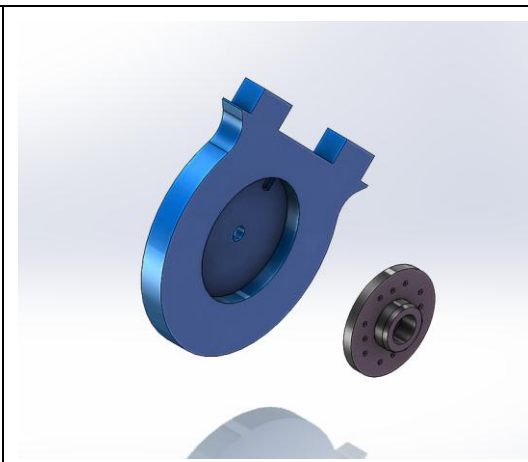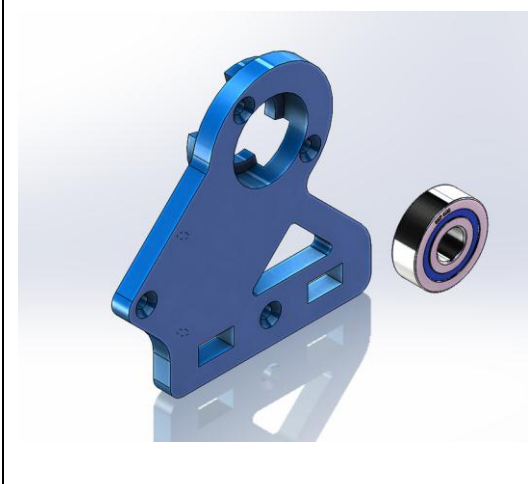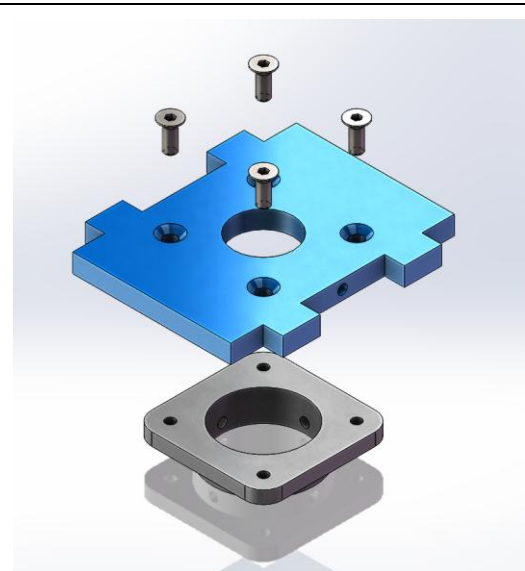|	
Task 1 – Insert the Servo arm into the ATrack-Helical Mounting Plate Left Arm. Glue in position using 2 Part Epoxy.	
Task 2 – *Insert 608zz Bearing into the ATrack-Main Arm Right.*	
Task 3 – Using an M3 Tap wrench Tap the 4 holes used to fix the Servo to the *ATrack-Main Arm Left.* Screw the Standard size servo (HS-322HD) to the *ATrack-Main Arm Left using 4 x M3 x 5mm SHC Screws.*	

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Task 4 –

Using an M3 Tap Wrench Tap the 4 holes in the ATrack-Bottom Plate Servo Mount.

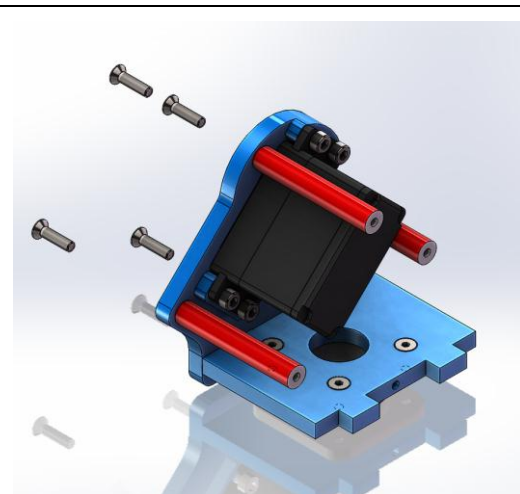Screw the ATrack-Bottom Plate to the ATrack-Bottom Plate Servo Mount using M3 x 8mm CSK Hex Screws.

Task 5 –

Using an M3 Tap Wrench Tap both hole's used to fix the ATrack-Bottom Plate to the ATrack Main Arms and tap each end of the 3 x 40mm Spacers.

Screw the ATrack Main Arm Left to ATrack-Bottom Plate using 1 x M3 x 12mm CSK Hex screw.

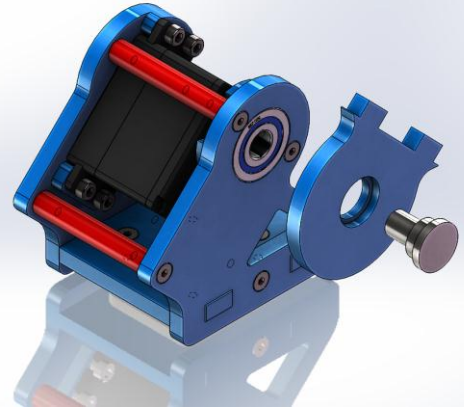Screw the 40mm Spacers to the ATrack Main Arm Left using 3 x M3 x 12mm CSK Hex Screws.

Task 9 –

Screw the ATrack-Main Arm Right to the assembly using 4 x M3 x 12mm CSK Hex Screws.

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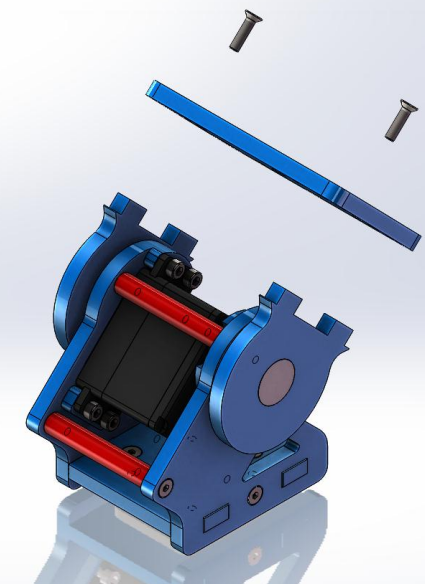|	
Task 10 - Push the ATrack-Alloy Pin through the ATrack-Helical Mounting Plate Right Arm and into the 608zz Bearing.	
Task 11 – *Push the assembled servo arm from Task 1 onto the servo spline and screw In place using the screw supplied with your servo.* *(it would be a good idea at this stage to plug your sevor into a powered receiver to centre your servo before fixing the servo arm in place)*	

Task 12 – Using an M3 Tap Wrench Tap both hole's used to fix the ATrack-Helical Mounting Plate. Screw the ATrack-Helical Mounting Plate to the assembly using 2 x M3 x 10mm CSK Hex.	