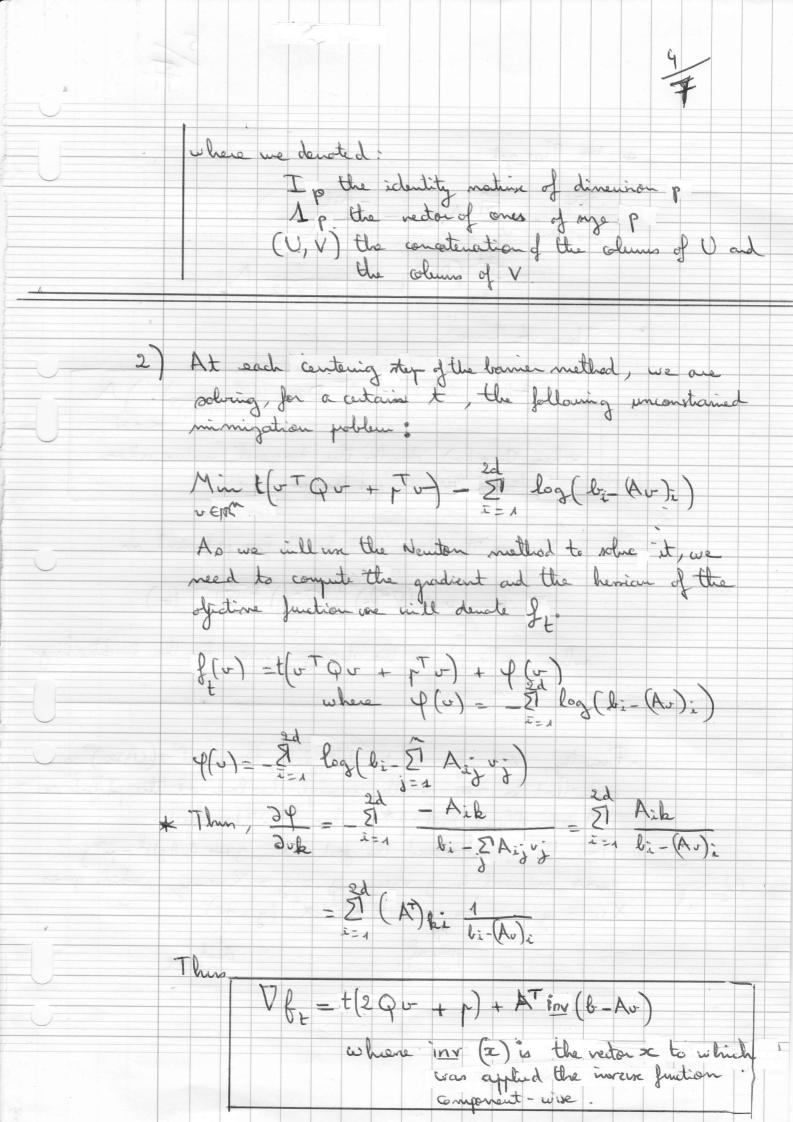


2/7 Thus, inf $\lambda ||w||_{2}$, $\mu^{T} \times \omega = - \sup_{\omega} \left[-\lambda \left(\frac{1}{\lambda} (x^{T} \mu^{T}) \omega - ||w||_{2} \right) \right]$ Junction of the norm 1. We already conjuted this conjugate in the previous homework. But for reminder, 8*(y)= sup ([] y = x = = [] |x : |) (x end) = su (Ži (y; sgn(xi)) x; of there exists $j \in [1, d]$ and that $j \neq 1$, we have considering the requese $\times (P) = (P \times S_i) \times (P \times I)$. $P_{y}(x(p)) = P(y-1) \xrightarrow{p \to +\infty}$ o similarly, if ther exists is made that y = <-1, considering the sequence x (P) = ((- P did) 1 \le \le m) , we have: $f_{3}(n(l)) = -p(y_{3}+1) \longrightarrow +\infty$ e finally, if for all $j \in [1, d]$, $y_j \in [-1, 1]$ 19g(n) | ≤ 2 | | yini | - 2 | ni) = \(\frac{1}{2} \rightarrow \

As fy (0) = 0, we can conclude that Frially we can conclude that: The dual of the (LASSO) problem is therefore : Max - 1/2 || m||2 - pT y st. (XTp) 1 & A V2 E [1, 1] Min v TQV + pTV (QP) VERN AV & & e IRMXM where Q = 1 In EIRM 1 = 4 € IR2d×m $A = (X^T, -X^T)$ E R2d b = 1121



* We also get: 306200 = 2d Aib (- - Ail) = 21 (AT) ki (b=-(Av);)2 A;e This we have $\nabla_{t}^{2} = 2tQ + A^{T} Ding \left(\frac{1}{(\delta_{x} + \lambda \nu)_{x})^{2}} \right) A$ when Ding (v) denotes the diagonal motion whose diagonal is the vector u Each Neuton tercition will be thefore performed as $v \leftarrow v - \omega \left(v, l\right) \left(\nabla^2 l_l(v)\right)^{-1} \nabla l_l(v)$ when a(v, ft) is the stepsize given by the backtracking

Experiments and comments

Below, I show results obtained for the following experiment:

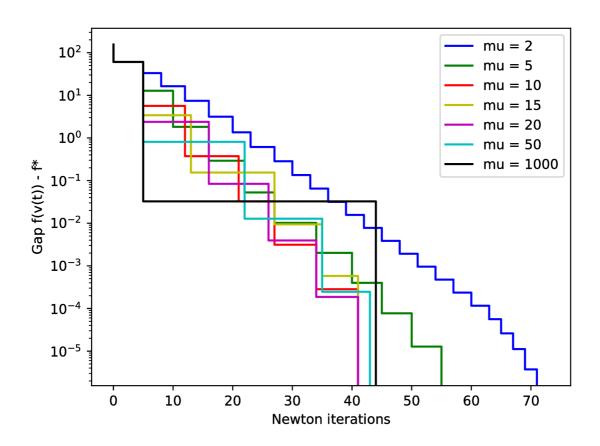
I generated a random matrix X of size (N=50,D=500) (values between -1 and 1), a vector of weights w of size D with 20 % of non-zero random entries (values between -1 and 1), and the vector of observations Y of size N by computing Xw.

I launched the barrier method to solve (QP) (for lambda=10) for various values of mu, on the same data (mu being the multiplicative factor by which we are increasing t after each centering step until convergence, t being the parameter of the barrier method introduced in page 4). Precision criterion was set to 10⁻⁴. Backtracking line search parameters were set to alpha=0.25 and beta=0.5, using the notations of the course.

On the figure below, I am plotting the gap $f(v(t)) - f^*$, where f is the objective function of (QP) ($f=v^TQv + p^Tv$), where v(t) is the estimate of the dual solution at the end of the centering step of parameter t, and where f^* is estimated by $f(v_{end})$ with v_{end} the last estimate (for the precision criterion stated above). The length of the steps correspond to the number of Newton iterations needed per centering step.

We can see first that the larger mu, the larger the number of Newton iterations needed per centering step but the smaller the number of outer iterations (centering steps) required for the precision criterion.

In addition, we see that the total number of Newton iterations (ie. for all centering steps) is the smallest for mu between 10 and 20, range which can be seen as achieving a compromise between the number of inner Newton iterations and the number of centering steps.



However I did not manage to interpret consistently the final subquestion relative to the impact on w.

From the strong duality (convex problem, linear equality constraints), we have that $z^*=v^*$ (cf. question 1), where the dual variable v is first called mu) or equally said that $Xw^*=v^*+y$. Hence one could recover an estimate of the primal solution w^* from the estimates of the dual solution v^* using the pseudo inverse of X.

However, how to interpret the difference between the true w (the one we used to generate the data) and the ones estimated by the lasso, since the lambda parameter of the lasso, ie. the weight of the L1-regularization, is not necessarily adequate with the number of non-zero entries we chose when generating w? Therefore, I am not sure about which information we could get (in addition to the first plot) from such an error curb, regarding the choice of mu.