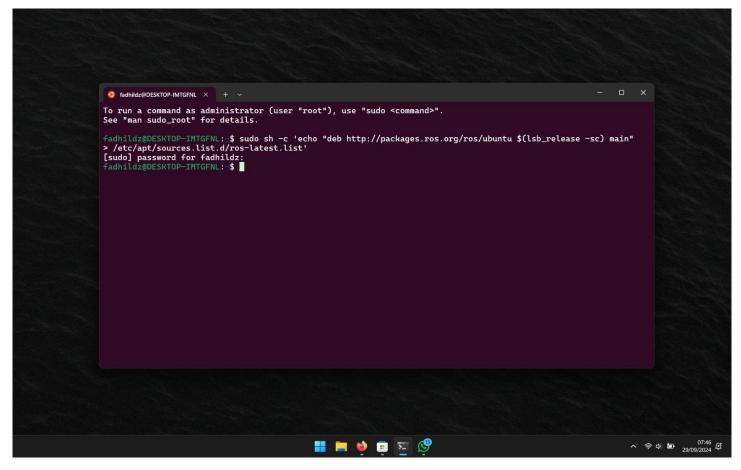
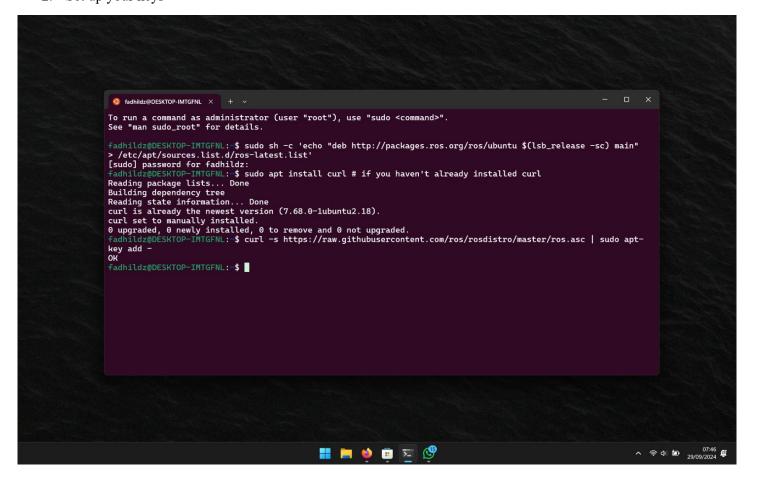
Tahap Instalasi ROS Noetic di Ubuntu 20.04.6 LTS (WSL)

Tutorial: http://wiki.ros.org/noetic/Installation/Ubuntu

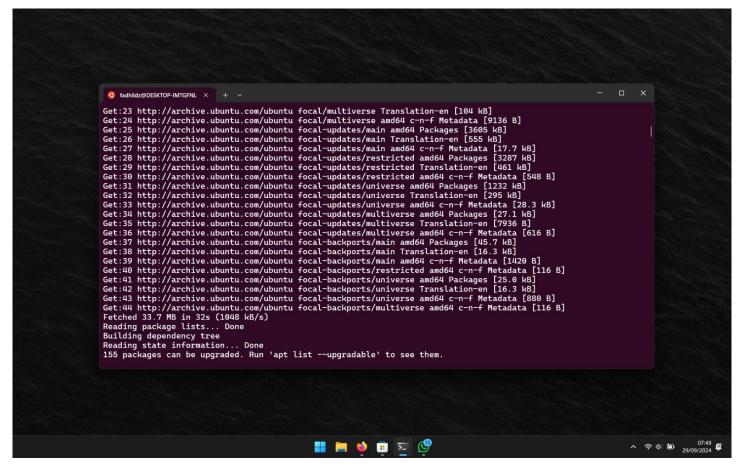
1. Setup your sources.list



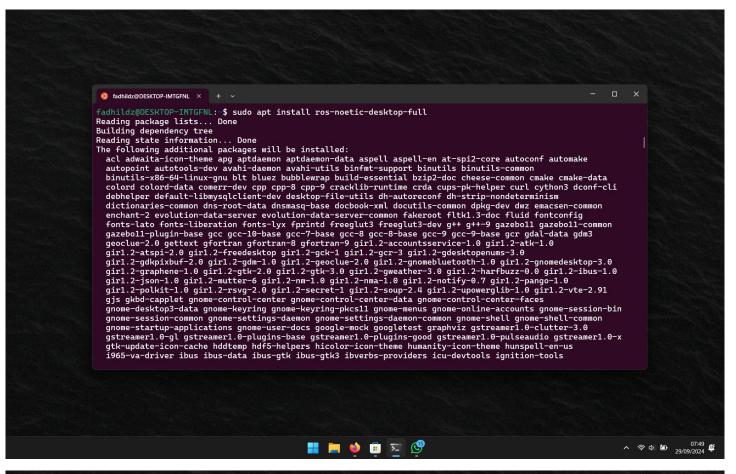
2. Set up your keys

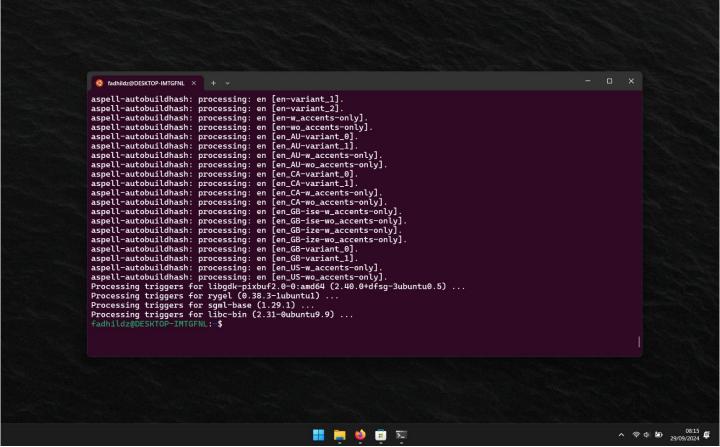


3. Installation

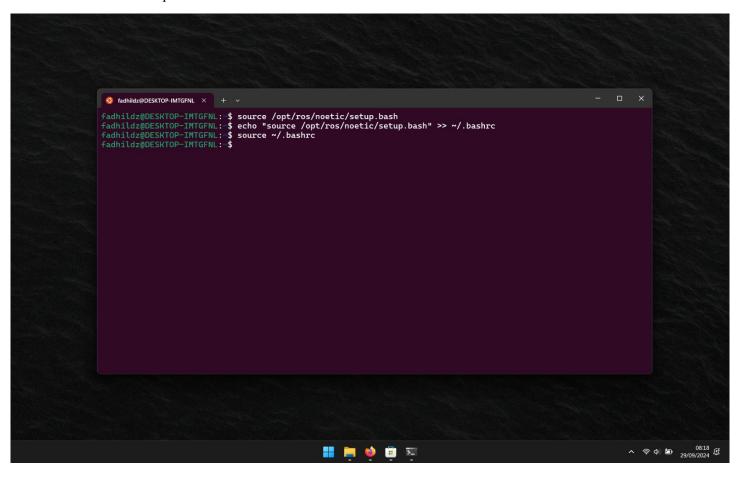


4. Install Desktop-Full Install

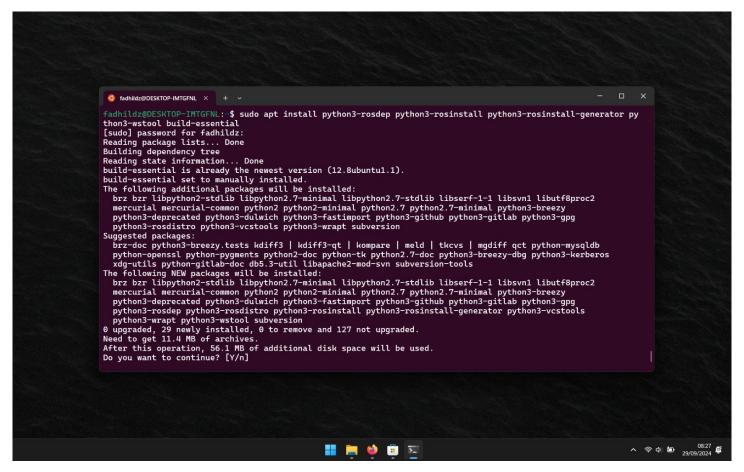




5. Environment setup



6. Dependencies for building packages



```
Setting up python3-rosdistro (0.9.1-100) ...
Setting up libsvn1:amd64 (1.13.0-3uburtu6.2) ...
Setting up python3-gitlab (1:2.0-11) ...
Setting up python3-gitlab (1:2.0-11) ...
Setting up python3-pitlab (1:2.0-12) ...
Setting up python3-pitlab (1:2.0-12) ...
Setting up libsython2-stdiis amd64 (2.7.17-ubuntu4) ...
Setting up subversion (1.13.0-3ubuntu6.2) ...
Setting up python3-precy (3.0.2-4ubuntu2) ...
Setting up python3-precy (3.0.2-4ubuntu2) ...
Setting up python2 (7.17-ubuntu4) ...
Setting up python (2.7.17-ubuntu4) ...
Setting up brz (2.7.0-ubuntu2) ...
Setting up python3-precysinstal (0.7.0-0-4) ...
Setting up python3-precysinstal (0.7.0-0-4) ...
Setting up mercurial (5.3.1-ubuntu1) ...

Creating config file (**te/maccurial/lagra.d/hgat.rc with new version Processing triggers for laberba (2.3-ubuntu9.9) ...
Processing triggers for deskton-file-utlla (0.24-ubuntu9.3) ...
Processing triggers for deskton-file-utlla (0.24-ubuntu3) ...
Processing triggers for fase-support (3.64ubuntu1) ...
Processing triggers for gonem-enus (3.36.0-lubuntu1) ...

fadh1dz8DESKTOP-INTGFNL: $
```

7. Initialize rosdep

