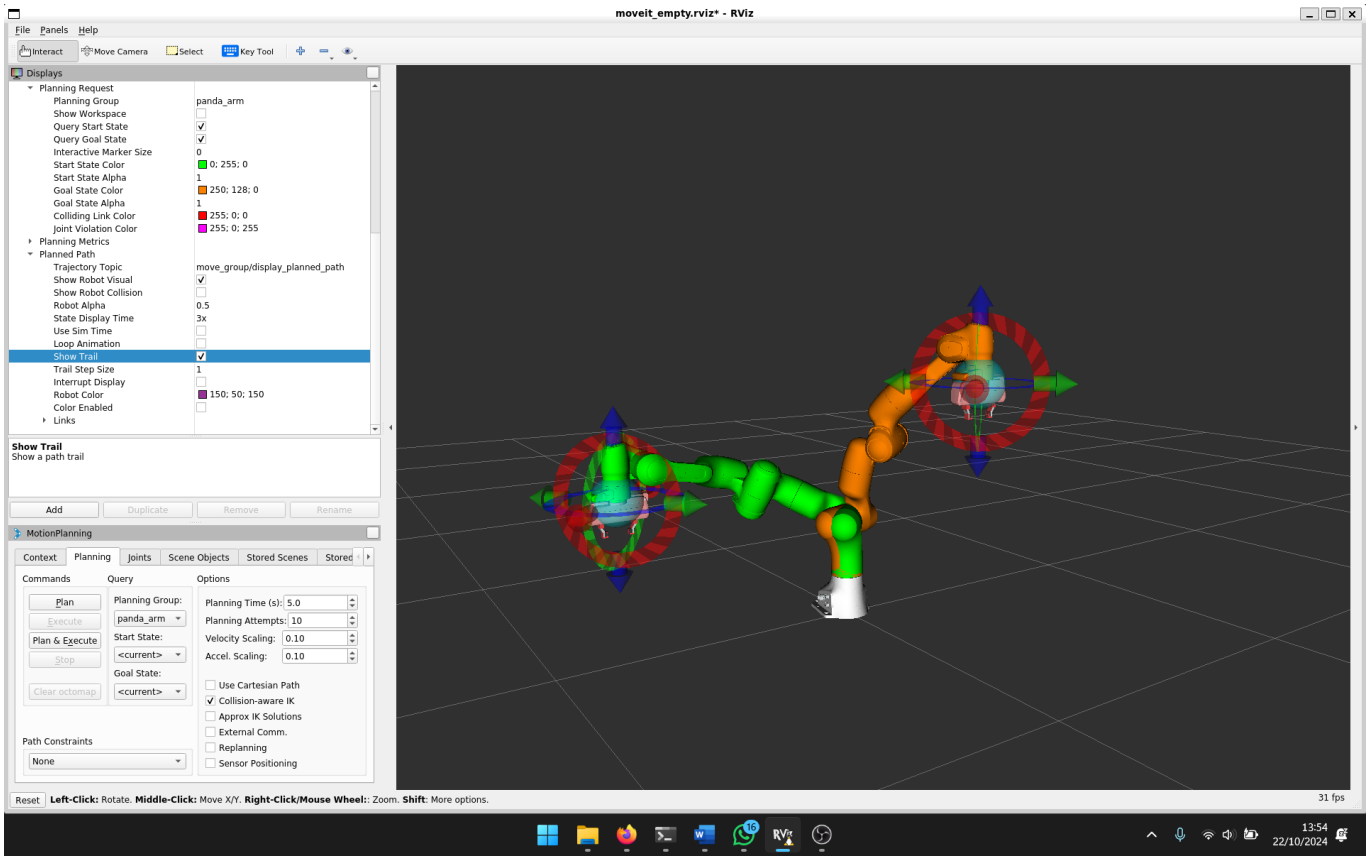
4. Pastikan fixed frame nya di setting ke **panda_link0**



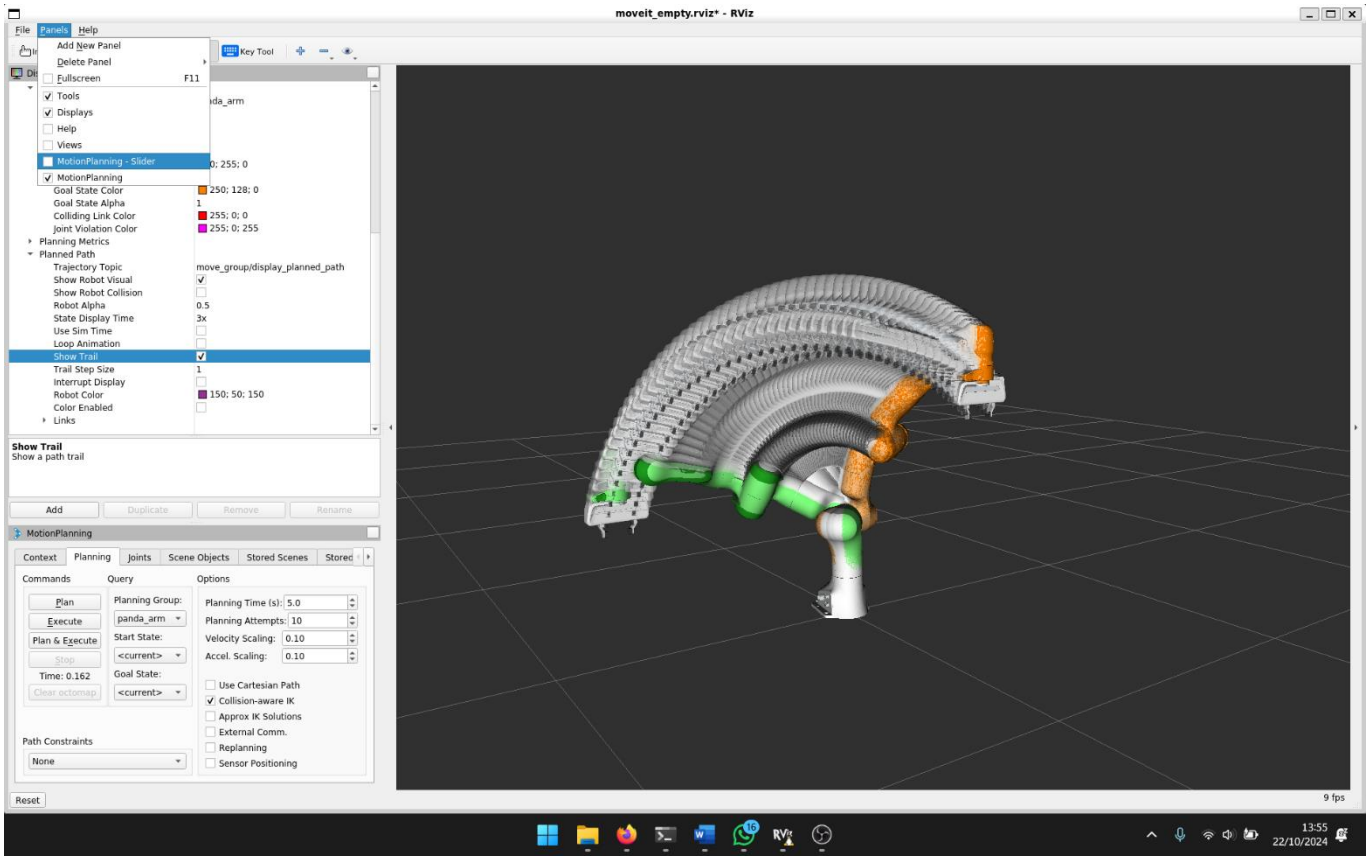
5. Setting sesuai dengan instruksi, lalu ubah posisi query start dan query goal nya.



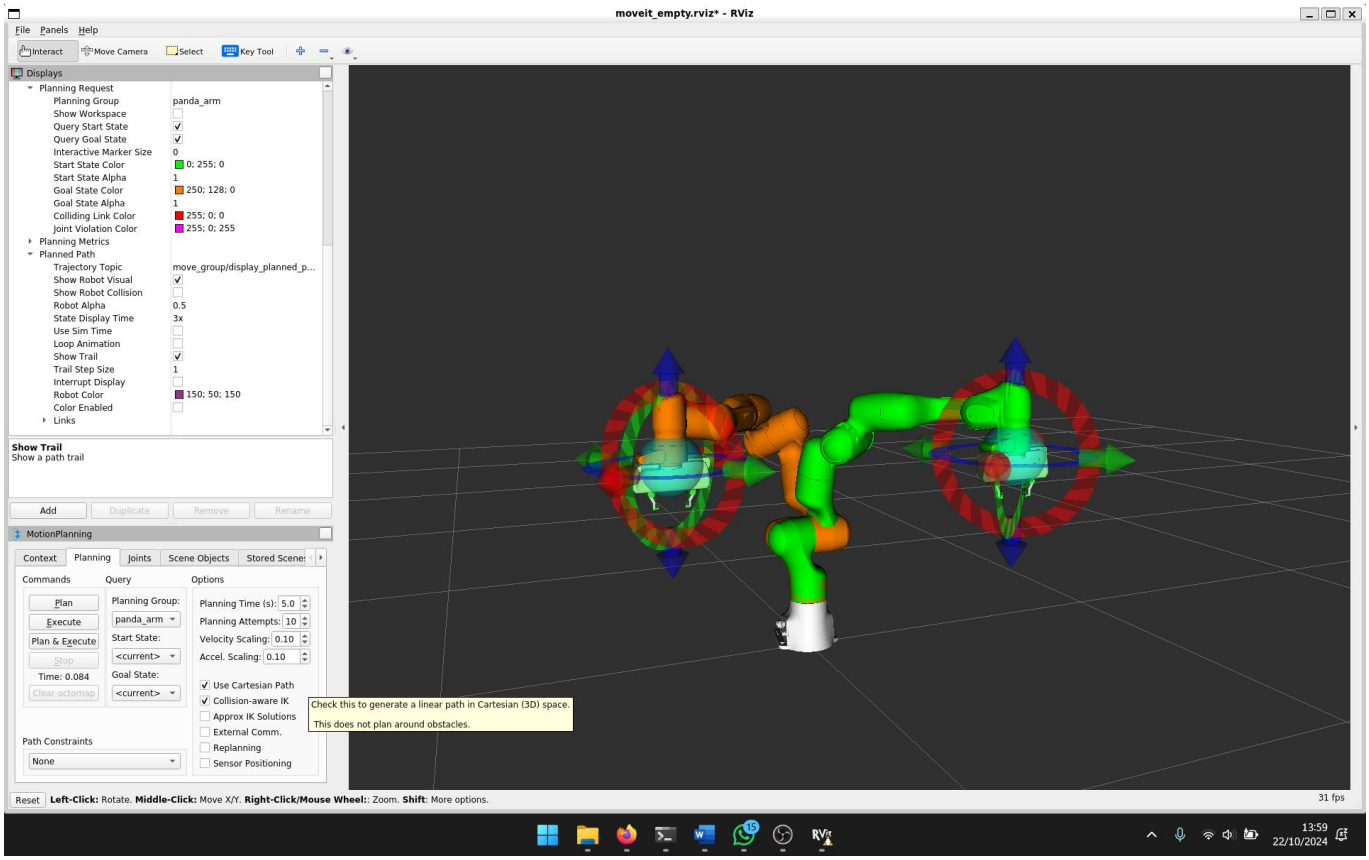
6. Nyalakan show trail untuk melihat pergerakan robot



7. Klik plan, maka robot akan bergerak dari query start (hijau) ke query goal (orange)



8. Nyalakan use cartesian path untuk melihat path cartesian lalu klik plan



9. Akan terlihat trail dari cartesian path.